

Introduction to Data Mining

04 - Principal Component Analysis

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WS 2023/2024, Bielefeld University

Registration for Presentations

- ▶ Registration for homework presentations is open.



Link: [Registration](#)

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- ▶ First come-first serve principle.



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- ▶ Submit other questions for the tutorials: [Link](#)



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- ▶ Voluntary for now; your feedback is appreciated!

Outline for this lecture

- ▶ (Almost) Full derivation of PCA, based on Ren and MacKay (2019)
- ▶ Factor analysis
- ▶ Factor rotations

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Examples:

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- ▶ Fourier transform
- ▶ Eigenfaces

Spooky example

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| mysterious loss of blood | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| two punctures on the neck | 1 | 1 | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| slash and bite wounds | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| paw prints | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| animal hair | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| full moon | 0 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 |
| age | 78 | 49 | 44 | 24 | 29 | 31 | 50 | 63 | 73 | 27 | 62 | 49 |

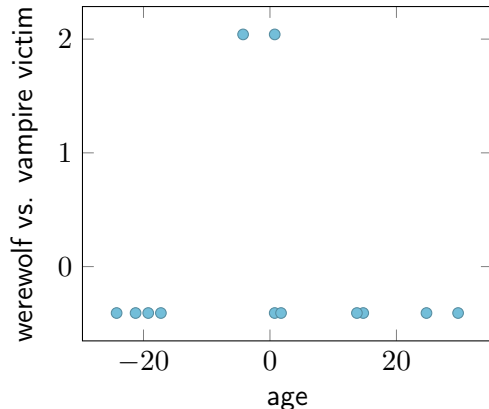
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- Which patterns jump out at you?

Spooky example (continued)

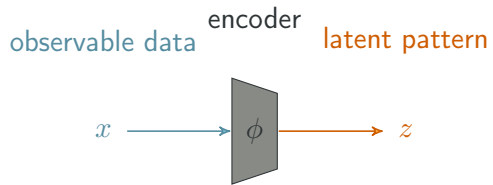
| feature | v_1 | v_2 |
|---------------------------|-------|-------|
| mysterious loss of blood | 0.00 | -0.41 |
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| age | 1.00 | 0.00 |

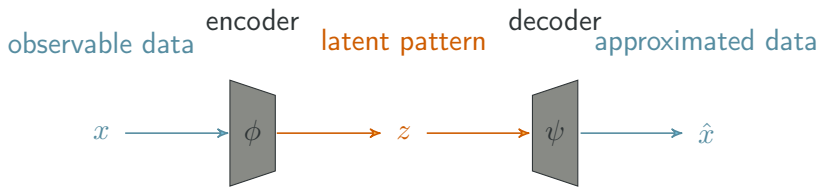


Principal Component Analysis

observable data

x





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- ▶ We try to find encoding function ϕ and decoding function ψ s.t. reconstruction error is minimized:

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- ▶ **But** both ϕ and ψ are affine maps

$$z = \phi(x) = \mathbf{U} \cdot x + a$$

$$\text{where } \mathbf{U} \in \mathbb{R}^{n \times m}, a \in \mathbb{R}^n$$

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- ▶ Trick question: What is the solution for $n \geq m$?

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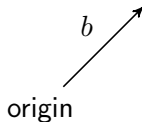
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6. Find optimal V

Decoding: Geometric interpretation

- ▶ Assume $m = 3$ and $n = 2$, and let v_1, v_2 be the columns of V .

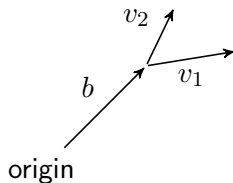
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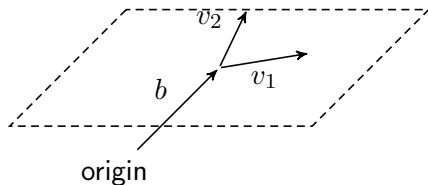
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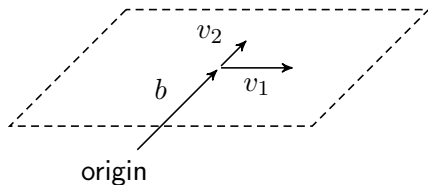
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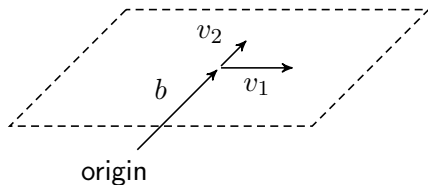
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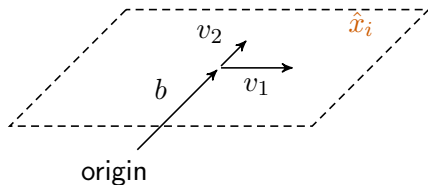
x_i



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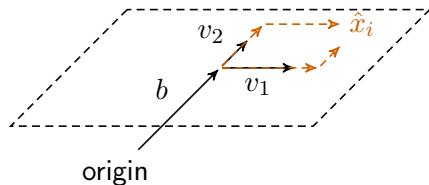
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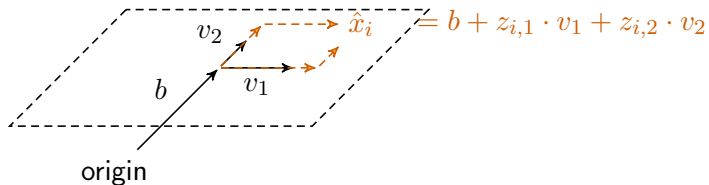
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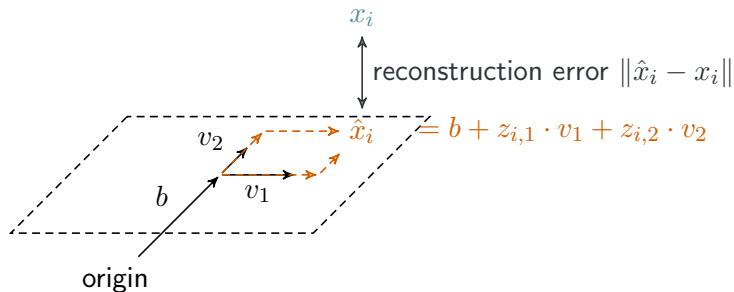
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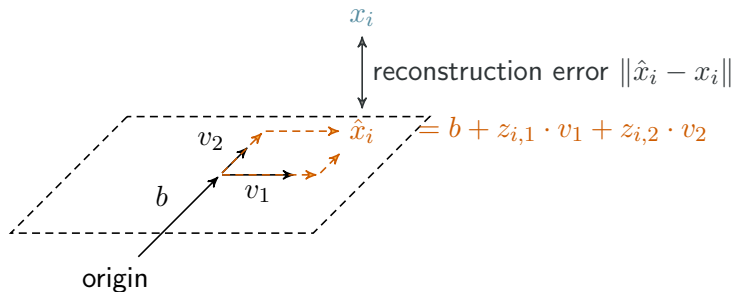
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In summary:

- ▶ Columns of V span a hyperplane that contains all possible decoded points
- ▶ Without loss of generality, we can assume V to be (semi-)orthogonal
- ▶ ... which means $V^T V = I$ (but $V V^T \neq I$!)

- ▶ Let's inspect the equation for \hat{x}_i :

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- ⇒ We can set a however we want, because b can correct for it
- ⇒ Without loss of generality, set $a = -\mathbf{U}\mu$, where μ is the mean: $\mu = \frac{1}{N} \sum_{i=1}^N x_i$

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Setting the gradient to zero yields $b = \mu$.

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$$\begin{aligned}\ell(\mathbf{U}) &= \sum_{i=1}^N \|\mathbf{V}z_i + \mu - x_i\|^2 \\ &= \sum_{i=1}^N \|\mathbf{V}\mathbf{U}(x_i - \mu) - (x_i - \mu)\|^2\end{aligned}$$

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$$\begin{aligned}\ell(U) &= \sum_{i=1}^N \|V z_i + \mu - x_i\|^2 \\ &= \sum_{i=1}^N \|V U (x_i - \mu) - (x_i - \mu)\|^2 \\ &= \sum_{i=1}^N (x_i - \mu)^T U^T V^T V U (x_i - \mu) - 2(x_i - \mu)^T U^T V^T (x_i - \mu) + (x_i - \mu)^T (x_i - \mu)\end{aligned}$$

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Deriving the optimal encoder (continued)

Let's compute the gradient:

$$\nabla_U \ell(\mathbf{U}) = \sum_{i=1}^N 2\mathbf{U}(x_i - \mu)(x_i - \mu)^T - 2\mathbf{V}^T(x_i - \mu)(x_i - \mu)^T$$

Deriving the optimal encoder (continued)

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- **attention!** The last step is only valid because C is positive (semi-)definite and, hence, invertible

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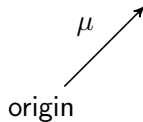
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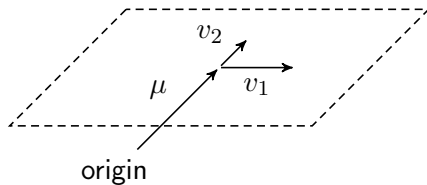
⇒ Therefore (and because \mathbf{V} is orthogonal), $\mathbf{U} = \mathbf{V}^T$

⇒ Only \mathbf{V} remains to be optimized – for which we need some geometry, again

Geometric interpretation (continued)

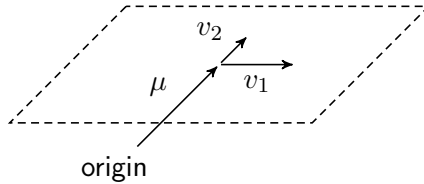


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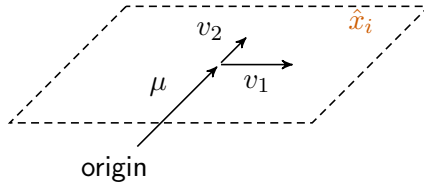
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x_i

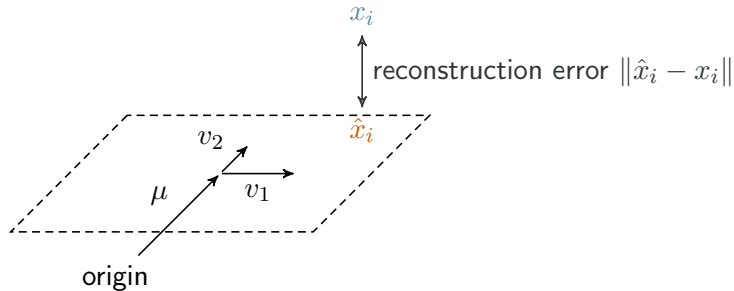


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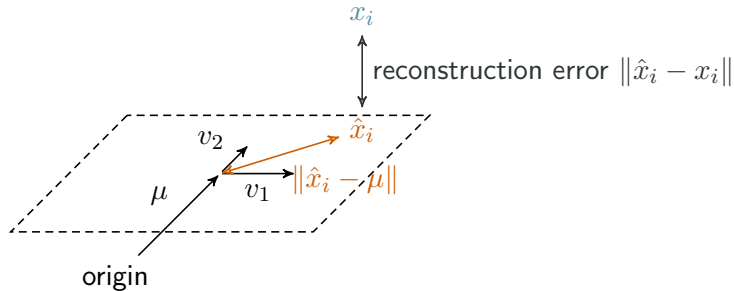
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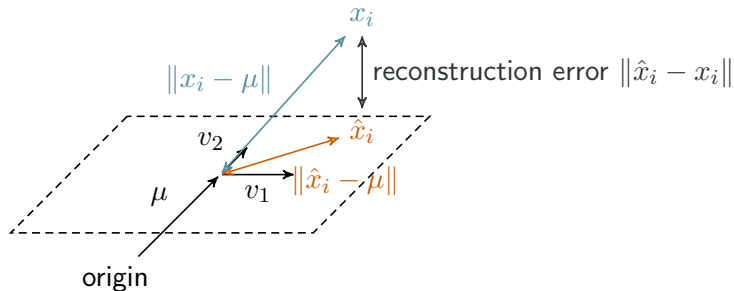
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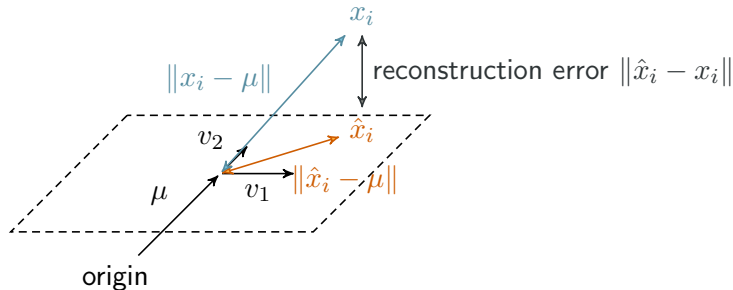


Geometric interpretation (continued)

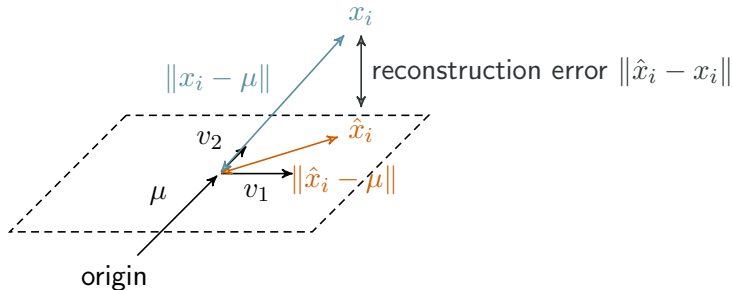


Geometric interpretation (continued)

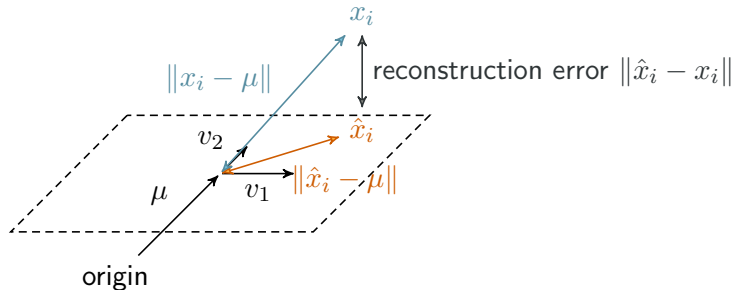




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- ⇒ Pythagoras: $\|\hat{x}_i - x_i\|^2 + \|\hat{x}_i - \mu\|^2 = \|x_i - \mu\|^2$

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New optimization target

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Deriving the optimal \mathbf{V}

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- Trick: To achieve orthogonal \mathbf{V} , optimize one column at a time; search for next column in orthogonal subspace, etc.

Deriving the first principal component

Recall: We need to set v to maximize

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⇒ Lagrangian is given as $\ell(v, \lambda) = -v^T \mathbf{C} v - \lambda \cdot (1 - v^T v)$

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Summary: PCA procedure

function PCA(data matrix \mathbf{X} with N rows and m columns, desired latent dimensionality $n \leq m$)

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return $\phi(x) = \mathbf{V}^T \cdot (x - \mu)$ and $\psi(z) = \mathbf{V} \cdot z + \mu$.

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Implementation: `sklearn.decomposition.PCA`

- Recall: Objective becomes variance of the data $\sum_{i=1}^N \|\hat{x}_i - \mu\|^2 = \lambda$

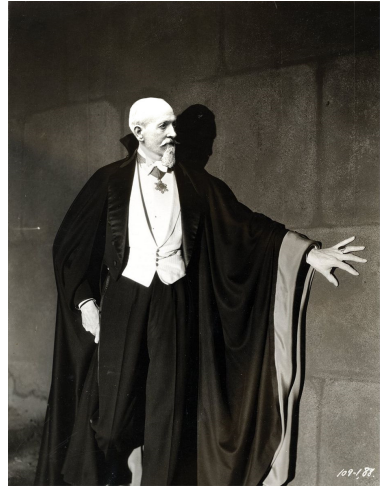
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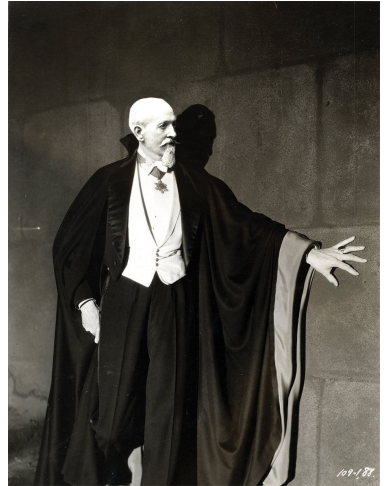
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- ⇒ Set n high enough to retain most of the variance (e.g. 95%)

Factor Analysis

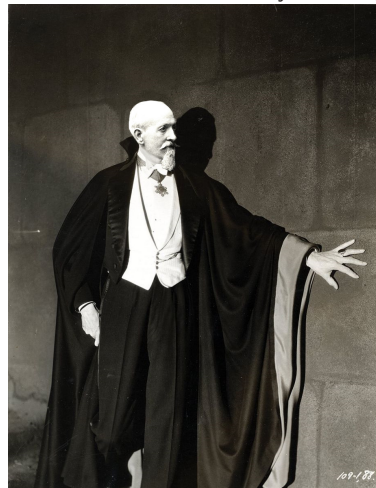
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- ▶ “Modern” Factor Analysis: Probabilistic version of PCA



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- ▶ “Modern” Factor Analysis: Probabilistic version of PCA
- ▶ Full derivation bit too complicated for this lecture ⇒ Refer to Barber (2012)



- ▶ Assume data is generated as $x = \mathbf{V}z + b + \epsilon$

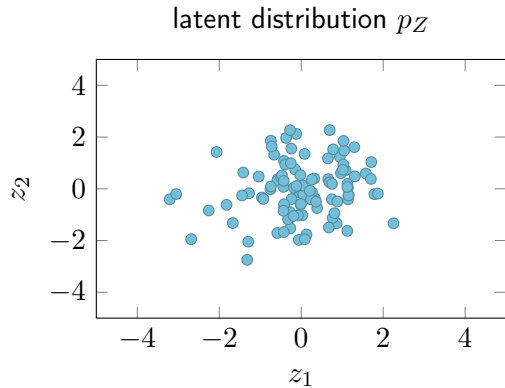
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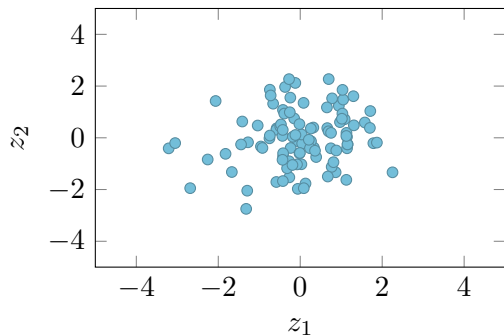
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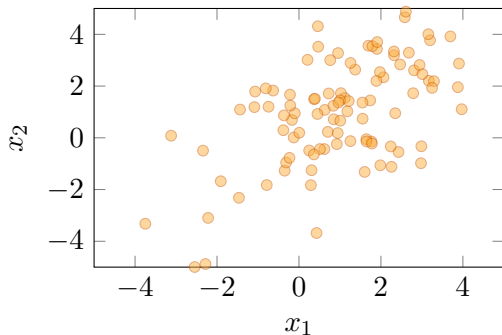
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- $\Rightarrow p_X(x)$ is Gaussian with mean b and covariance $\mathbf{V}\mathbf{V}^T + \Psi$ (this is not a trivial result! Follows from theory of Gaussians)



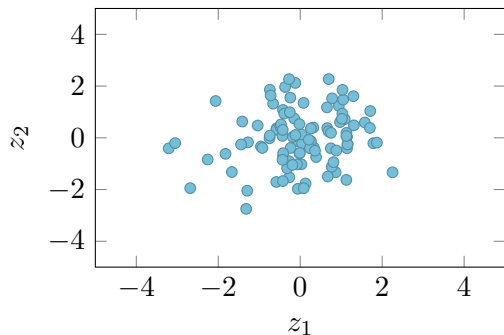
latent distribution p_Z



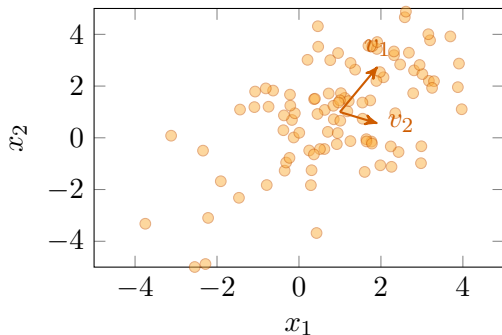
data distribution p_X



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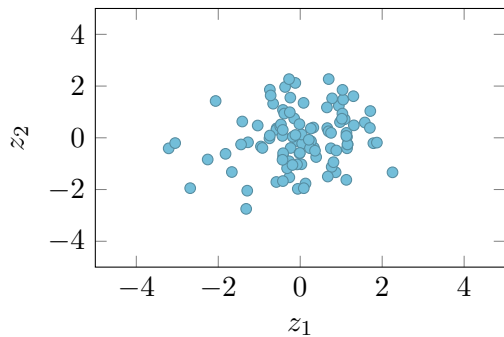


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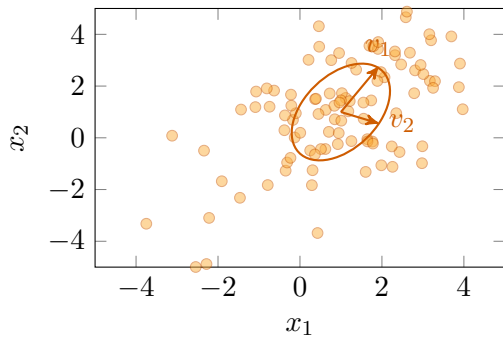




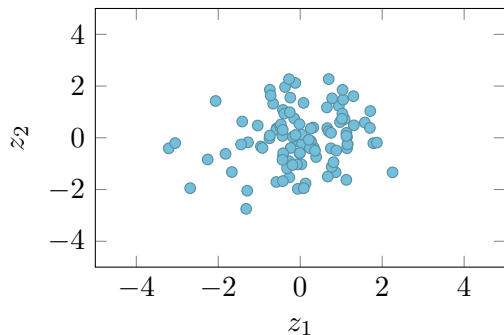
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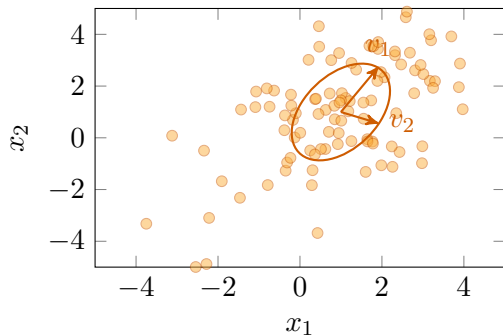
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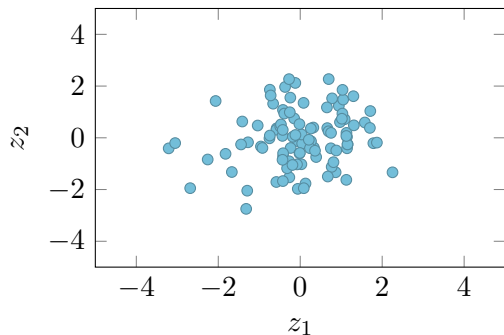


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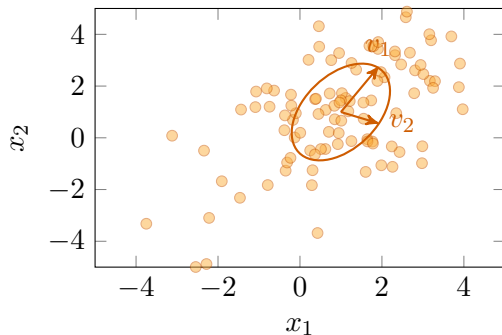


- V rotates and stretches data distribution

latent distribution p_Z



data distribution p_X



- ▶ V rotates and stretches data distribution
- ▶ columns of V can be interpreted as principal axes of the hyper-ellipse that forms the isoline of p_X (up to noise)

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$$\ell(\mathbf{V}, \mathbf{\Psi}, b) = \sum_{i=1}^N \frac{1}{2} \log \left[\det(2\pi\Sigma) \right] + \frac{1}{2}(x_i - b)^T \Sigma^{-1}(x_i - b)$$

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► Optimal \mathbf{V} is much harder to determine, requires a few tricks (Barber 2012)

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function FA(data matrix \mathbf{X} with N rows and m columns, desired latent dimensionality $n \leq m$)

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$\mathbf{V} \leftarrow \Psi^{\frac{1}{2}} \mathbf{U} \mathbf{\Lambda}^{\frac{1}{2}}$.

end for

end function

function FA(data matrix \mathbf{X} with N rows and m columns, desired latent dimensionality $n \leq m$)

 Compute mean $\mu = \frac{1}{N} \sum_{i=1}^N x_i$.

 Compute covariance matrix $\mathbf{C} = \frac{1}{N} \sum_{i=1}^m (x_i - \mu) \cdot (x_i - \mu)^T$.

 Set initial noise to $\Psi \leftarrow \text{diag}(\mathbf{C})$.

for desired number of iterations **do**

 Compute $\tilde{\mathbf{C}} \leftarrow \Psi^{-\frac{1}{2}} \mathbf{C} \Psi^{-\frac{1}{2}}$.

 Compute eigenvalue decomposition $\tilde{\mathbf{C}} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^T$.

 Keep only the n largest eigenvalues in $\mathbf{\Lambda}$ and the corresponding columns of \mathbf{U} .

$\mathbf{V} \leftarrow \Psi^{\frac{1}{2}} \mathbf{U} \mathbf{\Lambda}^{\frac{1}{2}}$.

$\Psi \leftarrow \text{diag}(\mathbf{C}) - \text{diag}(\mathbf{V} \mathbf{V}^T)$.

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end for

return \mathbf{V} , μ , Ψ .

end function

- ▶ Implementation: `sklearn.decomposition.FactorAnalysis`

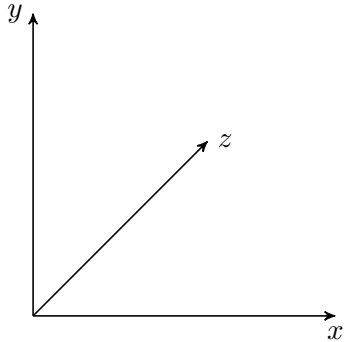
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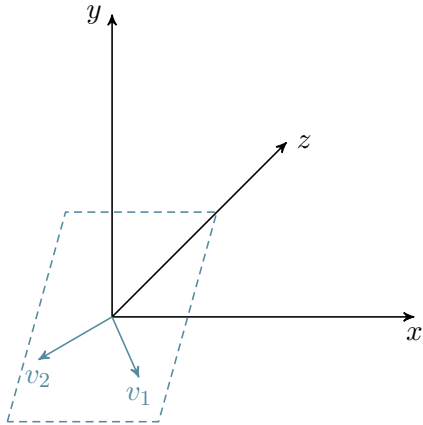
- ▶ Implementation: `sklearn.decomposition.FactorAnalysis`
- ▶ For $\Psi = \mathbf{0}$ (i.e.: no noise), model becomes equivalent to PCA
- ▶ But: V is not normalized
- ▶ Note: Encoding is **not** the focus of FA (it still works, though)

Factor Rotations

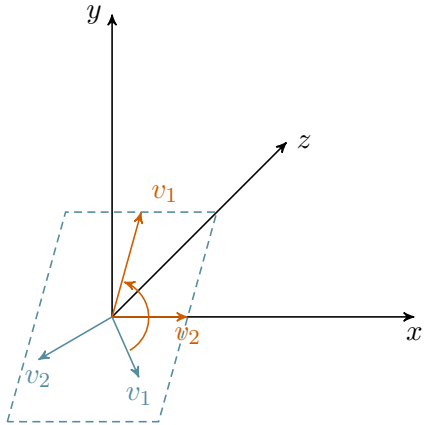
Factor Rotation Example



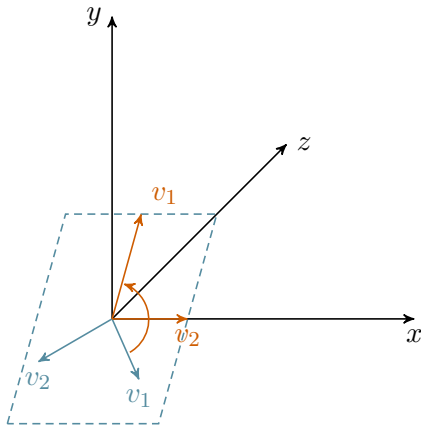
Factor Rotation Example



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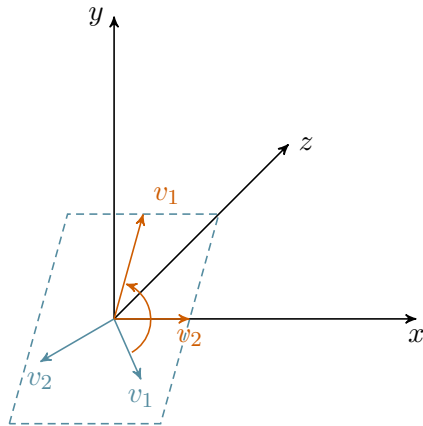


Factor Rotation Example



If R is a rotation matrix,
using VR instead of V has no effect

Factor Rotation Example



If \mathbf{R} is a rotation matrix,
using \mathbf{VR} instead of \mathbf{V} has no effect

because $\mathbf{VR}(\mathbf{VR})^T = \mathbf{VRR}^T\mathbf{V}^T = \mathbf{VV}^T$

- ▶ Choose the rotation \mathbf{R} that makes the factors “easiest to interpret”

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- ▶ Maximize variance in latent coordinates $\max_{\mathbf{R}} \sum_{i=1}^N \sum_{j=1}^n z_{i,j}^2$
- ▶ Nonlinear optimization, not discussed here, but implemented in Implementation: `sklearn.decomposition.FactorAnalysis`

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- ▶ factor analysis is more robust to noise but needs more iterations
- ▶ Interpretability can be enhanced with factor rotations

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