

# Machine Learning

Daniel Drake

May 11, 2020

## 1 Gradients, Jacobian, Ferchet Drivative, and Sub-Gradients

### Theorem 1.1. *Gradient*

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  be a Differentiable function.

Then  $\nabla f : \mathbb{R}^n \rightarrow \mathbb{R}^n$  where:

$$\nabla f(x) := \begin{bmatrix} \frac{\partial}{\partial x_1} f(x) \\ \vdots \\ \frac{\partial}{\partial x_n} f(x) \end{bmatrix} \forall x \in \mathbb{R}^n$$

is called the Gradient of  $f$ .

### Theorem 1.2. *Jacobian*

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$  where:

$$f(x) = \begin{bmatrix} f_1(x) \\ \vdots \\ f_m(x) \end{bmatrix} \forall x \in \mathbb{R}^n \text{ and } (\forall j \in \mathbb{N}_m)(f_j : \mathbb{R}^n \rightarrow \mathbb{R})$$

Then  $J_f : \mathbb{R}^n \rightarrow \mathbb{R}^{n \times m}$  where:

$$J_f(x) := \begin{bmatrix} \frac{\partial}{\partial x_1} f_1(x) & \cdots & \frac{\partial}{\partial x_n} f_1(x) \\ \vdots & \ddots & \vdots \\ \frac{\partial}{\partial x_1} f_m(x) & \cdots & \frac{\partial}{\partial x_n} f_m(x) \end{bmatrix}$$

### Theorem 1.3. *When the Jacobian is the Gradient*

Let  $f : \mathbb{R}^n \rightarrow \mathbb{R}$

Then  $(\nabla f(x) = (J_f(x))^T)(\forall x \in \mathbb{R}^n)$

### Theorem 1.4. *Chain Rule* Let $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $g : \mathbb{R}^m \rightarrow \mathbb{R}^k$ be differentiable functions.

Then:  $J_{g \circ f}(x) = J_g(f(x))J_f(x)$

## 2 Finite Composition Operator

### Definition 2.1. *Finite Composition Operator*

Let the collection  $X = \{X_j\}_{j=0}^n$  be a finite sequence of sets.

Further let  $\{T_j\}_{j=0}^{n-1}$  be a finite sequence of operators such that  $(\forall j \in \mathbb{N}_{n-1})(T_j : X_j \rightarrow X_{j+1})$   
Then  $T : X_0 \rightarrow X_n$  defined by:

$$T := \bigcirc_{j=0}^{n-1} T_j := \dots$$

is called the **Finite Composition Operator defined on  $X$** .

**Theorem 2.1. Finite Composition Jacobian**

Let  $T$  be defined as above.

Then:

$$J_T(x) = \dots$$

And so to calculate  $J_T$  we need to calculate each  $J_{T_j}$  for each  $j$  only once.

Proof on the next page:

*Proof:*

*Case:  $n = 1$*

$$X = \{X_0, X_1\}$$

$$T_0 : X_0 \rightarrow X_1$$

$$T^1(x) = T_0(x)$$

$$J_{T^1}(x) = J_{T_0}(x)$$

*Case:  $n = 2$*

$$X = \{X_0, X_1, X_2\}$$

$$T_0 : X_0 \rightarrow X_1$$

$$T_1 : X_1 \rightarrow X_2$$

$$T^2(x) = (T_1 \circ T_0)(x)$$

$$J_{T^2}(x) = J_{T_1 \circ T_0}(x) = J_{T_1}(T_0(x))J_{T_0}(x) = (J_{T_1} \circ T_0)(x) * J_{T_0}(x)$$

*Case:  $n = 3$*

$$X = \{X_0, X_1, X_2, X_3\}$$

$$T_0 : X_0 \rightarrow X_1$$

$$T_1 : X_1 \rightarrow X_2$$

$$T_2 : X_2 \rightarrow X_3$$

$$T^3(x) = (T_2 \circ T_1 \circ T_0)(x) = (T_2 \circ T^2)(x)$$

$$J_{T^3}(x) = J_{T_2 \circ T^2}(x) = J_{T_2}(T^2(x))J_{T^2}(x) = (J_{T_2} \circ T_1 \circ T_0)(x) * J_{T^2}(x) = (J_{T_2} \circ T_1 \circ T_0)(x) * ((J_{T_1} \circ T_0)(x) * J_{T_0}(x))$$

*Case:  $n = k$*

$$X = \{X_0, \dots, X_k\}$$

$$T_0 : X_0 \rightarrow X_1$$

$$\vdots$$

$$T_{k-1} : X_{k-1} \rightarrow X_k$$

$$T^k(x) = (\bigcirc_{j=0}^{k-1} T_j)(x) = (T_{k-1} \circ T^{k-1})(x)$$

$$J_{T^k}(x) = J_{T_{k-1} \circ T^{k-1}}(x) = J_{T_{k-1}}(T^{k-1}(x))J_{T^{k-1}}(x)$$

**Theorem 2.2. Examples:**

Let  $T : \mathbb{R}^n \rightarrow \mathbb{R}^n$  such that:

$$T(x) := \begin{bmatrix} \arctan(\pi_1(x)) \\ \vdots \\ \arctan(\pi_n(x)) \end{bmatrix} = \begin{bmatrix} \arctan(x_1) \\ \vdots \\ \arctan(x_n) \end{bmatrix}$$

Then

$$\begin{aligned} J_T(x) &= \begin{bmatrix} \frac{\partial}{\partial x_1} T_1(x) & \cdots & \frac{\partial}{\partial x_n} T_1(x) \\ \vdots & \ddots & \vdots \\ \frac{\partial}{\partial x_1} T_n(x) & \cdots & \frac{\partial}{\partial x_n} T_n(x) \end{bmatrix} = \begin{bmatrix} \frac{\partial}{\partial x_1} \arctan(x_1) & \cdots & \frac{\partial}{\partial x_n} \arctan(x_1) \\ \vdots & \ddots & \vdots \\ \frac{\partial}{\partial x_1} \arctan(x_n) & \cdots & \frac{\partial}{\partial x_n} \arctan(x_n) \end{bmatrix} \\ &= \begin{bmatrix} \frac{\partial}{\partial x_1} \arctan(x_1) & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \frac{\partial}{\partial x_n} \arctan(x_n) \end{bmatrix} = \begin{bmatrix} \frac{1}{x_1^2+1} & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & \frac{1}{x_n^2+1} \end{bmatrix} = I \begin{bmatrix} \frac{1}{x_1^2+1} \\ \vdots \\ \frac{1}{x_n^2+1} \end{bmatrix} \end{aligned}$$

**Theorem 2.3. Examples:**

Let  $T_b : \mathbb{R}^n \rightarrow \mathbb{R}^n$  such that:

$$T_b(x) := \begin{bmatrix} \pi_1(x) + b_1 \\ \vdots \\ \pi_n(x) + b_n \end{bmatrix} = \begin{bmatrix} x_1 + b_1 \\ \vdots \\ x_n + b_n \end{bmatrix}$$

Then

$$J_{T_b}(x) = \begin{bmatrix} \frac{\partial}{\partial x_1} [x_1 + b_1] & \cdots & \frac{\partial}{\partial x_n} [x_1 + b_1] \\ \vdots & \ddots & \vdots \\ \frac{\partial}{\partial x_1} [x_1 + b_1] & \cdots & \frac{\partial}{\partial x_n} [x_n + b_n] \end{bmatrix} = \begin{bmatrix} x_1 & \cdots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \cdots & x_n \end{bmatrix} = Ix$$

**Theorem 2.4. Examples:**

Let  $T_A : \mathbb{R}^n \rightarrow \mathbb{R}^m$  such that:

$$T_A(x) := \begin{bmatrix} \langle a_1, x \rangle \\ \vdots \\ \langle a_m, x \rangle \end{bmatrix} = \begin{bmatrix} \sum_{j=1}^n a_{1,j} x_j \\ \vdots \\ \sum_{j=1}^n a_{m,j} x_j \end{bmatrix} = \begin{bmatrix} a_{1,1} & \cdots & a_{1,n} \\ \vdots & \ddots & \vdots \\ a_{m,1} & \cdots & a_{m,n} \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = Ax$$

Then:

$$J_{T_A}(x) = \begin{bmatrix} \frac{\partial}{\partial x_1} \left[ \sum_{j=1}^n a_{1,j} x_j \right] & \cdots & \frac{\partial}{\partial x_n} \left[ \sum_{j=1}^n a_{1,j} x_j \right] \\ \vdots & \ddots & \vdots \\ \frac{\partial}{\partial x_1} \left[ \sum_{j=1}^n a_{m,j} x_j \right] & \cdots & \frac{\partial}{\partial x_n} \left[ \sum_{j=1}^n a_{m,j} x_j \right] \end{bmatrix} = \begin{bmatrix} a_{1,1} x_1 & \cdots & a_{1,n} x_n \\ \vdots & \ddots & \vdots \\ a_{m,1} x_1 & \cdots & a_{m,n} x_n \end{bmatrix}$$

### 3 Surjective Continuous Non-decreasing Bounded Functionals

Let  $B = \{f : \mathbb{R} \rightarrow [0, 1] \mid f \text{ is continuous and non-decreasing.}\}$

**Theorem 3.1.**  *$B$  is convex.*

**Theorem 3.2.**  *$B$  is translation invariant.*

**Theorem 3.3.**  *$B$  is not complete.*

**Theorem 3.4.** *Every element in  $B$  can be decomposed as a finite convex combination from  $B$*