check_and_create_pid_file →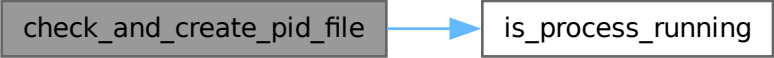 is_process_running