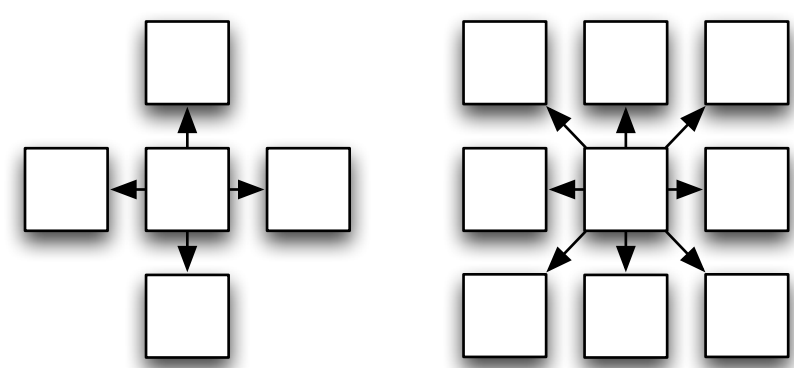


Fast and Optimal Pathfinding On Grid Maps

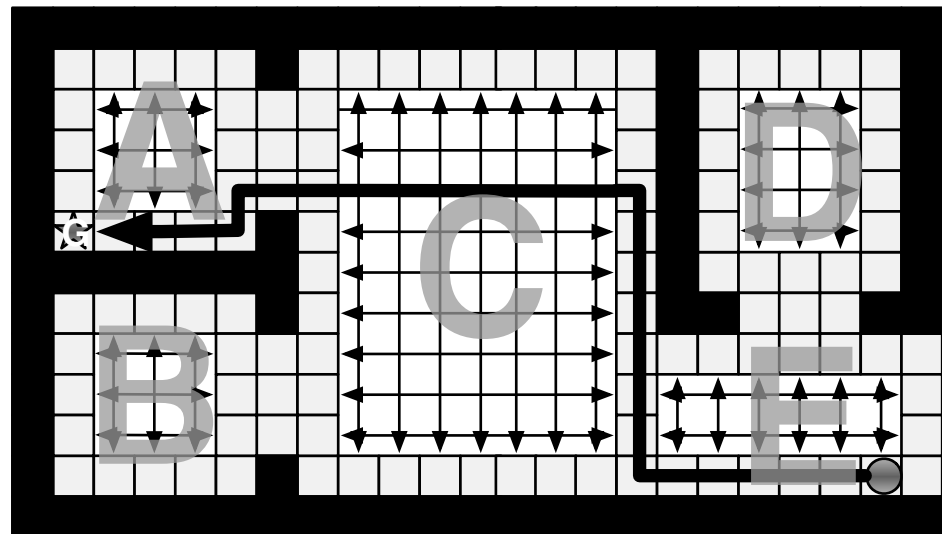
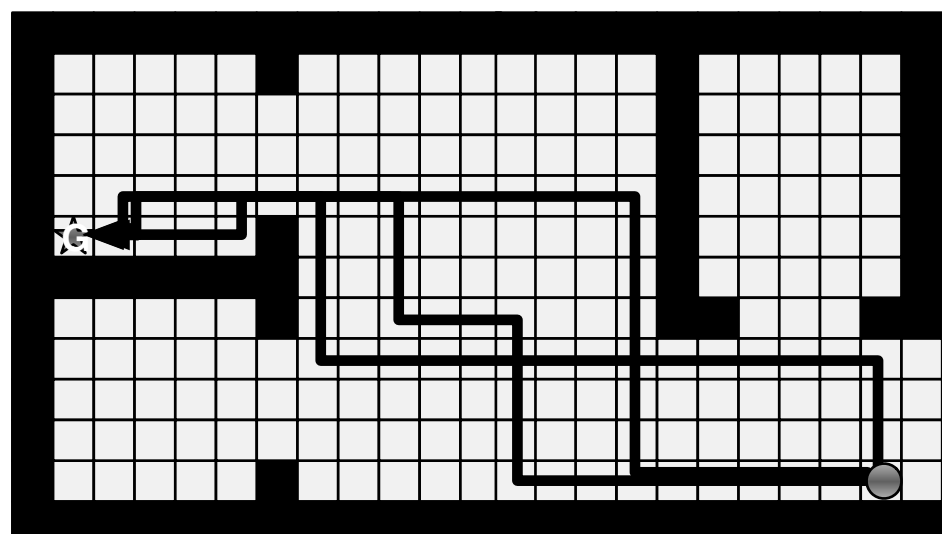
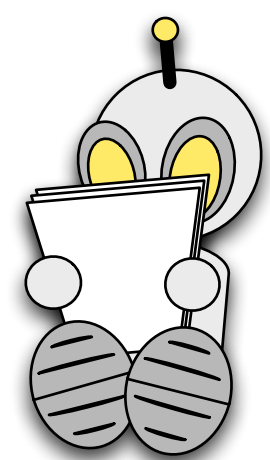
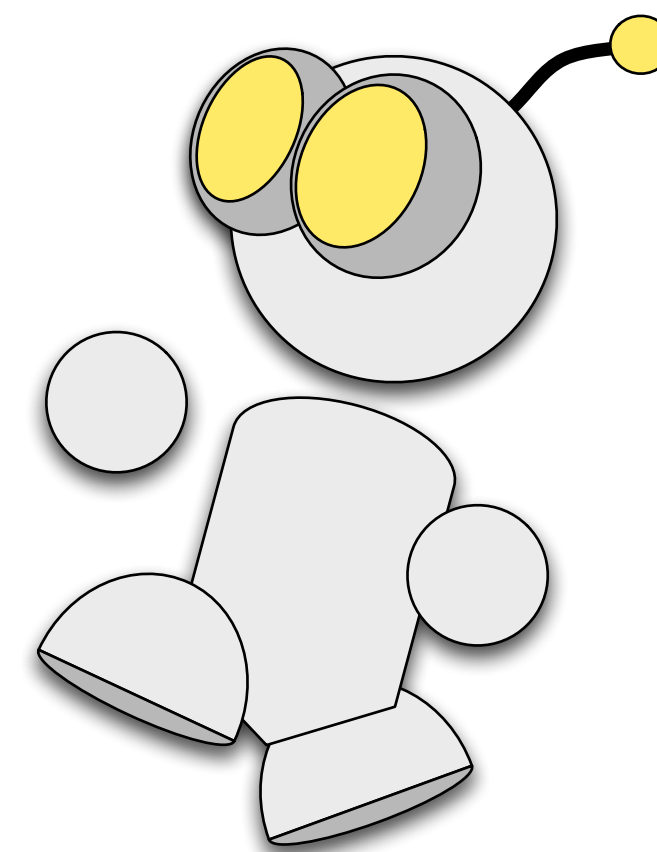
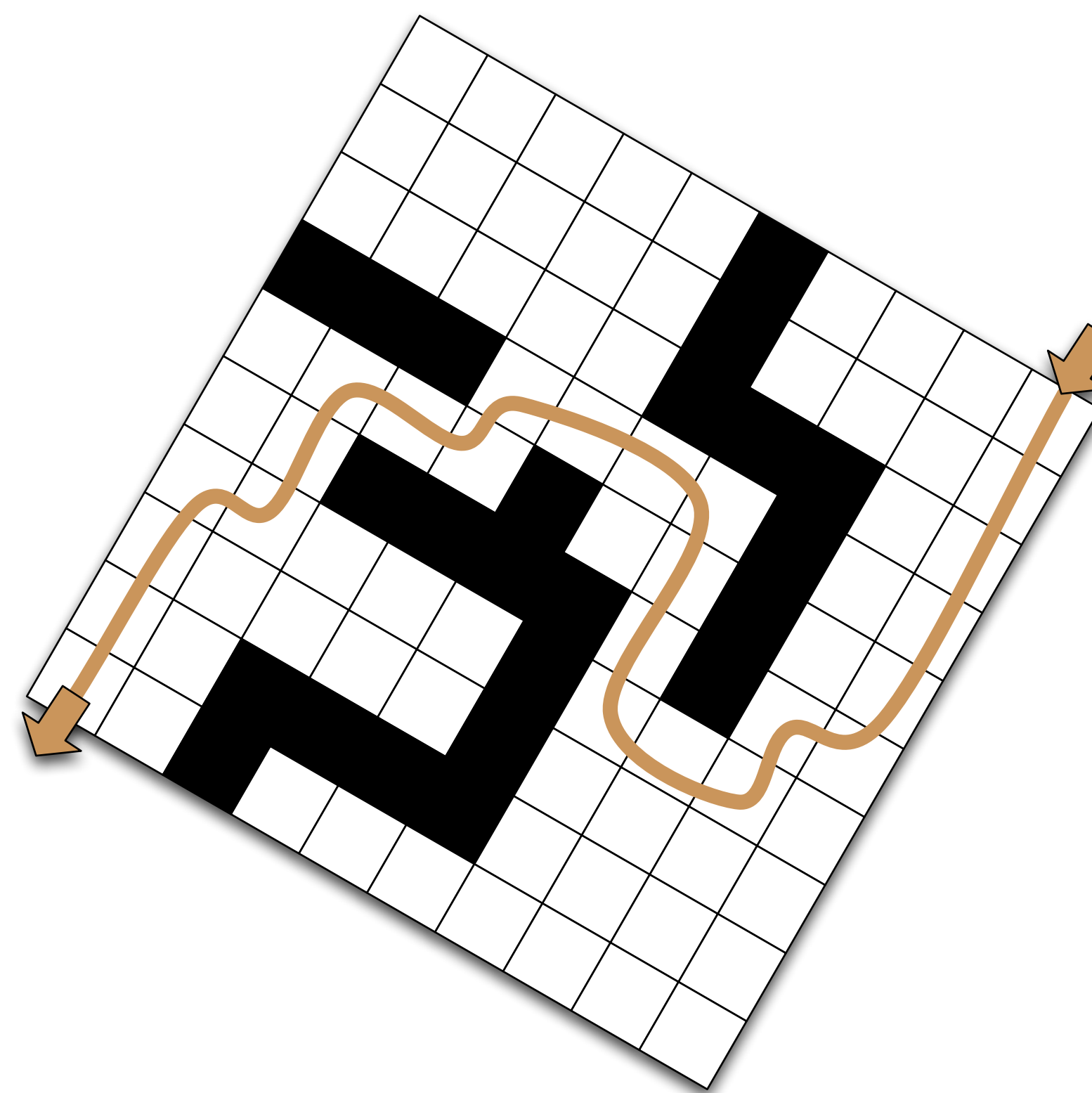
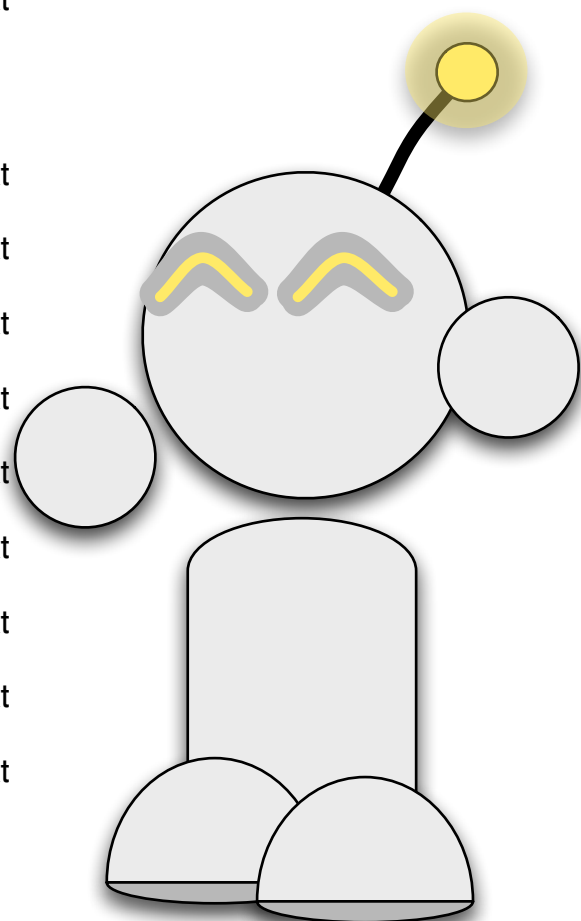
The Problem

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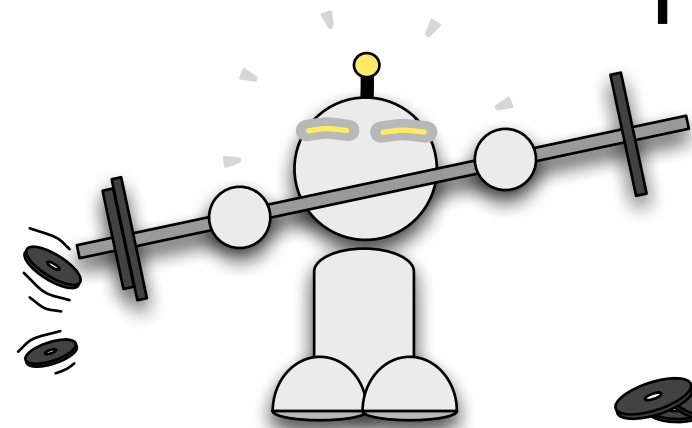
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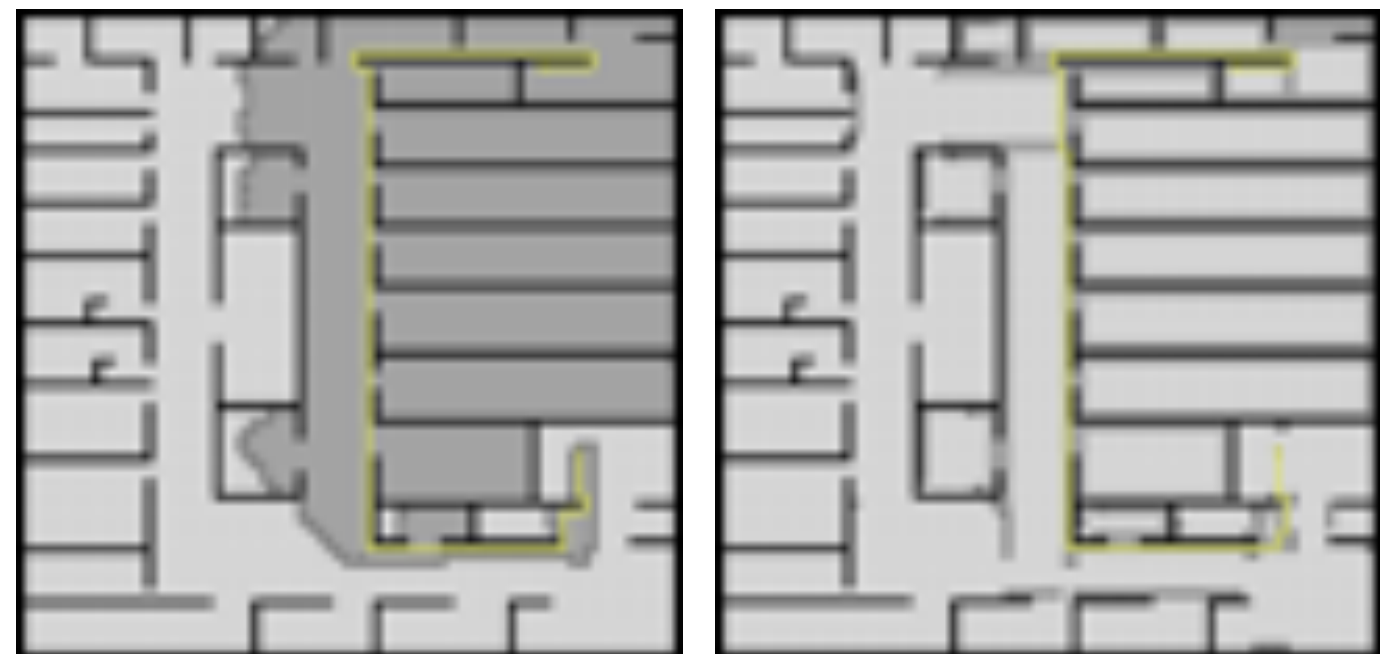
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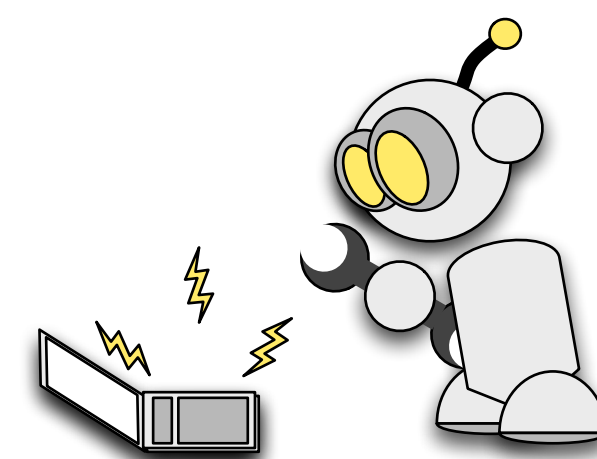
Results



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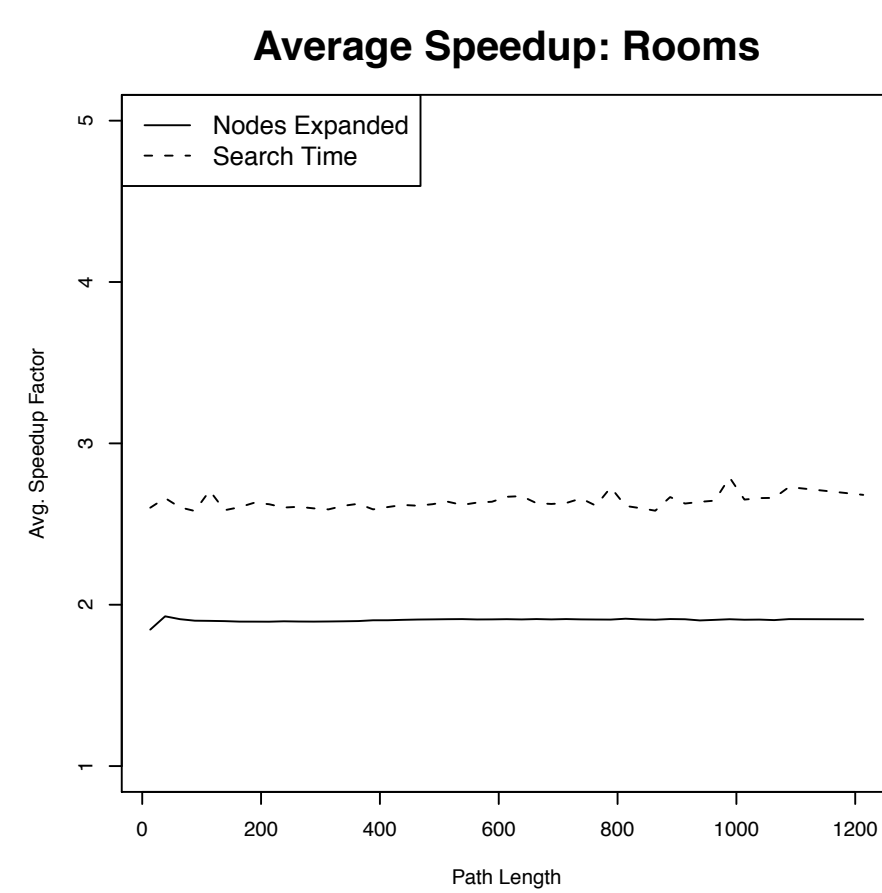
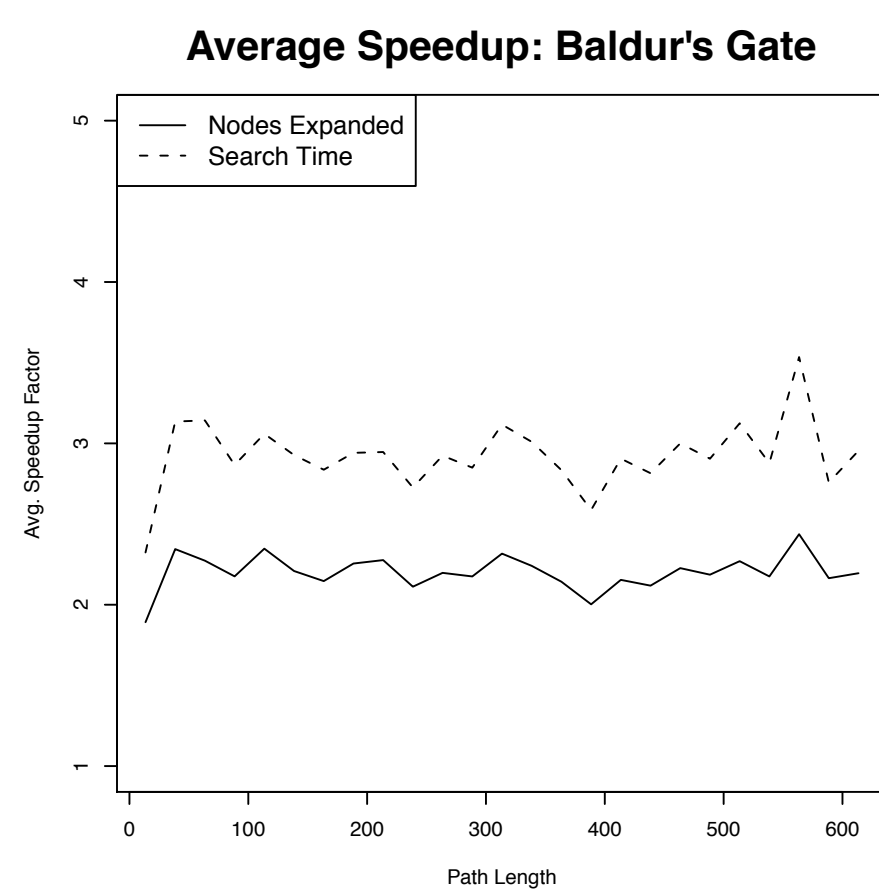
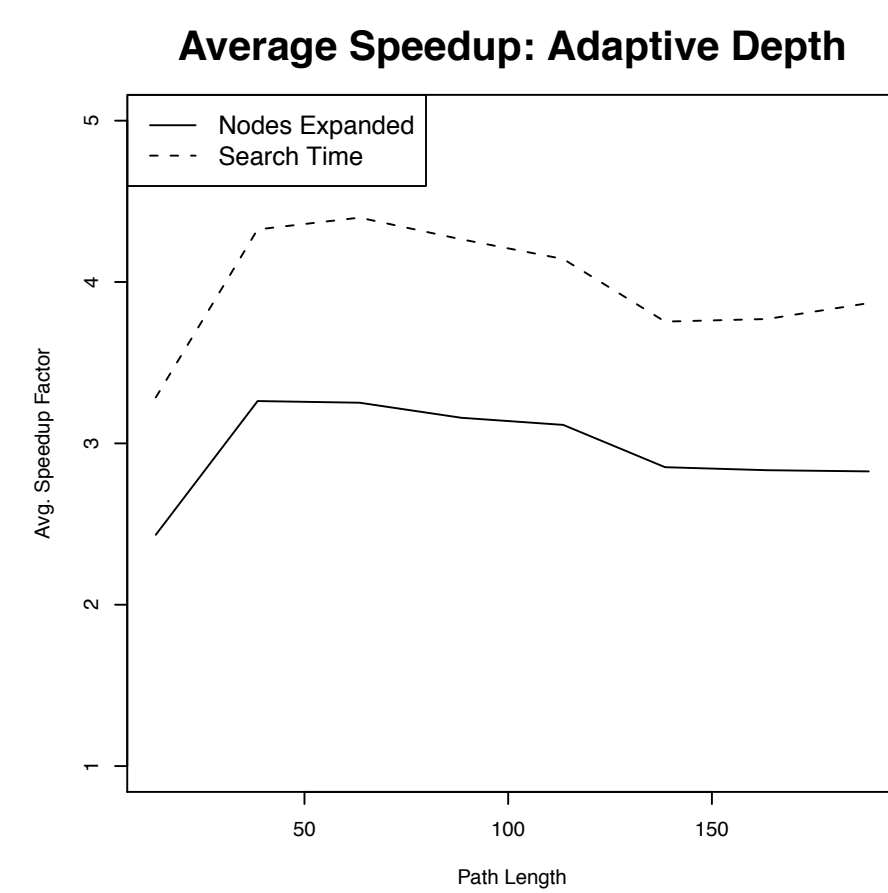
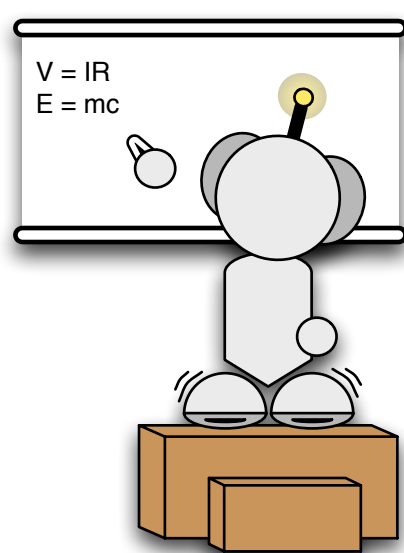
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Future Work

[illegible]

The Big Idea

[illegible]

More Information

[illegible]