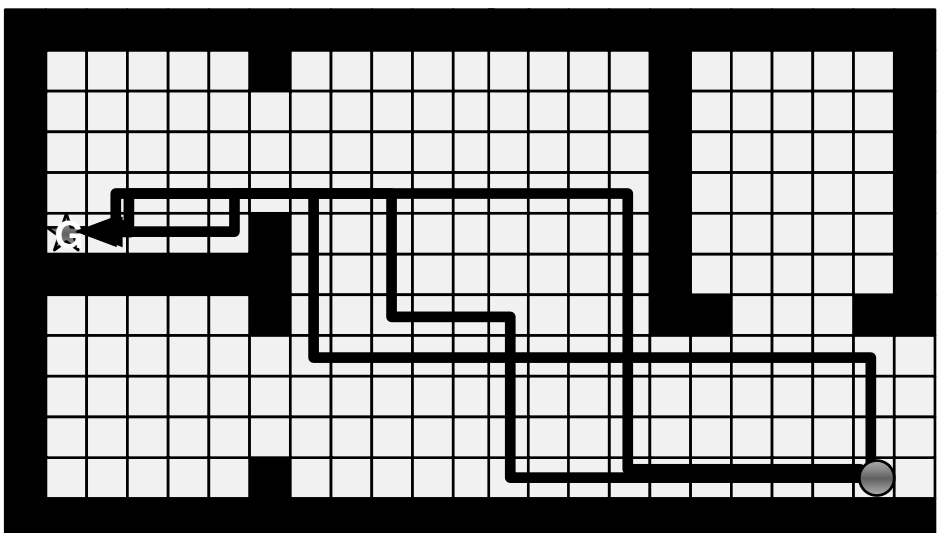
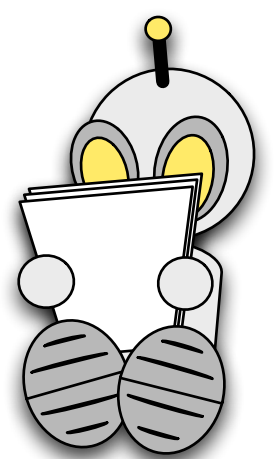


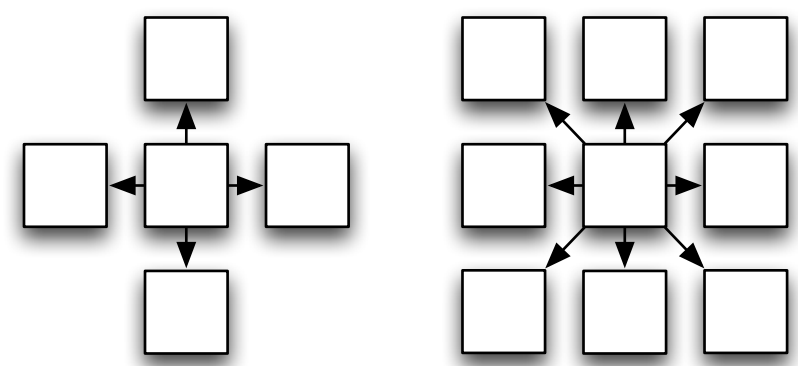
# Fast and Optimal Pathfinding On Grid Maps

## The Problem

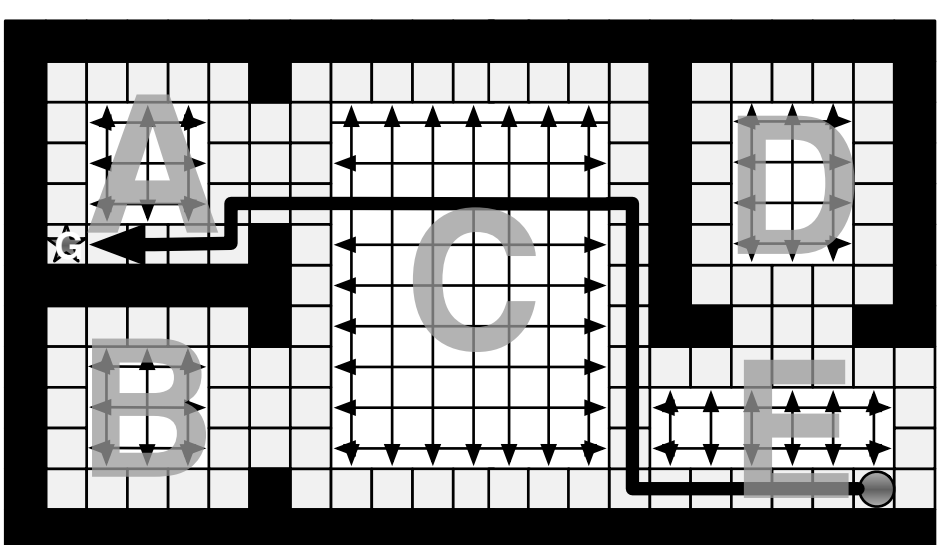
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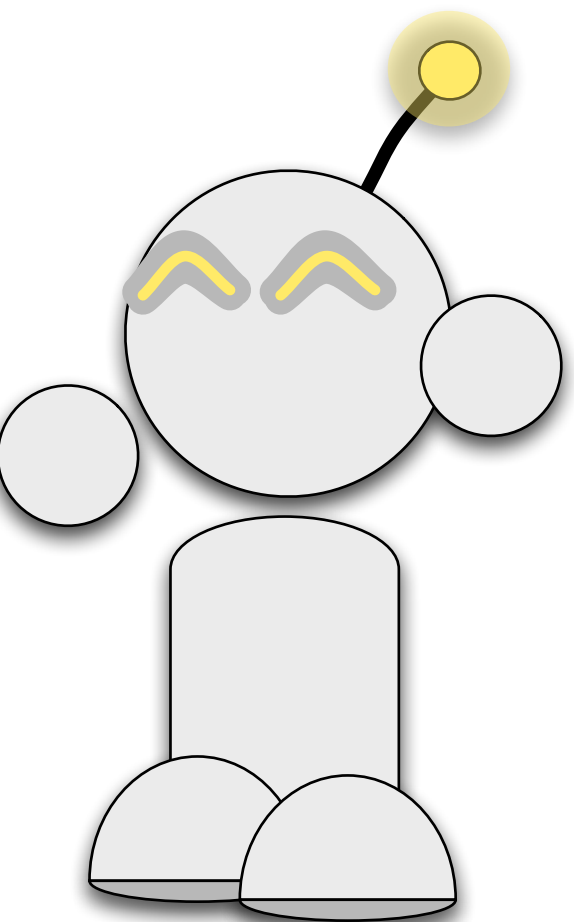
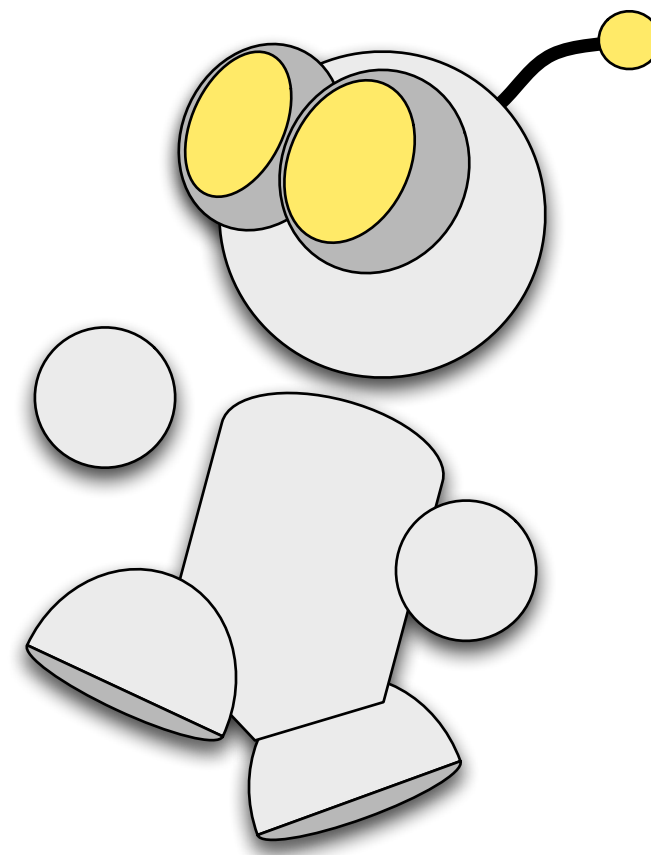
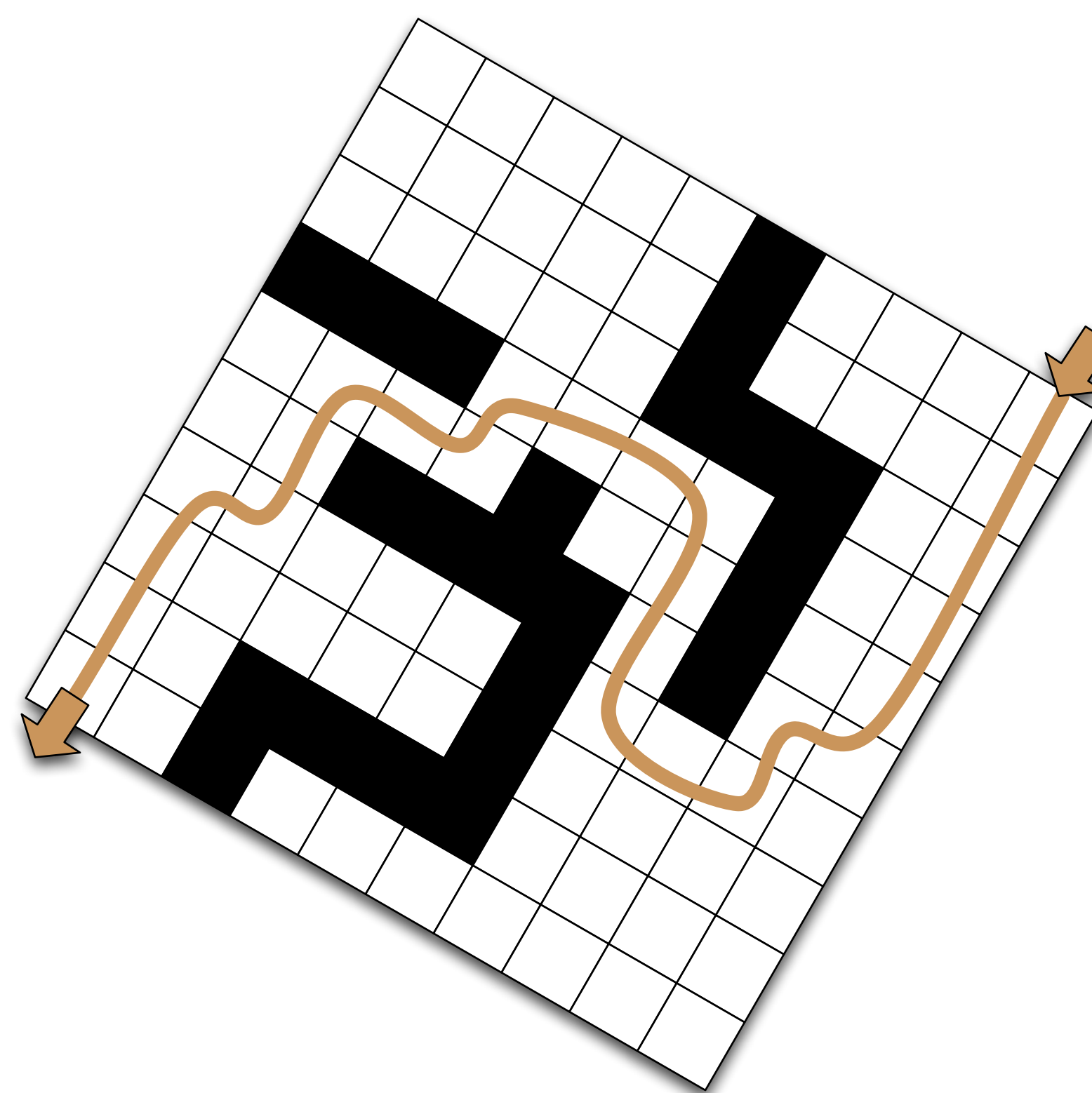
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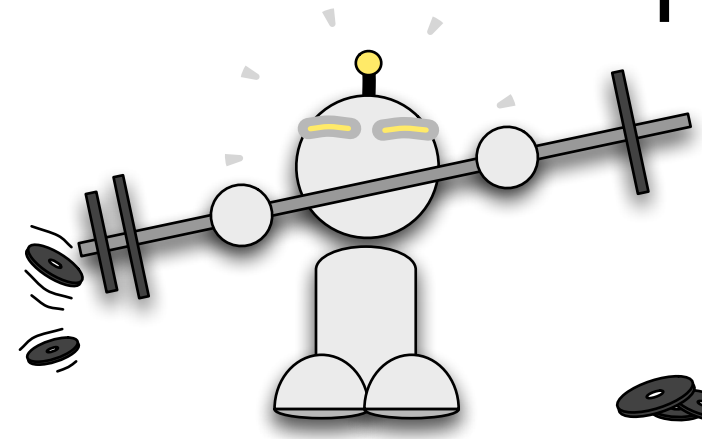
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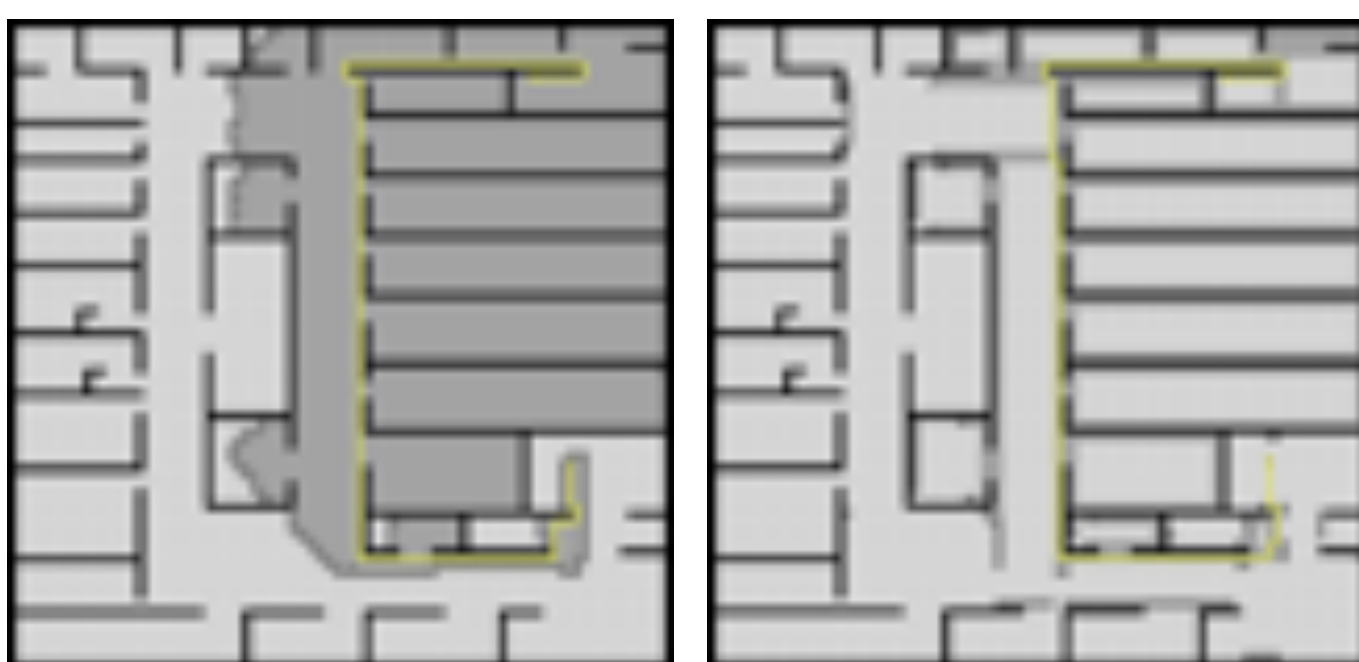
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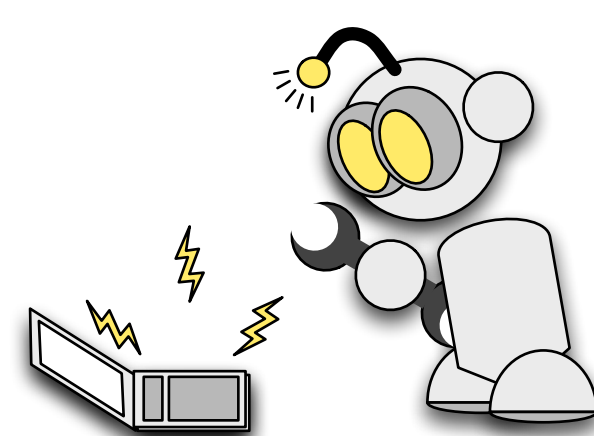
## Results



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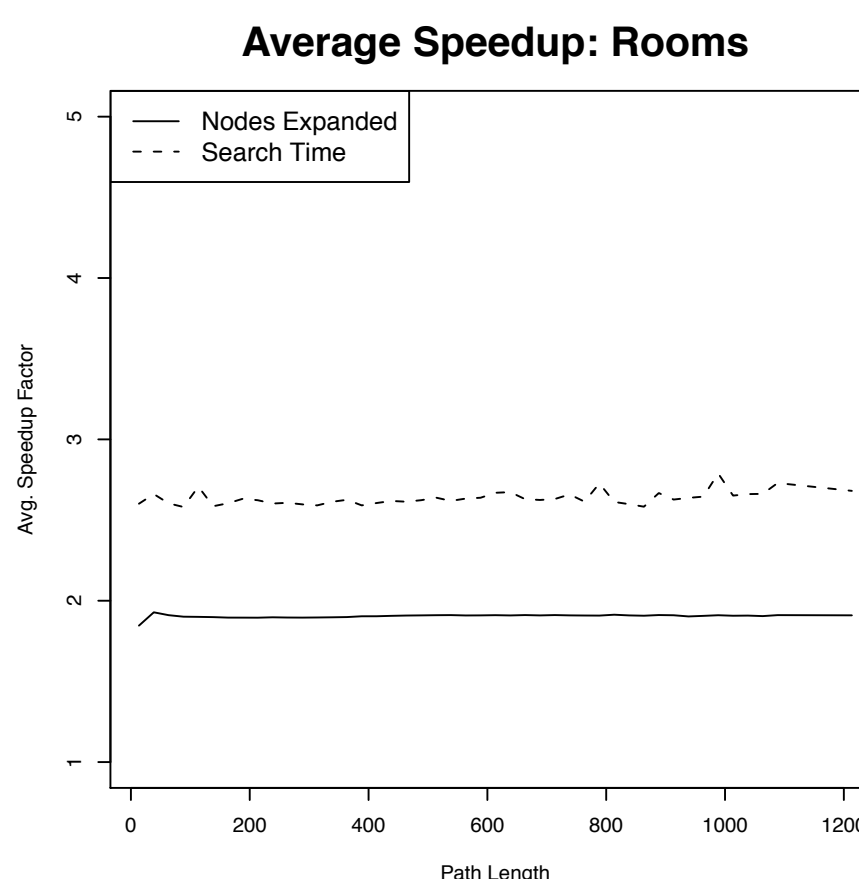
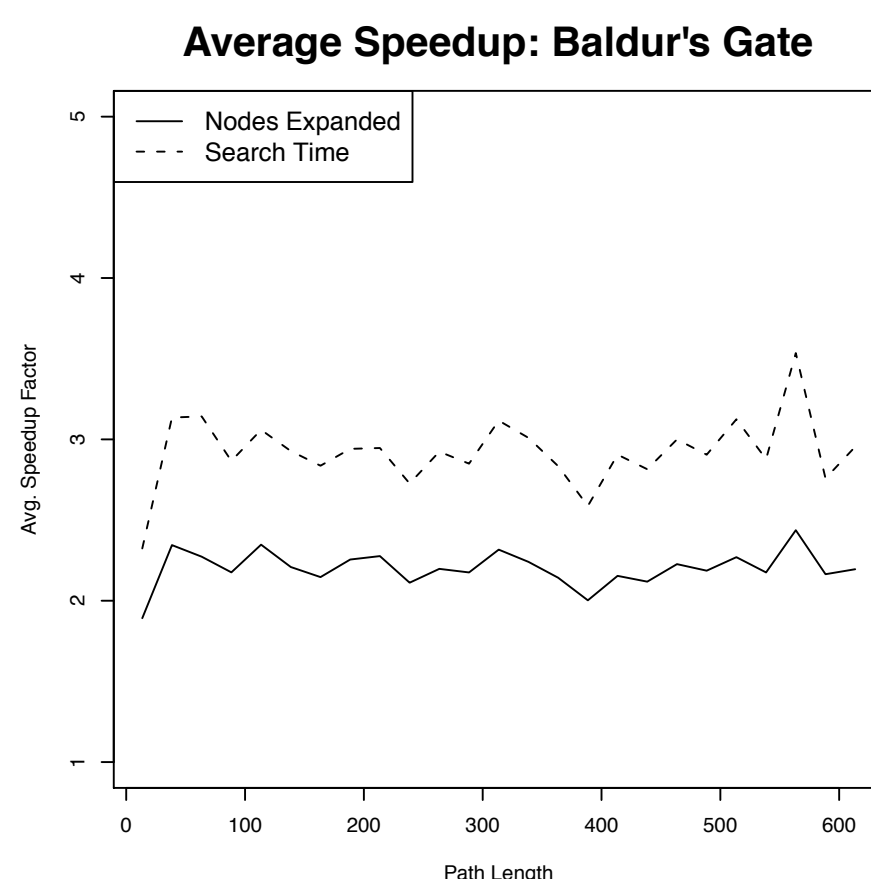
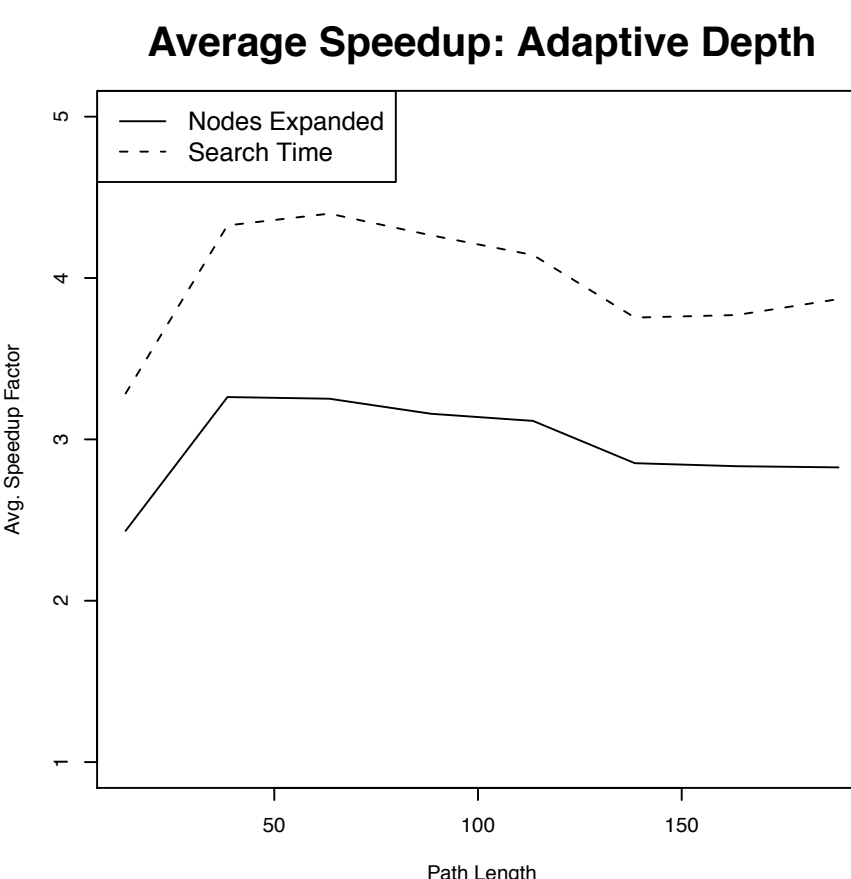
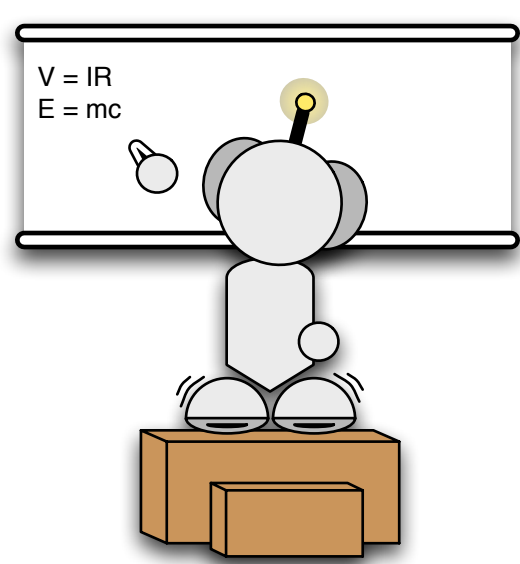
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## Future Work

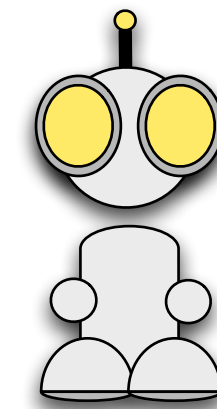
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## The Big Idea

[illegible]

## More Information

[illegible]

$$\begin{aligned} V &= IR \\ E &= mc \end{aligned}$$

