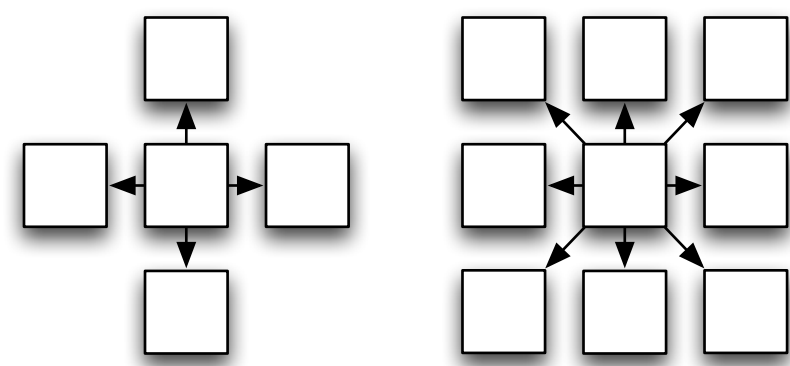


Fast and Optimal Pathfinding On Grid Maps

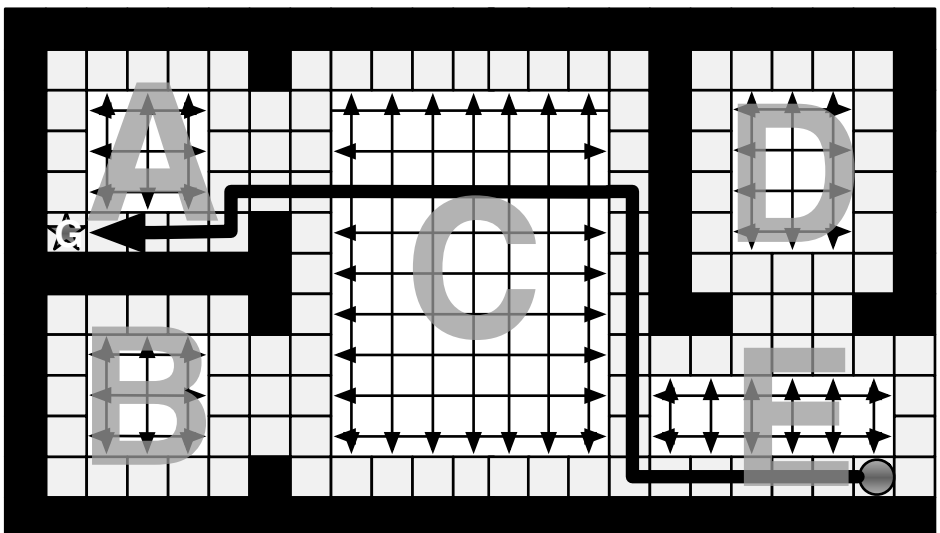
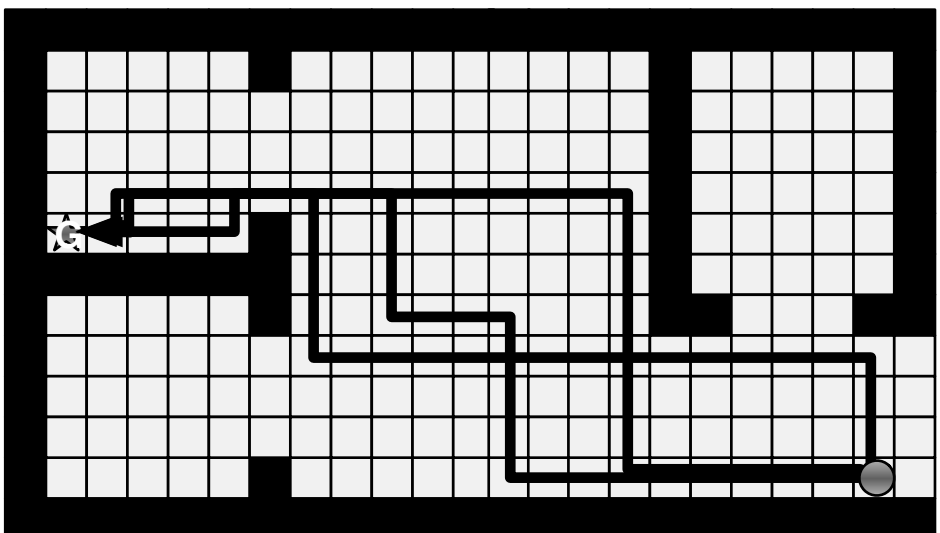
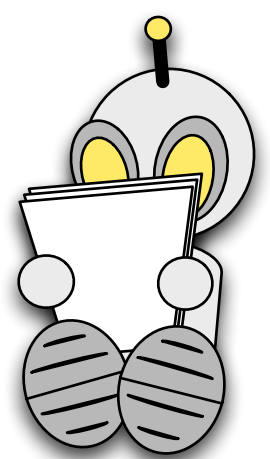
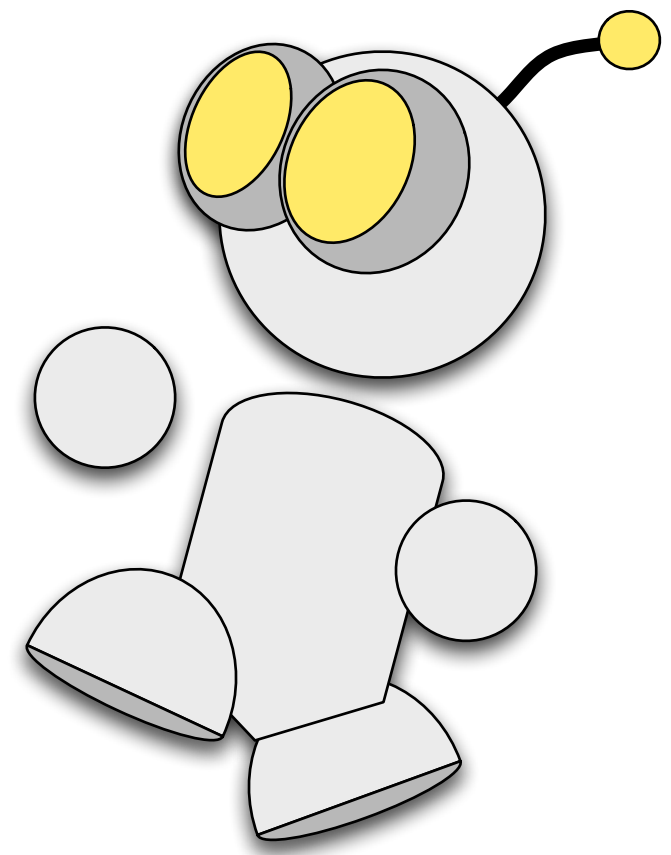
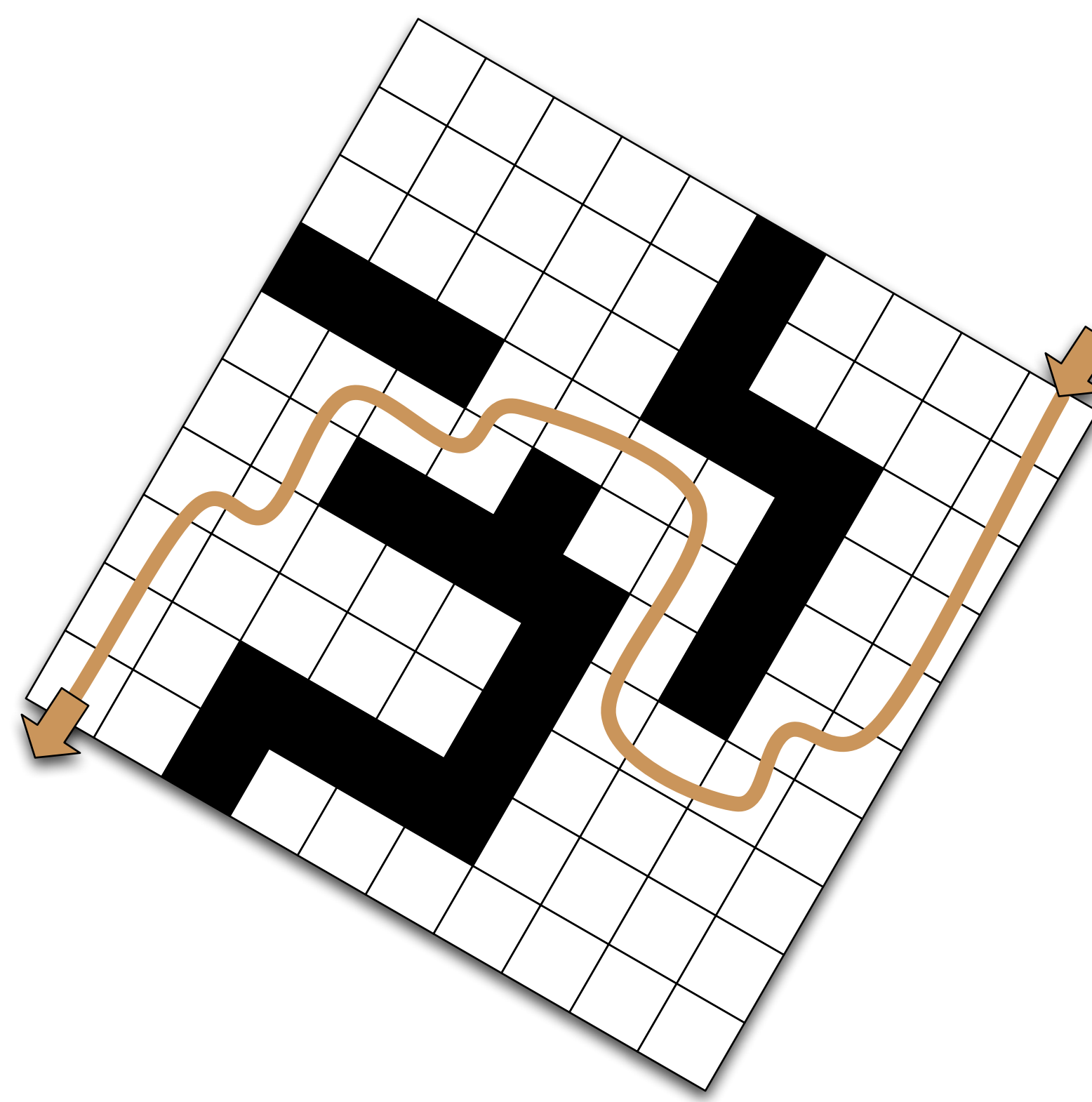
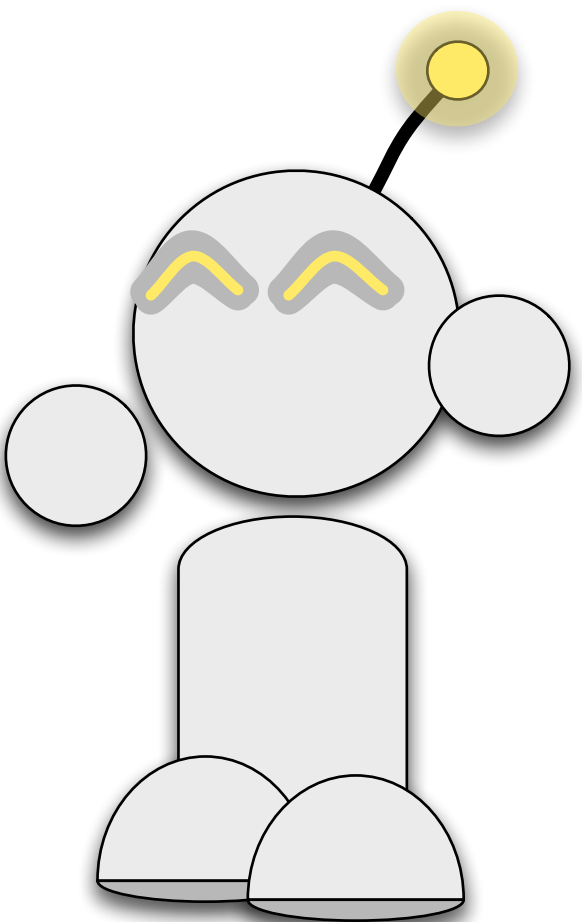
The Problem

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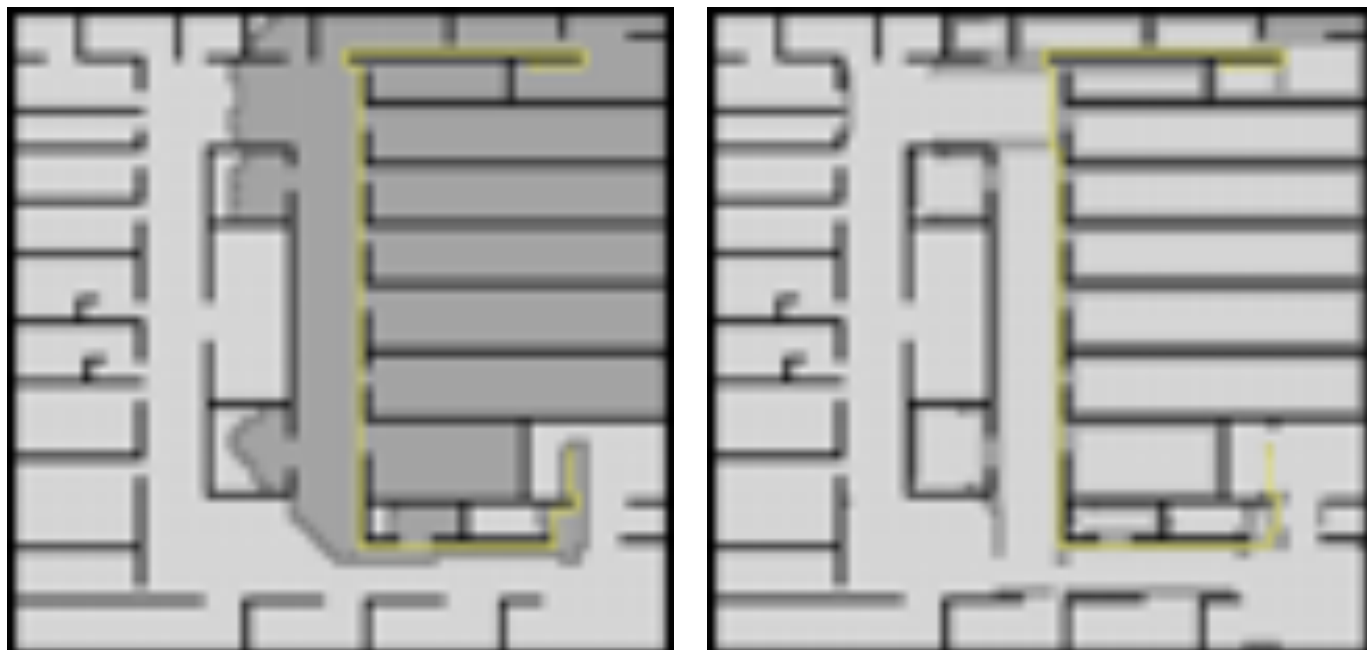
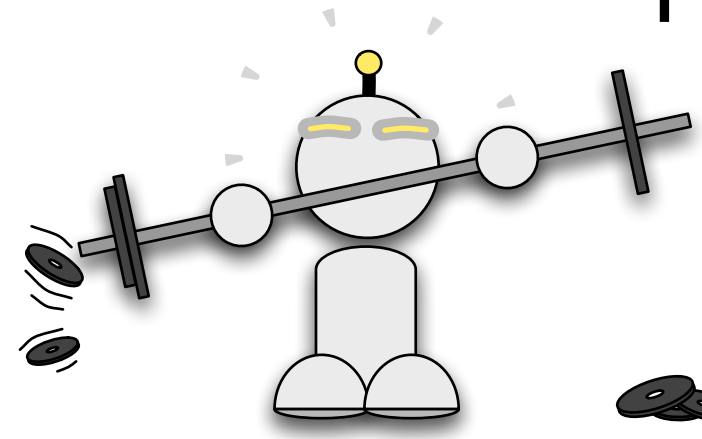


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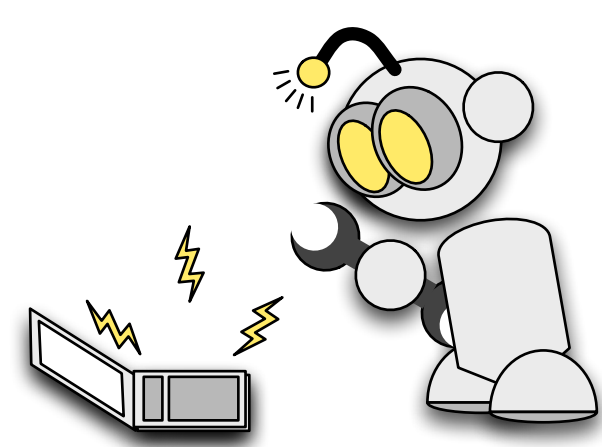
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Results

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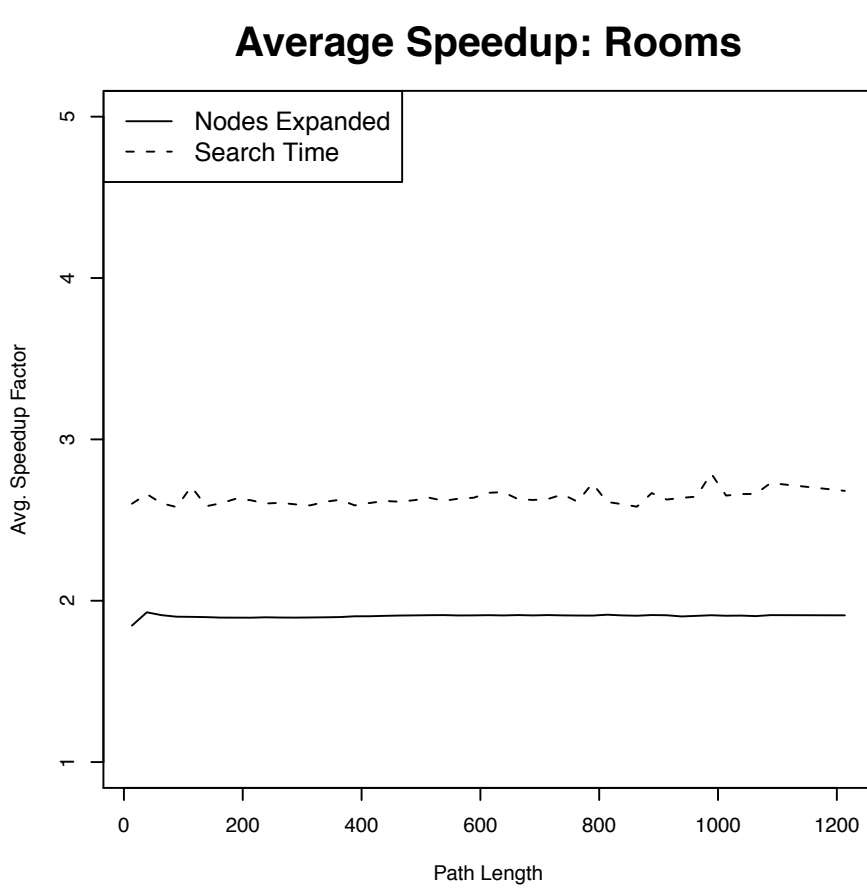
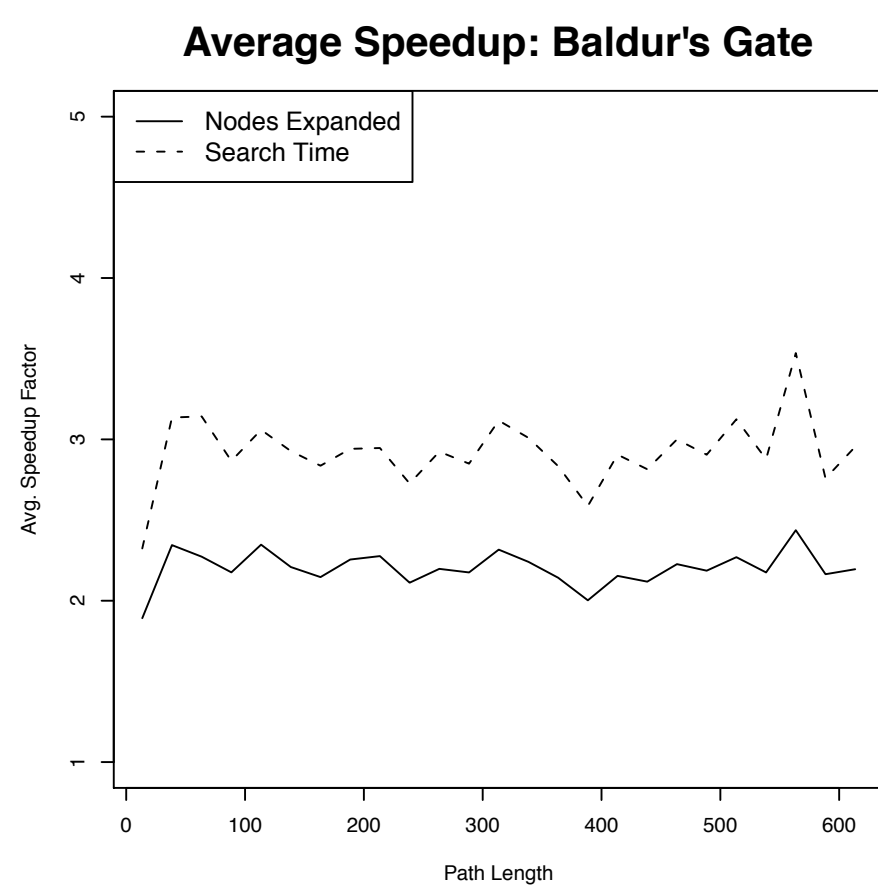
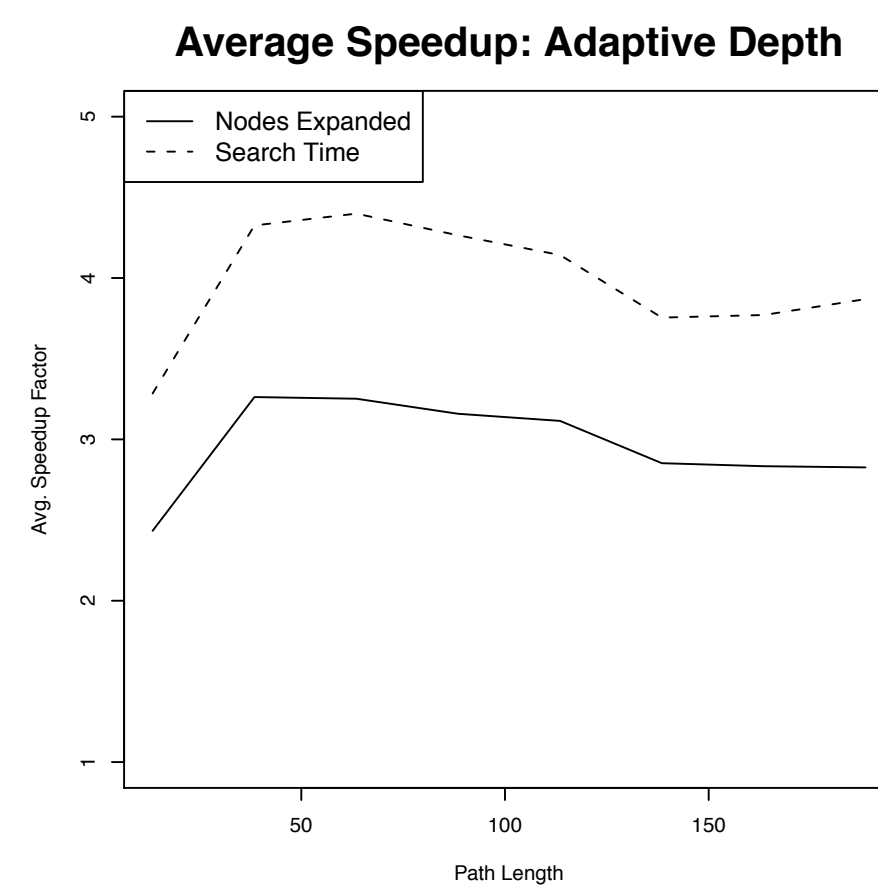
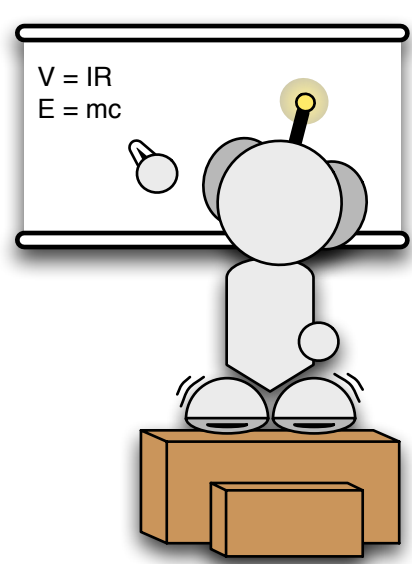


Future Work

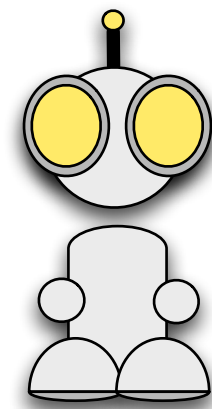
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The Big Idea

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More Information

[illegible]

$$\begin{array}{l} V = IR \\ E = mc \end{array}$$

