Report: Dialog Act Classification using Word Embeddings & Acoustic Features

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Abstract

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1 Introduction

The general task is to classify lexical and auditory speech into one of four predefined *dialog act classes*. A *dialog act*, in this context, represents informal information of how a dialog system should respond to a users input. The four provided classes are *statement*, *opinion*, *question* and *backchannel*. To solve this task we developed *convolutional neural networks* (CNN) that use lexical and acoustic features. For the development and training of the systems a subset of the *Switchboard Dialog Act Corpus* was used. In next chapters we discuss the development of the systems and subsequently to that the research question **INSERT HERE**.

2 Data & Data Preperation

In this section we discuss the *Switchboard Dialog Act Corpus* and the extraction of the lexical and acoustic features.

2.1 The Switchboard Dialog Act Corpus

The Switchboard Dialog Act Corpus [2], from now on abbreviated as SwDA, consists of recordings

	training	dev	test
opinion (~17%)	4984	1068	1070
question (\sim 8%)	2150	460	463
backchannel (~24%)	6792	1455	1458
statement (\sim 51%)	14459	3098	3099
sum	28385	6081	6090

Table 1: Displays the distribution of the four classes in the three data sets.

with corresponding transcripts. Each of these recordings is assigned to one of 42 dialog act classes. For this project we reduced the amount of classes down to four which are statement, opinion, question and backchannel. These classes are supersets of the 42 dialog act classes defined in the SwDA. The distribution of the four classes within the training, development and test set are shown in Table 1. The numbers illustrate a huge imbalance between the statement class and the other three classes. However, we decided against reducing the data into equally distributed sets because this would exclude at least one third of the training data. This is important to keep in mind for the evaluation of the systems because an educated guess would have an accuracy of around 51% by assigning all test examples to the statement class.

2.2 Input Data Generation

Lexical and acoustic features were employed in our systems and had to be extracted and formatted into a machine readable format. For the lexical features we decided to use *Google's* freely accessible word embeddings which were trained on 100 billion words [4]. As for the acoustic features we relied on *Mel Frequency Cepstral Coefficient* (MFCC) features which were extracted with the *openSMILE* feature extraction tool [1]. To ensure that data of different utterances could not be mixed the lexical and acoustic inputs were always stored with their respective one-hot vector in a tri-

ple data structure.

Lexical Features

The word embedding matrix E was generated by assigning each word to its corresponding 300 dimensional vector of the $Google\ word2vec$ model. If a word was not included in the model it was assigned a randomly generated 300 dimensional vector. Furthermore, we introduced a padding vector for the case that a sentence was shorter than our maximum sentence length. We decided to restrict the length of a single utterance to 100 words to not exclude to much lexical features for long utterances. The final size of the embedding matrix E was 11825×300 .

$$E = \begin{bmatrix} v_{1,1} & \dots & v_{1,300} \\ v_{2,1} & \dots & v_{2,300} \\ \vdots & \ddots & \vdots \\ v_{i,1} & \dots & v_{i,300} \end{bmatrix}$$

The lexical input for our systems is a vector x_{lex} were each word is represented by the index i of its corresponding vector in the embedding matrix E. The vector x_{lex} has a length of 100. Each element represents the index of a word in the utterance. The vector x_{lex} has the following shape: $x_{lex} = [i_1, i_2, ..., i_{100}]$ where i represents the index.

Acoustic Features

Each utterance had its acoustic features formatted into a matrix X_{aco} of shape 13×2000 . This matrix was generated by arranging 2000 *MFCC-frames* into a matrix. Each *frame* hereby consisted of 13 coefficients. The chosen *frames* were the first and last thousand *frames* of the audio recording. If a recording had less than 2000 *MFCC-frames* the matrix was padded with zero vectors.

$$X_{aco} = \begin{bmatrix} a_{1,1} & \dots & a_{1,2000} \\ a_{2,1} & \dots & a_{2,2000} \\ \vdots & \ddots & \vdots \\ a_{13,1} & \dots & a_{13,2000} \end{bmatrix}$$

Afterwards, to use minibatch processing it was necessary to reformat X_{aco} into a vector x_{aco} with the shape 1×26000 .

3 Baseline Systems

The architecture of the proposed *AcoLex* system is depicted in Figure 1. In this section we will explain the complete architecture of the system.

Furthermore, we will discuss its two core components: the lexical and the acoustic model.

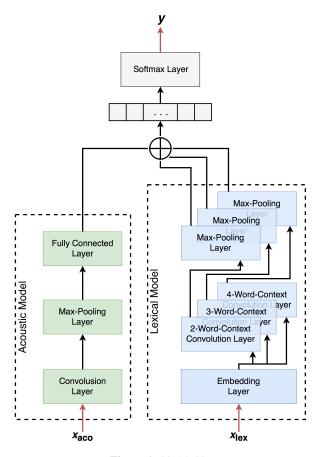


Figure 1: bla bla bla

3.1 Lexical Model

The *lexical model (LM)*, depicted on the right side in Figure 1, consists of three layers. The architecture is based on the system introduced by Kim (2014) [3]. The first layer is an embedding layer which was initialized with the embedding matrix E described in Section 2.2. The benefits of using an embedding layer is a significant reduction of the time needed to import the input files due to storing the vector of each word only once. Furthermore it enables the tuning of the embedding vectors for the classification task. The second layer is a convolution layer which uses three different filter sizes to capture different word contexts, namely 2word-, 3-word- and 4-word-contexts. Overall 300 filters are applied in the LM, were each filter type is used 100 times. The last layer is a max-pooling layer that returns the highest value of each filter output. Therefore, the final output of the LM are three 100 element long vectors.

3.2 Acoustic Model

The acoustic model (AM), shown on the left side in Figure 1, is developed similarly to the acoustic model presented by Ortega et. al (2018) [5]. Like the LM it utilizes three different layers. The first layer is a convolution layer with one filter type that captures 100 MFCC-frames at a time. We decided to use a stride of 50 to significantly reduce the processing time. The second layer is a max-pooling layer similar to the one in the LM. This layer returns a 100 element long vector. This output is fed into a fully connected layer which returns the final output of the AM which is a 100 element long vector.

3.3 AcoLex Model

Our proposed AcoLex Model employs a bi-CNN that consists of the LM and the AM to simultaneously process lexical and acoustic features. The outputs are then concatenated into one 400 element long vector which is then passed into a softmax layer to perform the dialog act classification task. The final output is a four element long vector were each element represents the probability for one dialog act class.

4 Training

The system was trained for 21 epochs with the *sto-chastic gradient descent* optimization algorithm over mini-batches of size 100. To obtain the best configuration the hyperparameters were tuned incrementally by fixing all hyperparameters except the tuned parameter. The hyperparameters of the best performing system are summarized in Table 2. For the *LM word2vec* [4] word embeddings were used and automatically tuned during the training process.

Hyperparameter	LM	AM
Filter width	2, 3, 4	100
Activation function	Relu	TanH
Word embeddings	word2vec	_
MFCC features	_	13
Dropout*	0.5	0.5
Learning Rate*	0.01	0.01
Mini-batch size*	100	100
# Feature maps*	100	100

Table 2: Hyperparameters marked with * are model independent and were set for the whole system.

5 Results

Model	Dev Accuracy	Test Accuracy
Acoustic		
Lexical	77.52	77.40
AcoLex	80.24	79.93

Table 3: Hyperparameters marked with * are model independent and were set for the whole system.

6 Research Question: None

7 Conclusion

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