	Rigid Robot	Soft Robot
Safety	**Definition**: The perception that a robot operates securely, performing tasks without posing risks or harm and often more safely than humans	
	Arguments: • Reliability & precision • Accuracy & consistency • Quick response time • *Ability to learn & adapt*	**Arguments**: • Reliability & precision • Accuracy & consistency • Quick response time • *Reduces risks of injury to humans and animals*
Risk	**Definition:** The perception that a robot's actions or operations are unsafe, potentially causing harm or posing greater risks than human performance	
	Arguments: • Risk of accidents, injuries, & technical failures • Risk of malfunction or *data security breaches* • *Faulty algorithms*	**Arguments**: • Risk of accidents, injuries, & technical failures • Risk of malfunction • *Environmentally vulnerable*
Technological Possibility	**Definition:** The functional capabilities and performance potential of a robot, focusing on its technical features and operational readiness	
	Arguments: • Improve healthcare • Efficiency & adaptability • *Precise*	**Arguments**: • Improve healthcare • Efficiency & adaptability • *Versaility, ease of use, & tailored theraphy*
Technological Limitation	**Definition:** The inherent constraints or shortcomings in a robot's technological capabilities	
	Arguments: • Limited learning abilities • Operational complexity • *Safety risks, & less emotional support*	**Arguments**: • Limited learning abilities • Operational complexity • *Over-reliance, & uncertain future prospects*

	Rigid Robot	Soft Robot
Human-Robot-Interaction pos.	**Definition:** The beneficial aspects of direct interactions between humans and (soft) robots, such as providing support to individuals (e.g., elderly or autistic persons)	
	Arguments: • Encourage social interaction • Emotional connection, & companionship • *Educational support*	**Arguments**: • Encourage social interaction • Emotional connection, & companionship • *Tactility & human comfort due to life-like features*
Human-Robot-Interaction neg.	**Definition:** The adverse aspects of direct interactions between humans and robots, focusing on challenges or negative outcomes specific to their engagement	
	Arguments: • Dependency & unhealthy relationships • Decline in human interaction • *Decline in social skills* • *Lack of physical warmth*	**Arguments**: • Dependency & unhealthy relationships • Decline in human interaction • *Strong emotional bonds & emotional manipulation*
Anthropo-morphism pos.	**Definition:** The positive evaluation of attributing human-like characteristics or behaviors to a robot, such as autonomy or emotions.	
	Arguments: • Emotional support & companionship • Facilitate interactions • *Limited tactile interaction*	**Arguments**: • Emotional support & companionship • Facilitate interactions • *Foster tactile intimacy & comfort in HRI*
Anthropo-morphism neg.	**Definition:** The negative evaluation of attributing human-like characteristics or behaviors to a robot, such as autonomy or emotions.	
	Arguments: • Lacking empathy & emotional intelligence • Lacking human complexity • *Uncanny valley* • *Autonomy*	**Arguments**: • Lacking empathy & emotional intelligence • Lacking human complexity • *False empathy*