# Coding Guidelines - Perception of Soft Robots

Before starting coding, if you have not mentally present the study and study design, please (a) click through our main study on risks and benefits of soft robots & read the scenario texts on (i) socially assistive robots + information "soft", (ii) search and rescue robots + information "soft", (b) read the randomly created sub-word list generated by the Shiny-App which we provide to you. The random sub-word list was created after summarization of a part of the concepts that have been written by participants in our CAM-study, (c) read the coding guidelines below (the category system) several times, (d) the "to consider" section below and (e) the graphical representation of possible connections between the concepts at the end of the document (p. 7). It is strongly recommended to display the coding guidelines on a second screen during coding or to print them out in advance.

#### Link to main study:

- (i) socially assistive:  $\frac{https://studien.psychologie.uni-freiburg.de/publix/564998da-e3fa-491b-8844-86464ce30ddc/df9ee6a1-1d9c-4013-a4f1-16e4785745b2/start$
- $(ii) search and rescue: \underline{https://studien.psychologie.uni-freiburg.de/publix/12e3668a-de47-446f-80e4-47be40be2f78/df9ee6a1-1d9c-4013-a4f1-16e4785745b2/start$

#### **General remarks:**

- After reviewing the coding guidelines, categorize the concepts from the provided word list into subordinated categories based on our coding guidelines, please consider the comment columns and the valence of the respective words.
  - Please use the "codes" of the categories for the coding process. This means you enter the
    codes of the respective categories in the first column of the wordlist "Superordinated" of
    the word list. The "codes" can be found in the first column of the coding guidelines.
  - Important: After our joint session, 4 new categories were added to the coding guidelines and two categories were modified: new categories: (i) technological limitations, (ii) technological possibilities, (iii) rest category, ambiv., (iv) rest category, neutr. Modified categories: (i) Perceived usefulness -> now: rest category, pos.: perceived usefulness, (ii) Perceived uselessness -> now: rest category, neg.: perceived uselessness.
- Important: The word list also includes our predefined concepts for the CAMs. Please do not summarize them into superordinate categories. The predefined terms are: "Vorteile", "Nachteile", "sozialer Assistenzroboter", "Rettungsroboter", [German]
- Please consider the <u>valence</u> and provided comments by the participants of the words for the coding process.
- Please carefully decide which category each concept belongs to.

#### How to proceed:

- To summarize the concepts, please do the following: In the third column of the wordlist (C) you will see concepts, which have been written by the participants in our study.
  - Based on our coding guidelines, you should consider which superordinate category the
    respective concept should be assigned to. You then enter the **code** of the superordinate term
    based on our coding guidelines in the first column ("Superordinate"). For example, the
    concept "Diskriminierung" could be superordinate into the category "MT" (Mistrust) from our
    coding guidelines.
- You should not summarize the predefined concepts (see general remarks above).

• If you are facing any problems or have any open questions regarding single concepts, please write them down in the respective comment column (2). Please do not talk to other rather during this process, because the independence of the raters is crucial.

#### Timeline for the three central tasks:

- 1. Done: finish the first coding process (each of us will code the same 100 concepts) till 20th of February
- 2. Done: we have a joint session to discuss possible ambiguities and difficulties in a hybrid meeting on the 27<sup>th</sup> of February
- 3. Please finish the second coding process till 18th of March

#### To consider

Please consider the following while coding:

- All the key points mentioned in the "Coding Rules" do not have to be fulfilled to assign the respective categories.
- If you have difficulties assigning the concepts from the wordlist to the given categories, sort them into the 4 "rest categories" (pos., neg., amiv., neutr. considering the valence) > you should use the comment column (2) to explain why you are assigning a term to a "rest category".
- In the end of the document, after the coding guidelines, you will find a graphic showing the complementary terms of the coding guidelines (such as safety vs. risk) as well the differentiation between the terms (coding rules).
- You can write comments if you have assigned concepts to categories but have questions/uncertainties.
- Please assign every word to one (but only) one of the provided codes in the category system.

If you have any questions or something is unclear, please send me an E-Mail: <a href="louisa.estadieu@philosophie.uni-freiburg.de">louisa.estadieu@philosophie.uni-freiburg.de</a>

## Coding Guidelines for Assessing Risks and Benefits of (Soft) Robots

| Code | Category | Definition   | Coding Rules  | Examples from data   |
|------|----------|--|---|--|
| SA   | safety   | <ul> <li>The belief that the robot is</li> <li>operating safely</li> <li>performing tasks without posing risks and/or harm to humans</li> <li>performing tasks even safer than humans</li> </ul> | Compared to "Trust" this concept primarily concerned with operational safety rather than overall reliability and integrity of the robot   | "Accuracy of execution"; "Safer for humans"; "Precision and efficiency"; "Reduced risk of injury"; "Quick action"            |
| R    | risk     | The belief that the robot is     operating unsafely     performing tasks that pose risks to humans     performing tasks riskier than humans  | Compared to "Mistrust" this concept emphasizes the assessment of risky behaviors and actions on the operational level, rather than focusing on the robot's overall reliability and integrity      | "Lack of accuracy"; "Slight damage"; "Possible malfunctions"   |
| Т    | trust    | The belief that the robot  • performs with integrity and/or reliability  • is thus considered trustworthy  | Compared to "Safety" this concept focuses on the overall reliability and integrity of the robot, rather than focusing solely on operational safety components                                     | "Consistency of care"; "objective/neutral"; "Adaptation to patient/client"; "better knowledge capacity"; "does not evaluate" |
| MT   | mistrust | The lack of belief that the robot  • performs tasks with integrity and/or reliability  • leading to mistrust, skepticism and/or doubt  | Compared to "Risk" this concept focuses on skepticism or doubts about the robot's reliability and integrity, rather than focusing on specific risky behaviors or actions on the operational level | "Discrimination against individuals"; "Favoritism"; "can be abused"; "Algorithm bias"  |

| AP   | anthropomor phism, pos.                        | Positive evaluation of the  attribution of human characteristics and/or behaviors to the robot  such as autonomy or emotions         | Compared to "HRI, pos.," this concept focuses more on the evaluation of specific positive robot characteristics than on the interaction itself   | "Autonomous decisions"; "Comforts the injured"; "Conversation partner for the lonely"                                 |
|------|--|--|--|---|
| AN   | anthropomor<br>phis, neg.                      | Negative evaluation of the  attribution or lack of human characteristics and/or behaviors to the robot  such as autonomy or emotions | Compared to "HRI, neg.," this concept focuses more on the evaluation of specific negative robot characteristics than on the interaction itself   | "Autonomous decisions"; "limited emotional intelligence"; "lack of empathy"   |
| HRIP | Human-<br>Robot-<br>Interaction =<br>HRI, pos. | Positive implications of the  • interaction between humans and robots  | Compared to "Social impact, pos.," this concept emphasizes positive aspects of the direct interaction of humans and robots, not broader societal impacts   | "Interaction with<br>elderly/autistic individuals";<br>"Assistance with feelings of<br>shame (objective/neutral)"     |
| HRIN | Human-<br>Robot-<br>Interaction =<br>HRI, neg. | Negative implications of the  • interaction between humans and robots  | Compared to "Social impact, neg.," this concept emphasizes negative aspects of interaction, not broader societal impacts   | "Unwanted emotional relationship"; "Impersonal"; "Exclusion"; "Dependency"  |
| SIP  | social impact, pos.                            | Positive impacts of     robots     human-robot- interaction on society   | Compared to "HRI, pos.," this concept is not about the direct interaction between humans and robots but emphasizes positive impacts that robots and HRI might have on society, including long term impacts | "more job opportunities";  "promotes social interaction/integration";  ""ustice (objectivity)";  "reduces loneliness" |

| SIN  | social impact, neg.                                | Negative impacts of     robots     human-robot- interaction society   | Compared to "HRI, neg.," this concept emphasizes negative impacts that robots and HRI might have on society, including long term impacts  | "fewer jobs"; "loss of human<br>nature"; "loss of human<br>interaction"; "loss of human<br>skills"; "coarsening of human<br>behavior"; "people being<br>replaced" |
|------|--|---|---|---|
| TP   | technological possibilities                        | Technological possibilities oft the robot   | Compared to "Trust", "HRI, pos." & "Social impact, pos." this concept focuses solely on the technological possibilities of the robot  | "permanent operational readiness"; "can overcome hurdles"   |
| TL   | technological<br>limitation                        | Technological limitations of the robot  | Compared to "Mistrust", "HRI, neg." & "Social impact, neg." this concept focuses solely on the technological limitations of the robot. It can be rated positively or negatively | "Limited know-how"; "limited autonomy"; "Defects"; "Limited learning ability"   |
| LC   | low cost   | Low cost of     robot fabrication and deployment     on a personal and/or societal level  | Compared to "High<br>Cost," this concept<br>focuses on economical<br>aspects and cost-<br>effectiveness in robot<br>development and<br>deployment                               | "inexpensive"; "cost-<br>efficient"; "cheap labor"  |
| НС   | high cost  | High cost of     robot fabrication and deployment     on a personal and/or societal level   | Compared to "Low<br>Cost," this concept<br>highlights the higher<br>financial investment<br>required for robot<br>development and<br>deployment                                 | "expensive"; "high costs"   |
| RCPP | rest category,<br>pos.:<br>perceived<br>usefulness | The belief that the robot is  useful and/or assistive and/or overall good  on a personal and/or societal level  the concept cannot be assigned, but is general positive | All positive terms that cannot be clearly assigned to one of the above-mentioned belong in this category. Can be concepts regarding usefulness, and others                      | "customized programming"; "for therapy"; "consistency of care"; "cognitive superiority"   |

| RCPN | rest category,<br>neg.:<br>perceived<br>uselessness | The belief that the robot is  useless and/or overall bad  on a personal and/or societal level  the concept cannot be assigned, but is general negative | All <u>negative</u> terms that cannot be clearly assigned to one of the above-mentioned belong in this category. Can be concepts regarding perceived uselessness, and others | "no specific expertise"; "difficult to adapt" |
|------|---|--|--|---|
| RCA  | rest category, ambiv.                               | <ul> <li>All terms that</li> <li>do not fall under above constructs,</li> <li>and/or are neither positive or negative but ambivalent</li> </ul>        | All terms that cannot be clearly assigned to one of the above-mentioned constructs because of their ambivalent valance belong in this category                               | "Unclear ethical behavior"; "Liability"       |
| RCN  | rest category, neutr.                               | <ul> <li>All terms that</li> <li>do not fall under above constructs,</li> <li>and/or are neighber positive/negative, ambivalent but neutral</li> </ul> | All terms that cannot be clearly assigned to one of the above-mentioned constructs because of their neutral valence belong in this category                                  | "Construction method"; "hybrid construction"  |

## Graphical representation of possible connections between the concepts

In the following graphic the complementary terms of the coding guidelines (such as safety vs. risk) are shown, whereby only the codes are written. Arrows on the left or right indicate that these terms were mentioned in the coding rules of the respective other term, which highlights the need to differentiate between these terms.

