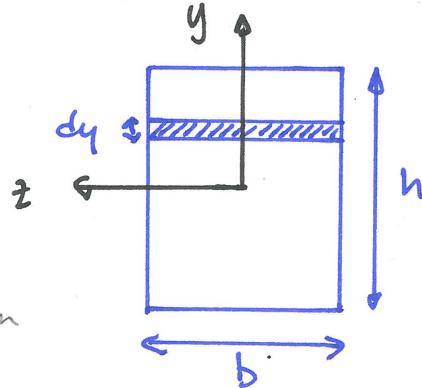
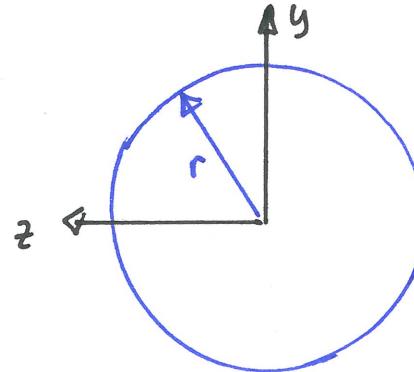


Moment of inertia

$$I_z = \int_A y^2 dA.$$



$$\begin{aligned} I_z &= \int_{-h/2}^{h/2} y^2 b dy \\ &= \frac{by^3}{3} \Big|_{-h/2}^{h/2} \\ &= \frac{b}{3} \left(\frac{h^3}{8} + \frac{h^3}{8} \right) \\ I_z &= \frac{bh^3}{12} \end{aligned}$$



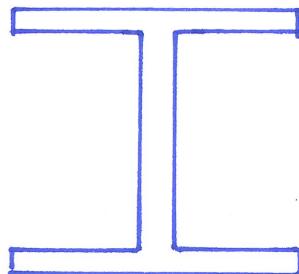
$$\begin{aligned} J &= \text{polar moment of inertia} \\ &= \int_A r^2 dA \\ &= \int_A (x^2 + y^2) dA \end{aligned}$$

$$\text{symmetry: } I_z = J/2$$

$$J = \int_0^r 2\pi r^3 dr = \frac{2\pi r^4}{4} = \frac{\pi r^4}{2}$$

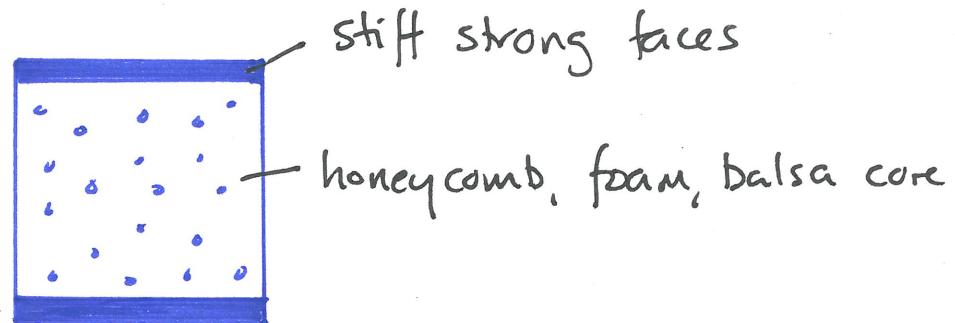
$$I_z = \frac{\pi r^4}{4}$$

- efficient cross-sections for resisting bending



slides -
natural sandwiches

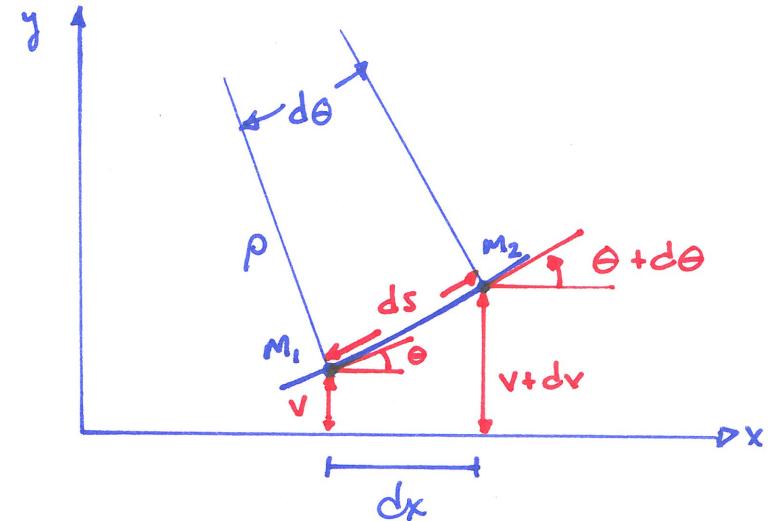
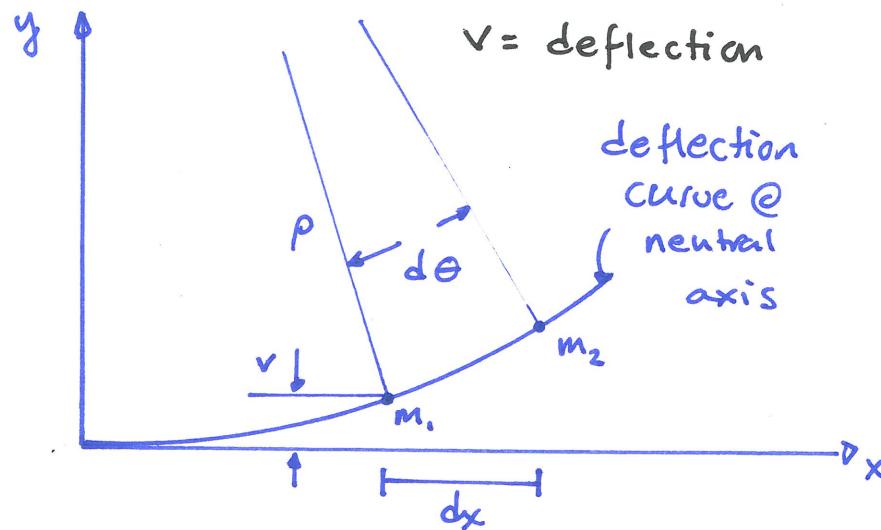
I-beam



sandwich beam

palms - density gradient

Beam deflections: differential eq'n of deflection curve



- deflection v in y direction
- angle of rotation θ = angle between x axis & tangent to deflection curve
- small deflections, small angles
- deflection at m_2 = ?

deflection of $m_2 = ?$

$$\rho d\theta = ds \quad \frac{1}{\rho} = \frac{d\theta}{ds} = K$$

approximations:

$$\textcircled{1} \quad \cos \theta = \frac{dx}{ds} \quad \text{small } \theta, \cos \theta \approx 1 \quad ds \approx dx$$

$$\textcircled{2} \quad \tan \theta = \frac{dv}{dx} \quad \text{small } \theta, \tan \theta = \theta = \frac{dv}{dx}$$

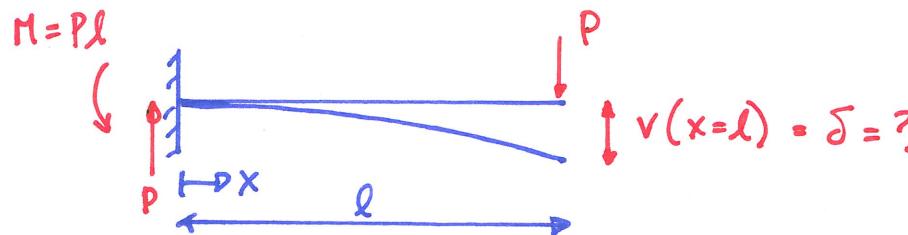
$$\therefore K = \frac{d\theta}{ds} = \frac{d\theta}{dx} = \frac{d^2v}{dx^2}$$

previously had $K = \frac{M}{EI}$

$$\therefore \frac{d\theta}{dx} = \frac{d^2v}{dx^2} = \frac{M}{EI}$$

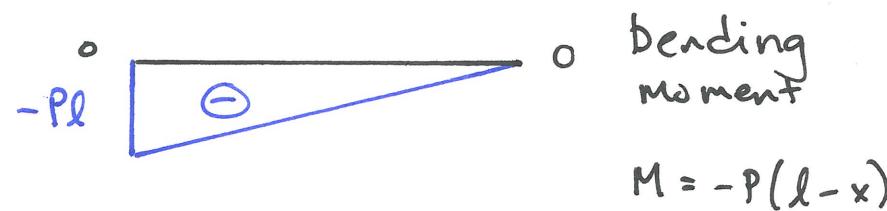
- can integrate $M(x)$ twice to get deflection, v
- get constants of integration from boundary conditions
- EI : flexural rigidity, important for deflections

Beam deflection example



find end deflection:

$$v(x=l) = \delta = ?$$



$$\frac{d^2v}{dx^2} = \frac{M}{EI} = -\frac{P(l-x)}{EI}$$

$$\frac{dv}{dx} = -\frac{P}{EI} \left[lx - \frac{x^2}{2} \right] + C_1$$

$$v(x) = -\frac{P}{EI} \left[\frac{lx^2}{2} - \frac{x^3}{6} \right] + C_1 x + C_2$$

boundary conditions: $x=0 \ v=0 \Rightarrow C_2 = 0$

$$x=0 \ \theta=0 \Rightarrow \frac{dv}{dx} = \theta = 0 \Rightarrow C_1 = 0$$

$$\delta = v(x=l) = -\frac{P}{EI} \left[\frac{l x^2}{2} - \frac{x^3}{6} \right] = -\frac{Pl^3}{3EI}$$

(down)

units: $\frac{[N][m^3]}{\left[\frac{N}{m^2}\right][m^4]} = [m]$

Note: for concentrated loads,

$$\delta \propto \frac{Pl^3}{EI}$$

loading configuration determines the constant

(e.g. cantilever, constant = 3)

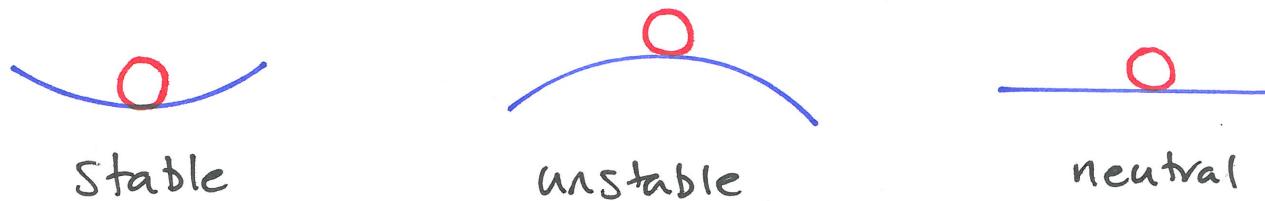
Column buckling

column - long slender member loaded in compression

buckling - instability phenomenon

stability - system stable if it returns to initial state after small perturbation
 - unstable if small perturbation leads to larger perturbation

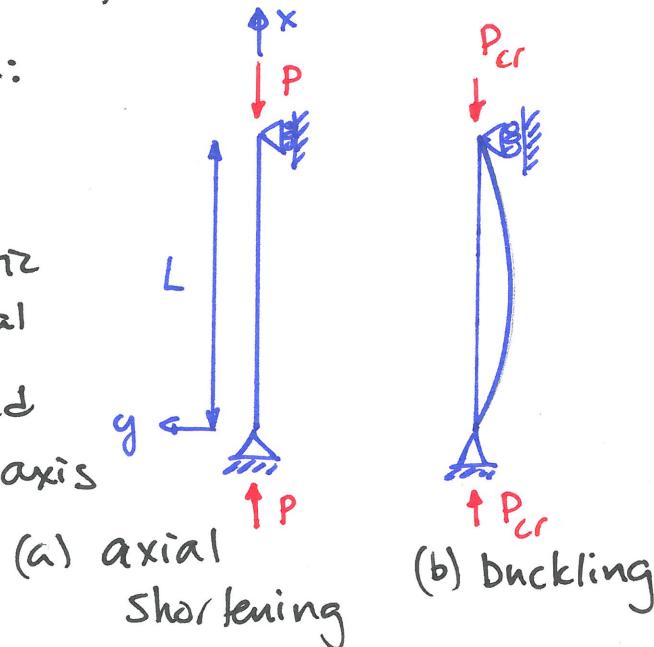
e.g.



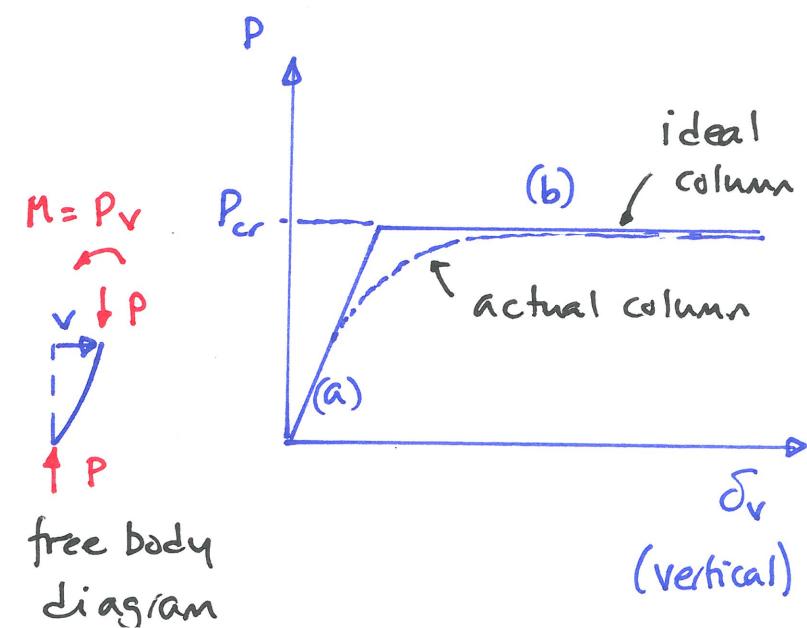
Column with pinned ends

ideal column:

- straight
- linear elastic material
- load aligned with column axis



(demo)



- Small P - column is stable, compresses linearly elastically + axially shortens
- increase P - at some critical load, becomes unstable \rightarrow buckles

$$P_{cr} = ?$$

$$M = Pv$$

$$\frac{d^2v}{dx^2} = \frac{M}{EI} = \frac{Pv}{EI} \quad \text{differential eq'n of buckled state}$$

solution of form: $v = C_1 \sin\left(\sqrt{\frac{P}{EI}} x\right) + C_2 \cos\left(\sqrt{\frac{P}{EI}} x\right)$

boundary conditions

$$x=0 \quad v=0 \Rightarrow C_2 = 0$$

$$x=L \quad v=0 \Rightarrow C_1 \sin\left(\sqrt{\frac{P}{EI}} L\right) = 0$$

$C_1 = 0 \Rightarrow$ column remains straight

$$\text{or } \sin\sqrt{\frac{P}{EI}} L = 0 \Rightarrow \sqrt{\frac{P}{EI}} L = n\pi \quad n = 1, 2, 3, \dots$$

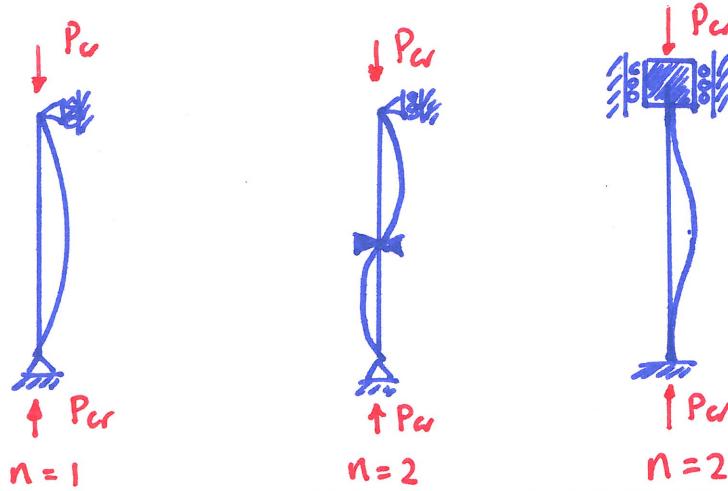
$$P_{cr} = \frac{n^2 \pi^2 EI}{L^2}$$

$$n = 1, 2, 3$$

"Euler load" "Euler buckling"

n = number of half-wavelengths along column length, L (end constraint factor)

$n = 1 \Rightarrow$ corresponds to pin-pin ends of column



$$P_{cr} = \frac{n^2 \pi^2 EI}{L^2}$$

- critical buckling load increases with:
 - material modulus
 - Moment of inertia
 - decreased length

- consider moment of inertia
- want constant I about all cross-sectional axes to have same buckling load about all axes
- circular cross-section attractive
- compare solid circular section + thin-walled hollow cylinder

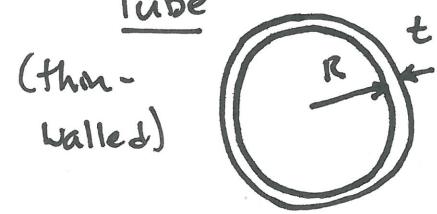
(demo)

Solid

$$I_s = \frac{\pi r^4}{4}$$

$$m_s = \rho \pi r^2$$

- for same mass, $\frac{\rho \pi r^2}{(\text{solid} + \text{tube})} = \rho 2\pi R t$
 $r = (2Rt)^{1/2}$

Tube

$$I_t = \pi R^3 t$$

$$m_t = \rho 2\pi R t$$

- for same mass, $\frac{I_t}{I_s} = \frac{\pi R^3 t}{\frac{\pi}{4} (2Rt)^2} = \frac{R}{t}$

- for same mass, tube has larger I than solid circular section, by a factor of R/t

- how large can R/t be? \Rightarrow limited by local buckling (kinking)

(demos)

$$\sigma_{\text{local}} = \frac{Et}{R \sqrt{3(1-\nu^2)}}$$

(axial compression of cylindrical tube)

- can increase resistance to local buckling by incorporating longitudinal + circumferential stiffeners (e.g. space shuttle fuel tanks, offshore oil platform legs)
- or by using honeycomb or foam core

e.g. plant stems, animal quills
Inside Plants article.

Column buckling example

A pin-ended Al column, with a solid circular cross-section, has a radius $r = 5\text{mm}$ & length $l = 0.1\text{m}$. $E_{\text{Al}} = 69\text{GPa}$, $\nu = 0.33$

(a) what is its critical Euler buckling load?

(b) What is the maximum critical Euler buckling load of a hollow Al cylindrical tube of the same mass+length? What are the tube's dimensions?

$$(a) P_c = \frac{n^2 \pi^2 EI}{l^2} \quad n=1 ; I = \frac{\pi r^4}{4} = \pi (.005)^4 / 4 = 4.91 \times 10^{-10} \text{m}^4 ; E = 69\text{GPa}$$

$$P_c = \frac{\pi^2 (69 \times 10^9) (4.91 \times 10^{-10})}{(0.1)^2} \frac{\text{N}}{\text{m}^2 \frac{\text{m}^4}{\text{m}^2}} = 33.4 \text{ kN}$$

(b) solid cylinder radius r

hollow cylinder radius, R , wall thickness, t

- same mass: $\pi r^2 = 2\pi R t$

$$Rt = r^2/2 = 0.005^2/2 = 1.25 \times 10^{-5} \text{ m}^2$$

- many combinations of R & t possible - want to maximize buckling load

- R/t limited by local buckling: equate σ_{local} $= \sigma_{\text{Euler}}$
(i.e. make R/t as large as possible
§ still avoid local buckling)

$$(\sigma_{Euler}) \frac{n^2 \pi^2 EI}{l^2 (2\pi R t)} = \frac{Et}{R \sqrt{3(1-\nu^2)}} \quad (\sigma_{local}) \quad n=1 \\ \sqrt{3(1-\nu^2)} = 1.64 \\ \nu = 0.33$$

$$\frac{\pi^2 \pi R^3 t}{l^2 (2\pi R t)} = \frac{t}{1.64 R}$$

$$\frac{\pi^2 R^2}{2l^2} = \frac{t}{1.64 R R} = \frac{1.25 \times 10^{-5}}{1.64 R^2} m^2$$

$$R = \left(\frac{1.25 \times 10^{-5} m^2}{1.64} \frac{2(0.1 m^2)}{\pi^2} \right)^{1/4}$$

$$R = 0.0111 m$$

$$t = \frac{1.25 \times 10^{-5} m^2}{0.0111} = 0.00112 m$$

$$\text{Note: } \frac{R}{t} = \frac{0.0111}{0.00112} \approx 10$$

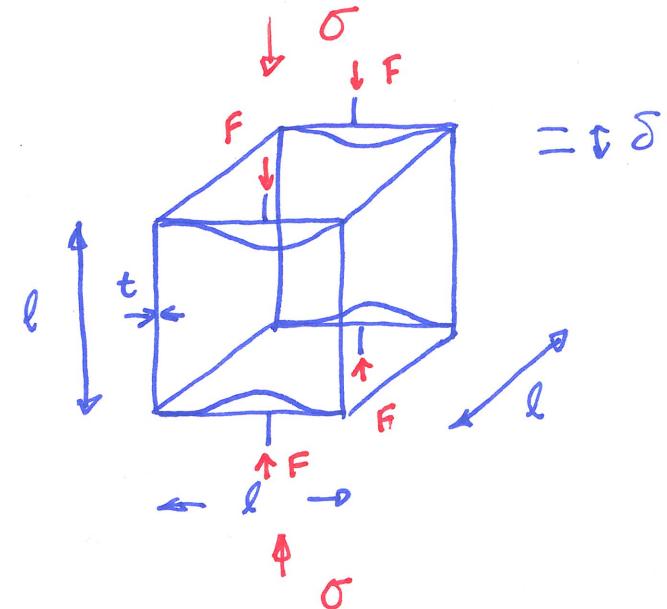
$$P_{cr} = \frac{\pi^2 EI}{l^2} = \frac{\pi^2 E \pi R^3 t}{l^2} \\ = \frac{\pi^3 (69 \times 10^9) (.0111)^3 (.00112)}{(0.1)^2} \frac{N \cdot m^3 \cdot m}{m^2 \cdot m^2}$$

$$P_{cr} = 328 \text{ kN}$$

* Per hollow tube $\sim 10 P_{cr \text{ solid cylinder}}$

Open cell foams - Young's modulus

- foams - complex geometry polyhedral cells
- can do first order model using dimensional arguments
- assume cell geometry of foams of different densities is similar.



Solid modulus, E_s

$$\sigma \propto \frac{F}{l^2}$$

$$E \propto \frac{\delta}{l}$$

$$\delta \propto \frac{Fl^3}{E_s I}$$

$$I \propto t^4$$

* = for foam

$$E^* = \frac{\sigma}{E} \times \frac{F}{l^2} \frac{l}{\delta} \propto \frac{F}{l} \frac{E_s t^4}{Fl^3} \propto E_s \left(\frac{t}{l}\right)^4$$

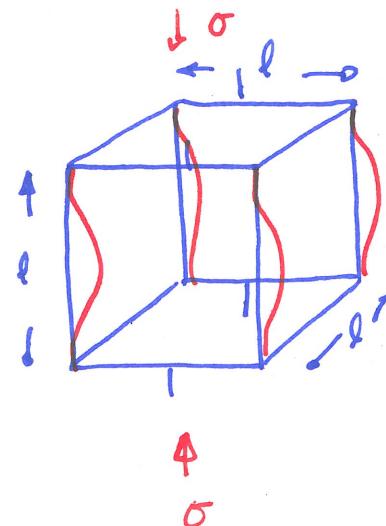
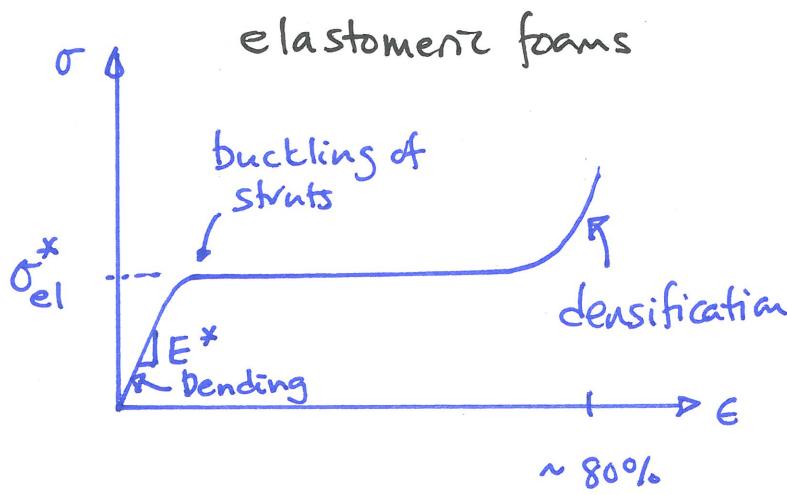
also:

$$\frac{\rho^*}{\rho_s} \propto \frac{M_s}{V_{\text{total}}} \frac{V_s}{M_s} \propto \frac{t^2 l}{l^3} \propto \left(\frac{t}{l}\right)^2$$

$$\therefore E^* = C_1 E_s \left(\frac{\rho^*}{\rho_s}\right)^2$$

cell geometry ↓ solid property → relative density
(volume fraction of solids)

Open cell foams - elastic buckling compressive strength



$$\sigma_{el}^* \propto \frac{P_{cr}}{l^2} \propto \frac{n^2 \pi^2 E_s I}{l^2 l^2} \propto E_s \left(\frac{l}{t}\right)^4$$

$$\sigma_{el}^* = C_2 E_s \left(\frac{\rho^*}{\rho_s}\right)^2$$

cell geometry solid relative density

- bands of cells progressively buckle until all have collapsed at high strains (~ 0.8)
- then opposing cell walls touch - become more difficult to strain further, stress rises sharply (densification)
- long stress plateau - high energy absorption @ low stress
• foams excellent at energy absorption