# Homework 3: Multi-Agent Search

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# Part I. Implementation (5%):

The explanation of each code is written in the comment of codes.

#### **Part 1: Minimax Search**

```
# Begin your code (Part 1)
    # raise NotImplementedError("To be implemented")
   # initial agent = 0 (pacman) => find max value first
   # initial cDepth = 0 (current depth)
    score, Action = self.max_value(0, 0, gameState)
    return Action
def max_value(self, agentIndex, cDepth, gameState): # agentIndex = 0(pacman)
    if gameState.isWin() or gameState.isLose() or cDepth == self.depth:
        return self.evaluationFunction(gameState), None
    legalActions = gameState.getLegalActions(agentIndex)
    bestV = -10000
    bestMove = "x"
    for action in legalActions:
        # check every value possible after current state
        score, _ = self.min_value(1, cDepth, gameState.getNextState(0, action))
        if bestV < score:</pre>
            bestV = score
            bestMove = action
    return bestV, bestMove
```

```
def min_value(self, agentIndex, cDepth, gameState): # agentIndex != 0(ghost)
    if gameState.isWin() or gameState.isLose() or cDepth == self.depth:
        return self.evaluationFunction(gameState), None
    legalActions = gameState.getLegalActions(agentIndex)
    bestV = 10000
    bestMove = "x"
    if gameState.getNumAgents() == (agentIndex+1):
        nextAgent = 0
        cDepth += 1 # last ghost reached, current depth++
        nextAgent = agentIndex + 1
    for action in legalActions:
        if nextAgent == 0: # the last ghost
            score, _ = self.max_value(0, cDepth, gameState.getNextState(agentIndex, action))
        else:
            score, _ = self.min_value(nextAgent, cDepth, gameState.getNextState(agentIndex, action))
        if bestV > score:
            bestV = score
            bestMove = action
    return bestV, bestMove
```

#### Part 2: Alpha-Beta Pruning

```
# Begin your code (Part 2)
   # initial agent = 0 (pacman) => find max value first
    # initial cDepth = 0 (current depth)
      initial alpha = -10000, beta = 10000
    score, Action = self.max_value(0, 0, gameState, -10000, 10000)
    return Action
def max_value(self, agentIndex, cDepth, gameState, alpha, beta): # agentIndex = 0(pacman)
    if gameState.isWin() or gameState.isLose() or cDepth == self.depth:
        return self.evaluationFunction(gameState), None
    legalActions = gameState.getLegalActions(agentIndex)
    bestV = -10000
    bestMove = "x"
    for action in legalActions:
        score, _ = self.min_value(1, cDepth, gameState.getNextState(0, action), alpha, beta)
        if bestV < score:</pre>
            bestV = score
            bestMove = action
        # prune
        if score > beta:
           break
        if score > alpha:
           alpha = score
    return bestV, bestMove
```

```
def min_value(self, agentIndex, cDepth, gameState, alpha, beta): # agentIndex != 0(ghost)
   if gameState.isWin() or gameState.isLose() or cDepth == self.depth:
       return self.evaluationFunction(gameState), None
   legalActions = gameState.getLegalActions(agentIndex)
   bestV = 10000
   bestMove = "x"
   if gameState.getNumAgents() == (agentIndex+1):
       nextAgent = 0
       cDepth += 1 # last ghost reached, current depth++
       nextAgent = agentIndex + 1
   for action in legalActions:
       if nextAgent == 0:
           score, _ = self.max_value(0, cDepth, gameState.getNextState(agentIndex, action), alpha, beta)
           score, _ = self.min_value(nextAgent, cDepth, gameState.getNextState(agentIndex, action), alpha, beta)
       if bestV > score:
           bestV = score
           bestMove = action
       # prune
       if score < alpha:</pre>
           break
       if score < beta:</pre>
           beta = score
   return bestV, bestMove
```

#### Part 3: Expectimax Search

```
# Begin your code (Part 3)
    # raise NotImplementedError("To be implemented")
    # initial agent = 0 (pacman) => find max value first
    # initial cDepth = 0 (current depth)
    score, Action = self.max_value(0, 0, gameState)
    return Action
# this part is same as minimax
def max_value(self, agentIndex, cDepth, gameState): # agentIndex = 0(pacman)
    if gameState.isWin() or gameState.isLose() or cDepth == self.depth:
        return self.evaluationFunction(gameState), None
    legalActions = gameState.getLegalActions(agentIndex)
    bestV = -10000
    bestMove = "x"
    for action in legalActions:
        score = self.exp_value(1, cDepth, gameState.getNextState(0, action))
        if bestV < score:</pre>
            bestV = score
            bestMove = action
    return bestV, bestMove
```

```
def exp_value(self, agentIndex, cDepth, gameState): # agentIndex != 0(ghost)
    if gameState.isWin() or gameState.isLose() or cDepth == self.depth:
        return self.evaluationFunction(gameState)
    legalActions = gameState.getLegalActions(agentIndex)
    # expect_score : add all score first, return (all_score/num_of_actions) in the end
    expect score = 0
    if gameState.getNumAgents() == (agentIndex+1):
        nextAgent = 0
        cDepth += 1
    else:
        nextAgent = agentIndex + 1
    for action in legalActions:
        if nextAgent == 0:
            score, _ = self.max_value(0, cDepth, gameState.getNextState(agentIndex, action))
            expect_score += score
            score = self.exp_value(nextAgent, cDepth, gameState.getNextState(agentIndex, action))
            expect_score += score
    return expect_score / len(legalActions)
```

#### **Part 4: Better Evaluation Function**

```
# Begin your code (Part 4)
# get infomation first
PacPos = currentGameState.getPacmanPosition()
legalActions = currentGameState.getLegalActions(0)
if currentGameState.getFood().asList():
   nearestFoodDistance = min([manhattanDistance(PacPos, food) for food in currentGameState.getFood().asList()])
    nearestFoodDistance = 0
capsules = currentGameState.getCapsules()
nearestCapsuleDistance = 0
if len(capsules) != 0:
    capsulesDistance = [manhattanDistance(PacPos, capsule) for capsule in capsules]
    nearestCapsuleDistance = min(capsulesDistance)
GhostStates = currentGameState.getGhostStates()
minGhostDistance = 1000
for ghostState in GhostStates:
    dist = manhattanDistance(PacPos, ghostState.getPosition())
    if dist < minGhostDistance:</pre>
       minGhostDistance = dist
       nearestScaredTime = ghostState.scaredTimer
isScared = nearestScaredTime > 1
# initialize Score num
Score = currentGameState.getScore() * 10
```

```
.....
rules:
1. if near food then go to eat
2. if near capsule then go to eat
3. if near ghost and ghost is scared then go to eat ghost
4. if near ghost but not scared then run away
5. STOP is the least preferrable action
# 1.
Score -= 10 * nearestFoodDistance
# 2.
if nearestCapsuleDistance <= 5:</pre>
    Score -= 20 * nearestCapsuleDistance
# 3.
if isScared:
    Score -= 2 * minGhostDistance
# 4.
else:
    Score += 10 * minGhostDistance
for action in legalActions:
    if action == Directions.STOP:
        Score += 1000
return Score
# End your code (Part 4)
```

# Part II. Results & Analysis (5%):

## Result of autograder

### **Better Evaluation Function**

My rules for Evaluation Function is:

- 1. Go to nearest food
- 2. Go to nearest capsule if near to any one of capsule
- 3. If ghost is scared then go to eat it
- 4. If ghost is not scared then run away
- 5. Make stop the least preferrable action to choose

I tried to change the weight of food distance (shown in the figure below), and I found out that it performs better when set as 10. Therefore I set constant for food to 10, and constant for capsule to 20.

```
# 1.
Score -= 10 * nearestFoodDistance
```

change this constant

```
python3 pacman.py -p ExpectimaxAgent -l smallClassic -a depth=2 -q -n 10
Pacman died! Score: -61
Pacman emerges victorious! Score: 885
Pacman died! Score: -383
Pacman emerges victorious! Score: 790
Pacman died! Score: -372
Pacman died! Score: -158
Pacman emerges victorious! Score: 398
Pacman died! Score: -92
Pacman emerges victorious! Score: 744
Pacman died! Score: -149
Average Score: 160.2
               -61.0, 885.0, -383.0, 790.0, -372.0, -158.0, 398.0, -92.0, 744.0, -149.0
Scores:
Win Rate:
               4/10 (0.40)
Record:
              Loss, Win, Loss, Win, Loss, Win, Loss, Win, Loss
```

set as 1

```
[> python3 pacman.py -p ExpectimaxAgent -l smallClassic -a depth=2 -q -n 10
Pacman emerges victorious! Score: 907
Pacman emerges victorious! Score: 931
Pacman emerges victorious! Score: 896
Pacman emerges victorious! Score: 840
Pacman emerges victorious! Score: 784
Pacman emerges victorious! Score: 937
Pacman emerges victorious! Score: 1113
Pacman emerges victorious! Score: 945
Pacman emerges victorious! Score: 950
Pacman emerges victorious! Score: 1360
Average Score: 966.3
              907.0, 931.0, 896.0, 840.0, 784.0, 937.0, 1113.0, 945.0, 950.0, 1360.0
Scores:
Win Rate:
             10/10 (1.00)
              Record:
```

set as 10

I set constant for isScared to 10 originally, but it didn't perform well, so I set it to 2 instead.

```
# 3.
if isScared:
    Score -= 2 * minGhostDistance
```

change this constant

```
rading scheme:

< 500: 0 points

⇒ 500: 2 points

⇒ 1000: 4 points

mmes not timed out (2 of 2 points)
stion part4: 10/10 ##
```

result for constant = 2

```
### Question part4: 7/10 ###
```

result for constant = 10