

# Systems Programming Presentation

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# File System Introduction

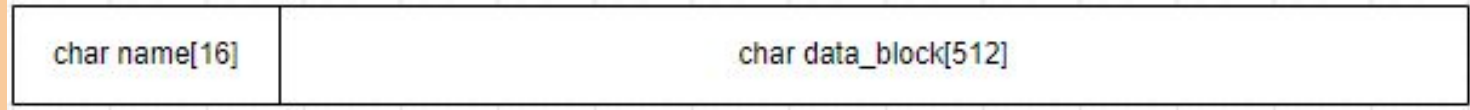
- Simplified version of Unix V7
- Uses Inodes to keep track of metadata for both files and directories
- All Inodes and data blocks are kept track of by the file system
- File system has a linked list of memory for the data blocks and Inodes
- The upper gig of memory is blocked out so the linked lists can be allocated there without interruption from the kernel

# Structure of an Inode

|                           |  |                               |                              |                              |                  |                               |                            |
|---------------------------|--|-------------------------------|------------------------------|------------------------------|------------------|-------------------------------|----------------------------|
| <code>uint8_t size</code> | <code>uint8_t<br/>num_of_pointers</code> | <code>bool_t is_direct</code> | <code>void *direct[0]</code> | <code>void *direct[1]</code> | <code>...</code> | <code>void *direct[14]</code> | <code>char name[16]</code> |
|---------------------------|--|-------------------------------|------------------------------|------------------------------|------------------|-------------------------------|----------------------------|

- The Inode contains the size of the data, the number of pointers that are active, if the first pointer is direct, and the list of pointers
- Only the first pointer in the array of pointers can be direct. It can be indirect
- The rest of the pointers must be indirect

# Structure of a File



- Each file contains a 16 byte array to represent the name, the index into the inode, and the 512 byte long data block



# Structure of the Memory Linked List



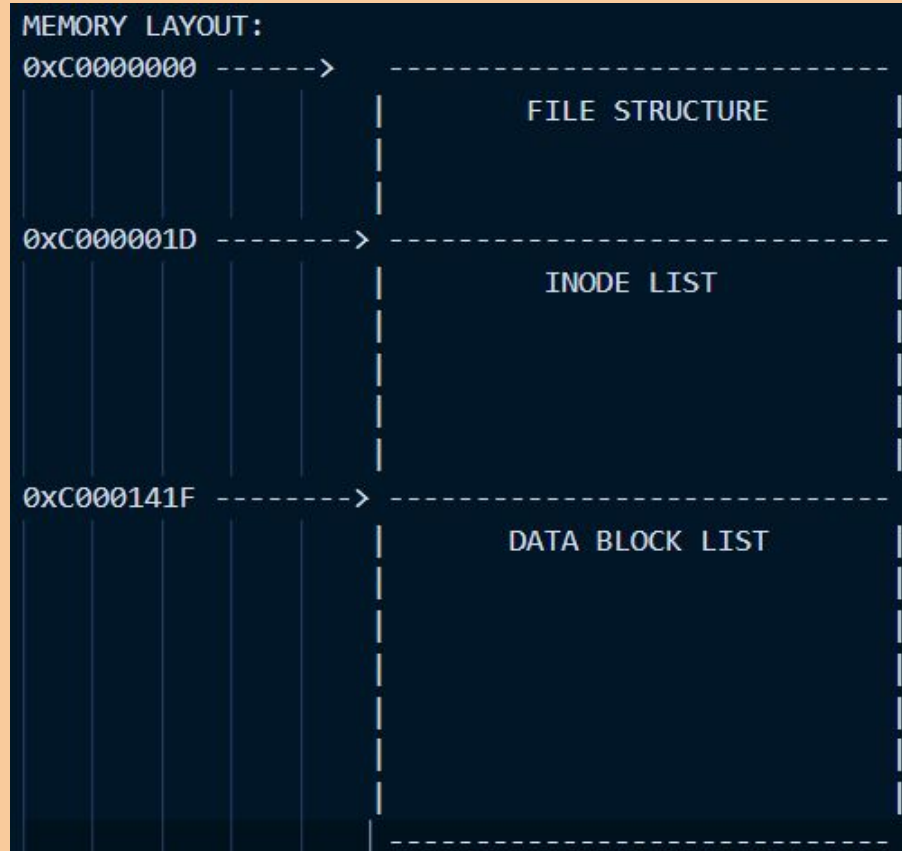
- The data pointer is used to pointer to either an Inode or a file
- The file system init process will allocate all of them before they are needed
- Each block will be allocated based on the predetermined size. This way, we don't have to use malloc or the kernel allocator for our files

# Structure of the File System

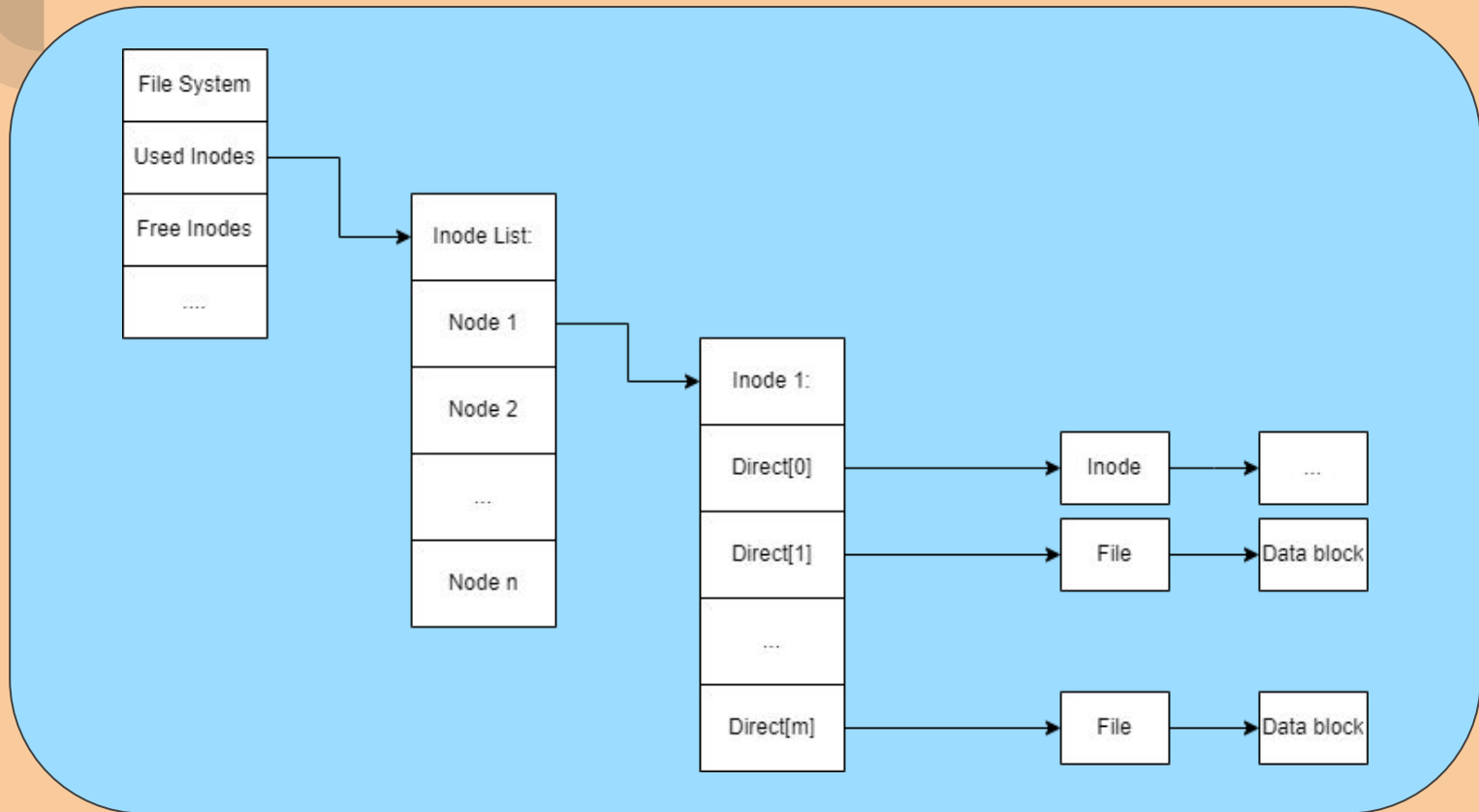
|                               |                             |                    |                    |                     |                     |                           |                            |
|-------------------------------|-----------------------------|--------------------|--------------------|---------------------|---------------------|---------------------------|----------------------------|
| uint32_t<br>num_free_pointers | uint32_t<br>num_free_blocks | list_s *free_nodes | list_s *used_nodes | list_s *free_blocks | list_s *used_blocks | Inode_s<br>*current_inode | Inode_s<br>*previous_inode |
|-------------------------------|-----------------------------|--------------------|--------------------|---------------------|---------------------|---------------------------|----------------------------|

- Contains the linked lists for the free/used data blocks and the free/used inodes
- Also contains the current number of free blocks/nodes and the current inode for the user and the previous inode

# Memory Layout



# How It Works







# What Can The File System Do?

- Create directories and files
- Read and write to files
- Add files into directories
- Delete the inodes and files
- Overwrites files so they are only spaces
- Move into a directory (but not out as of right now)
- Print information about the current directory



## What Went Well?

- I learned a lot about the Unix V7 file system and how it operates
- I learned more in detail about coding with structures in C
- I learned more about memory mapping and memory layouts using non-provided C allocation functions



# Problems Faced During My Portion

- Finding time to do this project outside of class
- Figuring out how my project can work with other group members
- Finding detailed and consistent documentation
- TESTING
- Deciding the overall structure and design of my system



# What Would I Change?

- Find a way to separate directories from Inodes since Inodes should only contain metadata about a structure, not the data itself
- Add functionality in the kernel process, so it can have different operations queued, and not be the only application running
- Change how I would have approached the beginning of the project



# AHCI Driver Introduction

- AHCI (Advanced Host Control Interface) is memory interface between system memory and SATA devices
- Implementing driver to handle communication with SATA hard drive
- Planned integration with file system through reading and writing files onto the hard drive

# Find AHCI Controller

- Enumerate PCI Bus
- AHCI Controller in systems is manufactured by Intel
  - vendor 0x8086 and device 0xA282
- AHCI Controllers are class 0x01 (Mass Storage Controller) and subclass 0x06 (Serial ATA Controller)
- Iterate through each bus and slot of PCI configuration space until device with those values is found.

| Register | Offset | Bits 31-24                    | Bits 23-16      | Bits 15-8           | Bits 7-0             |
|----------|--------|-------------------------------|-----------------|---------------------|----------------------|
| 0x0      | 0x0    | <u>Device ID</u>              |                 | <u>Vendor ID</u>    |                      |
| 0x1      | 0x4    | Status                        |                 | Command             |                      |
| 0x2      | 0x8    | <u>Class code</u>             | <u>Subclass</u> | Prog IF             | Revision ID          |
| 0x3      | 0xC    | BIST                          | Header type     | Latency Timer       | Cache Line Size      |
| 0x4      | 0x10   | Base address #0 (BAR0)        |                 |                     |                      |
| 0x5      | 0x14   | Base address #1 (BAR1)        |                 |                     |                      |
| 0x6      | 0x18   | Base address #2 (BAR2)        |                 |                     |                      |
| 0x7      | 0x1C   | Base address #3 (BAR3)        |                 |                     |                      |
| 0x8      | 0x20   | Base address #4 (BAR4)        |                 |                     |                      |
| 0x9      | 0x24   | <u>Base address #5 (BAR5)</u> |                 |                     |                      |
| 0xA      | 0x28   | Cardbus CIS Pointer           |                 |                     |                      |
| 0xB      | 0x2C   | Subsystem ID                  |                 | Subsystem Vendor ID |                      |
| 0xC      | 0x30   | Expansion ROM base address    |                 |                     |                      |
| 0xD      | 0x34   | Reserved                      |                 |                     | Capabilities Pointer |
| 0xE      | 0x38   | Reserved                      |                 |                     |                      |
| 0xF      | 0x3C   | Max latency                   | Min Grant       | Interrupt PIN       | Interrupt Line       |



# Find SATA Devices

- Devices can be found through HBA (Host Bus Adapter) registers
- Location of HBA registers is given by PCI BAR5 register, also known as AHCI Base Memory Register (ABAR)
- HBA registers have a ports implemented field
- Check each implemented port for a device
- If a port has a device connected, read signature to see if it's SATA



# Identify Correct Device

- Need to send IDENTIFY\_DEVICE command to each device found
- Commands are sent and results are received through Frame Information Structure (FIS) in memory
- Give the current port the addresses of different FIS data structures
  - Host to Device
  - Device to Host
  - Command Table
- Input command information into command table
- Send command by setting command bit
- Receive data in Physical Region Descriptor Table (PRDT) list of Command Table
- Verify that data received matches expected data of Western Digital HDD rather than Biwin SSD



Figure 4: HBA Memory Space Usage

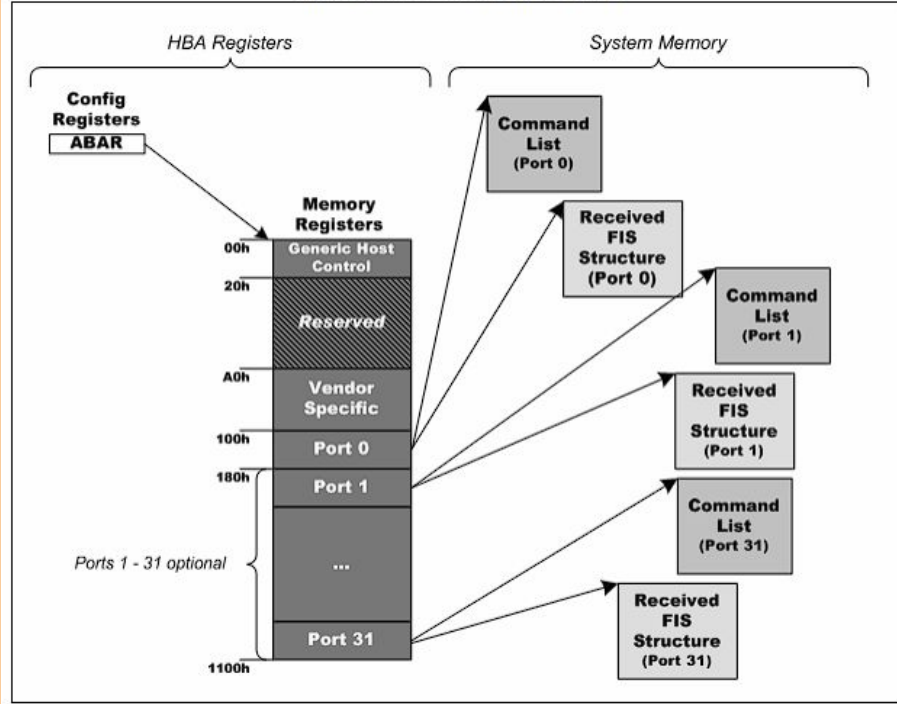
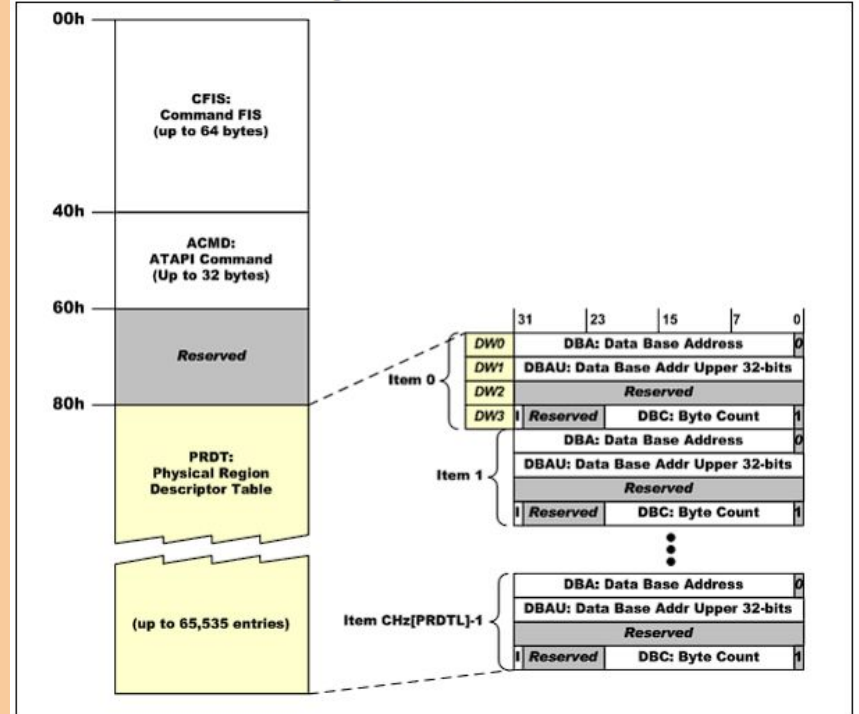


Figure 12: Command Table





# What Went Well

- Learned a lot about how device drivers work and are implemented
- More practice and understanding of C



# Problems Faced

- Failing to properly initialize various registers so commands can be sent/received
- Fear of hurting the boot drive
- Being able to internalize documentation



# What Would I Change?

- Make a more specific plan of steps I needed to take
- Follow better coding conventions so debugging is easier



# Parallel Port/Dot Matrix Printer

- General driver meant to receive and send data via parallel port.
  - Done via a PCI expansion card
- Communicate specifically to a dot matrix printer
- Done through simple port communication to both send and receive bytes



# Process

- Order a parallel port expansion card
- Identify the ports needed to talk through
  - Base off of linux addresses
  - Scan through PCI addresses
- Research status codes about the KX-P1180 Dot Matrix Printer
- Establish a “handshake” and begin communicating



# Parallel Port/PCI Card

- Like many others I had to go through PCI cards
- Parallel port does set different rules to communicate with
  - Any data needs to be sent in complete bytes
  - Once all data is sent, an additional byte needs to be sent to have the printer read in everything



# Dot Matrix Printer

- Establish a “handshake” and check on different possible status codes
  - First send a PRIME signal
  - BUSY, ERROR, PAPER OUT, OFF LINE
- If all good, wait for an ACK signal and start sending data
- Once all data is sent, send a STB signal to make the printer read in

|           | BUSY | SLCT | PO   | ERROR |
|-----------|------|------|------|-------|
| ON LINE   | LOW  | HIGH | LOW  | HIGH  |
| OFF LINE  | HIGH | LOW  | LOW  | LOW   |
| PAPER OUT | HIGH | LOW  | HIGH | LOW   |



| Signal pin | Return side pin | Signal       | Directin |
|------------|-----------------|--------------|----------|
| 1          | 19              | STB          | Input    |
| 2          | 20              | DATA 1       | Input    |
| 3          | 21              | DATA 2       |          |
| 4          | 22              | DATA 3       |          |
| 5          | 23              | DATA 4       |          |
| 6          | 24              | DATA 5       |          |
| 7          | 25              | DATA 6       |          |
| 8          | 26              | DATA 7       |          |
| 9          | 27              | DATA 8       |          |
| 10         | 28              | ACK          | Output   |
| 11         | 29              | BUSY         | Output   |
| 12         |                 | PO           | Output   |
| 13         |                 | SLCT         | Output   |
| 14         |                 | AUTO FEED XT | Input    |
| 15         |                 |              |          |
| 16         |                 | SG           |          |
| 17         |                 | FG           |          |
| 18         |                 | +5 V         | Output   |
| 31         | 30              | PRIME        | Input    |
| 32         |                 | ERROR        | Output   |
| 33         |                 | SG           |          |
| 34         |                 |              |          |
| 35         |                 |              |          |
| 36         |                 |              |          |

Pin Configuration



## What worked

- Accessing the PCI card
- Parallel port interfacing
- Receiving a status code from the printer



## What didn't work :(

- Sending data
- Changing printer states



# What problems did I face

- Port not being on the motherboard
- Time management with every other project I have
- Further web exploration instead of sticking to the same sources
- Obtain paper or try any paper in it



# What would I change

- Separate the functionality
  - Proper parallel port system driver
  - Standalone printer program
- Conforming to our established coding standards



# Questions