
First Term (Final Project 1)

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My profile

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Mastering Embedded System Online Diploma

www.learn-in-depth.com

Specification

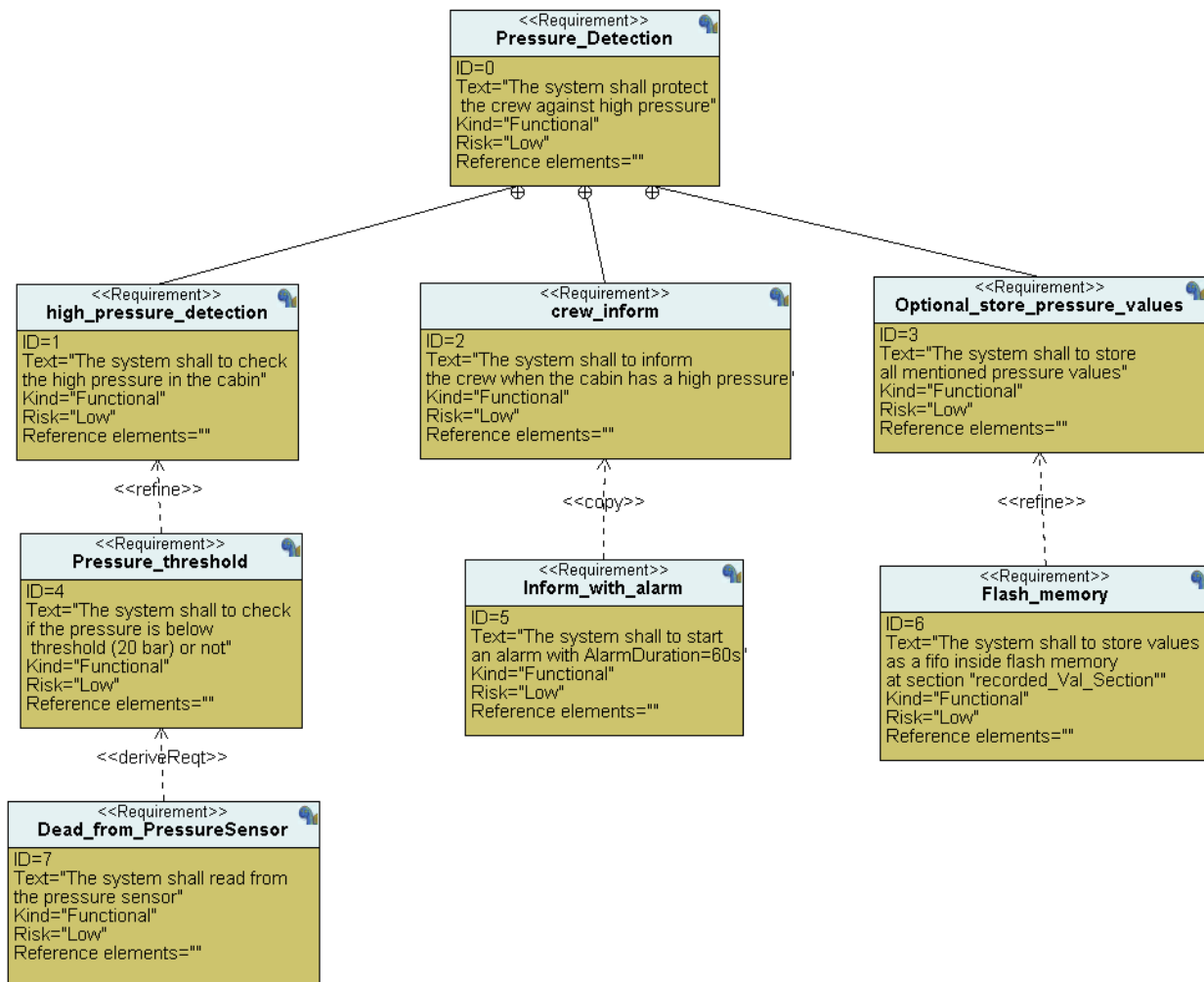
We need to deliver a Pressure Detection system.

after case studying, our system must do the following:

- 1- Informs the crew with **an alarm** when the pressure exceeds 20 bars.
- 2- The alarm duration equals 60 seconds.
- 3- Store pressure values into **FLASH** memory.

Requirements

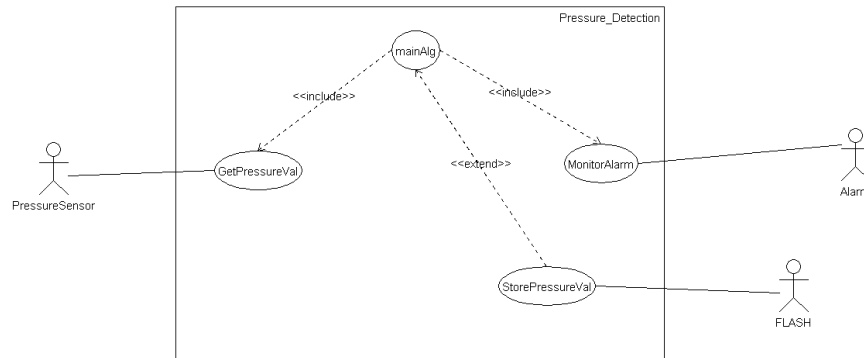
Our requirements diagram:



Analysis

• Use Case Diagram

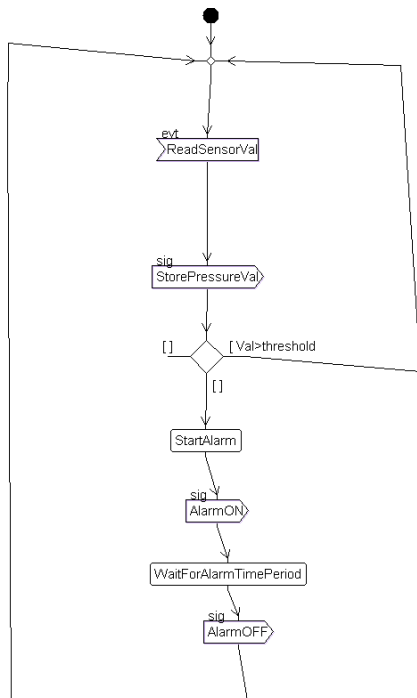
The following analysis helps us to know the main use cases and actors (sensors)



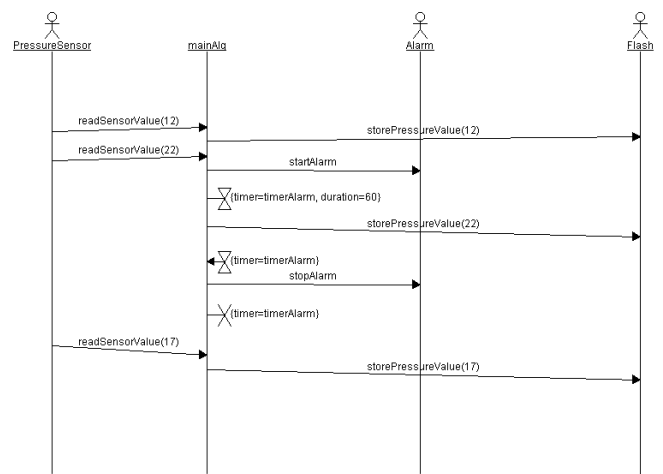
• Activity Diagram

Sequence Diagram

The following analysis helps us to know the flow of the system.

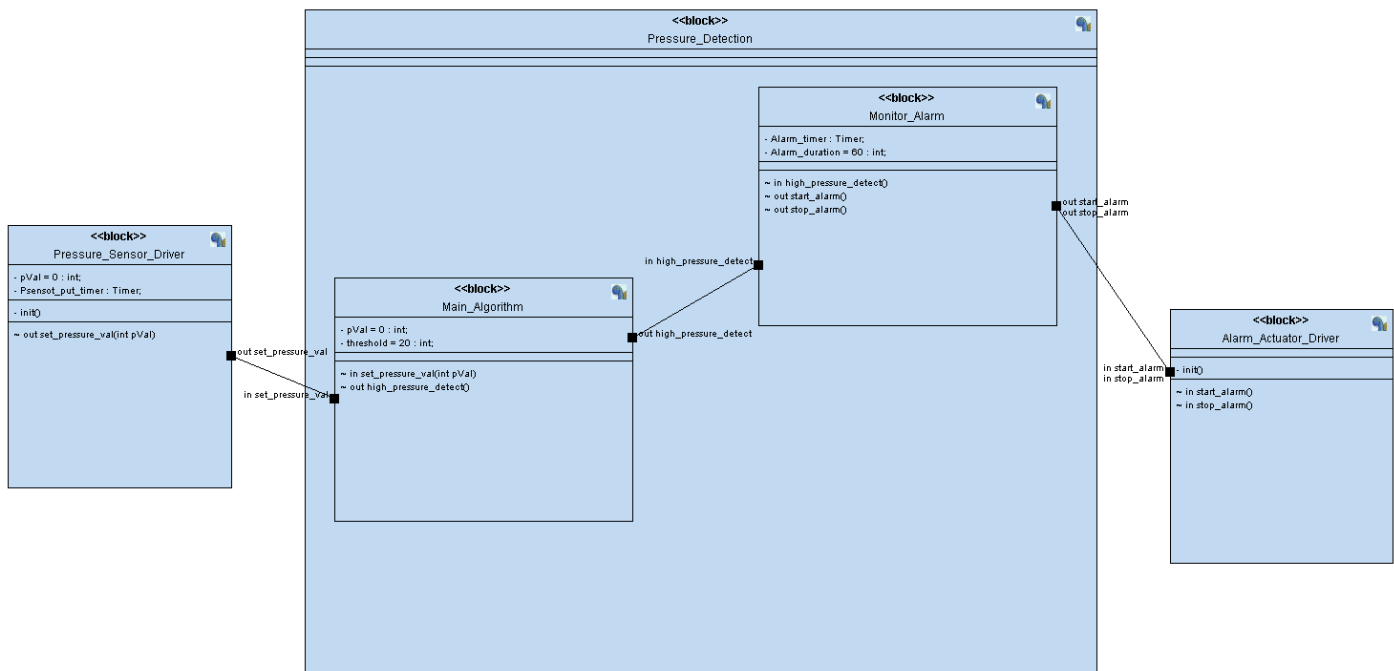


The following analysis helps us to know the algorithm of our system.

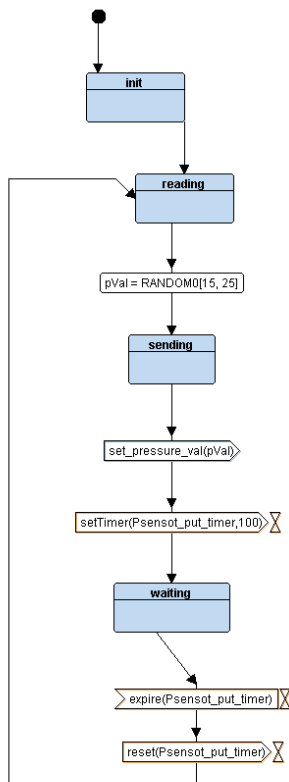


Design

1- Block Diagram



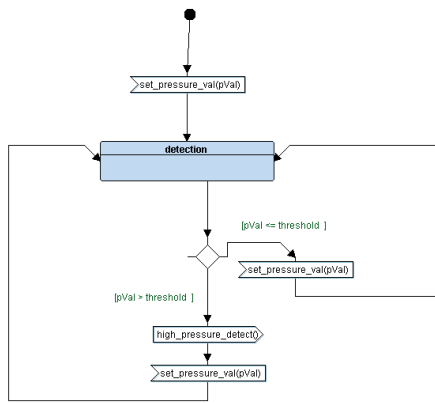
2- Pressure Sensor Driver – State diagram | PSD.h & PSD.c



```
2* * PSD.c
7
8 #include "PSD.h"
9 #include "driver.h"
10
11 //variables
12 static int pVal = 0;
13
14 //STATE Pointer to function
15 void (*PSD_state)();
16
17 //set random value for pressure
18 int PSD_set_pressure_random(int l, int r);
19
20 void PSD_init()
21 {
22     //initialize Pressure Sensor Driver
23     printf("PSD_init \n");
24 }
25
26 //first state
27 STATE_define(PSD_reading)
28 {
29     //state_name
30     PSD_state_id = PSD_reading;
31
32     //state_action --> read pressure value
33     pVal = getPressureVal();
34     //pVal = PSD_set_pressure_random(15,25);
35
36     //event check
37     printf("PSD_reading state: pressure=%d\n", pVal);
38
39     //moving to the next state
40     STATE(PSD_sending());
41 }
42
43 //second state
44 STATE_define(PSD_sending)
45 {
46     //state_name
47     PSD_state_id = PSD_sending;
48
49     //event check
50     printf("PSD_sending state: ... \n");
51
52     //moving to the next state
53     STATE(PSD_waiting());
54
55     //state_action --> send value to mainALG.c
56     set_pressure_val(pVal);
57 }
58
59 }
```

```
60
61 //second state
62 STATE_define(PSD_waiting)
63 {
64     //state_name
65     PSD_state_id = PSD_waiting;
66
67     //event check
68     printf("PSD_waiting state: setting a delay of 90 seconds\n");
69
70     //state_action --> set a 90 second delay
71     Delay(90000);
72
73     //get back to reading state
74     PSD_state = STATE(PSD_reading);
75 }
76
77
78
79 int PSD_set_pressure_random(int l, int r)
80 {
81     //this function generates random number in range 1 and r
82     int rand_num = (rand() % (r - 1 + 1)) + 1;
83     return rand_num;
84 }
85
2* * PSD.h
7
8 #ifndef PSD_H_
9 #define PSD_H_
10
11 #include "state.h"
12
13 //define states
14 enum{
15     PSD_reading,
16     PSD_sending,
17     PSD_waiting
18 }PSD_state_id;
19
20 //declare states functions for PSD
21 STATE_define(PSD_reading);
22 STATE_define(PSD_sending);
23 STATE_define(PSD_waiting);
24
25 //initialize Pressure Sensor Driver
26 void PSD_init();
27
28 //STATE Pointer to function
29 void (*PSD_state)();
30
31 #endif /* PSD_H_ */
32
```

3- Main Algorithm – State diagram | ALG.c & ALG.h



```

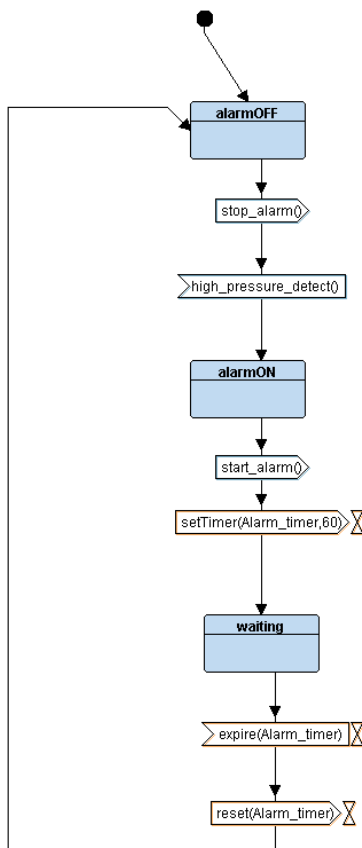
2* * AAD.c
7
8 #include "ALG.h"
9
10
11 //variables
12 static int ALG_pVal = 0;
13 static int ALG_threshold = 20;
14
15 //STATE Pointer to function
16 void (*ALG_state)();
17
18 //read from Pressure Sensor
19 void set_pressure_val(int pVal)
20 {
21     ALG_pVal = pVal;
22     printf(" PSD -----pVal=%d-----> ALG  \n", pVal);
23     if (ALG_pVal < ALG_threshold)
24         ALG_state = STATE(detection);
25     else
26     {
27         //first send signal to MonitorAlarm.c
28         high_pressure_detect();
29
30         //loop
31         ALG_state = STATE(detection);
32     }
33 }
34
35 STATE_define(detection)
36 {
37     //state_name
38     ALG_state_id = detection;
39
40     //event check
41     printf("ALG_detection state: ...\n");
42
43     //loop
44     ALG_state = STATE(detection);
45 }
46
  
```

ALG.h

```

2* * ALG.h
7
8 #ifndef ALG_H_
9 #define ALG_H_
10
11 #include "state.h"
12
13 //define states
14 enum{
15     detection
16 }ALG_state_id;
17
18 //declare states functions for mainALG
19 STATE_define(detection);
20
21 //STATE Pointer to function
22 void (*ALG_state)();
23
24 #endif /* ALG_H_ */
25
  
```

4- Monitor Alarm – State diagram | MonitorAlarm.c & MonitorAlarm.h



```

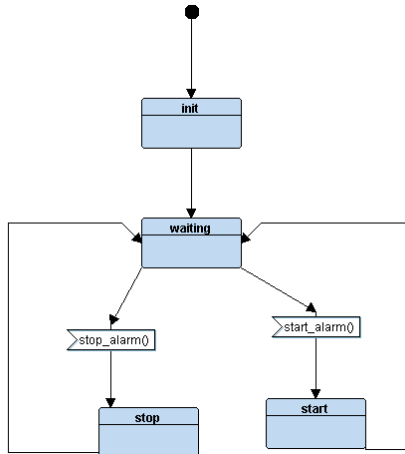
2* * MonitorAlarm.c
7
8 #include "MonitorAlarm.h"
9 #include "driver.h"
10
11 //variables
12 volatile static int alarmDuration = 60000;
13
14 //STATE Pointer to function
15 void (*M_state)();
16
17
18 void high_pressure_detect()
19 {
20     printf(" ALG ---->high pressure-----> MonitorAlarm  \n");
21     //moving to M_alarmON state
22     M_state = STATE(M_alarmON);
23     //M_state();
24 }
25
26 //first state
27 STATE_define(M_alarmOFF)
28 {
29     //state name
30     M_state_id = M_alarmOFF;
31
32     //event check
33     printf("M_alarmOFF state: ...\n");
34
35     //state action --> stop alarm
36     stop_alarm();
37 }
38
39
40 //second state
41 STATE_define(M_alarmON)
42 {
43     //state name
44     M_state_id = M_alarmON;
45
46     //event check
47     printf("M_alarmON state: ...\n");
48
49     //state action --> start alarm
50     start_alarm();
51
52     //moving to the next state
53     M_state = STATE(M_waiting);
54     //M_state();
55 }
56
57
58 //third state
59 STATE_define(M_waiting)
60 {
61     //state name
62     M_state_id = M_waiting;
63
64     //event check
65     printf("M_waiting state: starting a delay of 60 seconds\");
66
67     //state action --> set a 60 second delay
68     Delay(alarmDuration);
69
70     //moving to the next state
71     M_state = STATE(M_alarmOFF);
72     M_state();
73 }
74 }
75
  
```

MonitorAlarm.h

```

2* * MonitorAlarm.h
7
8 #ifndef MonitorAlarm_H_
9 #define MonitorAlarm_H_
10
11 #include "state.h"
12
13 //define states
14 enum{
15     M_alarmOFF,
16     M_alarmON,
17     M_waiting
18 }M_state_id;
19
20 //declare states functions for MonitorAlarm
21 STATE_define(M_alarmOFF);
22 STATE_define(M_alarmON);
23 STATE_define(M_waiting);
24
25 //STATE Pointer to function
26 void (*M_state)();
27
28 #endif /* MonitorAlarm_H_ */
29
  
```

5- Alarm Actuator – State diagram | AAD.c & AAD.h



```

2* * AAD.c
7
8 #include "AAD.h"
9 #include "driver.h"
10
11 //STATE Pointer to function
12 void (*AAD_state_ptr)();
13 /*
14 STATE_define(AAD_waiting);
15 STATE_define(AAD_start);
16 STATE_define(AAD_stop);*/
17
18 void AAD_init()
19 {
20     //initialize AAD
21     //printf("Alarm Actuator_driver_init \n");
22 }
23
24 STATE_define(AAD_waitingf)
25 {
26     //state name
27     AAD_state_id = AAD_waiting;
28
29     //printf("AAD_waiting state: ...\n");
30     AAD_state_ptr = STATE(AAD_waitingf);
31 }
32
33 STATE_define(AAD_startf)
34 {
35     //printf("AAD_start state: Alarm ON\n");
36
37     //state action --> set alarm actuator ON
38     Set_Alarm_actuator(0);
39
40     //moving to waiting state
41     AAD_state_ptr = STATE(AAD_waitingf);
42 }
43
44 STATE_define(AAD_stopf)
45 {
46     //printf("AAD_stop state: Alarm OFF\n");
47
48     //state action --> set alarm actuator OFF
49     Set_Alarm_actuator(1);
50
51     //moving to waiting state
52     AAD_state_ptr = STATE(AAD_waitingf);
53 }
54
55 void start_alarm()
56 {
57     //printf(" MonitorAlarm -----start_alarm-----> A
58     AAD_state_ptr = STATE(AAD_startf);
59     AAD_state_ptr();
60 }
61
62 void stop_alarm()
63 {
64     //printf(" MonitorAlarm -----stop_alarm-----> AA
65     AAD_state_ptr = STATE(AAD_stopf);
66     AAD_state_ptr();
67 }
68
  
```

AAD.h

```

2* * AAD.h
7
8 #ifndef AAD_H_
9 #define AAD_H_
10
11 #include "state.h"
12
13 //define states
14 enum{
15     AAD_waiting,
16     AAD_start,
17     AAD_stop
18 }AAD_state_id;
19
20 //declare states functions for AAD
21 STATE_define(AAD_waitingf);
22 STATE_define(AAD_startf);
23 STATE_define(AAD_stopf);
24
25 //initialize Pressure Sensor Driver
26 //void AAD_init();
27
28 //STATE Pointer to function
29 void (*AAD_state_ptr)();
30
31 #endif /* AAD_H_ */
  
```

1- Main.c | state.h

```

1*/* main.c
2
3 #include <stdio.h>
4 #include "ALG.h"
5 #include "PSD.h"
6 #include "AAD.h"
7 #include "MonitorAlarm.h"
8 #include "driver.h"
9
10 void setup()
11 {
12     //init all the drivers
13     GPIO_INITIALIZATION();
14     //init IRQ ...
15     //init HAL
16     //init block
17     PSD_init();
18     AAD_init();
19     //set states pointers for each block
20     PSD_state = STATE (PSD_reading);
21     ALG_state = STATE (detection);
22     M_state = STATE (M_alarmOFF);
23     AAD_state_ptr = STATE(AAD_waitingf);
24 }
25
26 int main()
27 {
28     volatile int d, a =0;
29     setup();
30
31     while(a<30)
32     {
33         //call state for each block
34         printf("\ntest: %d\n",a);
35         PSD_state();
36         ALG_state();
37         M_state();
38         AAD_state_ptr();
39         for(d=0; d<1000; d++);
40         a++;
41         printf("\n-----\n");
42     }
43
44     return 0;
45 }
  
```

```

2* * state.h
3
4 #ifndef STATE_H_
5 #define STATE_H_
6
7 #include <stdio.h>
8 #include <stdlib.h>
9
10 //Automatic state function generated
11 #define STATE_define(_statFUN_) void ST_##_statFUN_()
12 #define STATE(_statFUN_) ST_##_statFUN_
13
14 //states connection
15 void set_pressure_val(int pVal); //define it in the receiving block.c
16 void high_pressure_detect(); //define it in the receiving block.c
17 void start_alarm(); //define it in the receiving block.c
18 void stop_alarm(); //define it in the receiving block.c
19
20 #endif /* STATE_H_ */
  
```

testing Code

1- Successful output

```
Problems Tasks Console Properties Debugger Console
<terminated> [exit value: 0] unit4-project1-test3.exe [C:/C++ Application] C:\Users\hesham mohamed\workspace\C_Programming\unit4-project1-test3\Debug\unit4-project1-test3.exe (3/4/23, 8:29)
PSD_init
Alarm_Actuator_driver_init

test: 0
PSD_reading state: pressure=23
PSD_sending state: ...
PSD_waiting state: setting a delay of 90 seconds
    PSD -----pVal=23-----> ALG
    ALG -----high pressure-----> MonitorAlarm
ALG_detection state: ...
M_alarmOFF state: ...
    MonitorAlarm -----start_alarm-----> AAD
AAD_start state: Alarm ON
AAD_waiting state: ...

-----

test: 1
PSD_reading state: pressure=24
PSD_sending state: ...
PSD_waiting state: setting a delay of 90 seconds
    PSD -----pVal=24-----> ALG
    ALG -----high pressure-----> MonitorAlarm
ALG_detection state: ...
M_alarmOFF state: ...
    MonitorAlarm -----start_alarm-----> AAD
AAD_start state: Alarm ON
AAD_waiting state: ...

-----

test: 2
PSD_reading state: pressure=24
PSD_sending state: ...
PSD_waiting state: setting a delay of 90 seconds
    PSD -----pVal=24-----> ALG
    ALG -----high pressure-----> MonitorAlarm
ALG_detection state: ...
M_alarmOFF state: ...
    MonitorAlarm -----start_alarm-----> AAD
AAD_start state: Alarm ON
AAD_waiting state: ...

-----
```

Makefile & Startup & linker files

1- makefile

```
##@copyright : Hesham mohamed
##< replaced by the dependencies
##@ replaced by the target

CC=arm-none-eabi-
CFLAGS= -mcpu=cortex-m3 -gdwarf-2
INCS=-I .
LIBS=
#all .c files
SRC=$(wildcard *.c)
#anything .c replace it with .o
OBJ=$(SRC:.c=.o)
#all .s files
AS=$(wildcard *.s)
#anything .s replace it with .o
ASOBJ=$(AS:.s=.o)
Project_name=pressure_detection_project

all: $(Project_name).bin
    @echo "=====Build is Done, Hesham!===== "

%.o: %.s
    $(CC)as.exe $(CFLAGS) $< -o $@

#Here, it will use this target for every dependence with target .o and dependence .c
%.o: %.c
    $(CC)gcc.exe -c $(INCS) $(CFLAGS) -mthumb $< -o $@

$(Project_name).elf: $(OBJ) $(ASOBJ)
    $(CC)ld.exe -T linker-script.ld $(LIBS) $(OBJ) $(ASOBJ) -Map=map_file.map -o $@

$(Project_name).bin: $(Project_name).elf
    $(CC)objcopy.exe -O binary $(Project_name).elf $@

clean_all:
    rm *.o *.elf *.bin *.map

clean:
    rm *.elf *.bin *.map
```

2- startup

```
1 //startup.c
2 //Eng. Hesham Mohamed
3
4 #include <stdint.h>
5
6 //init the main() from main.c
7 extern int main(void);
8
9 //init the symbols from the linker
10 extern uint32_t _E_TEXT;
11 extern uint32_t _S_DATA;
12 extern uint32_t _E_DATA;
13 extern uint32_t _S_BSS;
14 extern uint32_t _E_BSS;
15
16 //to specify the stack_top location there are two ways
17 /*1st: to make sure that .BSS doesn't interface with the stack_top section in sram,
18 we will get its position size from the linker*/
19 extern uint32_t _STACK_TOP;
20 //2nd: booking 1024B located by .bss through an initialized array of int 256 element
21 static unsigned long stack_top[256];
22
23 //initializing handler functions
24 void _DEFAULT_handler(void);
25 void _reset(void);
26 void _NMI_handler(void) __attribute__((weak, alias ("_DEFAULT_handler")));
27 void _HARD_FAULT_handler(void) __attribute__((weak, alias ("_DEFAULT_handler")));
28 void _MM_FAULT_handler(void) __attribute__((weak, alias ("_DEFAULT_handler")));
29 void _BUS_FAULT_handler(void) __attribute__((weak, alias ("_DEFAULT_handler")));
30 void _USAGE_FAULT_handler(void) __attribute__((weak, alias ("_DEFAULT_handler")));
31
32
33 //to define vectors section there are two ways
34 /*
35 //1st: using array
36 uint32_t vectors[] __attribute__((section(".vectors"))) = {
37 // (uint32_t) &_STACK_TOP, //first way
38 (uint32_t) ((unsigned long)stack_top + sizeof(stack_top)), //second way
39 (uint32_t) &_reset,
40 (uint32_t) &_NMI_handler,
41 (uint32_t) &_HARD_FAULT_handler,
42 (uint32_t) &_MM_FAULT_handler,
43 (uint32_t) &_BUS_FAULT_handler,
44 (uint32_t) &_USAGE_FAULT_handler
45 };*/
46
47 /*2nd: using array of pointers to the handler functions*/
48 void (* const g_ptrn_func_vectors[])() __attribute__((section(".vectors"))) = {
49 (void (*)()) ((unsigned long)stack_top + sizeof(stack_top)), //stack top pointer
50 &_reset,
51 &_NMI_handler,
52 &_HARD_FAULT_handler,
53 &_MM_FAULT_handler,
54 &_BUS_FAULT_handler,
55 &_USAGE_FAULT_handler
56 };
57
58 void _reset(void)
59 {
60 int i=0;
61 //we need to copy data section from flash to sram
62 //we cast it to uchar to move byte by byte, but as we have make an alignment on the .data section
63 //we can use uint casting*/
64 uint32_t DATA_size = (unsigned char*)&_E_DATA - (unsigned char*)&_S_DATA;
65 unsigned char* P_src = (unsigned char*)&_E_TEXT;
66 unsigned char* P_dst = (unsigned char*)&_S_DATA;
67 for(i = 0; i<DATA_size; i++)
68 {
69 *((unsigned char*) P_dst++) = *((unsigned char*) P_src++);
70 }
71
72
73 //init .bss section in sram with value = 0
74 uint32_t BSS_size = (unsigned char*)&_E_BSS - (unsigned char*)&_S_BSS;
75 P_dst = (unsigned char*)&_S_BSS; //can i skip this step?? as _E_DATA == _S_BSS ??
76 for(i = 0; i<BSS_size; i++)
77 {
78 *((unsigned char*) P_dst++) = (unsigned char)0;
79 }
80
81 //jumping to the main()
82 main();
83 }
84
85 void _DEFAULT_handler(void)
86 {
87 _reset();
88 }
89
```

3- linker script

```
1 /* linker script: CortexM3
2 | Eng. Hesham Mohamed
3 | */
4
5 MEMORY
6 {
7 flash(RX) : ORIGIN = 0x08000000, LENGTH = 128k
8 sram(RWX) : ORIGIN = 0x20000000, LENGTH = 20k
9 }
10
11 SECTIONS
12 {
13 .text : {
14 | | | *(.vectors*)
15 | | | *(.text*)
16 | | | *(.rodata)
17 | | | _E_TEXT = . ;
18 }>flash
19
20 .data : {
21 | | | _S_DATA = . ;
22 | | | *(.data)
23 | | | . = ALIGN(4) ;
24 | | | _E_DATA = . ;
25 }> sram AT> flash
26
27 .bss : {
28 | | | _S_BSS = . ;
29 | | | *(.bss*)
30 | | | _E_BSS = . ;
31 | | | . = ALIGN(4) ;
32 | | | . = . + 0x1000;
33 | | | _STACK_TOP = . ;
34 }> sram
35
36 }
```


4- Run makefile

```
hesham mohamed@DESKTOP-GPKPFC5 MINGW32 /e/Study/Embedded System K.S/Unit 4/Project 1/Source
$ mingw32-make.exe
arm-none-eabi-gcc.exe -c -I . -mcpu=cortex-m3 -gdwarf-2 -mthumb PSD.c -o PSD.o
arm-none-eabi-gcc.exe -c -I . -mcpu=cortex-m3 -gdwarf-2 -mthumb startup.c -o startup.o
arm-none-eabi-gcc.exe -c -I . -mcpu=cortex-m3 -gdwarf-2 -mthumb main.c -o main.o
arm-none-eabi-gcc.exe -c -I . -mcpu=cortex-m3 -gdwarf-2 -mthumb ALG.c -o ALG.o
arm-none-eabi-gcc.exe -c -I . -mcpu=cortex-m3 -gdwarf-2 -mthumb MonitorAlarm.c -o MonitorAlarm.o
arm-none-eabi-gcc.exe -c -I . -mcpu=cortex-m3 -gdwarf-2 -mthumb AAD.c -o AAD.o
arm-none-eabi-gcc.exe -c -I . -mcpu=cortex-m3 -gdwarf-2 -mthumb driver.c -o driver.o
arm-none-eabi-ld.exe -T linker-script.ld PSD.o startup.o main.o ALG.o MonitorAlarm.o AAD.o driver.o -Map=map_file.map -o pressure_detection_project.elf
arm-none-eabi-objcopy.exe -O binary pressure_detection_project.elf pressure_detection_project.bin
=====Build is Done, Hesham!=====

hesham mohamed@DESKTOP-GPKPFC5 MINGW32 /e/Study/Embedded System K.S/Unit 4/Project 1/Source
$
```

Check sections!

- Using objdump.exe

```
hesham mohamed@DESKTOP-GPKPFC5 MINGW32 /e/Study/Embedded System K.S/Unit 4/Project 1/Source
$ arm-none-eabi-objdump.exe -h pressure_detection_project.elf

pressure_detection_project.elf:      file format elf32-littlearm

Sections:
Idx Name          Size      VMA       LMA       File off  Algn
---
 0 .text          00000540  08000000  08000000  00008000  2**2
CONTENTS, ALLOC, LOAD, READONLY, CODE
 1 .data          00000008  20000000  08000540  00010000  2**2
CONTENTS, ALLOC, LOAD, DATA
 2 .bss           00001424  20000008  08000548  00010008  2**2
ALLOC
 3 .debug_info     00000926  00000000  00000000  00010008  2**0
CONTENTS, READONLY, DEBUGGING
 4 .debug_abbrev   000004c2  00000000  00000000  0001092e  2**0
CONTENTS, READONLY, DEBUGGING
 5 .debug_loc      0000045c  00000000  00000000  00010df0  2**0
CONTENTS, READONLY, DEBUGGING
 6 .debug_aranges  000000e0  00000000  00000000  0001124c  2**0
CONTENTS, READONLY, DEBUGGING
 7 .debug_line     0000031e  00000000  00000000  0001132c  2**0
CONTENTS, READONLY, DEBUGGING
 8 .debug_str      00000322  00000000  00000000  0001164a  2**0
CONTENTS, READONLY, DEBUGGING
 9 .comment        00000011  00000000  00000000  0001196c  2**0
CONTENTS, READONLY
10 .ARM.attributes 00000033  00000000  00000000  0001197d  2**0
CONTENTS, READONLY
11 .debug_frame    00000300  00000000  00000000  000119b0  2**2
CONTENTS, READONLY, DEBUGGING
```

• Using readelf.exe

```
wslhan schmeide@kali:~/Documents/Study/Embedded_System_K_5/Unit_4/Project_1/Source$ arm-none-eabi-readelf.exe -a pressure_detection_project.elf
ELF Header:
  Magic:   7f 45 4c 01 01 00 00 00 00 00 00 00 00
  Class:   ELF32
  Data:    2's complement, little endian
  Version: 1 (current)
  OS/ABI:   UNIX - System V
  ABI Version: 0
  Type:    EXEC (Executable file)
  Machine: ARM
  Version: 0x1
  Entry point address: 0x8000000
  Start of program headers: 52 (bytes into file)
  Start of section headers: 73040 (bytes into file)
  Flags:    0x5000002, has entry point, Version5 EABI
  Size of this header: 52 (bytes)
  Size of program headers: 32 (bytes)
  Number of program headers: 2
  Size of section headers: 40 (bytes)
  Number of section headers: 16
  Section header string table index: 13

Section Headers:
 [Nr] Name                Type              Addr      Off      Size    ES Flg Lk Inf Al
 [ 0] .                     PROGBITS          00000000 000000 00000000 00 0 0 0
 [ 1] .text                 PROGBITS          08000000 080000 000540 00 AX 0 0 4
 [ 2] .data                 PROGBITS          20000000 010000 000008 00 WA 0 0 4
 [ 3] .bss                  PROGBITS          20000008 010008 001424 00 WA 0 0 4
 [ 4] .debug_info           PROGBITS          00000000 010008 000026 00 0 0 1
 [ 5] .debug_abbrev         PROGBITS          00000000 01092e 0004c2 00 0 0 1
 [ 6] .debug_loc            PROGBITS          00000000 010df0 00045c 00 0 0 1
 [ 7] .debug_aranges         PROGBITS          00000000 01124c 0000e0 00 0 0 1
 [ 8] .debug_line            PROGBITS          00000000 01132c 00031e 00 0 0 1
 [ 9] .debug_str             PROGBITS          00000000 01164a 000322 01 MS 0 0 1
[10] .comment               PROGBITS          00000000 01196c 000011 01 MS 0 0 1
[11] .ARM.attributes        PROGBITS          00000000 01197d 000033 00 0 0 1
[12] .debug_frame           PROGBITS          00000000 011980 000300 00 0 0 4
[13] .shstrtab              STRTAB           00000000 011cb0 00009d 00 0 0 1
[14] .symtab                SYMTAB           00000000 011fd0 0005a0 10 15 46 4
[15] .strtab                STRTAB           00000000 012570 0002ac 00 0 0 1
Key to Flags:
  W (write), A (alloc), X (execute), M (merge), S (strings)
  I (info), L (link order), G (group), T (TLS), E (exclude), x (unknown)
  O (extra OS processing required) o (OS specific), p (processor specific)

There are no section groups in this file.
```

```
Program Headers:
 Type           Offset    VirtAddr    PhysAddr    FileSiz MemSiz  Flg Align
 LOAD           0x008000 0x08000000 0x08000000 0x00540 0x00540 R E 0x8000
 LOAD           0x010000 0x20000000 0x08000540 0x00008 0x0142c RW 0x8000

Section to Segment mapping:
Segment Sections...
00   .text
01   .data .bss

There is no dynamic section in this file.

There are no relocations in this file.

There are no unwind sections in this file.
```

```
Symbol table '.symtab' contains 90 entries:
Num:  Value      Size Type      Bind    Vis     Ndx Name
 0: 00000000 0 NOTYPE  LOCAL   DEFAULT UND
 1: 08000000 0 SECTION LOCAL   DEFAULT 1
 2: 20000000 0 SECTION LOCAL   DEFAULT 2
 3: 20000008 0 SECTION LOCAL   DEFAULT 3
 4: 00000000 0 SECTION LOCAL   DEFAULT 4
 5: 00000000 0 SECTION LOCAL   DEFAULT 5
 6: 00000000 0 SECTION LOCAL   DEFAULT 6
 7: 00000000 0 SECTION LOCAL   DEFAULT 7
 8: 00000000 0 SECTION LOCAL   DEFAULT 8
 9: 00000000 0 SECTION LOCAL   DEFAULT 9
10: 00000000 0 SECTION LOCAL   DEFAULT 10
11: 00000000 0 SECTION LOCAL   DEFAULT 11
12: 00000000 0 SECTION LOCAL   DEFAULT 12
13: 00000000 0 FILE    LOCAL   DEFAULT ABS startup.c
14: 2000000c 0 NOTYPE  LOCAL   DEFAULT 3 $d
15: 2000000c 0 NOTYPE  LOCAL   DEFAULT 3 stack_top
16: 08000000 0 NOTYPE  LOCAL   DEFAULT 1 $d
17: 0800000a 0 NOTYPE  LOCAL   DEFAULT 1 $t
18: 0000008c 0 NOTYPE  LOCAL   DEFAULT 12 $d
19: 00000000 0 FILE    LOCAL   DEFAULT ABS PSD.c
20: 20000008 0 NOTYPE  LOCAL   DEFAULT 3 $d
21: 20000008 0 NOTYPE  LOCAL   DEFAULT 3 pval
22: 0800001c 0 NOTYPE  LOCAL   DEFAULT 1 $t
23: 00000010 0 NOTYPE  LOCAL   DEFAULT 12 $d
24: 00000000 0 FILE    LOCAL   DEFAULT ABS main.c
25: 08000170 0 NOTYPE  LOCAL   DEFAULT 1 $t
26: 000000d8 0 NOTYPE  LOCAL   DEFAULT 12 $d
27: 00000000 0 FILE    LOCAL   DEFAULT ABS ALG.c
28: 2000040c 0 NOTYPE  LOCAL   DEFAULT 3 $d
29: 2000040c 0 NOTYPE  LOCAL   DEFAULT 3 ALG_pval
30: 20000000 0 NOTYPE  LOCAL   DEFAULT 2 $d
31: 20000000 4 OBJECT  LOCAL   DEFAULT 2 ALG_threshold
32: 08000244 0 NOTYPE  LOCAL   DEFAULT 1 $t
33: 00000124 0 NOTYPE  LOCAL   DEFAULT 12 $d
34: 00000000 0 FILE    LOCAL   DEFAULT ABS MonitorAlarm.c
35: 20000004 0 NOTYPE  LOCAL   DEFAULT 2 $d
36: 20000004 4 OBJECT  LOCAL   DEFAULT 2 alarmDuration
37: 080002d0 0 NOTYPE  LOCAL   DEFAULT 1 $t
```

```
38: 0000010c 0 NOTYPE  LOCAL   DEFAULT 12 $d
39: 00000000 0 FILE    LOCAL   DEFAULT ABS AAD.c
40: 08000374 0 NOTYPE  LOCAL   DEFAULT 1 $t
41: 000001e8 0 NOTYPE  LOCAL   DEFAULT 12 $d
42: 00000000 0 FILE    LOCAL   DEFAULT ABS driver.c
43: 08000434 0 NOTYPE  LOCAL   DEFAULT 1 $t
44: 00000298 0 NOTYPE  LOCAL   DEFAULT 12 $d
45: 00000000 0 FILE    LOCAL   DEFAULT ABS
46: 08000540 0 NOTYPE  GLOBAL   DEFAULT 1 _E_TEXT
47: 080004c1 126 FUNC  GLOBAL   DEFAULT 1 GPIO_INITIALIZATION
48: 08000165 10 FUNC  WEAK     DEFAULT 1 _HARD_FAULT_handler
49: 20001410 4 OBJECT  GLOBAL   DEFAULT 3 PSD_state
50: 20001418 1 OBJECT  GLOBAL   DEFAULT 3 AAD_state_id
51: 08000165 10 FUNC  GLOBAL   DEFAULT 1 _DEFAULT_handler
52: 20001414 1 OBJECT  GLOBAL   DEFAULT 3 PSD_state_id
53: 08000375 10 FUNC  GLOBAL   DEFAULT 1 AAD_init
54: 08000029 40 FUNC  GLOBAL   DEFAULT 1 ST_PSD_reading
55: 080002ed 24 FUNC  GLOBAL   DEFAULT 1 ST_M_alarmOFF
56: 2000141c 4 OBJECT  GLOBAL   DEFAULT 3 ALG_state
57: 080003ad 32 FUNC  GLOBAL   DEFAULT 1 ST_AAD_startf
58: 080003ed 36 FUNC  GLOBAL   DEFAULT 1 start_alarm
59: 20000008 0 NOTYPE  GLOBAL   DEFAULT 2 _E_DATA
60: 08000459 24 FUNC  GLOBAL   DEFAULT 1 getPressureVal
61: 08000381 42 FUNC  GLOBAL   DEFAULT 1 ST_AAD_waitingf
62: 080003cd 32 FUNC  GLOBAL   DEFAULT 1 ST_AAD_stopf
63: 20000410 0 NOTYPE  GLOBAL   DEFAULT 3 _E_BSS
64: 08000471 80 FUNC  GLOBAL   DEFAULT 1 Set_Alarm_actuator
65: 080001cd 120 FUNC  GLOBAL   DEFAULT 1 main
66: 080002a5 42 FUNC  GLOBAL   DEFAULT 1 ST_detection
67: 08000331 66 FUNC  GLOBAL   DEFAULT 1 ST_M_waiting
68: 20001420 4 OBJECT  GLOBAL   DEFAULT 3 M_state
69: 08000165 10 FUNC  WEAK     DEFAULT 1 _BUS_FAULT_handler
70: 08000305 42 FUNC  GLOBAL   DEFAULT 1 ST_M_alarmON
71: 08000000 28 OBJECT GLOBAL   DEFAULT 1 q_ptr_func_vectors
72: 20000000 0 NOTYPE  GLOBAL   DEFAULT 2 _S_DATA
73: 20001410 0 NOTYPE  GLOBAL   DEFAULT 3 _STACK_TOP
74: 08000051 40 FUNC  GLOBAL   DEFAULT 1 ST_PSD_sending
75: 08000079 50 FUNC  GLOBAL   DEFAULT 1 ST_PSD_waiting
76: 0800001d 10 FUNC  GLOBAL   DEFAULT 1 PSD_init
77: 20001424 1 OBJECT  GLOBAL   DEFAULT 3 ALG_state_id
78: 08000171 90 FUNC  GLOBAL   DEFAULT 1 setup
79: 08000435 34 FUNC  GLOBAL   DEFAULT 1 delay
80: 08000165 10 FUNC  WEAK     DEFAULT 1 _NMI_handler
81: 20000008 0 NOTYPE  GLOBAL   DEFAULT 3 _S_BSS
82: 080000ad 182 FUNC  GLOBAL   DEFAULT 1 _reset
83: 08000411 36 FUNC  GLOBAL   DEFAULT 1 stop_alarm
84: 20001425 1 OBJECT  GLOBAL   DEFAULT 3 M_state_id
85: 20001428 4 OBJECT  GLOBAL   DEFAULT 3 AAD_state_ptr
86: 080002d1 28 FUNC  GLOBAL   DEFAULT 1 high_pressure_detect
87: 08000165 10 FUNC  WEAK     DEFAULT 1 _MM_FAULT_handler
88: 08000165 10 FUNC  WEAK     DEFAULT 1 _USAGE_FAULT_handler
```

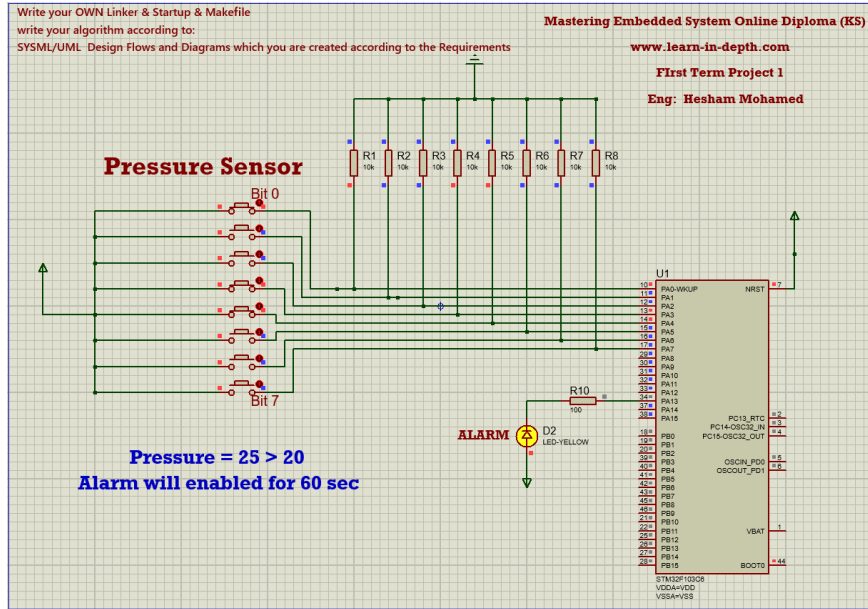
```
No version information found in this file.
Attribute Section: aeabi
File Attributes
  Tag_CPU_name: "Cortex-M3"
  Tag_CPU_arch: v7
  Tag_CPU_arch_profile: Microcontroller
  Tag_THUMB ISA_use: Thumb-2
  Tag_ABI_PCS_wchar_t: 4
  Tag_ABI_FP_denormal: Needed
  Tag_ABI_FP_exceptions: Needed
  Tag_ABI_FP_number_model: IEEE 754
  Tag_ABI_align_needed: 8-byte
  Tag_ABI_align_preserved: 8-byte, except leaf SP
  Tag_ABI_enum_size: small
  Tag_ABI_optimization_goals: Aggressive Debug
  Tag_CPU_unaligned_access: v6
```

Map file

1	Allocating common symbols			87	*(.data)	0x20000000	_S_DATA = .	172	.debug_aranges	0x00000060	0x20	ALG.o	
2	Common symbol	size	file	88	.data	0x20000000	0x0 PSD.o	173	.debug_aranges	0x00000080	0x20	MonitorAlarm.o	
3				89	.data	0x20000000	0x0 startup.o	175	.debug_aranges	0x000000a0	0x20	AAD.o	
4				90	.data	0x20000000	0x0 main.o	176	.debug_aranges	0x000000c0	0x20	driver.o	
5	PSD_state	0x4	PSD.o	91	.data	0x20000000	0x0 MonitorAlarm.o	177	.debug_line	0x00000000	0x31e		
6	AAD_state_id	0x1	main.o	92	.data	0x20000000	0x0 driver.o	181	.debug_line	0x00000000	0x4e	PSD.o	
7	PSD_state_id	0x1	PSD.o	93	.data	0x20000000	. = ALIGN (0x4)	182	.debug_line	0x0000004e	0xad	startup.o	
8	ALG_state	0x4	main.o	94	.data	0x20000000	_E_DATA = .	183	.debug_line	0x000000fb	0x8c	main.o	
9	M_state	0x4	main.o	95	.data	0x20000000	0x0 load address 0x00000548	184	.debug_line	0x00000187	0x48	ALG.o	
10	ALG_state_id	0x1	main.o	96	.data	0x20000000	0x0 PSD.o	185	.debug_line	0x000001cf	0x61	MonitorAlarm.o	
11	M_state_id	0x1	main.o	97	.data	0x20000000	0x0 PSD.o	186	.debug_line	0x00000230	0x53	AAD.o	
12	AAD_state_ptr	0x4	main.o	98	.data	0x20000000	0x0 PSD.o	187	.debug_line	0x00000283	0x9b	driver.o	
13				99	.igot.plt	0x20000000		188	.debug_str	0x00000000	0x322		
14	Memory Configuration			100	.igot.plt	0x00000000		189	.debug_str	0x00000000	0xed	PSD.o	
15				101				190	.debug_str	0x00000000	0x14f	(size before relaxing)	
16	Name	Origin	Length	Attributes	102	.bss	0x20000008	0x1424 load address 0x00000548	191	.debug_str	0x000000ed	0x8d	startup.o
17	flash	0x00000000	0x00020000	xr	103		0x20000008	_S_BSS = .	192	.debug_str	0x0000017a	0x15b	(size before relaxing)
18	sram	0x20000000	0x00005000	xrw	104	*(.bss*)			193	.debug_str	0x000001f9	0x1b6	(size before relaxing)
19	*default*	0x00000000	0xffffffff		105	.bss	0x20000008	0x4 PSD.o	194	.debug_str	0x0000017a	0x3b	ALG.o
20				106	.bss	0x2000000c	0x400 startup.o	195	.debug_str	0x00000234	0x134	(size before relaxing)	
21	Linker script and memory map			107	.bss	0x20000040c	0x0 main.o	196	.debug_str	0x00000234	0x5a	MonitorAlarm.o	
22				108	.bss	0x20000040c	0x4 ALG.o	197	.debug_str	0x0000028e	0x15f	(size before relaxing)	
23	.text	0x00000000	0x540	109	.bss	0x200000410	0x0 driver.o	200	.debug_str	0x0000028e	0x48	AAD.o	
24	*(.vectors*)			110	.bss	0x200000410	_E_BSS = .	201	.debug_str	0x0000028e	0x15e	(size before relaxing)	
25	.vectors	0x00000000	0x1c startup.o	111	.bss	0x200000410	. = ALIGN (0x4)	202	.debug_str	0x0000028e	0x4c	driver.o	
26				112	.bss	0x200000410	. = (. + 0x1000)	203	.debug_str	0x0000028e	0x128	(size before relaxing)	
27	*(.text*)			113	.bss	0x200000410	0x1000	204	.comment	0x00000000	0x11	PSD.o	
28	.text	0x0000001c	0x90 PSD.o	114	.bss	0x200000410	0x5 PSD.o	205	.comment	0x00000000	0x12	(size before relaxing)	
29				115	*fill*	0x200000410	PSD_state	206	.comment	0x00000000	0x12	startup.o	
30				116		0x200000410	PSD_state_id	207	.comment	0x00000000	0x12	main.o	
31				117	COMMON	0x200000410	0x14 main.o	208	.comment	0x00000000	0x12	ALG.o	
32				118	COMMON	0x200000410	AAD_state_id	209	.comment	0x00000000	0x12	MonitorAlarm.o	
33				119	COMMON	0x200000410	ALG_state_id	210	.comment	0x00000000	0x12	AAD.o	
34				120	COMMON	0x200000410	M_state	211	.comment	0x00000000	0x12	driver.o	
35				121	COMMON	0x200000410	ALG_state_id	212	.comment	0x00000000	0x12	driver.o	
36				122	COMMON	0x200000410	M_state_id	213	.comment	0x00000000	0x12	driver.o	
37				123	COMMON	0x200000410	AAD_state_ptr	214	.comment	0x00000000	0x12	driver.o	
38				124	COMMON	0x200000410		215	.comment	0x00000000	0x12	driver.o	
39				125	COMMON	0x200000410		216	.comment	0x00000000	0x12	driver.o	
40				126	COMMON	0x200000410		217	.comment	0x00000000	0x12	driver.o	
41				127	COMMON	0x200000410		218	.comment	0x00000000	0x12	driver.o	
42				128	COMMON	0x200000410		219	.comment	0x00000000	0x12	driver.o	
43				129	COMMON	0x200000410		220	.comment	0x00000000	0x12	driver.o	
44				130	COMMON	0x200000410		221	.comment	0x00000000	0x12	driver.o	
45				131	COMMON	0x200000410		222	.comment	0x00000000	0x12	driver.o	
46				132	COMMON	0x200000410		223	.comment	0x00000000	0x12	driver.o	
47				133	COMMON	0x200000410		224	.comment	0x00000000	0x12	driver.o	
48				134	COMMON	0x200000410		225	.comment	0x00000000	0x12	driver.o	
49				135	COMMON	0x200000410		226	.comment	0x00000000	0x12	driver.o	
50				136	COMMON	0x200000410		227	.comment	0x00000000	0x12	driver.o	
51				137	COMMON	0x200000410		228	.comment	0x00000000	0x12	driver.o	
52				138	COMMON	0x200000410		229	.comment	0x00000000	0x12	driver.o	
53				139	COMMON	0x200000410		230	.comment	0x00000000	0x12	driver.o	
54				140	COMMON	0x200000410		231	.comment	0x00000000	0x12	driver.o	
55				141	COMMON	0x200000410		232	.comment	0x00000000	0x12	driver.o	
56				142	COMMON	0x200000410		233	.comment	0x00000000	0x12	driver.o	
57				143	COMMON	0x200000410		234	.comment	0x00000000	0x12	driver.o	
58				144	COMMON	0x200000410		235	.comment	0x00000000	0x12	driver.o	
59				145	COMMON	0x200000410		236	.comment	0x00000000	0x12	driver.o	
60				146	COMMON	0x200000410		237	.comment	0x00000000	0x12	driver.o	
61				147	COMMON	0x200000410		238	.comment	0x00000000	0x12	driver.o	
62				148	COMMON	0x200000410		239	.comment	0x00000000	0x12	driver.o	
63				149	COMMON	0x200000410		240	.comment	0x00000000	0x12	driver.o	
64				150	COMMON	0x200000410		241	.comment	0x00000000	0x12	driver.o	
65				151	COMMON	0x200000410		242	.comment	0x00000000	0x12	driver.o	
66				152	COMMON	0x200000410		243	.comment	0x00000000	0x12	driver.o	
67				153	COMMON	0x200000410		244	.comment	0x00000000	0x12	driver.o	
68				154	COMMON	0x200000410		245	.comment	0x00000000	0x12	driver.o	
69				155	COMMON	0x200000410		246	.comment	0x00000000	0x12	driver.o	
70				156	COMMON	0x200000410		247	.comment	0x00000000	0x12	driver.o	
71				157	COMMON	0x200000410		248	.comment	0x00000000	0x12	driver.o	
72				158	COMMON	0x200000410		249	.comment	0x00000000	0x12	driver.o	
73				159	COMMON	0x200000410		250	.comment	0x00000000	0x12	driver.o	
74				160	COMMON	0x200000410		251	.comment	0x00000000	0x12	driver.o	
75				161	COMMON	0x200000410		252	.comment	0x00000000	0x12	driver.o	
76				162	COMMON	0x200000410		253	.comment	0x00000000	0x12	driver.o	
77				163	COMMON	0x200000410		254	.comment	0x00000000	0x12	driver.o	
78				164	COMMON	0x200000410		255	.comment	0x00000000	0x12	driver.o	
79				165	COMMON	0x200000410		256	.comment	0x00000000	0x12	driver.o	
80				166	COMMON	0x200000410		257	.comment	0x00000000	0x12	driver.o	
81				167	COMMON	0x200000410		258	.comment	0x00000000	0x12	driver.o	
82				168	COMMON	0x200000410		259	.comment	0x00000000	0x12	driver.o	
83				169	COMMON	0x200000410		260	.comment	0x00000000	0x12	driver.o	
84				170	COMMON	0x200000410		261	.comment	0x00000000	0x12	driver.o	
85				171	COMMON	0x200000410		262	.comment	0x00000000	0x12	driver.o	
86				172	COMMON	0x200000410		263	.comment	0x00000000	0x12	driver.o	
87				173	COMMON	0x200000410		264	.comment	0x00000000	0x12	driver.o	
88				174	COMMON	0x200000410		265	.comment	0x00000000	0x12	driver.o	
89				175	COMMON	0x200000410		266	.comment	0x00000000	0x12	driver.o	
90				176	COMMON	0x200000410		267	.comment	0x00000000	0x12	driver.o	
91				177	COMMON	0x200000410		268	.comment	0x00000000	0x12	driver.o	
92				178	COMMON	0x200000410		269	.comment	0x00000000	0x12	driver.o	
93				179	COMMON	0x200000410		270	.comment	0x00000000	0x12	driver.o	
94				180	COMMON	0x200000410		271	.comment	0x00000000	0x12	driver.o	
95				181	COMMON	0x200000410		272	.comment	0x00000000	0x12	driver.o	
96				182	COMMON	0x200000410		273	.comment	0x00000000	0x12	driver.o	
97				183	COMMON	0x200000410		274	.comment	0x00000000	0x12	driver.o	
98				184	COMMON	0x200000410		275	.comment	0x00000000	0x12	driver.o	
99				185	COMMON	0x200000410		276	.comment	0x00000000	0x12	driver.o	
100				186	COMMON	0x200000410		277	.comment	0x00000000	0x12	driver.o	
101				187	COMMON	0x200000410		278	.comment	0x00000000	0x12	driver.o	
102				188	COMMON	0x200000410		279	.comment	0x00000000	0x12	driver.o	
103				189	COMMON	0x200000410		280	.comment	0x00000000	0x12	driver.o	
104				190	COMMON	0x200000410		281	.comment	0x00000000	0x12	driver.o	
105				191	COMMON	0x200000410		282	.comment	0x00000000	0x12	driver.o	
106				192	COMMON	0x200000410		283	.comment	0x00000000	0x12	driver.o	
107				193	COMMON	0x200000410		284	.comment	0x00000000	0x12	driver.o	
108				194	COMMON	0x200000410		285	.comment	0x00000000	0x12	driver.o	
109				195	COMMON	0x200000410		286	.comment	0x00000000	0x12	driver.o	
110				196	COMMON	0x200000410		287	.comment	0x00000000	0x12	driver.o	
111				197	COMMON	0x200000410		288	.comment	0x00000000	0x12	driver.o	
112				198	COMMON	0x200000410		289	.comment	0x00000000	0x12	driver.o	
113				199	COMMON	0x200000410		290	.comment	0x00000000	0x12	driver.o	
114				200	COMMON	0x200000410		291	.comment	0x00000000	0x12	driver.o	
115				201	COMMON	0x200000410		292	.comment	0x00000000	0x12	driver.o	
116				202	COMMON	0x200000410		293	.comment	0x00000000			

Simulation results

1- Alarm ON



1- Alarm OFF

