

Assignment 2 Mathematical methods in physics

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Problem 1

We have a uniform string with fixed endpoints. The string is initially at rest in the equilibrium position, but there is a time-dependent driving force that is uniform in x . The PDE looks like this:

$$\frac{\partial^2 u}{\partial t^2}(x, t) = c^2 \frac{\partial^2 u}{\partial x^2}(x, t) + f(t)$$

A series solution to this PDE with time dependent coefficients would be given by a sine series due to the fixed endpoints. The solution would look like this:

$$u(x, t) = \sum_{n=1}^{\infty} u_n(t) \sin\left(\frac{n\pi}{L}x\right)$$

Similarly we can write the driving force as a sine series:

$$f(t) = \sum_{n=1}^{\infty} f_n(t) \sin\left(\frac{n\pi}{L}x\right)$$

We can compute the coefficients $f_n(t)$ using the formula:

$$f_n(t) = \frac{2}{L} \int_0^L f(t) \sin\left(\frac{n\pi}{L}x\right) dx = \frac{2f(t)}{n\pi}((-1)^{n+1} + 1)$$

This gives us the series:

$$f(t) = \sum_{n=1}^{\infty} \frac{4f(t)}{(2n-1)\pi} \sin\left(\frac{n\pi}{L}x\right)$$

We can now plug this into the PDE and get:

$$\sum_{n=1}^{\infty} \frac{\partial^2 u_n(t)}{\partial t^2} \sin\left(\frac{n\pi}{L}x\right) = c^2 \sum_{n=1}^{\infty} u_n(t) \frac{\partial^2}{\partial x^2} \left(\sin\left(\frac{n\pi}{L}x\right)\right) + \sum_{n=1}^{\infty} f_n(t) \sin\left(\frac{n\pi}{L}x\right)$$

We collect terms and write it as a single sum:

$$\sum_{n=1}^{\infty} \left(\frac{\partial^2 u_n(t)}{\partial t^2} - c^2 \frac{n^2 \pi^2}{L^2} u_n(t) - f_n(t) \right) \sin\left(\frac{n\pi}{L}x\right) = 0$$

By the uniqueness of fourirer series we can now conclude that each term in the sum must be equal to zero. This gives us a set of ODEs:

$$\frac{\partial^2 u_n(t)}{\partial t^2} - c^2 \frac{n^2 \pi^2}{L^2} u_n(t) = f_n(t)$$

IF we assume that $f(t) = \sin(\omega t)$ we can solve the ode:

$$\frac{\partial^2 u_n(t)}{\partial t^2} - c^2 \frac{n^2 \pi^2}{L^2} u_n(t) = f_n(t)$$

We can solve this like any other ODE we start by finding the homogeneous solution:

$$\frac{\partial^2 u_n(t)}{\partial t^2} - c^2 \frac{n^2 \pi^2}{L^2} u_n(t) = 0$$

This homogeneous solution can be found by physical reasoning. At time $t = 0$ the string is at rest in the equilibrium position and the only thing moving it from there is the driving force $f(t)$ and since we

are computing the homogeneous solution we set $f(t) = 0$. This means that the string wont move. If the string doesnt move we can conclude that the homogeneous solution is $u_n(t) = 0$. This means that the only solution to the ODE is the particular solution. To find that we make an ansatz $u_n(t) = A_n \sin(\omega t)$ and plug it into the ODE and since we know that we get zero when $f_n(t) = 0$ we only need to compute for odd n:

$$\frac{\partial^2 u_n(t)}{\partial t^2} - c^2 \frac{(2n-1)^2 \pi^2}{L^2} u_n(t) = \frac{4 \sin(\omega t)}{(2n-1)\pi}$$

This gives us:

$$-A_n \omega^2 \sin(\omega t) - c^2 \frac{(2n-1)^2 \pi^2}{L^2} A_n \sin(\omega t) = \frac{4 \sin(\omega t)}{(2n-1)\pi}$$

We can now divide by $\sin(\omega t)$ and get:

$$-A_n \omega^2 - c^2 \frac{(2n-1)^2 \pi^2}{L^2} A_n = \frac{4}{(2n-1)\pi}$$

This we can solve for A_n :

$$A_n = \frac{4}{(2n-1)\pi} \frac{1}{-\omega^2 - c^2 \frac{(2n-1)^2 \pi^2}{L^2}}$$

This gives us the solution to the ODE:

$$u_n(t) = \frac{4}{(2n-1)\pi} \frac{1}{-A_n \omega^2 - c^2 \frac{(2n-1)^2 \pi^2}{L^2}} \sin(\omega t)$$

If we substitue this into the series solution we get:

$$u(x, t) = \sum_{n=1}^{\infty} \frac{4}{(2n-1)\pi} \frac{1}{-A_n \omega^2 - c^2 \frac{(2n-1)^2 \pi^2}{L^2}} \sin(\omega t) \sin\left(\frac{n\pi}{L} x\right)$$

When ω approaches $\frac{\pi c}{L}$ the first mode resonates and the amplitude goes to infinity. On the other hand if we approach $\frac{2\pi c}{L}$ we dont get resonace since we dont have a mode that matches the driving force. This means that the amplitude will be finite.

Problem 2

Again we have a uniform string with fixed endpoints, and some frictional force acting on it. The PDE looks like this:

$$\rho_0 \frac{\partial^2 u}{\partial t^2}(x, t) = T_0 \frac{\partial^2 u}{\partial x^2}(x, t) - \beta \frac{\partial u}{\partial t}(x, t)$$

Since the PDE is linear and homogeneous and the boundary conditions also are linear and homogeneous we can use separation of variables. We can write the solution as a product of two functions:

$$u(x, t) = X(x)T(t)$$

We can now plug this into the PDE and get:

$$\rho_0 X(x) \frac{\partial^2 T(t)}{\partial t^2} = T_0 \frac{\partial^2 X(x)}{\partial x^2} T(t) - \beta X(x) \frac{\partial T(t)}{\partial t}$$

We can now divide by XTT_0 and get:

$$\frac{\rho_0}{T_0} \frac{1}{T(t)} \frac{\partial^2 T(t)}{\partial t^2} = \frac{\partial^2 X(x)}{\partial x^2} \frac{1}{X(x)} - \frac{\beta}{T_0} \frac{1}{T(t)} \frac{\partial T(t)}{\partial t}$$

From this we can form two ODEs:

$$\begin{aligned} \frac{\partial^2 X(x)}{\partial x^2} &= -\lambda X(x) \\ \frac{\rho_0}{T_0} \frac{\partial^2 T(t)}{\partial t^2} + \frac{\beta}{T_0} \frac{\partial T(t)}{\partial t} &= -\lambda T(t) \end{aligned}$$

We can now solve the ODEs. We begin with the spatial ODE:

$$\frac{\partial^2 X(x)}{\partial x^2} = -\lambda X(x)$$

We need to consider the different cases for λ , we begin with $\lambda = 0$:

$$\frac{\partial^2 X(x)}{\partial x^2} = 0$$

This gives us the solution:

$$X(x) = A + Bx$$

Plugging in the boundary conditions we get:

$$\begin{aligned} X(0) = 0 &\Rightarrow A = 0 \\ X(L) = 0 &\Rightarrow B = 0 \end{aligned}$$

This gives us the trivial solution $X(x) = 0$. Now we consider $\lambda > 0$:

$$\frac{\partial^2 X(x)}{\partial x^2} = -\lambda X(x)$$

This gives us the solution:

$$X(x) = A \cos(\sqrt{\lambda}x) + B \sin(\sqrt{\lambda}x)$$

Plugging in the boundary conditions we get:

$$\begin{aligned} X(0) = 0 &\Rightarrow A = 0 \\ X(L) = 0 &\Rightarrow B \sin(\sqrt{\lambda}L) = 0 \end{aligned}$$

This is satisfied if $\sin(\sqrt{\lambda}L) = 0$ which gives us the condition:

$$\sqrt{\lambda}L = n\pi \Rightarrow \lambda = \frac{n^2\pi^2}{L^2}$$

Now we check the case $\lambda < 0$:

$$\frac{\partial^2 X(x)}{\partial x^2} = -\lambda X(x)$$

This gives us the solution:

$$X(x) = Ae^{\sqrt{-\lambda}x} + Be^{-\sqrt{-\lambda}x}$$

Plugging in the boundary conditions we get:

$$\begin{aligned} X(0) = 0 &\Rightarrow A + B = 0 \\ X(L) = 0 &\Rightarrow Ae^{\sqrt{-\lambda}L} + Be^{-\sqrt{-\lambda}L} = 0 \end{aligned}$$

This gives us the condition:

$$e^{\sqrt{-\lambda}L} = -1$$

This is not possible since $e^{\sqrt{-\lambda}L}$ is always positive. This means that $\lambda < 0$ gives us no solutions. This means that the only solutions to the spatial ODE are given by $\lambda = \frac{n^2\pi^2}{L^2}$ and $X_n(x) = B_n \sin(\frac{n\pi}{L}x)$.

Now we solve the temporal ODE:

$$\frac{\rho_0}{T_0} \frac{\partial^2 T(t)}{\partial t^2} + \frac{\beta}{T_0} \frac{\partial T(t)}{\partial t} = -\lambda T(t)$$

We can plug in $\lambda = \frac{n^2\pi^2}{L^2}$ and get:

$$\frac{\rho_0}{T_0} \frac{\partial^2 T(t)}{\partial t^2} + \frac{\beta}{T_0} \frac{\partial T(t)}{\partial t} = -\frac{n^2\pi^2}{L^2} T(t)$$

We can now multiply by $\frac{T_0}{\rho_0}$ and get:

$$\frac{\partial^2 T(t)}{\partial t^2} + \frac{\beta}{\rho_0} \frac{\partial T(t)}{\partial t} = -\frac{n^2 \pi^2}{L^2} T(t)$$

From this we can form the characteristic equation:

$$r^2 + \frac{\beta}{\rho_0} r + \frac{n^2 \pi^2}{L^2} = 0$$

This gives us the solutions:

$$r_{1,2} = -\frac{\beta}{2\rho_0} \pm \sqrt{\left(\frac{\beta}{2\rho_0}\right)^2 - \frac{n^2 \pi^2}{L^2}}$$

Since β is small we can approximate $\left(\frac{\beta}{2\rho_0}\right)^2 = 0$ and get:

$$r_{1,2} = -\frac{\beta}{2\rho_0} \pm \sqrt{-\frac{n^2 \pi^2}{L^2}} = -\frac{\beta}{2\rho_0} \pm i \frac{n\pi}{L}$$

This gives us the solution:

$$T_n(t) = e^{-\frac{\beta}{2\rho_0} t} \left(C_n \cos\left(\frac{n\pi}{L} t\right) + D_n \sin\left(\frac{n\pi}{L} t\right) \right)$$

This gives us the general solution to the PDE:

$$u(x, t) = \sum_{n=1}^{\infty} B_n e^{-\frac{\beta}{2\rho_0} t} \left(C_n \cos\left(\frac{n\pi}{L} t\right) + D_n \sin\left(\frac{n\pi}{L} t\right) \right) \sin\left(\frac{n\pi}{L} x\right)$$

Now we can use the initial conditions to fix the coefficients. We have:

$$u(x, 0) = f(x) \Rightarrow \sum_{n=1}^{\infty} B_n C_n \sin\left(\frac{n\pi}{L} x\right) = f(x)$$

We can use the fourier series to compute the coefficients:

$$B_n C_n = \frac{2}{L} \int_0^L f(x) \sin\left(\frac{n\pi}{L}x\right) dx$$

Since $f(x)$ isn't specified we can leave the coefficients as they are. Now we can use the second initial condition $\frac{\partial u}{\partial t}(x, 0) = g(x)$:

$$\sum_{n=1}^{\infty} B_n \left(-\frac{\beta}{2\rho_0} C_n + \frac{n\pi}{L} D_n\right) \sin\left(\frac{n\pi}{L}x\right) = g(x)$$

Again we can use the fourier series to compute the coefficients:

$$B_n \left(-\frac{\beta}{2\rho_0} C_n + \frac{n\pi}{L} D_n\right) = \frac{2}{L} \int_0^L g(x) \sin\left(\frac{n\pi}{L}x\right) dx$$

From the exponential term we can see that a larger β will cause the amplitude to decay faster. The amplitude of the oscillations can be expressed as: $e^{-\frac{\beta}{2\rho_0} t} B_n \sqrt{C_n^2 + D_n^2}$. How the oscillatory nature of the different modes are affected by β I don't really understand.

Problem 3

We are given an operator L and we are asked to determine L^\dagger

$$L = a(x) \frac{d^2}{dx^2} + b(x) \frac{d}{dx} + c(x)$$

The operator L and its adjoint L^\dagger are correlated as:

$$\int_{x_0}^{x_1} u L^\dagger(v) - v L(u) dx = w(x) \Big|_{x_0}^{x_1}$$

We now need to determine L^\dagger and $w(x)$.

We start by insterting the expanded form of L and L^\dagger :

$$\int_{x_0}^{x_1} uL^\dagger(v) - vL(u)dx = \int_{x_0}^{x_1} uL^\dagger(v) - \int_{x_0}^{x_1} v \left(a(x) \frac{d^2u}{dx^2} + b(x) \frac{du}{dx} + c(x)u \right) dx$$

The second term can be split further:

$$\int_{x_0}^{x_1} va(x) \frac{d^2u}{dx^2} dx + \int_{x_0}^{x_1} vb(x) \frac{du}{dx} dx + \int_{x_0}^{x_1} c(x)uv dx$$

Using integration by parts we can now compute these terms:

$$\begin{aligned} \int_{x_0}^{x_1} va(x) \frac{d^2u}{dx^2} dx &= va(x) \frac{du}{dx} \Big|_{x_0}^{x_1} - \int_{x_0}^{x_1} \frac{du}{dx} \left(\frac{dv}{dx} a(x) + v \frac{da}{dx} \right) dx = \\ &= va(x) \frac{du}{dx} \Big|_{x_0}^{x_1} - \int_{x_0}^{x_1} \frac{du}{dx} \frac{dv}{dx} a(x) - \int_{x_0}^{x_1} \frac{du}{dx} v \frac{da}{dx} dx = \\ &= va(x) \frac{du}{dx} \Big|_{x_0}^{x_1} - \left(u \frac{dv}{dx} a(x) \Big|_{x_0}^{x_1} - \int_{x_0}^{x_1} u \left(\frac{d^2v}{dx^2} a(x) + \frac{dv}{dx} \frac{da}{dx} \right) dx \right) - \\ &\quad - \left(uv \frac{da}{dx} \Big|_{x_0}^{x_1} - \int_{x_0}^{x_1} u \left(\frac{d^2a}{dx^2} v + \frac{da}{dx} \frac{dv}{dx} \right) dx \right) \end{aligned}$$

$$\begin{aligned} \int_{x_0}^{x_1} vb(x) \frac{du}{dx} dx &= vb(x)u \Big|_{x_0}^{x_1} - \int_{x_0}^{x_1} u \left(\frac{dv}{dx} b(x) + v \frac{db}{dx} \right) dx \\ \int_{x_0}^{x_1} c(x)uv dx & \end{aligned}$$

If we put this all together we get:

$$\int_{x_0}^{x_1} vL(u)dx = v \frac{du}{dx} a - \frac{dv}{dx} ua - vu \frac{da}{dx} + vub \Big|_{x_0}^{x_1} + \int_{x_0}^{x_1} u \left(\frac{d^2v}{dx^2} a + v \frac{d^2a}{dx^2} + 2 \frac{dv}{dx} \frac{da}{dx} \right) - u \left(\frac{dv}{dx} b + v \frac{db}{dx} \right) + uvcdx$$

If we rewrite the orginial equation we get:

$$\int_{x_0}^{x_1} uL^\dagger(v)dx = \int_{x_0}^{x_1} vL(u)dx + w(x) \Big|_{x_0}^{x_1}$$

If we compare the two integrals we can see that:

$$L^\dagger = a(x) \frac{d^2}{dx^2} + \left(2 \frac{da}{dx} - b(x) \right) \frac{d}{dx} + \left(\frac{d^2 a}{dx^2} - \frac{db}{dx} + c(x) \right)$$

and

$$w(x) = v \frac{du}{dx} a - \frac{dv}{dx} u a - v u \frac{da}{dx} + v u b$$

In order for $L = L^\dagger$ we need to compare terms to find constraints.

$$\begin{aligned} a(x) &= a(x) \\ 2 \frac{da}{dx} - b(x) &= b(x) \\ \frac{d^2 a}{dx^2} - \frac{db}{dx} + c(x) &= c(x) \end{aligned}$$

In order for these equations to be satisfied we need to have $\frac{da}{dx} = b$. So $c(x)$ is arbitrary and $a(x)$ and $b(x)$ are related by $b(x) = \frac{da}{dx}$. If we have L on this form we can prove that it is of Sturm-Liouville type.

We begin by rewriting the formula for a sturm-liouville operator:

$$\frac{d}{dx} \left(p(x) \frac{d}{dx} \right) + q(x) = p(x) \frac{d^2}{dx^2} + \frac{dp}{dx} \frac{d}{dx} + q(x)$$

From here we can correlate a,b and c with p and q:

$$\begin{aligned} a(x) &= p(x) \\ b(x) &= \frac{dp}{dx} \\ c(x) &= q(x) \end{aligned}$$

So with the constraint $b(x) = \frac{da}{dx}$ we can conclude that L is of Sturm-Liouville type.

Since $L = L^\dagger$ is of Sturm-Liouville type we can conclude that it is self adjoint with all regular boundary conditions as long as $a(x)$ is smooth and positive and $c(x)$ is smooth and real. The regular boundary conditions are homogeneous and can be Dirichlet, Neumann or mixed.

In order for $L = L^\dagger$ to be self adjoint the boundary terms must vanish. This means that $w(x)$ must vanish at the boundaries. So as long as the boundary conditions on both u and v make them vanish at the boundaries $w(x)$ will vanish and $L = L^\dagger$ will be self adjoint.

Problem 4

In the coursebook a similar problem is worked out and the solution is given as:

$$\frac{T_0}{\rho_{max}} \left(\frac{\pi}{L} \right)^2 \leq \lambda_1 \leq \frac{T_0}{\rho_{min}} \left(\frac{\pi}{L} \right)^2$$

So now we just need to find ρ_{max} and ρ_{min} . We have:

$$\rho(x) = 1 + \frac{1}{100} \cdot \sin \left(100 \cdot \frac{2nx}{L} \right)$$

Since the sine function oscillates between -1 and 1 we can conclude that:

$$\begin{aligned} \rho_{max} &= 1 + \frac{1}{100} \\ \rho_{min} &= 1 - \frac{1}{100} \end{aligned}$$

This gives us the bounds:

$$\frac{T_0}{1 + \frac{1}{100}} \left(\frac{\pi}{L} \right)^2 \leq \lambda_1 \leq \frac{T_0}{1 - \frac{1}{100}} \left(\frac{\pi}{L} \right)^2$$

Problem 5

We need to use a trial function