

Dynamic Obstacle Mapping for the Visually Impaired Using Sensor Fusion

*

Johann Thor
Kristthorsson
University College London
johann.kristthorsson.15@ucl.ac.uk

Ifeanyi Ndu
University College London
ifeanyi.ndu.15@ucl.ac.uk

Veselin Pavlov
University College London
veselin.pavlov.15@ucl.ac.uk

Shuang Zhang
University College London
shuang.zhang.15@ucl.ac.uk

ABSTRACT

abstract goes here

Keywords

Sensor Fusion, Software Engineering, Visually Impaired, Blind,
Microsoft

1. INTRODUCTION

2. LITERATURE REVIEW

3. CONCLUSIONS

4. REFERENCES

APPENDIX

*A full version of this paper is available as *Author's Guide to Preparing ACM SIG Proceedings Using L^AT_EX₂ ϵ and BibTeX* at www.acm.org/eaddress.htm

Permission to make digital or hard copies of all or part of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. Copyrights for components of this work owned by others than ACM must be honored. Abstracting with credit is permitted. To copy otherwise, or republish, to post on servers or to redistribute to lists, requires prior specific permission and/or a fee. Request permissions from permissions@acm.org.

WOODSTOCK '97 El Paso, Texas USA

© 2016 ACM. ISBN 123-4567-24-567/08/06...\$15.00

DOI: 10.475/123_4