# Searching for Cyclic-Invariant Fast Matrix Multiplication Algorithms

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# Searching for Fast Matrix Multiplication Algorithms

# **Classical Matrix Multiplication:**

$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} = \begin{bmatrix} A_{11}B_{11} + A_{12}B_{21} & A_{11}B_{12} + A_{12}B_{22} \\ A_{21}B_{11} + A_{22}B_{21} & A_{21}B_{12} + A_{22}B_{22} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}$$

$$AB = C, \mathcal{O}(n^3), \text{ for } A, B \in \mathbb{R}^{n \times n}$$

Fast algorithms pre-compute sums and differences of inputs and then use the distributive property of multiplication followed by more sums to carefully cancel terms [1]. Strassen's 1969 algorithm is perhaps the best example, which has a computational cost of  $\mathcal{O}(n^{\log_2 7}) \approx \mathcal{O}(n^{2.81})$ .

# Constructing a Matrix Multiplication Tensor

# Matrix Multiplication as a Tensor Operation:

$$\mathcal{M} imes_1 vec(A) imes_2 vec(B) = \mathcal{M} imes_1 egin{bmatrix} A_{11} \ A_{12} \ A_{21} \ A_{22} \end{bmatrix} imes_2 egin{bmatrix} B_{11} \ B_{12} \ B_{21} \ B_{22} \end{bmatrix} = egin{bmatrix} C_{11} \ C_{21} \ C_{12} \ C_{22} \end{bmatrix} = vec(C^{\mathsf{T}})$$
 $\mathsf{M}_1 = egin{bmatrix} 1 \ 1 \end{bmatrix} \mathsf{M}_2 = egin{bmatrix} 1 \ 1 \end{bmatrix} \mathsf{M}_3 = egin{bmatrix} 1 \ 1 \end{bmatrix} \mathsf{M}_3 = egin{bmatrix} 1 \ 1 \end{bmatrix} \mathsf{M}_4 = egin{bmatrix} 1 \ 1 \end{bmatrix}$ 

For Example:

$$\mathsf{M}_{3} \times_{1} \begin{bmatrix} A_{11} \\ A_{12} \\ A_{21} \\ A_{22} \end{bmatrix} \times_{2} \begin{bmatrix} B_{11} \\ B_{12} \\ B_{21} \\ B_{22} \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} & A_{21} & A_{22} \end{bmatrix} \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} B_{11} \\ B_{12} \\ B_{21} \\ B_{22} \end{bmatrix} = A_{11}B_{12} + A_{12}B_{22} = C_{12}$$

#### Strassen's Algorithm as Factor Matrices of a KTensor:

$$A = \begin{bmatrix} 1 & 0 & 0 & 0 & 1 & 1 & -1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & -1 & 0 & 0 & 0 \end{bmatrix}$$

$$B = \begin{bmatrix} 1 & 1 & -1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & -1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 1 & 1 & -1 & 0 \end{bmatrix}$$

$$C = \begin{bmatrix} 1 & 0 & 1 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 & 0 & 0 \\ 1 & -1 & 0 & 0 & 0 & 1 & 1 \end{bmatrix}$$

$$C_{11} = M1 + M4 - M5 + M7$$

$$C_{12} = M3 + M5$$

$$C_{21} = M2 + M4$$

$$C_{22} = M1 - M2 + M4$$

#### Classic CPDGN Decomposition

$$\mathcal{M} = \sum_{r=1}^R A_r \circ B_r \circ C_r$$

min 
$$f(A, B, C) = \frac{1}{2} ||\mathcal{M} - [A, B, C]||^2$$

# **Gradient:**

$$\nabla \mathbf{f} = \left[ \text{vec} \left( \frac{\partial f}{\partial A} \right)^{\mathsf{T}} \text{vec} \left( \frac{\partial f}{\partial B} \right)^{\mathsf{T}} \text{vec} \left( \frac{\partial f}{\partial C} \right)^{\mathsf{T}} \right]^{\mathsf{T}}$$
where

where  $\frac{\partial f}{\partial A} = -M_{(1)}(C \odot B) + A(C^{\mathsf{T}}C * B^{\mathsf{T}}B)$ 

#### Jacobian:

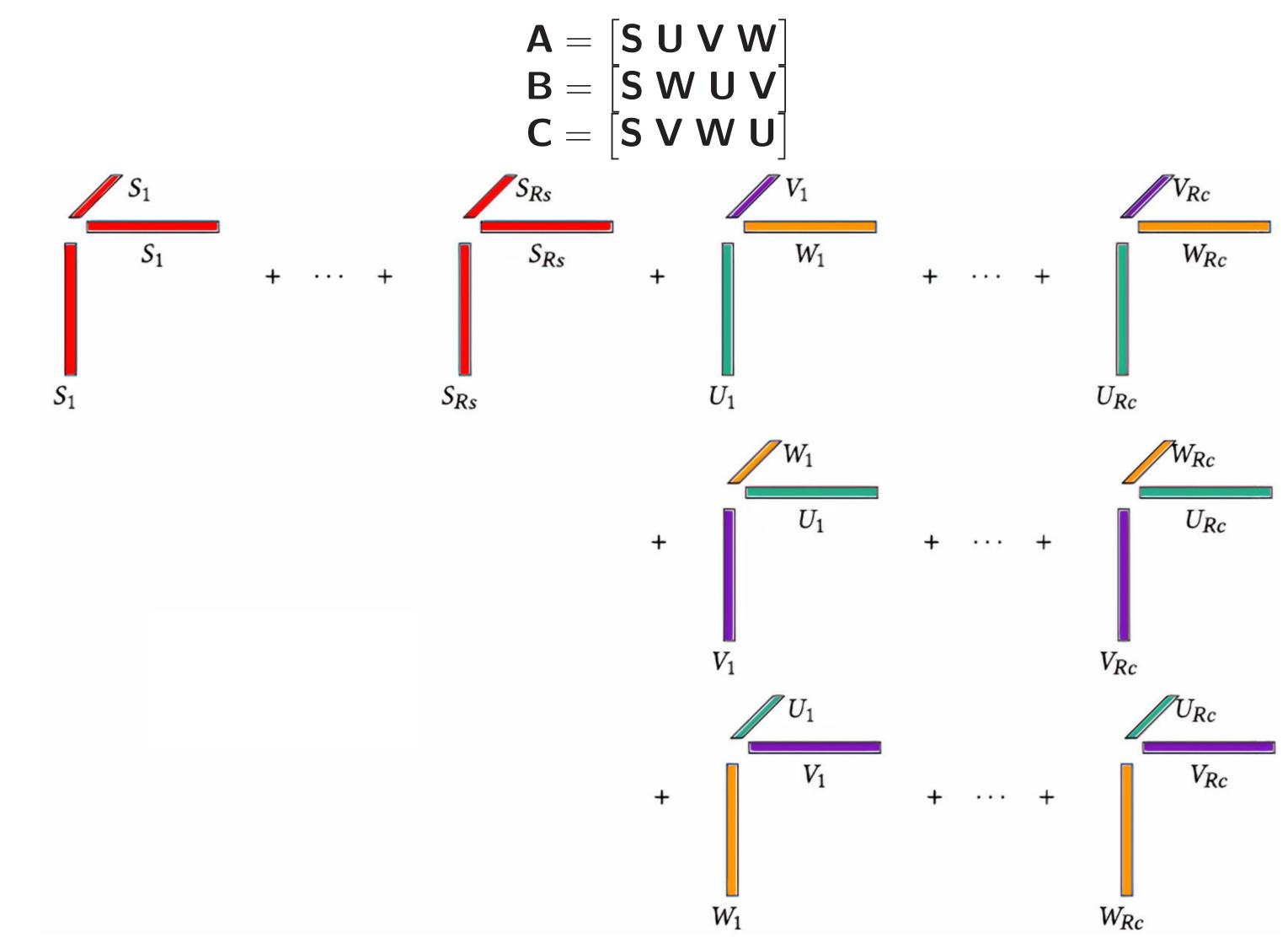
$$\mathbf{J} = [J_A \ J_B \ J_C]$$

where

$$J_A = -(C \odot B) \otimes I_n$$

#### Modifying CPDGN to search for Cyclic Invariance

#### **Substitutions and Derivations:**



$$\mathcal{M} = \sum_{q=1}^{Rs} S_q \circ S_q \circ S_q + \sum_{k=1}^{Rc} (U_k \circ V_k \circ W_k + W_k \circ U_k \circ V_k + V_k \circ W_k \circ U_k)$$

 $min\ f(S, U, V, W) = \frac{1}{2} ||\mathcal{M} - [S, S, S] - [U, V, W] - [W, U, V] - [V, W, U]||^2$ 

#### **Gradient:**

$$\nabla \mathbf{f} = \left[ \operatorname{vec}(\frac{\partial f}{\partial S})^{\mathsf{T}} \operatorname{vec}(\frac{\partial f}{\partial U})^{\mathsf{T}} \operatorname{vec}(\frac{\partial f}{\partial V})^{\mathsf{T}} \operatorname{vec}(\frac{\partial f}{\partial W})^{\mathsf{T}} \right]^{\mathsf{T}}$$

$$\frac{\partial f}{\partial U} = 3\left( S\left( (S^{\mathsf{T}}V) * (S^{\mathsf{T}}W) \right) + U\left( (V^{\mathsf{T}}V) * (W^{\mathsf{T}}W) \right) \right)$$

$$\frac{\partial f}{\partial U} = 3(S((S^{T}V) * (S^{T}W)) + U((V^{T}V) * (W^{T}W)) + V((W^{T}V) * (U^{T}W)) + W((U^{T}V) * (V^{T}W)) - M_{(1)}(V \odot W) - M_{(2)}(W \odot V) - M_{(3)}(V \odot W)$$

Jacobian:

$$\mathbf{J} = \begin{bmatrix} J_s \ J_u \ J_v \ J_w \end{bmatrix} \in \mathbb{R}^{n^3 \times n(R_s + 3R_c)}$$

$$J_u = (V \odot W) \otimes I_n + \Pi_2^\mathsf{T} \cdot (W \odot V) \otimes I_n + \Pi_3^\mathsf{T} \cdot (V \odot W) \otimes I_n$$

$$J^{\mathsf{T}}J \cdot vec(G) = \begin{bmatrix} J_s^{\mathsf{T}}J_s & J_s^{\mathsf{T}}J_u & J_s^{\mathsf{T}}J_v & J_s^{\mathsf{T}}J_w \\ J_u^{\mathsf{T}}J_s & J_u^{\mathsf{T}}J_u & J_u^{\mathsf{T}}J_v & J_u^{\mathsf{T}}J_w \\ J_v^{\mathsf{T}}J_s & J_v^{\mathsf{T}}J_u & J_v^{\mathsf{T}}J_v & J_v^{\mathsf{T}}J_w \\ J_w^{\mathsf{T}}J_s & J_w^{\mathsf{T}}J_u & J_w^{\mathsf{T}}J_v & J_w^{\mathsf{T}}J_w \end{bmatrix} \begin{bmatrix} vec(G_s) \\ vec(G_u) \\ vec(G_v) \\ vec(G_w) \end{bmatrix}$$

$$J_u^\mathsf{T} J_s vec(G_s) = 3vec\Big(G_s(S^\mathsf{T} V) * (S^\mathsf{T} W) + S\big((G_s^\mathsf{T} W) * (S^\mathsf{T} V) + (G_s^\mathsf{T} V) * (S^\mathsf{T} W)\big)\Big)$$

#### **Preliminary Results**

#### Findings so far:

$${\cal M}_2$$
 Rank 7  ${\cal M}_3$  Rank 23  ${\cal M}_4$  Rank 49 Rs=4, Rc=1 Rs=11, Rc=4 Rs=16, Rc=11 Rs=1, Rc=2 Rs=5, Rc=6 Rs=1, Rc=16 Rs=2, Rc=7

Table: Exact Solutions through Cyclic Invariant CPDGN

There is also evidence for numerical solution in Rs=8, Rc=5 for  $\mathcal{M}_3$  Rank 23 as well lower ranks. Additionally, there is evidence for several different Rs's for  $\mathcal{M}_4$  Rank 49.

**Future Work:** Explore the possibility of numeric solutions in places named above, as well as searching for lower ranks in  $\mathcal{M}_4$  and bigger Matrix Multiplication Tensors.

### References

- 1. Rouse, Kathryn Z., and Grey M. Ballard. "On the Efficiency of Algorithms for Tensor Decompositions and Their Applications." Wake Forest University, 2018. Print.
- 2. G. Ballard, C. Ikenmeyer, J. Landsberg and N. Ryder, The geometry of rank decompositions of matrix multiplication II: 3x3 matrices, Journal of Pure and Applied Algebra, Volume 223, Number 8, pp. 3205 3224, 2018.