# ProBot: Egg Painter Mini v1.1

assembly instruction



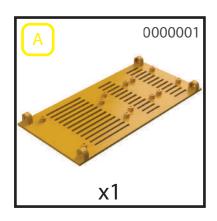
www.probot.xyz

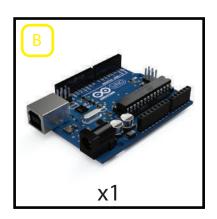




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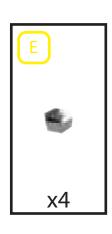
#### Installation of electronics in the case bottom











A Case Bottom

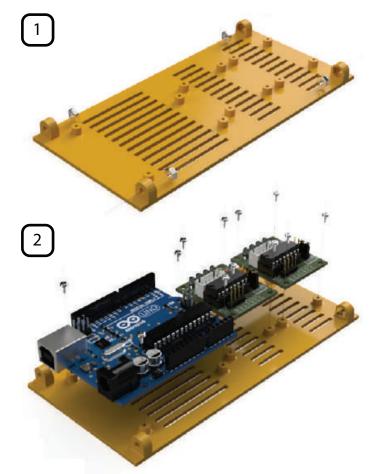
B Arduino UNO

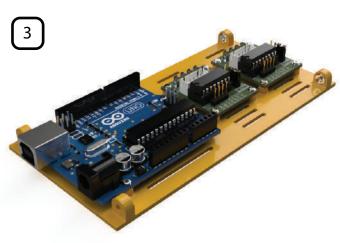
LIL N2003 Ston

ULN2003 Stepper Motor Driver Board

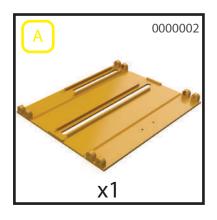
M2x4 Screw

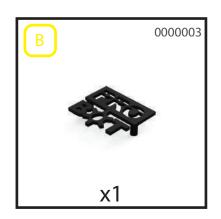
M3 Nut

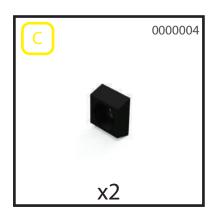


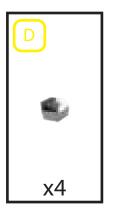


#### Assembling the case top











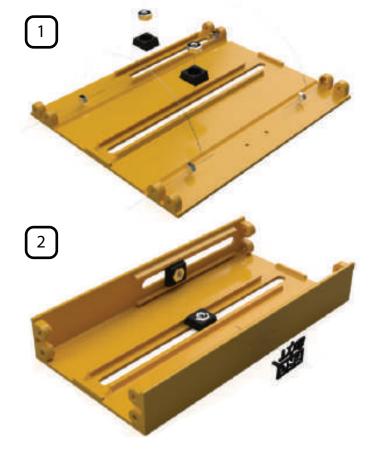
A Case Top

B Logo

M5 Nut Holder

D M3 Nut

E M5 Nut



























- A 15mm Rubber Gasket
- B Axis R
- C 15x20 Spring
- Spring Holder
- E 608zz Bearing

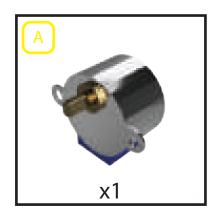
- Axis R Holder
- G Axis R Lock
- H M5 Bolt Holder Bottom
- M5x20 Bolt
- M5 Bolt Holder Top

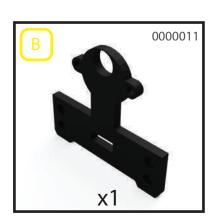




#### 4

#### Assembling the left egg holder

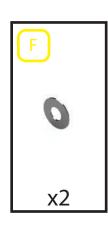














A 28byj-48-12v Stepper Motor

B Axis L Holder

C Axis L

24mm Rubber Gasket

E M3x12 Screw

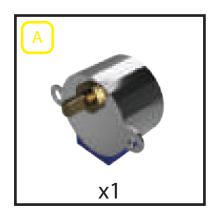
F M3 Washer

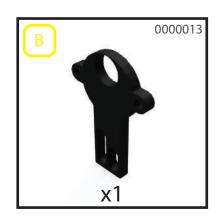
M3 Nut





#### Assembling the hand bottom

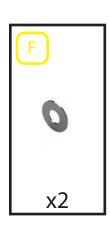


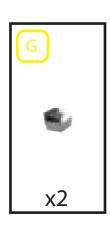












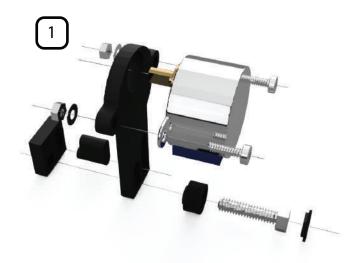






- A 28byj-48-12v Stepper Motor
- B Hand Holder
- C Hand Holder Guide
- D Hand Holder Guide Case

- M3x12 Screw
- F M3 Washer
- G M3 Nut
- H M5 Bolt Holder Bottom







M5x20 Bolt

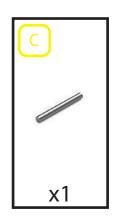


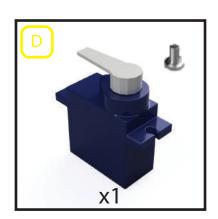
M5 Bolt Holder Top

## Assembling the hand





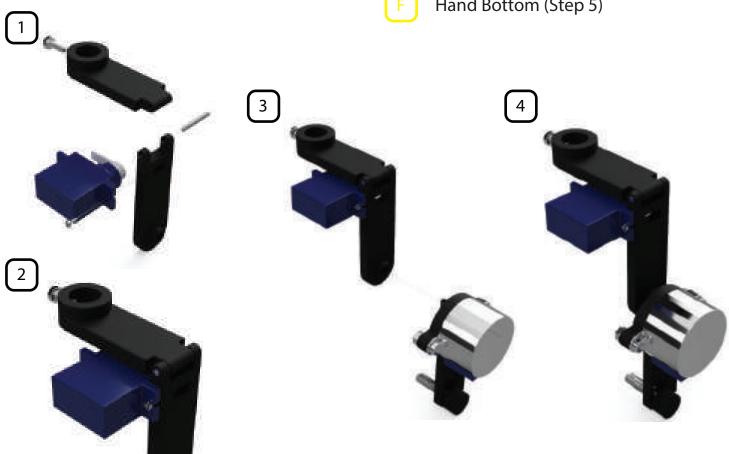




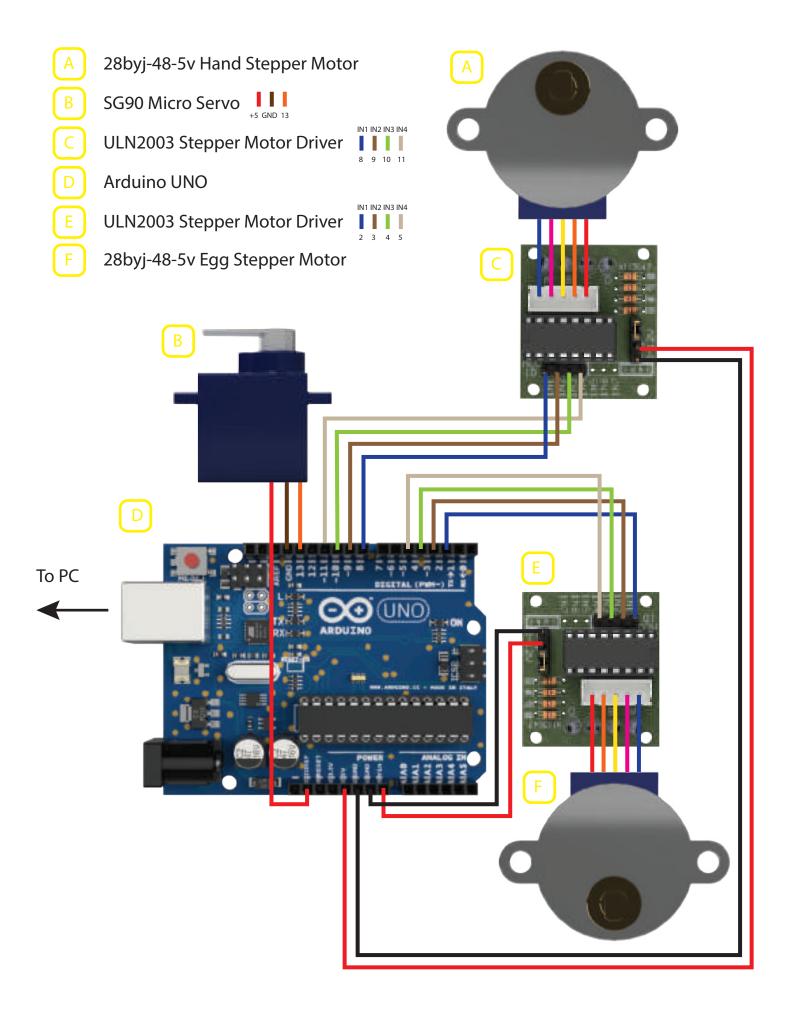




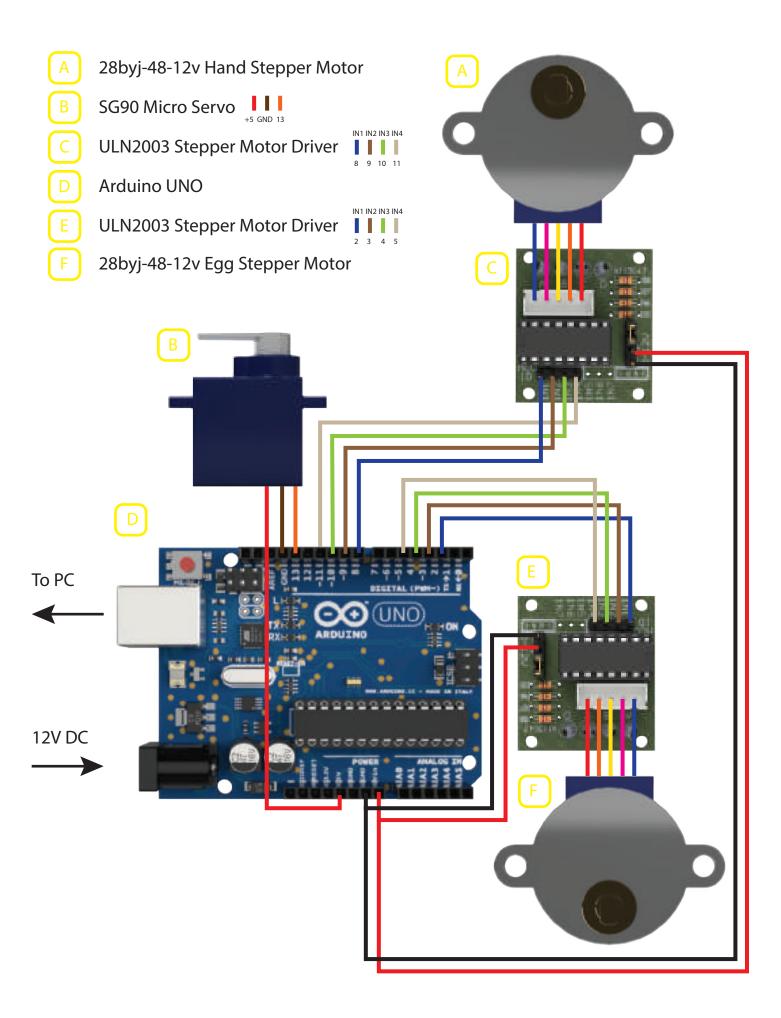
- Hand H
- Hand V
- 2 x 18mm Iron Nail without a hat
- SG90 Micro Servo
- M3x16 Screw
- Hand Bottom (Step 5)



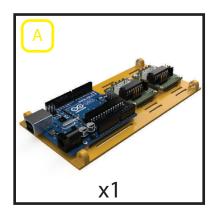
#### Telectronics connection (5v Stepper Motors)

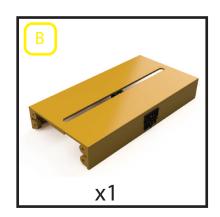


## Electronics connection (12v Stepper Motors)



## Final assembly

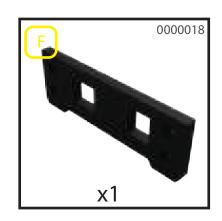
















- A Case Bottom (Step 1)
- B Case Top (Step 2)
- C Left Egg Holder (Step 4)
- D Hand (Step 6)
- E Right Egg Holder (Step 3)

- F Case Right
- G M3x12 Screw
- H M3x16 Screw

