Midterm homework problems

Marco Biroli

November 15, 2020

1 Divergence and Laplacian

1. We have the definition of Christoffel symbols:

$$\Gamma_{ij}^k = \frac{\partial \mathbf{e}_i}{\partial x^j} \cdot \mathbf{e}^k$$

Then we have that:

$$\nabla \cdot \mathbf{V} = \partial_i (V^j \mathbf{e_j})^i = \frac{\partial V^i}{\partial x^i} + \Gamma^i_{ij} V^j = V^i_{,i} + \frac{1}{2} g^{im} (g_{mi,j} + g_{mj,i} - g_{ij,m}) V^j$$

Then:

...

- 2. Since the determinant is an invariant scalar of the matrix then from the relation: $g^{\mu\nu} = g^{-1}c^{\mu\nu}$ we know that c transforms in the exact same way as g does. Since g is a tensor then so is c.
- 3. We have that:

$$g = \sum_{\nu} g_{\mu\nu} c^{\mu\nu} \text{ hence } \frac{\partial g}{\partial g_{\mu\nu}} = \frac{\partial}{\partial g_{\mu\nu}} \sum_{\nu'} g_{\mu\nu'} c^{\mu\nu'} = c^{\mu\nu}$$

4. We have that:

$$g^{\mu\nu}g_{\mu\nu,\gamma} = \partial_{\gamma}\log g$$

We have that:

$$\partial_{\gamma}g(g_{\mu\nu}) = (\partial_{\gamma}g)g_{\mu\nu} + g\partial_{\gamma}g_{\mu\nu}$$

We have that:

$$\partial_{\gamma}g = \frac{\partial}{\partial g_{\mu\nu}} \frac{\partial g_{\mu\nu}}{\partial \gamma} g = \frac{\partial}{\partial g_{\mu\nu}} g_{\mu\nu,\gamma} g = g_{\mu\nu,\gamma} c^{\mu\nu}$$

Hence:

...

5. We start from the end and we differentiate to obtain:

$$\frac{1}{\sqrt{|g|}}\partial_{\gamma}(\sqrt{|g|}V^{\gamma}) = V^{\gamma}_{,\gamma} + \frac{1}{\sqrt{|g|}}V^{\gamma}\frac{1}{2\sqrt{|g|}}\partial_{\gamma}|g| = V^{\mu}_{,\mu} + \frac{1}{2}V^{\gamma}\frac{\partial_{\gamma}|g|}{|g|} = V^{\mu}_{,\mu} + \frac{1}{2}V^{\gamma}\log|g|$$

Now using question 4 we re-obtain the formula of question 1 and this concludes the proof.

6. Using the above formula by replacing: $V_{\gamma}=f_{,\gamma}$ (hence $V^{\gamma}=g^{\gamma\mu}f_{,\mu}$) we obtain:

$$\nabla^2 f = \frac{1}{\sqrt{|g|}} \partial_{\gamma} (\sqrt{|g|} f^{,\gamma}) = \frac{1}{\sqrt{|g|}} \partial_{\gamma} (\sqrt{|g|} g^{\gamma \mu} f_{,\mu})$$

7. In spherical coordinates we have that:

$$[g_{\mu\nu}] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{pmatrix}$$

Then in order to apply the previous formula we need to compute g and $[g^{\mu\nu}]$. We have quite simply:

$$g = r^4 \sin^2 \theta$$
 and $g^{\mu\mu} = \frac{1}{g_{\mu\mu}}$ and $g^{\mu\nu} = 0$ otherwise.

Plugging this in the previous formula we obtain:

$$\nabla^2 f = \frac{1}{r^2 \sin \theta} \partial_\gamma (r^2 \sin \theta g^{\gamma \mu} f_{,\mu}) = \frac{1}{r^2 \sin \theta} \left(\partial_r (r^2 \sin \theta f_{,r}) + \partial_\theta (\sin \theta f_{,\theta}) + \partial_\varphi (\frac{1}{\sin \theta} f_{,\varphi}) \right)$$

Now simplifying the derivatives gives:

$$\nabla^2 f = \frac{1}{r^2 \sin \theta} \left(\sin \theta \partial_r (r^2 f_{,r}) + \partial_\theta (\sin \theta f_{,\theta}) + \frac{1}{\sin \theta} \partial_\varphi f_{,\varphi} \right)$$
$$= \frac{1}{r^2} \partial_r (r^2 f_{,r}) + \frac{1}{r^2 \sin \theta} \partial_\theta (\sin \theta f_{,\theta}) + \frac{1}{r^2 \sin^2 \theta} \partial_\varphi f_{,\varphi}$$

8. Repeating an identical argument but using:

$$[g_{\mu\nu}] = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & r^2 \end{pmatrix}$$

Gives us immediately that:

$$\nabla^2 f = \frac{1}{r} \partial_{\gamma} (rg^{\gamma \mu} f_{,\mu}) = r^{-1} (\partial_z (rf_{,z} + \partial_r (rf_{,r}) + \partial_{\phi} (r^{-1}f_{,\phi}))) = f_{,zz} + r^{-1}f_{,r} + f_{,rr} + r^{-2}f_{,\phi\phi}$$

2 Rotating coordinate frame.

1. We have that:

$$t = t$$
 and $z = z'$ and $r = r'$ and $\phi = \phi' - \Omega t$

Hence we immediately get that:

$$\mathrm{d}t = \mathrm{d}t$$
 and $\mathrm{d}z = \mathrm{d}z'$ and $\mathrm{d}r = \mathrm{d}r'$ and $\mathrm{d}\phi = \mathrm{d}\phi' - t\mathrm{d}\Omega - \Omega\mathrm{d}t = \mathrm{d}\phi' - \Omega\mathrm{d}t$

Where in the last equality we add the assumption that we place ourselves in a rotating frame at constant angular velocity. Now plugging this in the expression for a line element we obtain:

$$ds^{2} = -c^{2}dt^{2} + (dz')^{2} + (dr')^{2} + (r')^{2}(d\phi')^{2} = -c^{2}dt^{2} + dz^{2} + dr^{2} + r^{2}(d\phi + \Omega dt)^{2}$$

$$= -c^{2}dt^{2} + dz^{2} + dr^{2} + r^{2}d\phi^{2} + r^{2}\Omega^{2}dt^{2} + 2r^{2}\Omega d\phi dt$$

$$= (r^{2}\Omega^{2} - c^{2})dt^{2} + dz^{2} + dr^{2} + r^{2}d\phi^{2} + 2r^{2}\Omega dt d\phi$$

Hence we also get:

$$[g_{\mu\nu}] = \begin{pmatrix} (r^2\Omega^2 - c^2) & 0 & 0 & r^2\Omega \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ r^2\Omega & 0 & 0 & r^2 \end{pmatrix}$$

2. The inverse can be immediately obtained through it's cofactor formulation and gives:

$$[g^{\mu\nu}] = \begin{pmatrix} -\frac{1}{c^2} & 0 & 0 & \frac{\Omega}{c^2} \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ \frac{\Omega}{c^2} & 0 & 0 & \frac{c^2 - r^2 \Omega^2}{c^2 r^2} \end{pmatrix} \text{ and } g = -c^2 r^2$$

3. We have that:

$$\begin{pmatrix} t' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \Omega t & \sin \Omega t & 0 \\ 0 & -\sin \Omega t & \cos \Omega t & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix}$$

Now notice that the transition matrix is orthogonal hence we immediately have that:

$$\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos \Omega t & -\sin \Omega t & 0 \\ 0 & \sin \Omega t & \cos \Omega t & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} t' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} t \\ x \\ y \\ z \end{pmatrix}$$

Hence we obtain immediately that:

$$ds^{2} = -c^{2}dt^{2} + dx^{2} + dy^{2} + dz^{2} = -c^{2}dt^{2} + (d(x'\cos\Omega t - y'\sin\Omega t))^{2} + (d(x'\sin\Omega t + y'\cos\Omega t))^{2} + (dz')^{2}$$
$$= -c^{2}dt^{2} + (\cos\Omega t dx' - x'\Omega dt\sin\Omega t - \sin\Omega t dy' - y'\Omega dt\cos\Omega t)^{2} = \dots$$

4. We have that:

$$\begin{pmatrix} -1 + h_{00} & h_{01} & h_{02} & h_{03} \\ h_{10} & 1 + h_{11} & h_{12} & h_{13} \\ h_{20} & h_{21} & 1 + h_{22} & h_{23} \\ h_{30} & h_{31} & h_{32} & 1 + h_{33} \end{pmatrix} = \begin{pmatrix} -(1 - (x^2 + y^2)\Omega^2) & \Omega y & -\Omega x & 0 \\ \Omega y & 1 & 0 & 0 \\ -\Omega x & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Hence we get:

$$[h_{\mu\nu}] = \begin{pmatrix} (x^2 + y^2)\Omega^2 & \Omega y & -\Omega x & 0\\ \Omega y & 0 & 0 & 0\\ -\Omega x & 0 & 0 & 0\\ 0 & 0 & 0 & 0 \end{pmatrix}$$