



# Action-Conditioned 3D Human Motion Synthesis with Transformer VAE

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<https://imagine.enpc.fr/~petrovim/actor/>

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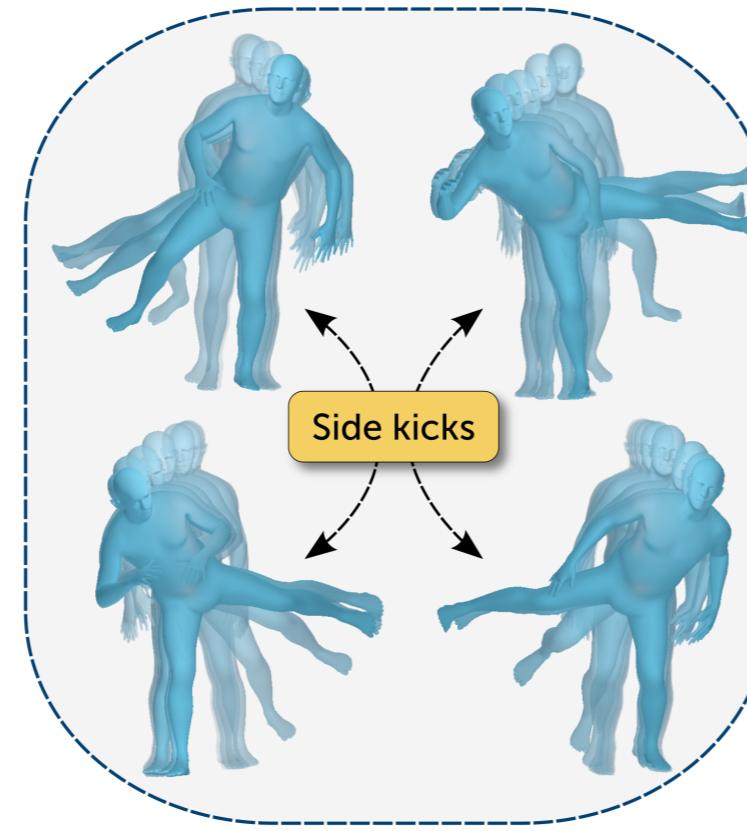
## Introduction

### • Goal & contributions

- Generating synthetic but realistic and diverse human motion sequence given an **action label**
- Learning from noisy 3D body poses estimated from monocular action recognition datasets<sup>3 4 5</sup>

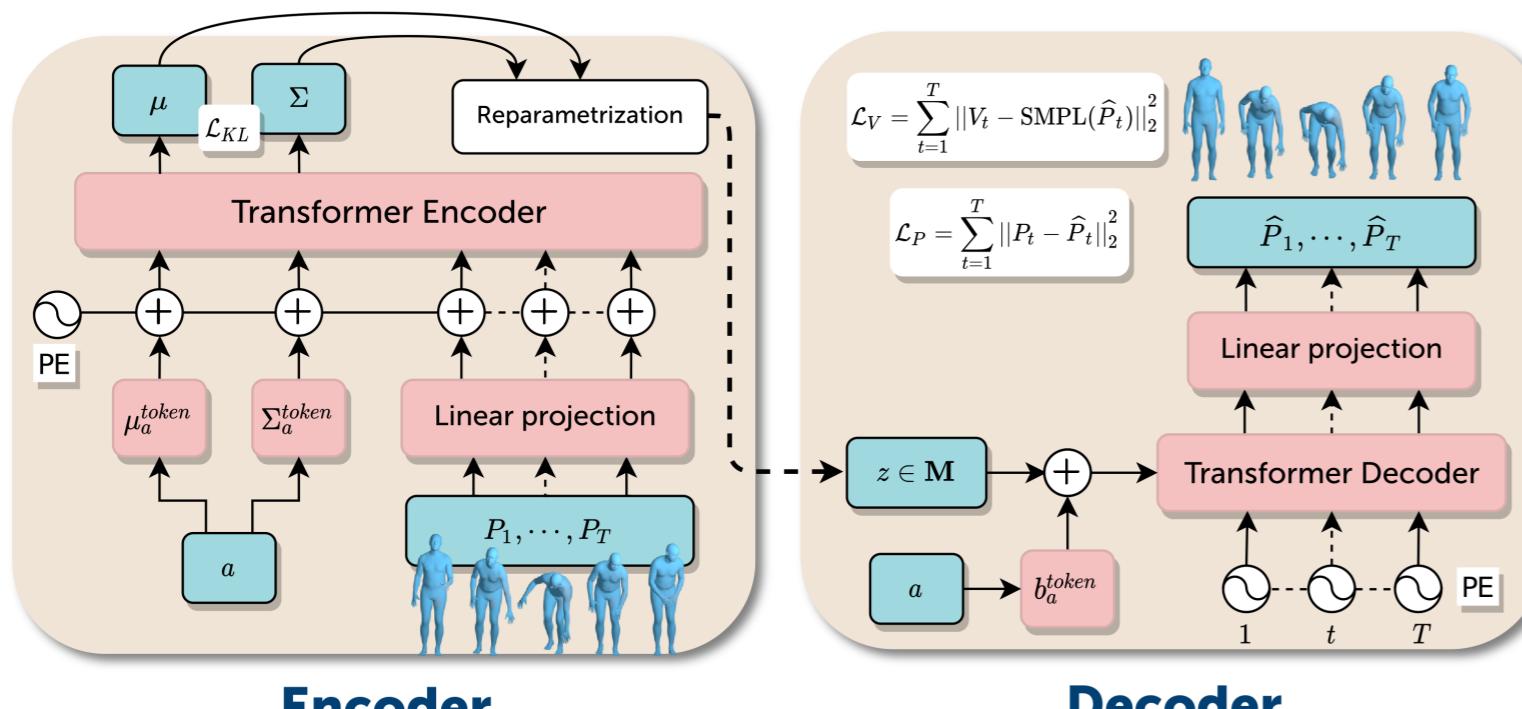
### • Motivations

- Augmenting existing Mocap datasets, which are expensive and limited in size
- Serving as additional training data for motion recognition
- A compact action-aware latent space for human motions



## ACTOR: Action-Conditioned TransfORmer VAE

- Non-autoregressive Transformer architecture
- Learnable tokens  $\mu_a^{token}$  and  $\Sigma_a^{token}$
- Allows to generate variable length sequences with various body shapes
- Sequence-level Variational autoencoder (VAE)
- Loss terms on rotations and vertices (SMPL<sup>1</sup>)



## References

Loper et al. SMPL: A skinned multi-person linear model 2015

Ji et al. A large-scale RGB-D database for arbitrary-view human action recognition 2018

Kocabas et al. VIBE: Video inference for human body pose and shape estimation 2020

Liu et al. NTU RGB+D 120: A large-scale benchmark for 3D human activity understanding 2019

Guo et al. Action2Motion: Conditioned generation of 3D human motions 2020

## Training data

### NTU13<sup>4</sup> (13 actions)

- RGB-D dataset, subset of NTU-120
- SMPL poses estimated with VIBE



Salute

### UESTC<sup>3</sup> (40 actions)

- RGB-D dataset
- SMPL poses estimated with VIBE



Jumping jack

### HumanAct12<sup>5</sup> (12 actions)

- RGB-D + polarization images, subset of PHSPDataset
- SMPL poses estimated



Throw

Throw

## Qualitative results

The generated sequences are realistic, diverse and smooth.



### Action-Conditioned TransfORmer VAE (ACTOR)

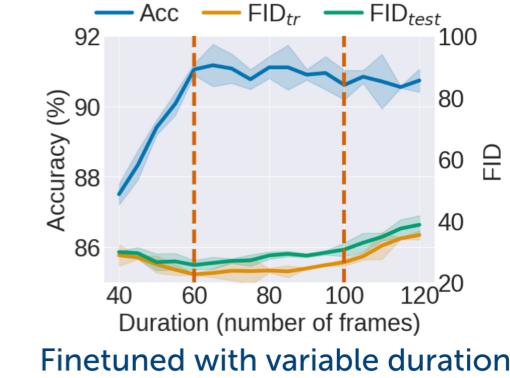
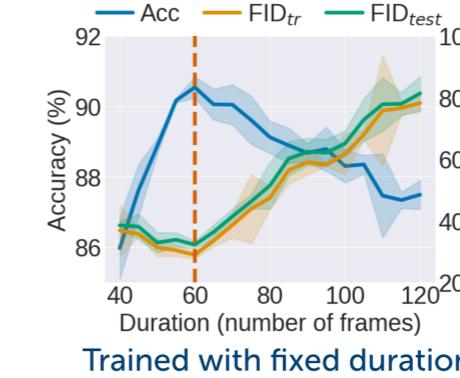
Arm circling Left stretching Pickup Side kick Throwing Rope skipping Sitting down Bending torso Drinking Salute

## Generating variable-length sequences

We evaluate the capability of the models trained on UESTC<sup>3</sup> with

- fixed size (60 frames)
  - variable-size (between 60/100 frames)
- on generating various durations.

The performance is overall improved when the model has previously seen duration variations in training.



## Comparison with previous works

### Metrics

**FID:** Fr  chet Inception Distance  
(Similarity between GT distribution and the generation distribution)

**Acc:** Action recognition accuracy

**Div:** Diversity

**Multimod:** Multimodality  
(Per-action diversity)

Method	FID <sub>tr</sub> ↓	Acc. ↑	NTU-13 <sup>4</sup>		HumanAct12 <sup>5</sup>				
			Div. →	Multimod. →		FID <sub>tr</sub> ↓	Acc. ↑	Div. →	Multimod. →
Real [Action2Motion]	0.03	99.9	7.11	2.19		0.09	99.7	6.85	2.45
Real*	0.02	99.8	7.07	2.25		0.02	99.4	6.86	2.60
CondGRU	28.31	7.80	3.66	3.58		40.61	8.0	2.38	2.34
Two-stage GAN	13.86	20.2	5.33	3.49		10.48	42.1	5.96	2.81
Act-MoCoGAN	2.72	99.7	6.92	0.91		5.61	79.3	6.75	1.06
Action2Motion <sup>6</sup>	0.33	94.9	7.07	2.05		2.46	92.3	7.03	2.87
ACTOR (ours)	<b>0.11</b>	97.1	7.08	2.08		<b>0.12</b>	<b>95.5</b>	6.84	2.53