Mathis Petrovich

PhD Student





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Mathux

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Summary I am an ELLIS PhD student in the IMAGINE computer vision team of École des Ponts ParisTech (ENPC) and in the Perceiving Systems Department of Max Planck Institute for Intelligent Systems (MPI-IS). I am co-advised by Gül Varol (ENPC) and Michael J. Black (MPI).

Research Experience

2020 - present: PhD student, ENPC/MPI, France/Germany

Subject: Controllable human motion synthesis via generative models

Advisors: Gül Varol and Michael J. Black

2019 - 2020 : Research Intern, RIKEN AIP, University of Kyoto, Japan

9 months

Subject: Machine learning and optimal transport

Advisor: Makoto Yamada

2019: Research Intern, DxO Labs, France

6 months

Subject: Semantic segmentation and image matting

Advisor: Wolf Hauser

2018: Research Intern, Carnegie Mellon University, United States

5 months

Subject: Object tracking in videos

Advisor: Martial Hebert

2017: Research Intern, LIF, France

2 months

Subject: Correction strategy for natual language parser

Advisor: Alexis Nasr

Education

2020 - present: ENPC/MPI, PhD student

France/Germany

Paris, France

Controllable human motion synthesis

2016 - 2020: École Normale Supérieure (ENS) Paris-Saclay, MSc

Research engineering school, theoretical and applied computer science

o 2018 - 2019: ENS Paris-Saclay, Master 2

Master MVA: machine learning and computer vision

2017 - 2018: ENS Paris-Saclay, Master 1

Master of research in theoretical computer science (MPRI)

o 2016 - 2017: Diderot University, BSc

Theoretical computer science

2014 - 2016: Lycée Masséna

Nice, France

Preparation course for exams to enter French engineering schools

Academic Activities

Publications

- 2022, 3DV: Nikos Athanasiou, Mathis Petrovich, Michael J. Black, Gül Varol TEACH: Temporal Action Composition for 3D Human.
- o 2022, ECCV (Oral): Mathis Petrovich, Michael J. Black, Gül Varol TEMOS: Generating diverse human motions from textual descriptions.
- 2021, ICCV: Mathis Petrovich, Michael J. Black, Gül Varol ACTOR: Action-Conditioned 3D Human Motion Synthesis with Transformer VAE.

- o 2022, ECML: Mathis Petrovich*, Chao Liang*, Ryoma Sato, Yanbin Liu, Yao-Hung Hubert Tsai, Linchao Zhu, Yi Yang, Ruslan Salakhutdinov, Makoto Yamada FROT: Feature Robust Optimal Transport for High-dimensional Data.
- o 2020, MLCB: Dinesh Singh, Héctor Climente-González, Mathis Petrovich, Eiryo Kawakami, Makoto Yamada

FsNet: Feature Selection Network on High-dimensional Biological Data.

o 2020, arXiv: Mathis Petrovich, Makoto Yamada

FALL: Fast local linear regression with anchor regularization.

o 2020, ICMEW: Abhishek Goswami, Mathis Petrovich, Wolf Hauser, Frederic Dufaux *Tone Mapping Operators: Progressing Towards Semantic-Awareness.*

Reviewing

- Computer Vision and Pattern Recognition (CVPR) 2023
- International Journal of Computer Vision (IJCV) 2022
- o Transactions on Pattern Analysis and Machine Intelligence (TPAMI) 2022
- European Conference on Computer Vision (ECCV) 2022
- Computers & Graphics 2021

Teaching

- o 2021 2022: ENS Paris-Saclay, Teaching Assistant, M2 (Master MVA) Object recognition and computer vision (RecVis)
- o 2020 2021: ENPC, Teacher, L3 (Bachelor) Introduction to programming, in C++ (1PROG)

Presentations

- 10/2022: ECCV, Israel, oral presentation
- o 09/2022: **ECML PKDD**, France, presentation
- o 05/2022: MPI, Germany, PS seminar
- o 04/2022: ENPC Retreat, France, tutorial
- o 03/2022: A3SI, France, PhD students' seminar
- o 10/2021: **ICCV**, Virtual, poster
- o 09/2021: ELLIS Doctoral Symposium, Germany, poster
- o 09/2021: Riken AIP, Virtual, unit seminar
- o 06/2021: MSTIC doctoral school, Virtual, Doctoral day

Open-source repositories

Mathux/TEMOS

5 þ Mathux/ACTOR 242 ★ 34 ₺

Mathux/FALL

Miscellaneous

Research interests

- Computer vision
- Machine learning
- 3D human motion
- Generative models
- Optimal transport
- Local linear regression

References

o Gül Varol: gul.varol@enpc.fr

o Michael J. Black: black@tuebingen.mpg.de

Languages

• **French:** Native speaker

• **English:** C1 Level (IELTS Band 7)

• **German:** Basic Level