Features for The Data Logger (Rev Iteration 4)

- 1. The data logger will communicate to host software via USB as a serial port
- 2. The data logger will communicate to host software via TCP/IP
- 3. The data logger can request a version command to get the current version of firmware
- 4. The data logger will capture data once triggered into an internal log
 - 4.1. 0 to 6 digital inputs simultaneously
 - 4.2. 0 to 6 analog inputs
 - 4.3. 0 to 3 comm inputs
 - 4.3.1. 0-2 are UART channels
 - 4.3.2. 3-4 are I2C slave channels
 - 4.3.3. 5-6 are SPI slave channels
 - 4.3.4. 7 is a CAN channel
- 5. The data logger will support a simple parameter system for configuring the device
 - 5.1. Digital Inputs
 - 5.1.1. Which are Recorded?
 - 5.1.2. Which have Pull-Up Resistors?
 - 5.1.3. Which have Pull-Down Resistors?
 - 5.1.4. Which are Debounced?
 - 5.2. Analog Inputs
 - 5.2.1. Which are Recorded?
 - 5.2.2. Which are Filtered?
 - 5.2.3. Filter Coefficient for Filter Used
 - 5.3. UART Inputs
 - 5.3.1. Which are Recorded?
 - 5.3.2. What Baud Rate for Each?
 - 5.4. Overall Sampling
 - 5.4.1. Number of Samples to Record (1 4096)
 - 5.4.2. Capture Rate (msec. 5 10,000)
 - 5.5. There should be a command to get and set all parameter values
- 6. The data logger will support triggering of the capture system
 - 6.1. When configured, it will be disarmed. An arm command is required to ARM it.
 - 6.2. It will support different mutually-exclusive trigger modes
 - 6.2.1. Now (Command Only)
 - 6.2.2. When a Digital bit or bits have changed
 - 6.2.3. When a Digital bit or bits are specific state(s)
 - 6.2.4. When a Digital bit or bits have gone through a specific sequence of state(s)
 - 6.2.5. When we reach a particular timestamp
 - 6.2.6. When an Analog channel crosses a Threshold Value
 - 6.2.7. When a Comm channel receives a sequence of Bytes

- 7. The data logger will support a command for requesting a result set.
 - 7.1. It will contain all Digital, Analog, or Comm information Captured in that Tick.
 - 7.2. This can be repeated until all data has been read.
 - 7.3. The Results are Encoded using the MessagePack standard.
- 8. The data logger will support host checking or setting of its internal timestamp. The timestamp will be msec since wakeup by default.
- 9. The data logger will use 4 LED's to represent state:
 - 9.1. LED1 Blink when waiting to be Armed. Solid when Armed.
 - 9.2. LED2 Blink when waiting on Trigger. Solid when Triggered.
 - 9.3. LED3 Blink when Capturing. Solid when Capture Complete.
 - 9.4. LED4 Blink when Capture Complete and Data Available
 - 9.5. ERRORS Errors during Capture will blink LED1 and LED4 together
- 10. The data logger will support a command to reset all settings back to defaults
 - 10.1. Effects all Params and the Capture system
- 11. The data logger will use the message protocol matching the framing specified in "Ghost In the Machine"
 - 11.1. We will extend the protocol to support messages longer than 9 bytes by adding letters (A for 10, B for 11, ... Z for 35).
- 12. The data logger will support a filter for analog channels