Lecture hours 9-11

This Tutorial is a review for the midterm.

## **Definitions**

**Definition** (Subspace - Span version). A subspace of  $\mathbb{R}^n$  is a set of vectors in  $\mathbb{R}^n$  that can be described as a span of vectors.

**Definition** (Subspace - Standard version). A subspace of  $\mathbb{R}^n$  subset V of  $\mathbb{R}^n$  with the following properties:

- (i) V is a non-empty set.
- (ii) If  $\vec{u}$  is in V ,  $\vec{u}$  is also in V for any scalar  $k \in \mathbb{R}$  (We say V is closed under scalar multiplication.)
- (iii) If  $\vec{u}$  and  $\vec{w}$  are in V, their sum  $\vec{u} + \vec{w}$  is also in V. (We say V is closed under addition.)

**Definition** (Basis). The vectors  $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_m$  are a basis of a subspace V if they span V and are linearly independent. In other words, a basis of a subspace V is the minimal set of vectors needed to span all of V.

**Definition** (Dimension of a subspace). The dimension of the subspace V is the number of vectors in a basis of V.

**Definition** (Linear Transformations). We define a linear transformation  $T: \mathbb{R}^n \to \mathbb{R}^m$  as a function with two properties:

- 1.  $T(\vec{x} + \vec{y}) = T(\vec{x}) + T(\vec{y})$  for all  $\vec{x}, \vec{y} \in \mathbb{R}^n$  (we say T preserves vector addition)
- 2.  $T(\vec{x}) = cT(\vec{x})$  for all  $\vec{x} \in \mathbb{R}^n$  and  $c \in \mathbb{R}$  (we say T preserves scalar multiplication)

**Problem 21** (Subspace). Suppose that V is the set of all solutions of the homogeneous system

$$\begin{cases} x_1 + 2x_2 - 2x_3 + 2x_4 - x_5 = 0, \\ x_1 + 2x_2 - x_3 + 3x_4 - 2x_5 = 0, \\ 2x_1 + 4x_2 - 7x_3 + x_4 + x_5 = 0. \end{cases}$$
(5.1)

Show that V is a subspace of  $\mathbb{R}^5$ .

**Problem 22** (Basis of a subspace). Let U be a subspace of  $\mathbb{R}^5$  defined by  $U=\{(x_1,x_2,x_3,x_4,x_5)\in\mathbb{R}^5:x_1=3x_2,x_3=7x_4\}$ . Find a basis for U.

**Problem 23** (Basis of a subspace). Suppose  $\{\vec{v}_1, \vec{v}_2, \vec{v}_3, \vec{v}_4\}$  is a basis of  $\mathbb{R}^4$ . Prove that

$$\{\vec{v}_1 + \vec{v}_2, \vec{v}_2 + \vec{v}_3, \vec{v}_3 + \vec{v}_4, \vec{v}_4\}$$

is also a basis of  $\mathbb{R}^4$ .

**Problem 24** (Linear Transformations). Find  $a,b\in\mathbb{R}$  such that  $T:\mathbb{R}^3\to\mathbb{R}^2$  defined by

$$T(x, y, z) = (2x - 4y + 3z + b, 6x + axyz)$$

is a linear transformation.

**Problem 25** (Linear Transformations). Let  $T: \mathbb{R}^n \to \mathbb{R}^n$  be a linear transformation and let  $\vec{v_1}, \dots, \vec{v_k}$  be vectors in  $\mathbb{R}^n$ . True or false? If false, give a counter-example. If true, explain why.

- a) If the vectors  $T(\vec{v_1}), \dots, T(\vec{v_k})$  are linear independent, then  $\vec{v_1}, \dots, \vec{v_k}$  are also linear independent.
- b) If the vectors  $\vec{v_1}, \dots, v_k$  are linear independent, then  $T(\vec{v_1}), \dots, T(\vec{v_k})$  are also linear independent.