

## Lecture hours 3-4

### Definitions

**Definition** (Rank of a matrix). The rank of a matrix is the number of leading ones in the rref of that matrix.

**Definition** (Linear Combination). A linear combination of the vectors  $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n$  is an expression of the form  $c_1\bar{v}_1 + c_2\bar{v}_2 + \dots + c_n\bar{v}_n$  where  $c_1, c_2, \dots, c_n$  are real numbers. So it's just a sum of multiples of the vectors  $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n$ .

**Definition** (Span). The span of the vectors  $\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n$  is all possible linear combinations of these vectors, and it is denoted by  $span(\bar{v}_1, \bar{v}_2, \dots, \bar{v}_n)$ .

**Definition** (Homogeneous System). A homogeneous system of linear equations is a system in which each equation has no constant term.

**Problem 6** (Rank of a coefficient matrix). Suppose you have a system of three linear equations for two unknowns.

- a) What is the largest possible rank the coefficient matrix could have? What is the smallest possible rank?
- b) If the system is consistent, what is the largest possible number of free variables in the solution? What is the smallest possible number?
- c) What are the possibilities for the number of solutions?

Now suppose you have a different system, this time there are three linear equations for four unknowns.

- d) What is the largest possible rank the coefficient matrix could have? What is the smallest possible rank?
- e) If the system is consistent, what is the largest possible number of free variables in the solution? What is the smallest possible number?
- f) What are the possibilities for the number of solutions?

**Problem 7** (Linear systems with parameters). For the linear system

$$\begin{aligned}x - y + 2z &= 4, \\ 3x - 2y + 9z &= 14, \\ 2x - 4y + az &= b,\end{aligned}$$

find real numbers  $a$  and  $b$  such that:

- a) The system has a unique solution.
- b) The system has infinitely many solutions.
- c) The system is inconsistent.

**Problem 8** (Span 1). Is the vector

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

in the span of the vectors

$$\vec{u}_1 = \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \vec{u}_2 = \begin{bmatrix} 3 \\ 5 \end{bmatrix} ?$$

Are there vectors in  $\mathbb{R}^2$  that are not in the span of  $\vec{u}_1$  and  $\vec{u}_2$ ? Explain why or why not.

**Problem 9** (Span 2). Consider the three vectors in  $\mathbb{R}^3$ :

$$\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 1 \\ t \\ 0 \end{bmatrix}, \vec{v}_3 = \begin{bmatrix} -1 \\ -1 \\ s \end{bmatrix},$$

where  $s, t \in \mathbb{R}$ . What are the values of  $s$  and  $t$  so that  $\vec{v}_1, \vec{v}_2$ , and  $\vec{v}_3$  span:

- a) A line.
- b) A plane.
- c) All of  $\mathbb{R}^3$ .

**Problem 10** (Homogeneous systems). Suppose you have a *homogeneous* system of three equations for three unknowns  $x, y$ , and  $z$ . The coefficient matrix of this system has rank 3. What is the solution? Why?

**Problem 11.** (Linear combinations) The vectors  $\vec{x}$  and  $\vec{y}$  are in the span of the vectors  $\vec{w}_1$  and  $\vec{w}_2$ . The vector  $\vec{z}$  is a linear combination of  $\vec{x}$  and  $\vec{y}$ . Is  $\vec{z}$  in the span of  $\vec{w}_1$  and  $\vec{w}_2$ ? Why or why not?