

Concluding the discussion on independent/dependent eigenvectors

It hope it is clear by now when to expect to have independent eigenvectors and when not.

- If no repeated eigenvalues then eigenvectors are certainly going to be independent.
- If eigenvalues are repeated then we might or might not have independent eigenvectors.
 - *Case of independent eigenvectors:*

If the null space of the shifted matrix $(A - \lambda I)$ has a dimension that is equal to the multiplicity of λ then the eigenvectors corresponding to this value of λ are independent.

Example: $A = \begin{pmatrix} 3 & 0 \\ 0 & 3 \end{pmatrix}$

here we have $\lambda=3$ (repeated 2 times) and the dimension of the null space of the shifted matrix $(A-3I)$ is 2. Therefore, we have independent eigenvectors.

Example: $A = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{pmatrix}$

here we have $\lambda=3$ (repeated 2 times) and the dimension of the null space of the shifted matrix $(A-3I)$ is 2. Therefore, we have independent eigenvectors. We also have $\lambda=5$ and this will produce another independent eigenvector.

- *Case of dependent eigenvectors:*

If the null space of the shifted matrix $(A - \lambda I)$ has a dimension that is less than the multiplicity of λ then we have dependent eigenvectors.

Example: $A = \begin{pmatrix} 3 & 1 \\ 0 & 3 \end{pmatrix}$

here we have $\lambda=3$ (repeated 2 times) and the dimension of the null space of the shifted matrix $(A-3I)$ is 1 (which is less than the multiplicity of $\lambda=3$). Therefore, we have dependent eigenvectors (in other words, there is a shortage in eigenvectors).

Diagonalizing a matrix

We now know that we can write $Ax = \lambda x$. This in face is very useful in putting the matrix in simpler form (factorizing). Particularly, if the matrix A has independent eigenvectors then we can sort of foresee a matrix with numbers only (the eigenvalues, λ 's) and another matrix with independent vectors (the eigenvectors, x 's).

We know that $Ax_1 = \lambda_1 x_1$, also $Ax_2 = \lambda_2 x_2$, and so on. Now let's write all x 's together in one matrix and same thing on the right hand side:

$$A \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix} = \begin{bmatrix} \lambda_1 x_1 & \lambda_2 x_2 & \dots & \lambda_n x_n \end{bmatrix}$$

$$= \begin{bmatrix} x_1 & x_2 & \dots & x_n \end{bmatrix} \begin{pmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & \lambda_n \end{pmatrix}$$

diagonal matrix with λ 's in the diagonal

$$AS = S\Lambda$$

$$S^{-1}AS = \Lambda$$

$$A = S\Lambda S^{-1}$$

(diagonalization of A), or
(factorization of A)

Note: this diagonalization/factorization can only be valid if A has independent eigenvectors (due to the inverse operation needed on S).

As a result, consider A^2 , if $Ax = \lambda x$
 $A^2x = \lambda Ax = \lambda^2 x$ (eigenvalues of A^2 are λ^2 , eigenvectors of A^2 are same) #1

$$A = S \Lambda S^{-1}$$

$$A^2 = (S \Lambda S^{-1})(S \Lambda S^{-1})$$

$$= S \Lambda^2 S^{-1} \text{ (so this is similar to \#1 but in a matrix form)}$$

$$\text{Furthermore, } A^k = S \Lambda^k S^{-1}$$

We can see that eigenvalues tell a lot about the power of a matrix.

Theorem: $A^k \rightarrow 0$ as $k \rightarrow \infty$ if all $|\lambda_i| < 1$. If all $|\lambda_i| \geq 1$ then $A^k = S \Lambda^k S^{-1}$ is not going to work. (because we don't know how far k could go)

Notes:

- A pure eigenvalue/eigenvector approach needs independent eigenvectors. If we don't have independent eigenvectors then A can't be diagonalized using this approach.
- If A is diagonal then $A = \Lambda$

Example: $A = \begin{bmatrix} 2 & 1 \\ 0 & 2 \end{bmatrix}$

$$|A - \lambda I| = (2 - \lambda)^2 = 0, \lambda_1 = \lambda_2 = 2, (A - 2I) = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}$$

We have one independent eigenvector $x = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

Therefore, we can't diagonalize A using eigenvalue, eigenvector approach.

Example: $A = \begin{bmatrix} 3 & 2 & 1 \\ 2 & 3 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

finding the eigenvalues using the characteristic equation; $\lambda_1 = 5, \lambda_2 = \lambda_3 = 1$

Take a quick look at the shifted A matrix using the repeated value, $(A - 1I) = \begin{bmatrix} 2 & 2 & 1 \\ 2 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$

you can see that its null space has a dimension of 1 which is less than 2, the multiplicity of $\lambda = 1$. Therefore, once again we can't diagonalize A using eigenvalue, eigenvector approach.

Example: $A = \begin{bmatrix} 3 & 2 & 1 \\ 2 & 3 & 0 \\ 1 & 0 & 1 \end{bmatrix}$

use the characteristic equation to find the eigenvalues: $\lambda_1 = 0.238, \lambda_2 = 1.636, \lambda_3 = 5.124$. since all λ 's are different, then we know for sure that A can be written as $S \Lambda S^{-1}$. All we have to do now is to find the eigenvectors.

Look at this snapshot in octave, I am sure you can understand it by now.

```
>> A = [3 2 1; 2 3 0; 1 0 1]
```

```
>> [S, Lambda]=eig(A) ←
```

```
S =
```

```
-0.55481  0.42186  0.71709
```

```
0.40181 -0.61887  0.67495 ←
```

```
0.72852  0.66260  0.17385
```

```
Lambda =
```

Diagonal Matrix

You can just run `eig(A)` to return the eigenvalues of A . You can also return the arguments of `eig(A)` in two matrices S , Λ

The eigenvectors are here. Corresponding to the λ 's in the order they exist in the matrix Λ . $S = [x_1 \ x_2 \ x_3]$

0.23844	0	0	
0	1.63667	0	← Lambda = λ_1 0 0
0	0	5.12489	0 λ_2 0
			0 0 λ_3

To double check:

```
>> S*Lambda*inv(S)
```

ans =

3.00000	2.00000	1.00000	
2.00000	3.00000	0.00000	← which is obviously A
1.00000	-0.00000	1.00000	