



output: steering angle

**fc4**: fully-connected layer

**fc3**: fully-connected layer

**fc2**: fully-connected layer

**fc1**: fully-connected layer

**conv5**: 64@1x18

convolutional layer

**conv4**: 64@3x20

convolutional layer

**conv3**: 48@5x22

convolutional layer

**conv2**: 36@14x47

convolutional layer

**conv1**: 24@31x98

convolutional layer

input: 200x66 RGB pixels