



output: steering angle

fc3: fully-connected layer

fc2: fully-connected layer

fc1: fully-connected layer

conv5: 64@1x18
convolutional layer

conv4: 64@3x20
convolutional layer

conv3: 48@5x22
convolutional layer

conv2: 36@14x47
convolutional layer

conv1: 24@31x98
convolutional layer

input: 200x66 RGB pixels