



output: steering angle

**fc4:** output: steering angle

**fc3:** fully-connected layer

**fc2:** fully-connected layer

**fc1:** fully-connected layer

**conv5:** 64@1x18

convolutional layer

**conv4:** 64@3x20

convolutional layer

**conv3:** 48@5x22

convolutional layer

**conv2:** 36@14x47

convolutional layer

**conv1:** 24@31x98

convolutional layer

input: 200x66 RGB pixels