

Powerplay

Evolutionary powerplay for Nascence materials

- This example contains a search for classifiers

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Imports

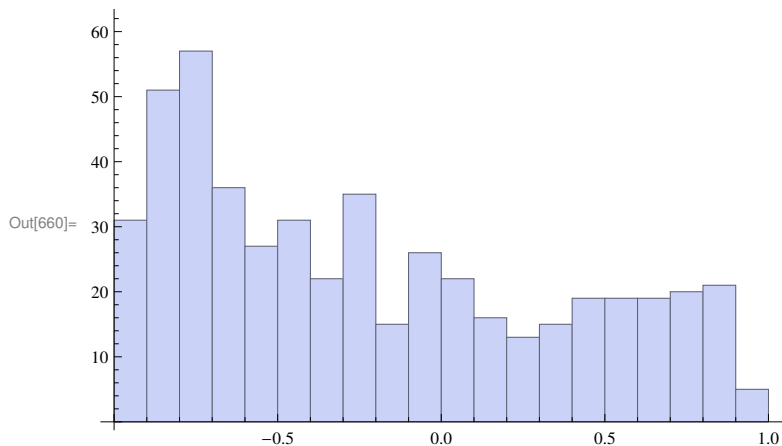
```
In[9]:= Import["../libMLP/bp9.m"]  
  
In[26]:= Import["../libNES/nes10.m"]  
  
In[209]:= Import["../libCoSyNE/libCosyne9.m"]
```

VM

Virtual material is a simple MLP here :

```
In[407]:= actF := 2 / (1 + Exp[-#]) - 1 &  
  
In[410]:= actF = Tanh;  
  
In[656]:= vm = randomNet[{10, 50, 20, 1}];  
  
In[463]:= evalVM[vm_, x_] := Last@fwdPass[vm, x]  
  
In[657]:= res = Sort@Flatten[evalVM[vm, #] & /@RandomReal[{-1, 1}, {500, 10}]];  
          Min@res  
          Max@res  
  
Out[658]= -0.972087  
  
Out[659]= 0.957285
```

```
In[660]:= Histogram[res, 20]
```



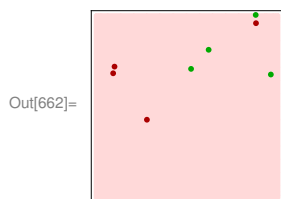
```
In[416]:= evalVM[vm_, config_, input_] := evalVM[vm, Join[config, input]]
```

```
In[643]:= plotBounds[vm_, config_, set_] :=
  With[{points = (First /@ #) & /@ SortBy[GatherBy[set, Last], #][1, 2, 1] &]}, Show[{
    ContourPlot[evalVM[vm, config, {x, y}], {x, -1, 1},
      {y, -1, 1}, Contours -> {0}, ContourShading -> {LightRed, LightGreen},
      ContourStyle -> Directive[Black, Dashed], FrameTicks -> False, ImageSize -> 100],
    ListPlot[points, PlotStyle -> {Darker@Red, Darker@Green}]
  }]]
```

```
In[661]:= evalVM[vm, config, {1, 1}]
```

Out[661]= {-0.601582}

```
In[662]:= plotBounds[vm, config, trainingSet]
```



Powerplay Example - 2-space Classifiers

```
In[8]:= SetDirectory[NotebookDirectory[]]
```

Out[8]= /home/koutnij/Dropbox/math/nascence

In this example a space of classifiers is explored.

```
In[1]:= maxTasks = 1000;
```

```
In[814]:= SeedRandom[30];
taskSet = RandomReal[{-1, 1}, {maxTasks, 2}];
```

```
In[480]:= currentTask = 1;
```

First point in the task set :

```
In[816]:= trainingSet = {{taskSet[[1]], {1}}}
```

```
Out[816]= {{{-0.71618, 0.607906}, {1}}}
```

```
In[698]:= trainingSet =
  {{taskSet[[1]], {1}}, {taskSet[[2]], {-1}}, {taskSet[[3]], {1}}, {taskSet[[4]], {-1}},
  {taskSet[[5]], {1}}, {taskSet[[6]], {-1}}, {taskSet[[7]], {1}}, {taskSet[[8]], {-1}}};
```

XOR :

```
In[682]:= xorSet = MapThread[Append[{#1}, {#2}] &, {Tuples[{-0.9, 0.9}, 2], {-1, 1, 1, -1}}
```

```
Out[682]= {{{-0.9, -0.9}, {-1}}, {{-0.9, 0.9}, {1}}, {{0.9, -0.9}, {1}}, {{0.9, 0.9}, {-1}}}
```

```
In[684]:= trainingSet = xorSet;
```

```
In[789]:= fitFn[g_, set_] := With[
  {diff = Flatten[(evalVM[vm, g, #] & /@ set[[All, 1]]) - set[[All, 2]]}, Total[diff^2]]
```

```
In[790]:= fitFn[g_] := fitFn[g, trainingSet]
```

```
In[788]:= solvesAllTasksQ[g_, set_] :=
  Equal[Sign@Flatten[(evalVM[vm, g, #] & /@ set[[All, 1]])], Flatten@set[[All, 2]]]
```

```
In[706]:= solvesAllTasksQ[g_] := solvesAllTasksQ[g, trainingSet]
```

```
In[791]:= optimize[pop_, fitFn_, trainingSet_, nGen_] :=
  Module[{popTmp}, NestWhile[(popTmp = coSyNEstep[#, fitFn[#, trainingSet] &,
    minimize → True, mutate → 0.8, permuteAll → True, verbose → False, elite → 1];
    Print[{popTmp[[1, 1]], solvesAllTasksQ[popTmp[[1, 2]], trainingSet]}];
    Print@plotBounds[vm, popTmp[[1, 2]], trainingSet]; popTmp) &,
    pop, Not[solvesAllTasksQ[pop[[1, 2]], trainingSet]] &, 1,
    nGen]]
```

```
In[792]:= reevaluate[pop_, fitFn_] := SortBy[{fitFn[#, #] & /@ pop[[All, 2]], First]
```

```
In[793]:= appendTask[set_, config_] := With[{point = taskSet[[Length[set] + 1]]},
  Append[set, {point, -Sign[evalVM[vm, config, point]]}]]
```

```
In[807]:= powerplay[fitFn_, popSize_, nGen_, nTasks_] := Module[{pop, set},
  set = {{taskSet[[1]], {1}}}; (*first task*)
  pop = SortBy[
    newRandomPop[popSize, dim, NormalDistribution[0, 1], fitFn[#, set] &], First];
  Print["Generated population"];
  Nest[
    (Print["# of tasks : " <> ToString@Length[set]];
     pop = optimize[pop, fitFn, set, nGen]; (*optimize*)
     set = appendTask[set, pop[[1, 2]]]; (*add next task*)
     pop = reevaluate[pop, fitFn[#, set] &];
     pop) &
    , pop, nTasks]
]
```

Example Experiment

Powerplay with population size of 8, 30 generations of CoSyNE and 10 consecutive classification tasks to solve :

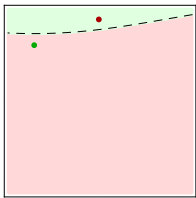
```
In[818]:= powerplay[fitFn, 8, 30, 10]
```

Generated population

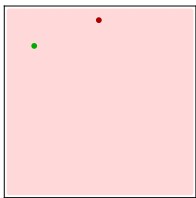
of tasks : 1

of tasks : 2

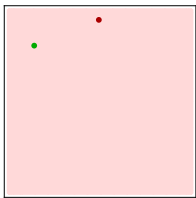
{2.34823, False}



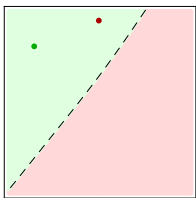
{2.09571, False}



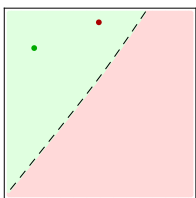
{2.00215, False}



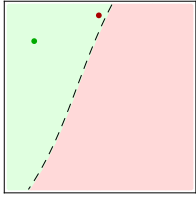
{1.91676, False}



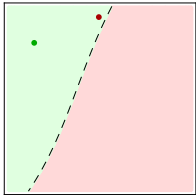
{1.91676, False}



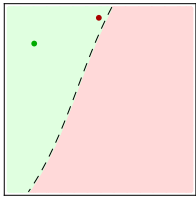
{1.69548, False}



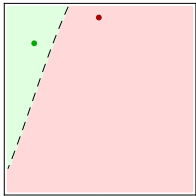
{1.69548, False}



{1.69548, False}

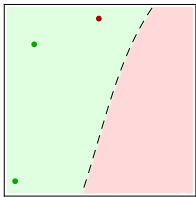


{1.5368, True}

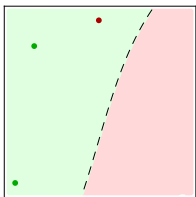


of tasks : 3

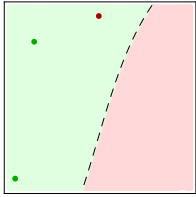
{2.30423, False}



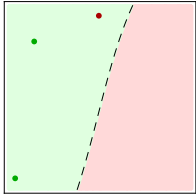
{2.30423, False}



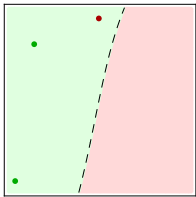
{2.30423, False}



{2.28959, False}



{2.28359, False}



{2.23056, False}

