P452 MIDSEM EXAM

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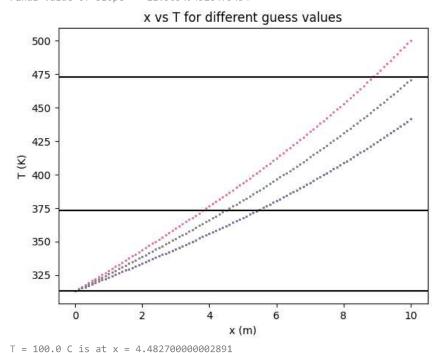
QUESTION 1

```
import mylibrary.nr as nr # Newton raphson library file
import mylibrary.rf as rf # Regula falsi library file
import math
def f(x): # Given function
    return math.log(0.5*x) - math.sin(2.5*x)
def d(x): # Derivative of given function
    return ((1/x) - (2.5*math.cos(2.5*x)))
a = 1.5
b = 2.5
rf.main(f,a,b)
print("")
print("")
nr.main(f,d,2.2)
    REGULA-FALSI
     -----
    Iterations:
    11.801724402995978
    3.331808148122123
    2.6129970798432707
    2.650113267327452
    2.6232515278445754
    2.623140751344172
    No. of Iterations: 6
    The required root is: 2.623140751344172
    NEWTON-RAPHSON
     _____
    Initial guess for newton raphson= 2.2
    Iterations:
    2.8080273965694733
    2.585564275463139
    2.6227428603830814
    2.6231402751560946
    No. of Iterations: 4
    The required root is: 2.6231402751560946
```

QUESTION 2

```
import mylibrary.shoot as shoot # Library file for Shooting method
# RK4 method is used inside shooting method library file
def dzdx(z,y,x):
                    # Differential d2T/dx2
                                               \# z = dT/dx
                                                                # y = T
    return 0.01*(y-293.15)
def dydx(z,y,x):
                    # Differential dT/dx
    return (z)
x0=0.0
y0=40.0+273.15 #In Kelvin scale # Temperature at x=0
xn=10.0
               \# xn = L = 10 m
dx=0.1
a=40.0+273.15 #In Kelvin scale # Temperature at x=0
b=200.0+273.15 #In Kelvin scale # Temperature at x=L
ci=10 # Initial guess value for shooting method
T=100+273.15 #In Kelvin scale # Required Temperature
x_T=shoot.main(x0,y0,xn,dx,a,b,ci,dydx,dzdx,T)
print("T =",T-273.15,"C is at x =",x_T)
# 3 horizontal lines indicate temperatures
# 313.15K , 373.15K , 473.15K
```

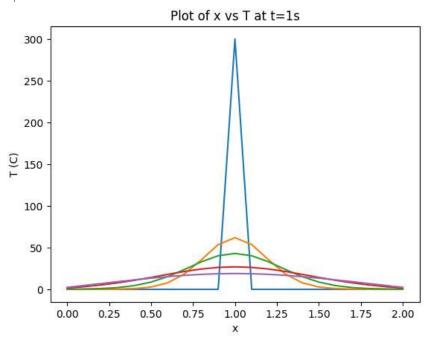
Initial guess slope = 10
Final value of slope = 12.505494528475454



QUESTION 3 using forward explicit method

```
import matplotlib.pyplot as plt
import math
# Solution of 1-D heat equation using forward explicit method
def pde():
   1x=2
   nx=20
   lt=20
   nt=100000
   hx=lx/nx
   ht=lt/nt
   a=ht/(hx*hx)
   V0=[0.0]*(nx+1)
   V1=[0.0]*(nx+1)
   T0=[]
    print('alpha = ',a)
    for i in range (0,nx+1):
       V0[i]=0.0
       T0.append(hx*i)
   V0[int(nx/2)]=300
    plt.plot(T0,V0)
    for i in range (1,1001):
       for j in range (0,nx+1):
           if j==0:
               V1[j]=(1-2*a)*V0[j] + a*V0[j+1]
           elif (j==nx):
               V1[j]=a*V0[j-1] + (1-2*a)*V0[j]
           else:
               V1[j]=a*V0[j-1] + (1-2*a)*V0[j] + a*V0[j+1]
       for k in range (0,nx+1):
           V0[k]=V1[k]
       if i=100 or i=200 or i=500 or i=1000 or i=2000 or i=5000 or i=10000 or i=20000 :
           plt.plot(T0,V0)
    plt.title("Plot of x vs T at t=1s")
   plt.xlabel("x")
    plt.ylabel("T (C)")
pde()
plt.show()
```

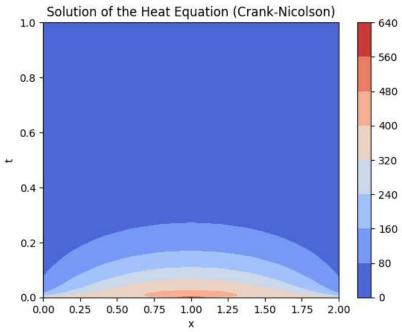
alpha = 0.0199999999999997



Question 3 using Crank Nicolson method (For showing countour surface plot)

```
import mylibrary.crnk as crnk #Importing Crank-Nicolson differential equation solver library file
import mylibrary.gji as gji #Importing Gauss Jordan matrix inverter library file
import mylibrary.mm as mm #Importing Matrix multiplication library file
import numpy as np
L = 2 # Length of the rod
T = 1 # Total time
Nx = 10 # Number of spatial points
Nt = 1000 # Number of time steps
alpha = (T/Nt)/((L/Nx)**2)
print("Alpha = ", alpha)
A=[]
B=[]
for i in range(Nx + 1):
    row=[]
   for j in range(Nx + 1):
       row.append(0.0)
   A.append(row)
for i in range(Nx + 1):
   row=[]
   for j in range(Nx + 1):
       row.append(0.0)
   B.append(row)
A=np.matrix(A)
B=np.matrix(A)
# Initialize solution matrix
for i in range(Nx + 1):
    row=[]
   for j in range(Nt + 1):
       row.append(0.0)
   u.append(row)
u=np.matrix(u)
#Initial condition
for i in range (Nx+1):
   if (i==((Nx/2))):
       u[i,0]=573.15
   else:
       u[i,0]=373.15
# Crank-Nicolson time-stepping module
# The values of matrix A and B are calculated manually
for i in range (Nx+1):
   for j in range (Nx+1):
       if i==j:
           A[i,j]=1+(4*alpha)
           B[i,j]=1-(4*alpha)
```

The Crank-Nicolson parameter(alpha) is selected for which the contour plot is most stable.



QUESTION 4

OUESTION 5

import mylibrary.lud as lud # LU Decomposition linear equation solver library file
path="D:\\P452 codes\\matrix.csv" # File path of the augmented matrix file
lud.main(path)

The input augmented matrix is :

1.0	-1.0	4.0	0.0	2.0	9.0	19.0
0.0	5.0	-2.0	7.0	8.0	4.0	2.0
1.0	0.0	5.0	7.0	3.0	-2.0	13.0
6.0	-1.0	2.0	3.0	0.0	8.0	-7.0
-4.0	2.0	0.0	5.0	-5.0	3.0	-9.0
0.0	7.0	-1.0	5.0	4.0	-2.0	2.0

The solution of the given linear equations using LU decomposition method is :

```
a1 = -1.761817043997862
a2 = 0.8962280338740133
a3 = 4.051931404116158
```