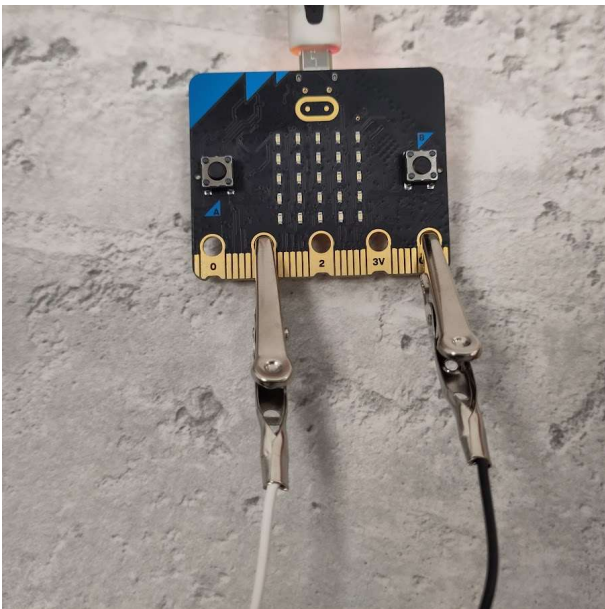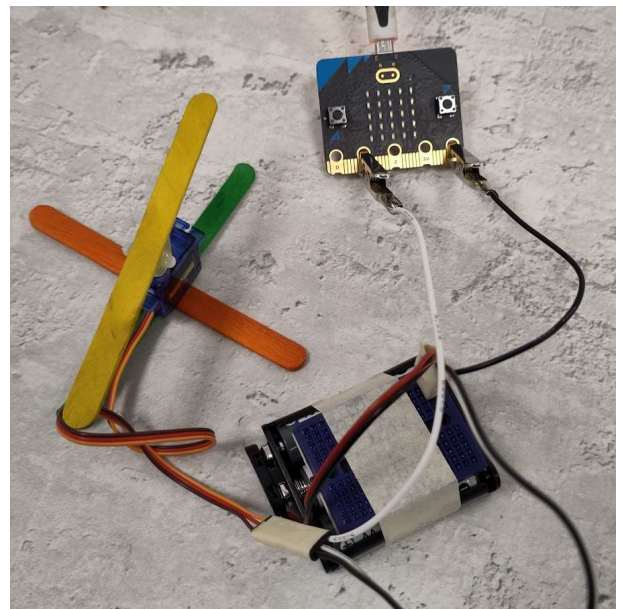1) Find the three loose connectors.

2) Connect the black connector to the battery pack. It only fits one way round.

3) Clip the crocodile clip on the white wire to pin1, and the black wire to pin GND.

4) Test it – does the servo move when you run your code?