

CORTX DTM, roadmap

or Crusoe's personal diary

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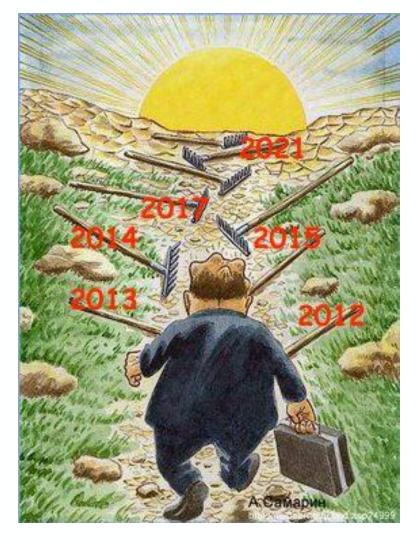
DTM0, Episode I – The Phantom Menace



DTM0, Episode II – Attack of the Clones



DTM0, Episode 100500 – A New Hope



DTM0, Use-case study

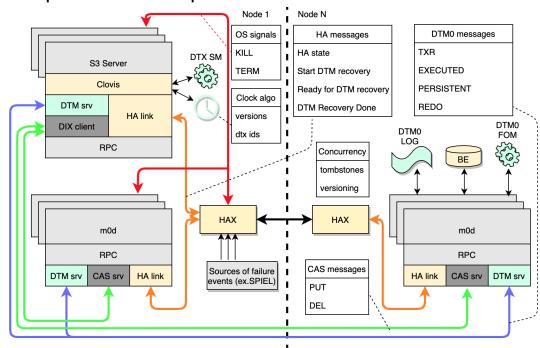
- Happy path
- 1 transient failure of persistent participant and subsequent DTM recovery
- 1 transient failure of persistent participant and subsequent another 1 subsequent failure during recovery
- N transient failures of originators
- N transient failures of originators and k failures of persistent participants
- DTM recovery stop
- DTM during persistent failures
- Client interface w.r.t. distributed transactions
- HA callbacks
- Metadata update
- S3 interraction
- long living tombstones and log records
- m0d recovery with sequential ongoing IO from one client
- m0d recovery without ongoing IO with a single client
- m0d recovery with two clients and ongoing independent IO

- DTM Log truncation
- death of originator
- Dependency tracking
- DTM message delivery during failures
- DTM transaction and record versions
- clock synchronisation
- clock desynchronization
- failure model
- recovery: redo+put/del execution, ordering
- how long with 3-way replication 3 participant can be in transient?
- new originator after fail
- how the states of participants are propagated the dtm logic (confd)
- clean startup
- recovering startup
- Cluster start usecase after shutdown
- Cluster shutdown



DTM0, Significant moving parts of the design (1)

Component landscape



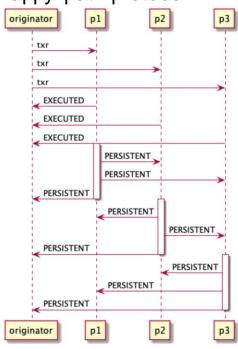
on txr receipt

```
if (!already_executed(txr)) {
    tx_open(be_tx);
    result = execute(be_tx, txr);
    txr.state[self] = EXECUTED;
    log(be_tx, txr);
    tx_close();
}
sender.send(EXECUTED, txr.id,
result);
```

on commit (local transaction containing txr is logged):

```
for (process in txr.participants)
    { /* including self */
        /* send with retries until
    reply or receiver failure. */
    process.send(PERSISTENT,
    txr.id, self);
}
```

Happy path protocol

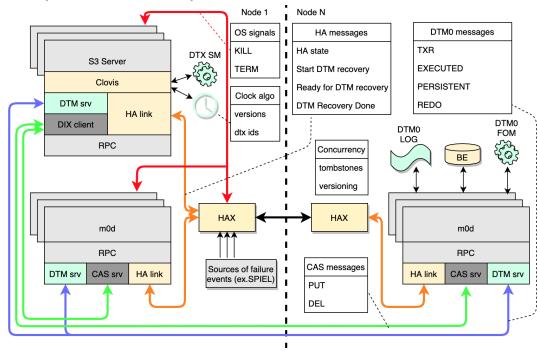


on PERSISTENT(txid, process) receipt:

```
txr = log.find(txid);
tx_open(be_tx);
txr.state[process] = PERSISTENT;
/* +1 to account for txr.state[self] */
if (count(txr.state[], state == PERSISTENT) + 1 > K) {
    wakeup(tx); /* tx is STABLE */
} if (all(txr.state[], state == PERSISTENT ...)) {
    log.prune(txid); /* tx is DONE */
}
tx close(be tx);
Seagate | 2020 |
```

DTM0, Significant moving parts of the design (2)

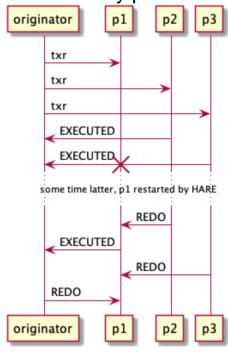
Component landscape



on HA.state(process, ONLINE) receipt:

```
for (txr in log) {
    if (process in txr.participants[] &&
    txr.state[process] < PERSISTENT) {
        process.send(REDO, txr);
    }
}</pre>
```

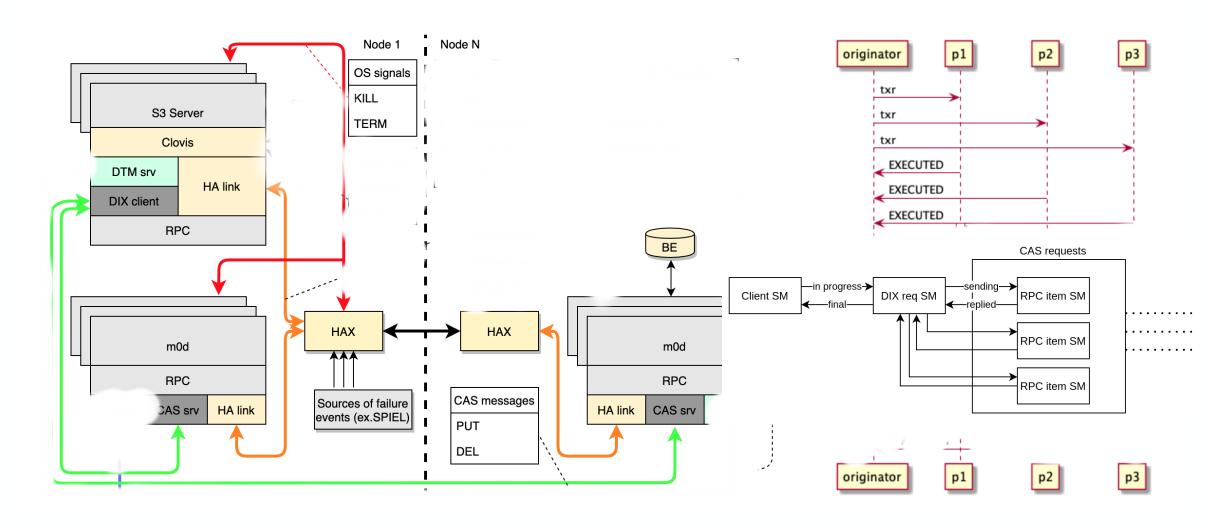
Recovery protocol



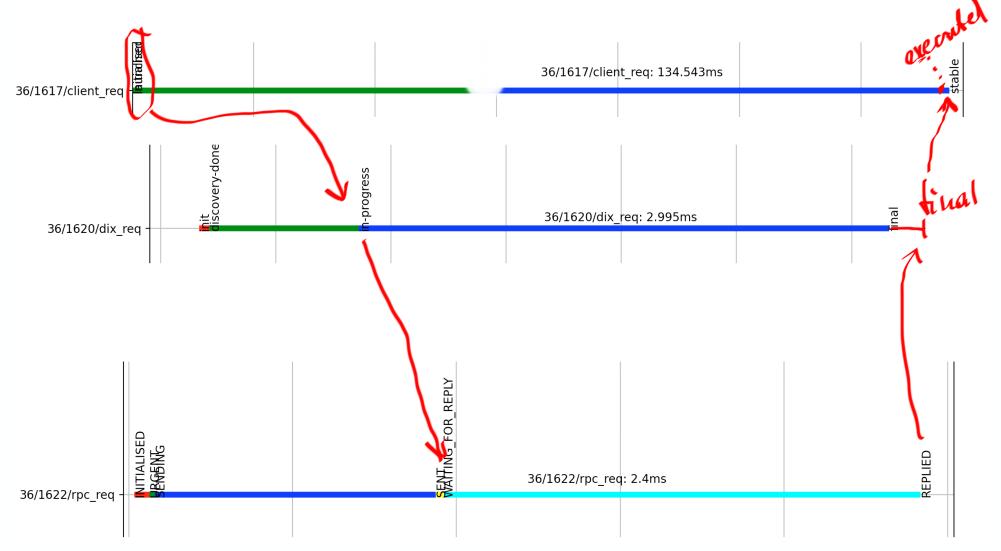
on HA.state(process, FAILED) receipt:

```
for (txr in log) {
    if (all(txr.state[], state == PERSISTENT ||
    process.state == FAILED)) {
        log.prune(txid); /* tx is DONE */
    }
}
```

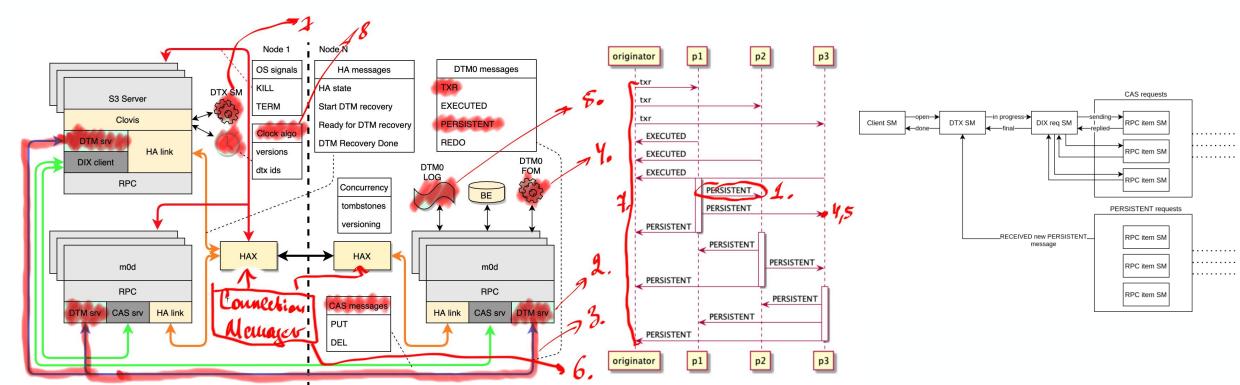
DTM0, What do we have, analysis (1)



DTM0, What do we have, analysis (2)



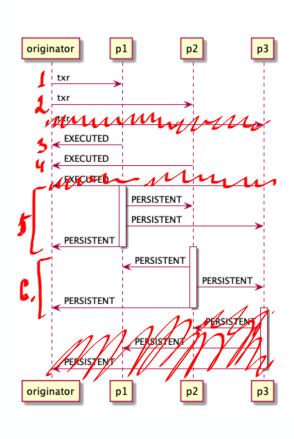
DTM0, What do we NEED to start? Analysis

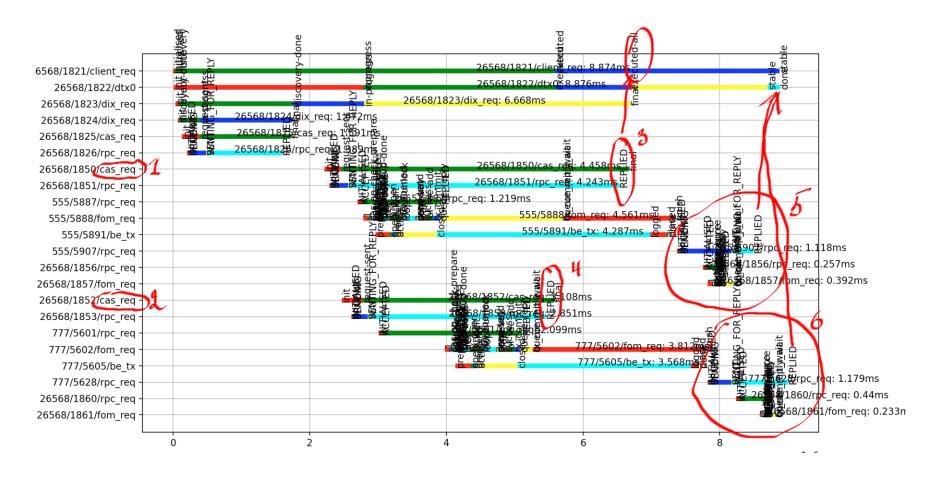


- 1. Introduce PERSISTENT messages
- 2. Implement new DTM service
- 3. Establish connections between DTM services
- 4. Implement PERSISTENT message processing logic
- 5. Introduce DTM log to store information needed for the recovery
- 6. Introduce connection manager kludge to connect DTM services as HARE is not yet fully functional
- 7. Introduce DTX state machine on the client side.
- 8. Introduce clock algorithm



DTM0, Happy path scenarios under the microscope





DTM0, One interesting story

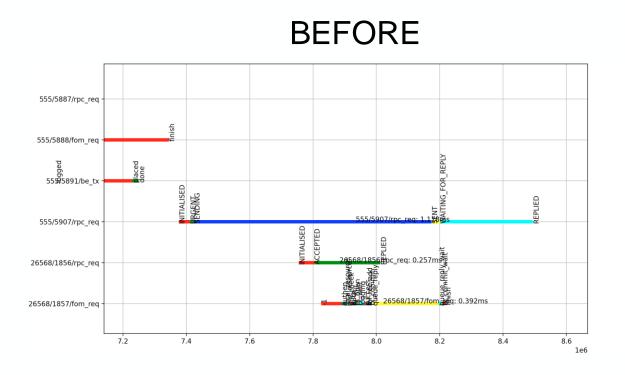
- Start and stop scenario (getting rid of connection manager).
- There is a need to send DTM messages in face of failures to counterparts
- To send a message it's needed to establish connection
- There're two options:
 - #A: to establish/close connections on events like process is ONLINE or OFFLINE;
 - #B: to connect lazily on demand when the connection is really needed.
- Caveeat: if the HARE doesn't support EOS that some of related processes will not receive an appropriate amount of HA.ONLINE, HA.OFFLINE messages therefore will not be connected properly.
- Conclusion: chose option #B, define RPC failure model

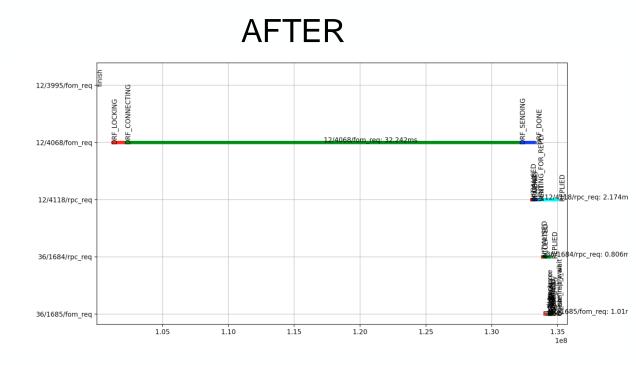


DTM0, RPC failure model

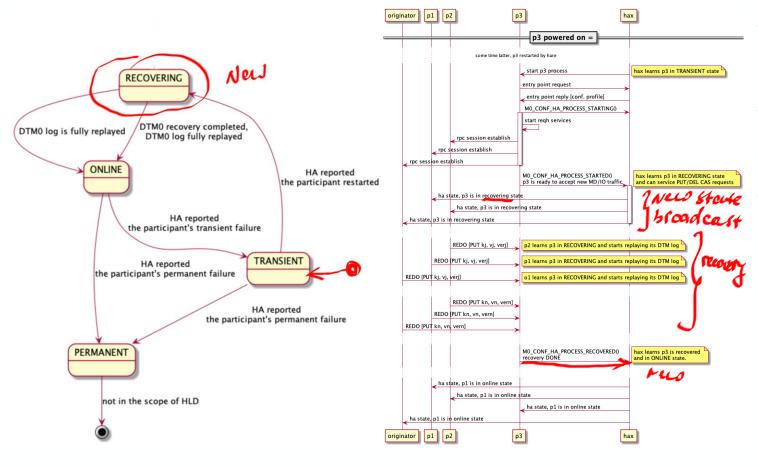
- TL;DL: "timeout is not a failure".
- Assumptions:
 - A message is either request or a reply or one-way.
 - Requests between a pair of processes are delivered in order.
 - Duplicate requests are suppressed (related to DTM0 messages and achieved employing versioning, proper implementation of tx_already_executed() and persistency capturing txr, reply, and other meaningful information).
 - A message can be sent only once.
 - Timeout is not a failure and message send timeouts are infinite.
 - States of connections/sessions/messages are defined w.r.t. HA messages.
 - A message can be transmitted if the connection is ACTIVE.
 - HA never fails (if it fails, the process being under HA track never sees this and should be killed by HA or killed itself due to keep-alive algorithm logic).

DTMO, Finally, how does the PERSISTENT message look like?





DTM0, Recovery: we just started. What was identified?



- Add new RECOVERING state to all motr processes;
- Add new messages in MOTR<->HARE interaction;
- HARE need to suport EOS.

DTM0, Again, where we are?

```
• [DONE] DTMO happy path scenario;
• [DONE] DTM0 start/stop scenarios;
• [IN PROGRESS] DTMO simple recovery scenario;
• [TODO] Basic S3 integration;
• [TODO] DTM0 test;
• [TODO] DTMO basic deployment;
• [TODO] (future) Metadata update;
• [TODO] (future) DTMO for IO.
```

QUESTIONS?