

# Concurrency Objectives

- Mutual exclusion (e.g., A and B don't run at same time)
  - solved with locks
- Ordering (e.g., B runs after A does something)
  - solved with condition variables and semaphores

# 31. Semaphore

- 1. Protect Critical Sections
- 2. Use as Condition Variable
- 3. Solve Bounded Buffer Problem
- 4. Reader-Writer Locks



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## Semaphore: A definition

- An object with an integer value
  - We can manipulate with two routines;
    - sem\_wait() and sem\_post().
  - Initialization
    - Declare a semaphore s and initialize it to the value 1
    - The second argument, 0, indicates that the semaphore is shared between threads in the same process.

```
#include <semaphore.h>
sem_t s;
sem_init(&s, 0, 1); // initialize s to the value 1
```

# Interact with semaphore

- sem\_wait()
  - If the value of the semaphore was one or higher when called sem\_wait(), return right away.
  - It will cause the caller to **suspend execution** waiting for a subsequent post.
  - When negative, the value of the semaphore is equal to the number of waiting threads.

```
int sem_wait(sem_t *s) {
    decrement the value of semaphore s by one
    wait if value of semaphore s is negative
}
```

# Interact with semaphore (Cont.)

- sem\_post()
  - Simply **increments** the value of the semaphore.
  - If there is a thread waiting to be woken, wakes one of them up.

```
int sem_post(sem_t *s) {
   increment the value of semaphore s by one
   if there are one or more threads waiting, wake one
}
```

# Possible Implementation

# Binary Semaphores (Locks)

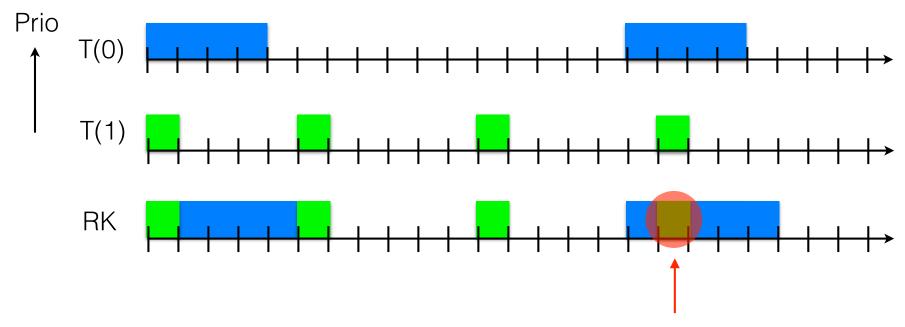
- What should **X** be?
  - The initial value should be 1.

**Thread Trace: Single Thread Using A Semaphore** 

Value of Semaphore	Thread 0
1	
1	call sema_wait()
0	sem_wait() returns
0	(crit sect)
0	call sem_post()
1	sem_post() returns

# Critical Section (buffer) unprotected

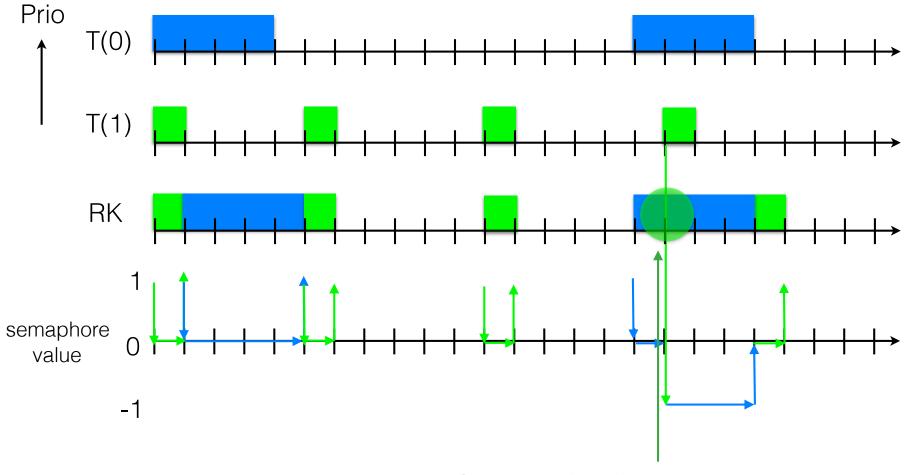
- Two periodic threads: T(0) and T(1)
  - Priority scheduling: T(1) has higher Priority than T(0)
- T(0) and T(1) share a buffer during runtime each instance



Content of buffer in undefined state

# Critical Section (buffer) protected

by semaphore



Content of buffer protected

# Two Threads Using A Semaphore Thread Trace

Value	Thread 0	State	Thread 1	State
1		Running		Ready
1	call sem_wait()	Running		Ready
0	sem_wait() retruns	Running		Ready
0	(crit set: begin)	Running		Ready
0	Interrupt; Switch → T1	Ready		Running
0		Ready	call sem_wait()	Running
-1		Ready	decrement sem	Running
-1		Ready	(sem < 0)→sleep	sleeping
-1		Running	Switch → T0	sleeping
-1	(crit sect: end)	Running		sleeping
-1	call sem_post()	Running		sleeping
0	increment sem	Running		sleeping
0	wake(T1)	Running		Ready
0	sem_post() returns	Running		Ready
0	Interrupt; Switch → T1	Ready		Running
0		Ready	sem_wait() retruns	Running
0		Ready	(crit sect)	Running
0		Ready	call sem_post()	Running
1		Ready	sem_post() returns	Running

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## Semaphores As Condition Variables

```
sem_t s;
void *
child(void *arg) {
    printf("child\n");
    sem post(&s); // signal here:
                  // child is done
    return NULL;
}
 int
main(int argc, char *argv[]) {
    sem_init(&s, 0, X); // what should X be?
    printf("parent: begin\n");
    pthread t c;
    pthread_create(c, NULL, child, NULL);
    sem wait(&s); // wait here for child
    printf("parent: end\n");
    return 0;
```

- What should **X** be?
  - The initial value should be 0.

What we would like to see here is:

```
parent: begin child parent: end
```

# Parent Waiting For Child (Case 1) Thread Trace

The parent call sem\_wait() before the child has called sem\_post().

Val	Parent	State	Child	State
0	Create(Child)	Running	(Child exists; is runnable)	Ready
0	call sem_wait()	Running		Ready
-1	decrement sem	Running		Ready
-1	(sem < 0)→sleep	sleeping		Ready
-1	Switch→Child	sleeping	child runs	Running
-1		sleeping	call sem_post()	Running
0		sleeping	increment sem	Running
0		Ready	wake(Parent)	Running
0		Ready	sem_post() returns	Running
0		Ready	Interrupt; Switch→Parent	Ready
0	sem_wait() returns	Running		Ready

# Parent Waiting For Child (Case 2) Thread Trace

The child runs to completion before the parent call sem\_wait().

Val	Parent	State	Child	State
0	Create(Child)	Running	(Child exists; is runnable)	Ready
0	Interrupt; switch→Child	Ready	child runs	Running
0		Ready	call sem_post()	Running
1		Ready	increment sem	Running
1		Ready	wake(nobody)	Running
1		Ready	sem_post() returns	Running
1	parent runs	Running	Interrupt; Switch→Parent	Ready
1	call sem_wait()	Running		Ready
0	decrement sem	Running		Ready
0	(sem<0)→awake	Running		Ready
0	sem_wait() returns	Running		Ready

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## The Producer/Consumer

#### (Bounded-Buffer) Problem

- Producer: put() interface
  - Wait for a buffer to become **empty** in order to put data into it.
- Consumer: get() interface
  - Wait for a buffer to become **filled** before using it.

```
int buffer[MAX];
int fill = 0;
int use = 0;

void put(int value) {
   buffer[fill] = value;  // line f1
   fill = (fill + 1) % MAX;  // line f2
}

int get() {
   int tmp = buffer[use];  // line g1
   use = (use + 1) % MAX;  // line g2
   return tmp;
}
```

# A Solution: Adding empty/full

(Bounded-Buffer) Problem

```
sem_t empty;
sem_t full;
void *producer(void *arg) {
  int i;
  for (i = 0; i < loops; i++) {
      sem_wait(&empty); // line P1
               // line P2
      put(i);
      sem_post(&full); // line P3
}
void *consumer(void *arg) {
  int i, tmp = 0;
  while (tmp != -1) {
      sem_wait(&full); // line C1
                  // line C2
      tmp = get();
      sem_post(&empty); // line C3
      printf("%d\n", tmp);
```

# Result of First Attempt?

- Imagine that MAX is greater than 1.
  - If there are multiple producers, race condition can happen at line f1.
  - It means that the old data there is overwritten.
- We've forgotten here is mutual exclusion.
  - The filling of a buffer and incrementing of the index into the buffer is a **critical section**.

```
int buffer[MAX];
int fill = 0;
int use = 0;

void put(int value) {
   buffer[fill] = value; // line f1
   fill = (fill + 1) % MAX; // line f2
}
```

# A Solution: Adding Mutual Exclusion

(Bounded-Buffer) Problem

```
sem_t empty;
sem t full;
sem_t mutex;
void *producer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {</pre>
         sem_wait(&mutex); // line p0 (NEW LINE)
        sem_wait(&empty); // line p1
        put(i);
                      // line p2
        sem_post(&full); // line p3
         sem post(&mutex); // line p4 (NEW LINE)
void *consumer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        sem_wait(&mutex);  // line c0 (NEW LINE)
sem_wait(&full);  // line c1
        int tmp = get();  // line c2
sem_post(&empty);  // line c3
        sem_post(&mutex); // line c4 (NEW LINE)
        printf("%d\n", tmp);
```



Imagine two thread: one producer and one consumer....

### No Solution: It's a deadlock

- Imagine two thread: one producer and one consumer.
  - The consumer **acquire** the mutex (line c0).
  - The consumer calls sem\_wait() on the full semaphore (line c1).
  - The consumer is blocked and yield the CPU.
    - The consumer still holds the mutex!
  - The producer **calls** sem\_wait() on the binary mutex semaphore (line p0).
  - The producer is now **stuck** waiting too.
    - a classic deadlock!

A Solution: Adding Mutual Exclusion

(Bounded-Buffer) Problem

```
Correctly!
sem_t empty;
sem t full;
sem_t mutex;
void *producer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        sem wait(&empty); // line p1
        sem wait(&mutex);
                           (MOVED MUTEX HERE...)
        put(i);
                            // line n/
        sem_post(&mutex);
                           (MOVED MUTEX HERE...)
        sem post(&full);
                           // line p3
void *consumer(void *arg) {
    int i;
    for (i = 0; i < loops; i++) {
        sem wait(&full);
                            // line c1
        sem wait(&mutex);
                           (MOVED MUTEX HERE...)
        int tmp = get();
                            // line c2
        sem post(&mutex);
                           (MOVED MUTEX HERE...)
        sem post(&empty);
                           // line c3
}
```

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### Reader-Writer Locks

Imagine a number of concurrent list operations, including inserts and simple lookups.

#### ■ insert:

- Change the state of the list
- A traditional **critical section** makes sense.

#### ■ lookup:

- Simply read the data structure.
- As long as we can guarantee that no insert is on-going, we can allow many lookups to proceed **concurrently**.
- This special type of lock is known as a reader-writer lock.

### Reader-Writer Locks

- Only a single writer can acquire the lock.
- Once a reader has acquired a read lock,
  - More readers will be allowed to acquire the read lock too.
  - A writer will have to wait until all readers are finished.

## Acquire/Release Reader-Writer-Lock

```
void rwlock_acquire_readlock(rwlock_t *rw) {
    sem_wait(&rw \rightarrow lock);
    rw \rightarrow readers ++;
    if (rw \rightarrow readers = 1)
        sem_wait(&rw \rightarrow writelock); // first reader acquires writelock
    sem_post(&rw \rightarrow lock);
}

void rwlock_release_readlock(rwlock_t *rw) {
    sem_wait(&rw \rightarrow lock);
    rw \rightarrow readers --;
    if (rw \rightarrow readers = 0)
        sem_post(&rw \rightarrow writelock); // last reader releases writelock
    sem_post(&rw \rightarrow lock);
}
```

```
void rwlock_acquire_writelock(rwlock_t *rw) {
    sem_wait(&rw→writelock);
}

void rwlock_release_writelock(rwlock_t *rw) {
    sem_post(&rw→writelock);
}
```

# Summary Reader-Writer-Lock

- The reader-writer locks have fairness problem.
  - It would be relatively easy for reader to starve writer.
  - How to prevent more readers from entering the lock once a writer is waiting?

