

- 1. Create
- 2. Wait
- 3. Lock
- 4. CV



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Thread Creation

- How to create and control threads?
- pthread_create(thread, attr, start_routine, arg)
 - thread: Used to interact with this thread.
 - attr: Used to specify any attributes this thread might have.
 - Stack size, Scheduling priority, ...
 - start_routine: the function this thread start running in.
 - arg: the argument to be passed to the function (start routine)
 - a void pointer allows us to pass in any type of argument.

Thread Creation (Cont.)

- If start_routine instead required another type argument, the declaration would look like this:
 - An integer argument:

Return an integer:

Example: Creating a Thread

```
#include <pthread.h>
typedef struct __myarg_t {
    int a;
    int b;
} myarg_t;
void *mythread(void *arg) {
    myarg_t *m = (myarg_t *) arg;
    printf("%d %d\n", m \rightarrow a, m \rightarrow b);
    return NULL;
}
int main(int argc, char *argv[]) {
    pthread_t p;
    int rc;
    myarg_t args;
    args.a = 10;
    args.b = 20;
    rc = pthread create(δp, NULL, mythread, δargs);
```

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Wait for a thread to complete

- pthread_join(thread, value_ptr)
 - thread: Specify which thread to wait for
 - value_ptr: A pointer to the return value
 - Because pthread_join() routine changes the value, you need to pass in a pointer to that value.

```
int pthread_join(pthread_t thread, void **value_ptr);
```

Example: Waiting for Thread Completion

```
#include <stdio.h>
#include <pthread.h>
#include <assert.h>
#include <stdlib.h>
typedef struct __myarg_t {
    int a;
    int b:
} myarg_t;
typedef struct __myret_t {
    int x;
    int y;
} myret t;
void *mythread(void *arg) {
    myarg_t *m = (myarg_t *) arg;
    printf("%d %d\n", m\rightarrowa, m\rightarrowb);
    myret_t *r = malloc(sizeof(myret_t));
    r \rightarrow x = 1;
    r \rightarrow y = 2;
    return (void *) r;
```

Example: Waiting for Thread Completion

Example: Dangerous code

- Be careful with how values are returned from a thread.
 - \blacksquare When the variable \mathbf{r} returns, it is automatically de-allocated.

```
void *mythread(void *arg) {
    myarg_t *m = (myarg_t *) arg;
    printf("%d %d\n", m \rightarrow a, m \rightarrow b);
    myret_t r; // ALLOCATED ON STACK: BAD!
    r.x = 1;
    r.y = 2;
    return (void *) &r;
}
```

Simpler Argument Passing to a Thread

Just passing in a single value

```
pthread_100.c
 void *mythread(void *arg) {
     int m = (int) arg;
     printf("%d\n", m);
     return (void *) (arg + 1);
 int main(int argc, char *argv[]) {
     pthread_t p;
     int m;
     pthread create(&p, NULL, mythread, (void *) 100);
     pthread join(p, (void **) &m);
     printf("returned %d\n", m);
     return 0;
                                                   ./pthread 100
                                                   100
                                                   returned 101
```

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Locks

- Provide mutual exclusion to a critical section
- Interface:
 - pthread_mutex_lock(mutex)
 - pthread_mutex_unlock(mutex)
- No other thread holds the lock
 - the thread will acquire the lock and enter the critical section.
- If another thread hold the lock
 - the thread will not return from the call until it has acquired the lock.

Initialize Locks

- All locks must be properly initialized.
 - One way: using PTHREAD_MUTEX_INITIALIZER
 - The dynamic way: using pthread_mutex_init()

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;

int rc = pthread_mutex_init(&lock, NULL);
assert(rc = 0); // always check success!
```

Example: Locks

```
#include <pthread.h>
int main(int argc, char const *argv[])
{
    int x=0;
    pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;

    pthread_mutex_lock(&lock);
    x = x + 1; // or whatever your critical section is pthread_mutex_unlock(&lock);

    return 0;
}
```

Check errors code when using locks

An example wrapper

```
// Use this to keep your code clean but check for failures
// Only use if exiting program is OK upon failure
void Pthread_mutex_lock(pthread_mutex_t *mutex) {
   int rc = pthread_mutex_lock(mutex);
   assert(rc = 0);
}
```

More calls to lock

- These two calls are also used in **lock acquisition**
 - trylock(): return failure if the lock is already held
 - timelock(): return after a timeout or after acquiring the lock

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Condition variables

- Condition variables are useful when some kind of signaling must take place between threads.
- pthread_cond_wait():
 - Put the calling thread to sleep.
 - Wait for some other thread to signal it.
- pthread_cond_signal():
 - Unblock at least one of the threads that are blocked on the condition variable

Using wait and signal

- A thread calling wait routine:
 - The wait call releases the lock when putting said caller to sleep.
 - Before returning after being woken, the wait call **re-acquire the** lock.

```
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t init = PTHREAD_COND_INITIALIZER;

pthread_mutex_lock(&lock);
while (initialized = 0)
    pthread_cond_wait(&init, &lock);
pthread_mutex_unlock(&lock);
```

A thread calling signal routine:

```
pthread_mutex_lock(&lock);
initialized = 1;
pthread_cond_signal(&init);
pthread_mutex_unlock(&lock);
```

Coming back from wait

- The waiting thread **re-checks** the condition **in a while loop**, instead of a simple if statement.
 - Without rechecking, the waiting thread will continue thinking that the condition has changed **even though it has not**.

```
mutex_lock(δlock);
while (initialized = 0)
   pthread_cond_wait(δinit, δlock);
pthread_mutex_unlock(δlock);
...
```

Don't ever do this

- A thread calling wait routine:
- A thread calling signal routine:
- It performs poorly in many cases.
 - just wastes CPU cycles.
- It is error prone.

```
while(initialized = 0)
; // spin

initialized = 1;
```

Compiling and Running

- To compile them, you must include the header pthread.h
 - Explicitly link with the **pthreads library**, by adding the -pthread flag.

```
prompt> gcc -o main main.c -Wall -pthread
```

For more information,

```
prompt> man -k pthread
```

