ECE 490-ST :: Wireless Computing

- Lesson 19
  - The one where I begin by apologizing


HYPERVENTILATE!

When Modeling

- They will not always match reality.
  - Intrinsic problems in the model
  - Intrinsic problems in the simulation engine
- You need to a) understand the problem b) understand your modeling system and c) understand your measurement system

- Always test your equipment!

ECE 490-ST :: Wireless Computing

- Lesson 19
  - The one where I start by apologizing
  - And then go on to discuss
    Low Power Programming

These wires will program our microcontroller
Remove jumpers and connect as follows:

REMINDER

- ON 490 BOARD, make sure that the power jumper is between pins 2 and 3. This will let the Launchpad power our MCU.

Goals for today

- Make a pulsed beeping program that consumes the lowest power possible

Lesson Plan

- Measure power draw from last lesson's program
- Remove low-power clocking and measure power draw
- Make it so the beep "pulses" Beep … Beep … Beep
  - Measure power draw between two states, and control duty cycle to make effective resistor

These lines control the frequency of the beep

```
//*******************************************************************************
// MSP430F2011 Program
//
// 2.5 kHz Generator
//
//  The program outputs an annoying tone
//
//*******************************************************************************

//Which one to include???
#include  <msp430x20x2.h>
#include  <msp430x20x1.h>



/*unsigned char a;       // 1 byte = 8 bits
unsigned short b;       // 2 bytes = 16 bits
unsigned long c;        // 4 bytes = 32 bits
*/

void main(void)
{
    unsigned short icounter;        // counter for beeper loop

  // Disable Entire System
  //  _BIS_SR(LPM4_bits);

  /* Don't worry about this */
  // Turn DCO to slowest clock (method from Errata sheet)
  DCOCTL = 0x00;
  // Set RSEL bits
  BCSCTL1 &= 0xF0;    // 0b1111_0000 -> Clear out previous setting
  /*BCSCTL1 |= 0x00;    // Place new setting for RSEL : 0b0000_xxxx
  DCOCTL |= 0x00;     // Place new setting for DCO  : 0bxxx0_0000*/
  BCSCTL2 |= DIVM0; //Divide MCLK by 2
  /* Ok, back to worrying */

  WDTCTL = WDTPW + WDTHOLD;                 // Stop watchdog timer

    // Set P1.ALL to be Output ports
  P1OUT = 0x00;
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 while (1){
    // Generate ?? kHz tone -- Tone 1
    for ( icounter = ??? ; icounter >= 0 ; icounter-- ) {
      // Toggle Pin ON
      P1OUT ^= BIT2;
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This for loop controls duration of beep (actually it does nothing right now)

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STEP 1

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This for loop controls duration of beep (actually it does nothing right now)

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Make it so, and measure power

Remove from Launchpad, send 3.3V to the VDD line, measure the current

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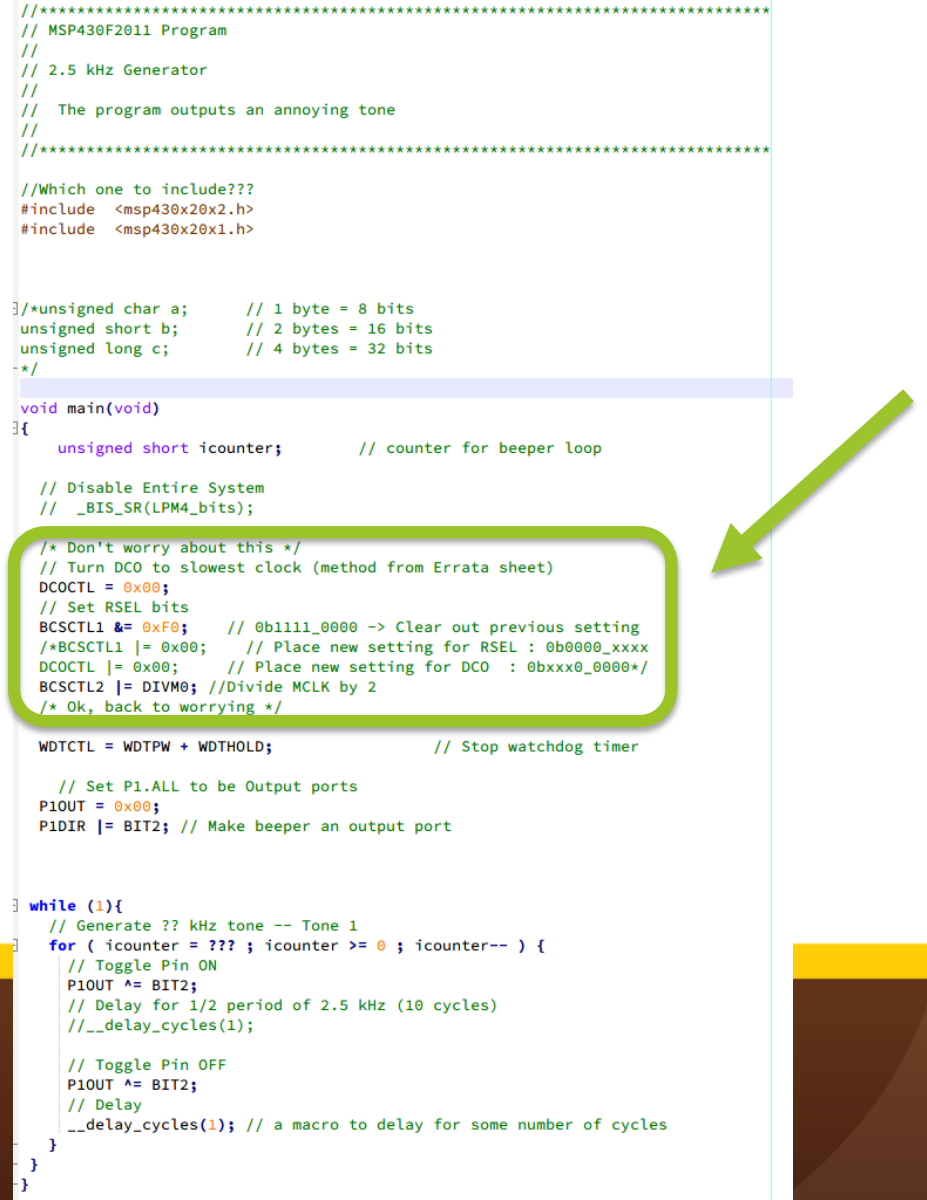
Hmm, what if we delete this nice little section and leave the MSP430 in the default clock mode?



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Hmm, what if we delete this nice little section and leave the MSP430 in the default clock mode?

Now, adjust to keep roughly the same beeping output (beep tone, and beep duty cycle)

And …

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STEP 2

Hmm, what if we delete this nice little section and leave the MSP430 in the default clock mode?

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And …

Measure the power

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Now we basically have 2 states:

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Now we basically have 2 states:

1) Doot – Doot'ing a beep.

2) Waiting until we can Doot –Doot a beep.

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MEEEEEEEEEP

ZZZZZZZZZZ

Now we basically have 2 states:

1) Doot – Doot'ing a beep.

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If we made a program that ONLY **beeped**, how much power does it consume? What is its effective load?

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Now we basically have 2 states:

1) Doot – Doot'ing a beep.

2) Waiting until we can Doot –Doot a beep.

If we made a program that ONLY **waited**, how much power does it consume? What is its effective load?

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If we made a program that spent X time making a BEEP and Y time waiting, we can create it to be an effective load!

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TO DO LIST

(It's an assignment)

1) Count the cycles.
    1) Time on = for loop iterations * (total number of delay cycle)
    2) Time off = for loop iterations * (number of delay cycles)
2) Fill out the sheet that will:
    1) Alter beep code to pulse and measure power
    2) Remove default clock and measure power
    3) Control duty cycle to make an effective 7 ohm resistor

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