

Exceptions and Interrupts

Lecture 3

Exceptions and Interrupts

used by RP2040

- Exceptions
- Interrupts
- Boot

Exceptions

for the ARM Cortex-M0+ processor

Bibliography

for this section

Joseph Yiu, *The Definitive Guide to ARM® Cortex®-M0 and Cortex-M0+ Processors, 2nd Edition*

- Chapter 4 - *Architecture*
 - Section 4.4 - *Stack Memory Operations*
 - Section 4.5 - *Exceptions and Interrupts*
- Chapter 8 - *Exceptions and Interrupts*
 - Section 8.1 - *What are Exceptions and Interrupts*
 - Section 8.2 - *Exception types on Cortex-M0 and Cortex-M0+*

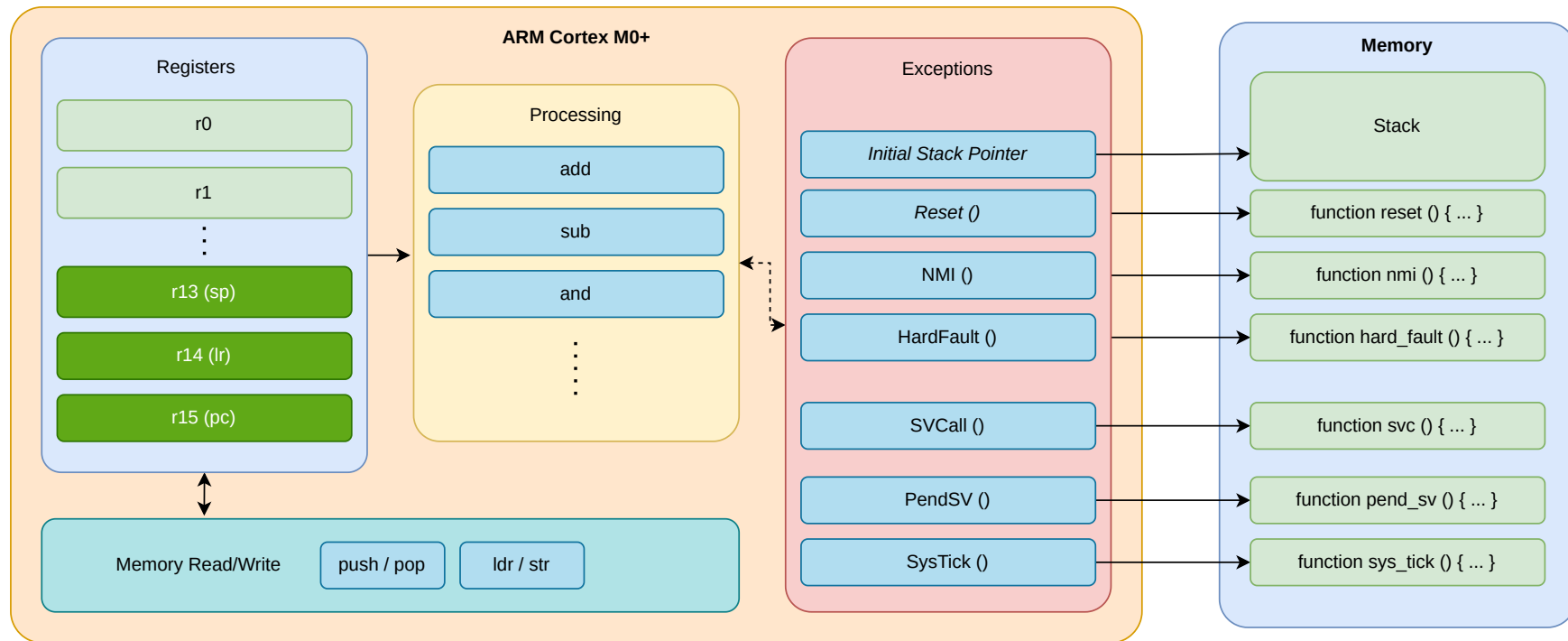
Processor Exceptions

what happens if something does not work as required



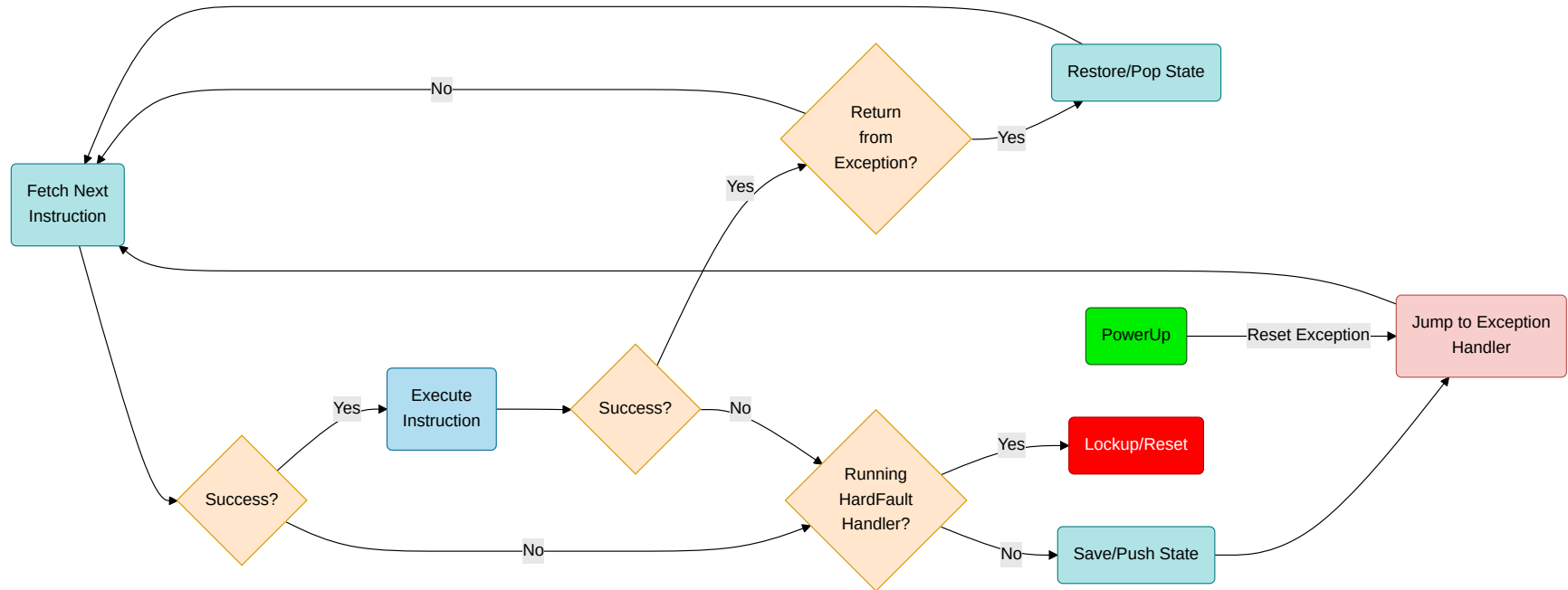
ARM Cortex-M0+ Exceptions

what happens if something does not work as required



Exception (HardFault) Handling

ARM Cortex-M0+ has one **actual exception**, *HardFault*



- the exception table of RP2040 at address 0x1000_0100 (start of the boot area + 4 bytes)
- the processor generates a *Reset* exception when it starts

Interrupts

for ARM Cortex-M0+

Bibliography

for this section

Joseph Yiu, *The Definitive Guide to ARM® Cortex®-M0 and Cortex-M0+ Processors, 2nd Edition*

- Chapter 8 - *Exceptions and Interrupts*
 - Section 8.1 - *What are Exceptions and Interrupts*
 - Section 8.3 - *Brief Overview of the NVIC*
 - Section 8.4 - *Definition of Exception Priority Levels*
 - Section 8.5 - *Vector Table*
 - Section 8.6 - *Exception Sequence Overview*
- Chapter 11 - *Fault Handling*
 - Section 11.1 - *Fault Exception Overview*
 - Section 11.2 - *What Can Cause a Fault*
 - Section 11.7 - *Lockup*

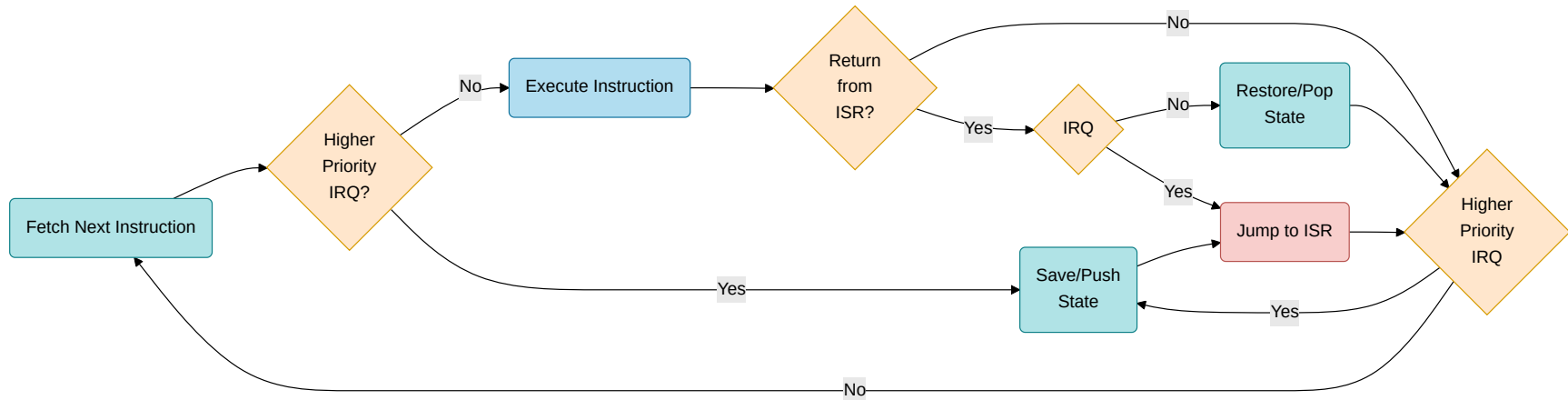
ARM Cortex-M0+ Interrupts

some hardware device notifies the MCU



Interrupt Handling

ARM Cortex-M0+



IRQ Interrupt Request

ISR Interrupt Service Routine

- the interrupt vector (table) of RP2040 starts at address 0x1000_0040 (after the exceptions table with 15 interrupts)
- ARM Cortex-M0+ has a maximum of 32 interrupt requests (IRQs)

Exceptions are Software Interrupt Requests

with a negative IRQ number and a higher priority



Boot

of the RP2040

Bibliography

for this section

Raspberry Pi Ltd, *RP2040 Datasheet*

- Chapter 2 - *System Description*
 - Section 2.7 - *Boot sequence*
 - Section 2.8 - *Bootrom*
 - Subsection 2.8.1 - *Processor Controlled Boot Sequence*

Boot

how the ARM Cortex-M0+ starts



- the *start_address* for RP2040 is 0x1000_0100
- RP2040 has another boot loader that it loads from 0x1000_0000

Boot

The RP2040 boot process



The internal boot loader cannot be overwritten and assures that bricking the device is difficult.

* drawing is not at scale, code and data are significantly greater than the interrupt vector

Set Fault Handler

bare metal, pac or embassy-rs

```
// defined by the cortex-m-rt crate
pub struct ExceptionFrame {
    r0: u32,
    r1: u32,
    r2: u32,
    r3: u32,
    r12: u32,
    lr: u32,
    pc: u32,
    xpsr: u32,
}
```

`HardFault` never returns

```
1  #[exception]
2  unsafe fn HardFault(_frame: &ExceptionFrame) -> ! {
3      panic!("HardFault {:?}", frame);
4  }
```

Set SysTick Handler

bare metal, PAC or embassy-rs

```
1  #[exception]
2  unsafe fn SysTick() {
3      // execute at a fixed interval
4  }
```

Set Interrupt Handlers

bare metal, PAC

embassy-rs already defined the interrupts as it needs them

| IRQ | Interrupt Source | IRQ | Interrupt Source | IRQ | Interrupt Source | IRQ | Interrupt Source | IRQ | Interrupt Source |
|-----|------------------|-----|------------------|-----|------------------|-----|------------------|-----|------------------|
| 0 | TIMER_IRQ_0 | 6 | XIP_IRQ | 12 | DMA_IRQ_1 | 18 | SPI0_IRQ | 24 | I2C1_IRQ |
| 1 | TIMER_IRQ_1 | 7 | PIO0_IRQ_0 | 13 | IO_IRQ_BANK0 | 19 | SPI1_IRQ | 25 | RTC_IRQ |
| 2 | TIMER_IRQ_2 | 8 | PIO0_IRQ_1 | 14 | IO_IRQ_QSPI | 20 | UART0_IRQ | | |
| 3 | TIMER_IRQ_3 | 9 | PIO1_IRQ_0 | 15 | SIO_IRQ_PROC0 | 21 | UART1_IRQ | | |
| 4 | PWM_IRQ_WRAP | 10 | PIO1_IRQ_1 | 16 | SIO_IRQ_PROC1 | 22 | ADC_IRQ_FIFO | | |
| 5 | USBCTRL_IRQ | 11 | DMA_IRQ_0 | 17 | CLOCKS_IRQ | 23 | I2C0_IRQ | | |

```
1  #[interrupt]
2  unsafe fn IO_IRQ_BANK0 {
3      // so some work when a pin interrupt triggers
4  }
```

Use interrupts in embassy-rs

embassy-rs registers interrupt handlers and exposes a high level API

| IRQ | Interrupt Source | IRQ | Interrupt Source | IRQ | Interrupt Source | IRQ | Interrupt Source | IRQ | Interrupt Source |
|-----|------------------|-----|------------------|-----|------------------|-----|------------------|-----|------------------|
| 0 | TIMER_IRQ_0 | 6 | XIP_IRQ | 12 | DMA_IRQ_1 | 18 | SPI0_IRQ | 24 | I2C1_IRQ |
| 1 | TIMER_IRQ_1 | 7 | PI00_IRQ_0 | 13 | IO_IRQ_BANK0 | 19 | SPI1_IRQ | 25 | RTC_IRQ |
| 2 | TIMER_IRQ_2 | 8 | PI00_IRQ_1 | 14 | IO_IRQ_QSPI | 20 | UART0_IRQ | | |
| 3 | TIMER_IRQ_3 | 9 | PI01_IRQ_0 | 15 | SIO_IRQ_PROC0 | 21 | UART1_IRQ | | |
| 4 | PWM_IRQ_WRAP | 10 | PI01_IRQ_1 | 16 | SIO_IRQ_PROC1 | 22 | ADC_IRQ_FIFO | | |
| 5 | USBCTRL_IRQ | 11 | DMA_IRQ_0 | 17 | CLOCKS_IRQ | 23 | I2C0_IRQ | | |

```
1  #[embassy_executor::main]
2  async fn main(_spawner: Spawner) {
3      let p = embassy_rp::init(Default::default());
4      let mut button = Input::new(p.PIN_20, Pull::None);
5
6      loop {
7          info!("Waiting for the button press");
8
9          // waits for interrupt (sent by button)
10         // IO_IRQ_BANK0
11         button.wait_for_high().await;
12
13         info!("Button was pressed");
14     }
15 }
```

Conclusion

we talked about

- Exceptions
- Interrupts
- How the RP2040 boots and loads the software