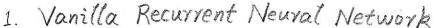
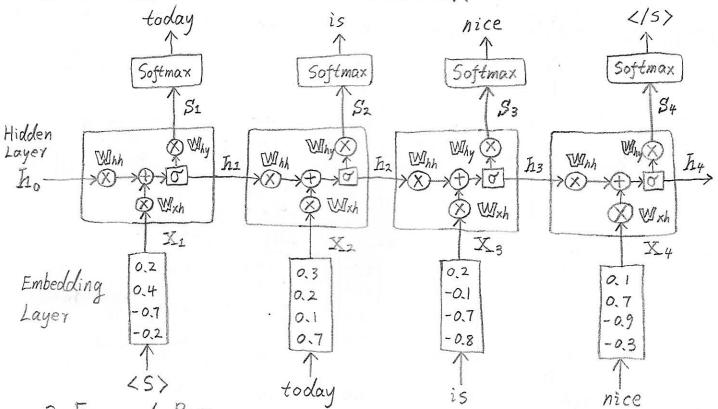
IX RECURRENT NEURAL NETWORK





2. Forward Pass

$$We = \left\{ \text{"hello": } X_1, \text{"what": } X_2, \dots, \text{"zaltan": } X_{v-size} \right\}$$

$$Xt = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{256} \end{bmatrix}$$
, hidden_size = 256

$$ht = \sigma(W_{xh} \cdot X_t + W_{hh} \cdot h_{t-1})$$

256 x 1

$$= \frac{1}{1 + e^{-(Wxh \cdot X_t + Whh \cdot h_{t-1})}}$$

$$St = Why \cdot ht = \begin{bmatrix} S_t(y_n) \\ S_t(y_2) \\ \vdots \\ S_t(y_m) \end{bmatrix}, Y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{bmatrix}$$

When
$$y = y_t$$

$$dS_t(y_t) = \frac{e^{S_t(y_t)}}{\sum_{y' \in Y} e^{S_t(y')}} - 1$$

$$= p_t(y_t) - 1$$

When Y + Yt

$$dS_{t}(y) = \frac{e^{S_{t}(y)}}{\sum_{y' \in Y} e^{S_{t}(y')}} = p_{t}(y)$$

$$dS_{t} = \frac{\partial \cos s_{t}}{\partial S_{t}} = \begin{bmatrix} dS_{t}(y_{1}) \\ dS_{t}(y_{t}) \end{bmatrix} = \begin{bmatrix} p_{t}(y_{1}) \\ \vdots \\ p_{t}(y_{t}) - 1 \\ \vdots \\ p_{t}(y_{m}) \end{bmatrix}$$

$$= \begin{array}{c|c} P_{t}(y_{1}) & O \\ \vdots & \vdots \\ P_{t}(y_{t}) - 1 & = P_{t} - 1y = y_{t} \odot \\ \vdots & \vdots \\ P_{t}(y_{m}) & O \end{array}$$

4. Mathematical Helpers

D. Definition 1

If U and V are vectors, then

$$= \operatorname{diag} (\mathcal{U}) \cdot \mathcal{V}$$

$$= \operatorname{diag} (\begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix}) \cdot \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} u_1 & 0 & \cdots & 0 \\ 0 & u_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & u_n \end{bmatrix} \cdot \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} u_1 v_1 \\ u_2 v_2 \\ \vdots \\ u_n v_n \end{bmatrix}$$

3. Lemma 1

V and h are vectors. W is a matrix. $dv = \frac{\partial \ell}{\partial v}$ is known. $V = f(W \cdot h)$, where f is an element-wise function. Then $dh = \frac{\partial \ell}{\partial h} = W^T \cdot (f'(W \cdot h) \circ dv)$, O and $dv = \frac{\partial \ell}{\partial h} = (f'(W \cdot h) \circ dv)$

 $dW = \frac{\partial \ell}{\partial W} = (f'(W \cdot h) \cdot dV) \cdot h^{T}$ 2

Proof:

$$\begin{split} \mathcal{C} &= g(f(W \cdot h)), \text{ where } V = f(W \cdot h), \ Z = W \cdot h \\ \frac{\partial \ell}{\partial h} &= \frac{\partial f}{\partial h} \cdot \frac{\partial \ell}{\partial f} \ (\text{ Chain rule, D.l., Plo4, Denominator-Layout}) \\ &= (\frac{\partial Z}{\partial h} \cdot \frac{\partial f}{\partial Z}) \cdot \frac{\partial \ell}{\partial f} \ (\text{ Chain rule, again}) \end{split}$$

$$= \frac{\partial Wh}{\partial h} \cdot \frac{\partial f(z)}{\partial z} \cdot \frac{\partial \ell}{\partial v}$$

$$=\frac{\partial Wh}{\partial h}$$
. $\operatorname{diag}(f'(Z))\cdot dV$

$$= \frac{\partial W \cdot h}{\partial h} \cdot (f'(Wh) \circ dV) \quad (Definition 1)$$

$$W = \begin{bmatrix} w_{11} & w_{12} & \cdots & w_{1n} \\ w_{21} & w_{22} & \cdots & w_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ w_{m1} & w_{m2} & \cdots & w_{mn} \end{bmatrix}, \quad \tilde{h} = \begin{bmatrix} h_1 \\ h_2 \\ \vdots \\ h_n \end{bmatrix}, \quad \text{then}$$

$$Wh = \begin{bmatrix} w_{11}h_{1} + w_{12}h_{2} + \cdots + w_{1n}h_{n} \\ w_{21}h_{1} + w_{22}h_{2} + \cdots + w_{2n}h_{n} \end{bmatrix} = \begin{bmatrix} Z_{1} \\ Z_{2} \\ \vdots \\ Z_{m1}h_{1} + w_{m2}h_{2} + \cdots + w_{mn}h_{n} \end{bmatrix}$$

$$\frac{\partial Wh}{\partial h} = \begin{bmatrix} \frac{\partial Z_1}{\partial h_1} & \frac{\partial Z_2}{\partial h_1} & \cdots & \frac{\partial Z_m}{\partial h_1} \\ \frac{\partial Z_1}{\partial h_2} & \frac{\partial Z_2}{\partial h_2} & \cdots & \frac{\partial Z_m}{\partial h_2} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial Z_1}{\partial h_n} & \frac{\partial Z_2}{\partial h_n} & \cdots & \frac{\partial Z_m}{\partial h_n} \end{bmatrix} = \begin{bmatrix} w_{11} & w_{21} & \cdots & w_{m1} \\ w_{12} & w_{22} & \cdots & w_{m2} \\ \vdots & \vdots & \ddots & \vdots \\ w_{1n} & w_{2n} & \cdots & w_{mn} \end{bmatrix} = w^T$$

(Denominator - Layout)

$$dh = \frac{\partial \ell}{\partial h} = W^{T} \cdot (f'(Wh) \circ dV)$$

Let
$$W_1 = \begin{bmatrix} w_{11} \\ w_{12} \\ \vdots \\ w_{1n} \end{bmatrix}$$
, $W_2 = \begin{bmatrix} w_{21} \\ w_{22} \\ \vdots \\ w_{2n} \end{bmatrix}$, ..., $W_m = \begin{bmatrix} w_{m1} \\ w_{m2} \\ \vdots \\ w_{mn} \end{bmatrix}$, then

$$t = g(f(Wh))$$

$$= g(f(\begin{bmatrix} w_1^T \\ w_2^T \\ \vdots \\ w_m^T \end{bmatrix} \cdot h))$$

$$= g(f(\begin{bmatrix} w_{i}^{T} \cdot h \\ w_{i}^{T} \cdot h \\ \vdots \\ w_{m}^{T} \cdot h \end{bmatrix}) = g(f(\begin{bmatrix} z_{i} \\ z_{2} \\ \vdots \\ z_{m} \end{bmatrix}))$$

$$= g(\begin{bmatrix} f(z_{1}) \\ f(z_{2}) \\ \vdots \\ f(z_{m}) \end{bmatrix}) = g(\begin{bmatrix} v_{i} \\ v_{2} \\ \vdots \\ v_{m} \end{bmatrix})$$

$$\frac{\partial \ell}{\partial w_{i}} = \frac{\partial v_{i}}{\partial w_{i}} \cdot \frac{\partial \ell}{\partial v_{i}} \quad (Chain Rule)$$

$$= (\frac{\partial z_{i}}{\partial w_{i}} \cdot \frac{\partial v_{i}}{\partial z_{i}}) \cdot \frac{\partial \ell}{\partial v_{i}} \quad (Chain Rule)$$

$$= \frac{\partial w_{i}^{T} h}{\partial w_{i}} \cdot f'(z_{i}) \cdot dv_{i}$$

$$= \frac{\partial (w_{i1}h_{i} + w_{i2}h_{2} + \dots + w_{in}h_{n})}{\partial w_{in}} \cdot f'(z_{i}) \cdot dv_{i}$$

$$= \frac{\partial (w_{i1}h_{i} + w_{i2}h_{2} + \dots + w_{in}h_{n})}{\partial w_{in}} \cdot f'(z_{i}) \cdot dv_{i}$$

$$= \begin{vmatrix} h_1 \\ h_2 \\ \vdots \\ h_n \end{vmatrix} \cdot f'(Zi) \cdot dVi$$

$$dw_i^T = \frac{\partial^\ell}{\partial w_i^T} = f'(z_i) \cdot dv_i \cdot L^T$$

$$dW = \frac{\partial \ell}{\partial W} = \begin{bmatrix} \frac{\partial \ell}{\partial W_1^T} \\ \frac{\partial \ell}{\partial W_2^T} \\ \vdots \\ \frac{\partial \ell}{\partial W_m^T} \end{bmatrix} = \begin{bmatrix} f'(z_1) \cdot dv_1 \\ f'(z_2) \cdot dv_2 \\ \vdots \\ f'(z_m) \cdot dv_m \end{bmatrix} \cdot h^T$$

$$= (f'(W \cdot h) \circ dv) \cdot h^{\mathsf{T}} \qquad \Box$$

3. Corollary 1

If
$$V = f(Wh) = Wh$$
, then

$$dh = W^T \cdot dv$$
 3

$$dW = dv \cdot h^T \oplus$$

$$f(Wh) = f(\begin{bmatrix} Z_1 \\ Z_2 \\ \vdots \\ Z_m \end{bmatrix}) = \begin{bmatrix} f(Z_1) \\ f(Z_2) \\ \vdots \\ f(Z_m) \end{bmatrix} = \begin{bmatrix} Z_1 \\ Z_2 \\ \vdots \\ Z_m \end{bmatrix}$$

$$f'(Wh) = f'(\begin{bmatrix} z_1 \\ z_2 \\ \vdots \\ z_m \end{bmatrix}) = \begin{bmatrix} f'(z_1) \\ f'(z_2) \\ \vdots \\ f'(z_m) \end{bmatrix} = \begin{bmatrix} \frac{dz_1}{dz_1} \\ \frac{dz_2}{dz_2} \\ \vdots \\ \frac{dz_m}{dz_m} \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$$

$$U$$
, V and S are vectors. $S = U \circ f(V)$.

$$du = \frac{\partial \ell}{\partial u}, dv = \frac{\partial \ell}{\partial v}, dS = \frac{\partial \ell}{\partial S}, \text{ then}$$

$$du = f(v) \circ ds$$
 5

Proof:

$$t = g(S) = g(\mathcal{U} \circ f(V))$$

$$du = \frac{\partial S}{\partial u} \cdot \frac{\partial \ell}{\partial S} = f(v) \cdot dS$$

$$dv = \frac{\partial S}{\partial V} \cdot \frac{\partial \ell}{\partial S} = \frac{\partial f}{\partial V} \cdot \frac{\partial S}{\partial f} \cdot \frac{\partial \ell}{\partial S} = f'(V) \circ \mathcal{U} \circ dS \quad \Box$$

5) Corollary 2

If
$$f(v) = v$$
, then

5. Backward Pass - Continue

Since
$$St = Why \cdot ht$$
,

$$dht = W_{hy}^{\mathsf{T}} \cdot dS_t \quad (by 3). \quad 9$$

$$dW_{hy} = dS_t \cdot h_t^T \quad (by \oplus) \quad \boxed{0}$$

$$=\begin{bmatrix} w_{xh_{11}} & w_{xh_{12}} & \cdots & w_{xh_{1n}} \\ w_{xh_{21}} & w_{xh_{22}} & \cdots & w_{xh_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ w_{xh_{m1}} & w_{xh_{m2}} & \cdots & w_{xh_{mn}} \end{bmatrix} \begin{bmatrix} x_{t_1} \\ x_{t_2} \\ \vdots \\ x_{t_n} \end{bmatrix} + \begin{bmatrix} w_{hh_{11}} & w_{hh_{22}} & \cdots & w_{hh_{2n}} \\ w_{hh_{m1}} & w_{hh_{m2}} & \cdots & w_{hh_{mn}} \end{bmatrix} \begin{bmatrix} h_{t-11} \\ h_{t-12} \\ \vdots \\ h_{t-1n} \end{bmatrix}$$

$$= \begin{bmatrix} w_{xh11} & w_{xh12} & \cdots & w_{xh1n} & w_{xh11} & w_{xh12} & \cdots & w_{xh1n} \\ w_{xh21} & w_{xh22} & \cdots & w_{xh2n} & w_{xh21} & w_{xh22} & \cdots & w_{xh2n} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ w_{xhn1} & w_{xhn2} & \cdots & w_{xhnn} & w_{xhnn} & w_{xhnn} & w_{xhnn} \end{bmatrix} \cdot \begin{pmatrix} x_{t1} \\ x_{t2} \\ \vdots \\ h_{t-1n} \\ h$$

$$= \left[\begin{array}{c} \mathbb{W}_{\times h} & \mathbb{W}_{hh} \end{array} \right] \cdot \left[\begin{array}{c} \mathbb{X}_{t} \\ h_{t-1} \end{array} \right]$$

$$\begin{bmatrix} d \, \mathbb{W}_{xh} \, d \, \mathbb{W}_{hh} \end{bmatrix} = (\sigma'(T_{rnn} \, Z_t) \circ dh_t) \cdot \begin{bmatrix} \, \mathbb{X}_t^\mathsf{T} \, h_{t-1}^\mathsf{T} \, \end{bmatrix}$$

$$d \, \mathbb{W}_{xh} = (\sigma'(T_{rnn} \, Z_t) \circ dh_t) \cdot \mathbb{X}_t^\mathsf{T} \quad \boxed{5}$$

$$d \, \mathbb{W}_{hh} = (\sigma'(T_{rnn} \, Z_t) \circ dh_t) \cdot h_{t-1}^\mathsf{T} \quad \boxed{6}$$

Backpropagation_Through_Time_Vanilla_RNN():

$$\frac{\partial \ell_{t}}{\partial S_{t}} = P_{t} - 1y = y_{t} \odot$$

$$\frac{\partial \ell_t}{\partial W_{hy}} = \frac{\partial \ell_{t+1}}{\partial W_{hy}} + \frac{\partial \ell_t}{\partial S_t} \cdot \vec{h}^T \quad \boxed{0}$$

$$\frac{\partial \ell_t}{\partial h_t} = \frac{\partial \ell_{t+1}}{\partial h_t} + W_{hy}^{\mathsf{T}} \cdot \frac{\partial \ell_t}{\partial S_t}$$
 3

$$\frac{\partial l_t}{\partial W_{xh}} = \frac{\partial l_{t+1}}{\partial W_{xh}} + (\sigma'(T_{rnn} Z_t) \circ \frac{\partial l_t}{\partial h_t}) \cdot X_t^T$$
(5)

$$\frac{\partial \ell_{t}}{\partial W_{hh}} = \frac{\partial \ell_{t+1}}{\partial W_{hh}} + (\sigma'(T_{rnn} Z_{t}) \circ \frac{\partial \ell_{t}}{\partial h_{t}}) \cdot h_{t-1} @$$

$$\frac{\partial \mathcal{L}_{t}}{\partial X_{t}} = W_{xh}^{\mathsf{T}} \cdot (\sigma'(\mathsf{T}_{ynn} Z_{t}) \circ \frac{\partial \mathcal{L}_{t}}{\partial h_{t}}) \quad (2)$$

$$\sqrt{\frac{\partial lt}{\partial h_{t-1}}} = W_{hh} \cdot (\sigma'(T_{rnn} Z_t) \circ \frac{\partial lt}{\partial h_t})$$
(3)

Comments:

)
$$\frac{\partial \ell_t}{\partial W_{hy}}$$
, $\frac{\partial \ell_t}{\partial W_{hh}}$, $\frac{\partial \ell_t}{\partial h_t}$ are aggregated through time since

$$\frac{\partial l_{\text{total}}}{\partial W} = \frac{\partial l_{\text{t=T}} + l_{\text{t=T-1}} + \dots + l_{\text{t=1}}}{\partial W} = \frac{\partial l_{\text{t=T}}}{\partial W} + \frac{\partial l_{\text{t=T-1}}}{\partial W} + \dots + \frac{\partial l_{\text{t=1}}}{\partial W}$$

2)
$$\sigma'(T_{ran} Z_t) = \sigma(T_{ran} Z_t) - \sigma^2(T_{ran} Z_t) = \sigma([W_{xh} W_{hh}] \begin{bmatrix} X_t \\ h_{t-1} \end{bmatrix}) - \sigma^2([W_{xh} W_{hh}] \begin{bmatrix} X_t \\ h_{t-1} \end{bmatrix})$$