10/3/25, 5:56 AM OneNote

Ch4 Fundamental Subspace

Monday, 27 January 2025 5:05 PM

$$A = \begin{pmatrix} x_1 & y_1 & z_1 \\ x_2 & \cdots \\ x_m & & \end{pmatrix}$$

Ench vector \$\vec{x}\$ in 1R", A\$\vec{x}\$ yields vector 1R".

Definition 4.1.

15t;
$$A = (V_1 \cdots V_n)$$

• Column Space of A is subspace of Rⁿ given by

 $(A) = (V_1 \cdots V_n)$
 $(A) \in \mathbb{R}^m \cup \mathbb{R}^n$
 $(A) \in \mathbb{R}^m \cup \mathbb{R}^n$

Actions to
$$A = \begin{pmatrix} 3 & \frac{1}{5} \\ \frac{1}{5} & \frac{1}{5} \end{pmatrix}$$

That $\vec{V} \in (0.04)$

Any C_1 , C_2 yields the required \vec{V} .

That $\vec{W} \in Nnl(A)$

$$\begin{bmatrix} \frac{1}{3} & \frac{2}{4} \\ \frac{1}{5} & \frac{1}{6} \end{bmatrix} \begin{bmatrix} W_1 \\ W_2 \end{bmatrix} = \begin{bmatrix} W_1 + 2w_2 \\ 3w_1 + 4w_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \frac{1}{3} & \frac{2}{4} \\ \frac{1}{5} & \frac{1}{6} \end{bmatrix} \times \begin{bmatrix} 0 & 0 \\ 0 & -4 & 0 \end{bmatrix} \times \begin{bmatrix} 0 & 0 \\ 0 & -4 & 0 \end{bmatrix}$$

i. $V_1 = 0$, $V_2 = 0$.

(et A=(v,vn) Nw((A) is a subspace. - Non-empty: OENWI(A) - (losure under additioni $A(\vec{x} + \vec{y}) = (x_1 + y_1) \vec{v}_1 + \dots + (x_n + y_n) \vec{v}_n$ = $\vec{x}_1 \vec{v}_1 + \dots + \vec{x}_n \vec{v}_n + \vec{y}_1 \vec{v}_1 + \dots + \vec{y}_n \vec{v}_n$ = A x + A y A=(00) = 0 to 1. X tye Wrl (A)

Closure under multiplication \$ ENW (A), A EIR. A[AX): (Ax,)V, + -- + (Axn) Vn = 2(x, v, + m + x, v,) Sing of ENNICA) · AzielvullA)

Definition 4.3.

- · rank (A) := dim (Col (A))
- · nullity (A) := dim (Nul(A))

Activity: 4.3 Field file tank and mility:

(1) A:
$$\begin{pmatrix} 1 & -1 & 0 \\ 0 & 1 \end{pmatrix}$$

(2) B = $\begin{pmatrix} 1 & 3 & 2 & -1 \\ 0 & 1 & -1 & 1 \end{pmatrix}$

Reark:

(a) (A) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_2(\begin{pmatrix} -1 \\ 0 \end{pmatrix}) + c_3(\begin{pmatrix} 0 \\ 1 \end{pmatrix})$, where c_3 , $c_4 \in \mathbb{R}$.

(b) (B) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_3(\begin{pmatrix} 0 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

Since $\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ in the pints => discleric(A)) = 2

(i) (B) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_3(\begin{pmatrix} 0 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(i) (B) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_3(\begin{pmatrix} 0 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(ii) (B) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_3(\begin{pmatrix} 0 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(ii) (B) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_3(\begin{pmatrix} 0 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iii) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_3(\begin{pmatrix} 0 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iii) (B) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_3(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_3(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_3(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_3(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_3(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_3(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_2(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_3(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_3(\begin{pmatrix} 1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix}) + c_4(\begin{pmatrix} -1 \\ -1 \end{pmatrix})$

(iv) (b) = $c_1(\begin{pmatrix} 1 \\ 0 \end{pmatrix}) + c_3(\begin{pmatrix} 1 \\$

Definition 4.4

A:

$$A: \begin{pmatrix} \alpha_{11} & \alpha_{12} & \cdots & \alpha_{1n} \\ \alpha_{21} & \alpha_{22} & \cdots & \alpha_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_{m1} & \alpha_{m2} & \cdots & \alpha_{mn} \end{pmatrix}$$

A^T z $\begin{pmatrix} \alpha_{11} & \alpha_{21} & \cdots & \alpha_{mn} \\ \alpha_{12} & \alpha_{22} & \cdots & \alpha_{m2} \\ \vdots & \vdots & \ddots & \vdots \\ \alpha_{1n} & \alpha_{2n} & \cdots & \alpha_{mn} \end{pmatrix}$

Definition 4.6 A: mxn mathx,

3rd Subspace: Row(A) = Col(A^T) $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \rightarrow \begin{pmatrix} \times \\ \times \end{pmatrix}$

4.2 Rurle - Nullity,

```
Activity 4.4. Let A > \delta \times 3 matrix.

A: \begin{pmatrix} x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \\ x_3 & y_3 & z_3 \end{pmatrix}

(1) Suppose A has 2 pivot solvans. ((o) 1, 3)

Then \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} and \begin{pmatrix} z_1 \\ z_2 \\ z_3 \end{pmatrix} are linearly independed.

i. (o)(A): Span \left\{\begin{pmatrix} x_1 \\ x_3 \\ x_3 \end{pmatrix}, \begin{pmatrix} z_1 \\ z_2 \\ z_3 \end{pmatrix}\right\}

Rank A = \dim(A(A)) = 2.

No. A = \dim(A(A)) = 2.

The vector of column A = 0 and A = 0 and A = 0 determined.

i. A = 0 in A = 0 ky A = 0 ky A = 0 determined.

i. A = 0 ky A = 0 ky
```

Theorem 4.7.

Let A = mxn matrix with r pivot columns,

- rank (A) = r
- nullity (A) = n-r. $\left(\tilde{\chi}^2 \left(\frac{\chi}{\chi_m}\right) \in Nul(A)\right) + \tilde{\chi}^2 + \tilde{\chi}^2$

Collary 4.8.

4.3 Homogenous Systems and the Geometry of Systems.

Definition 4.9.

- ALL constants = 0. { 2x - y = 0 -) homogenaus.

Thousen 4.10.

Solution set to any Novogeness system of equations

- solution set = [Val (A)
- As AX = 0, set of solution = Nul (A)

OneNote

$$\begin{cases} x + 2y + 4z = 0 \\ x + y - z = 0 \\ y + 5z = 0 \end{cases} \begin{pmatrix} 1 & 1 & 1 \\ 0 & 1 & 5 \end{pmatrix} \begin{pmatrix} 2 \\ 2 \\ 1 & 1 & -1 \\ 0 & 1 & 5 \end{pmatrix} \begin{pmatrix} 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 1 & 5 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\$$

theoren 4.13

Solution set to a considert system with coefficient motion A.

$$= \{\vec{p}' + \vec{v} \mid \vec{v} \in Nul(A)\}$$

where positional vector solution to the system of linear equations

Remark 44

- Homogenous

Remak 4.1J

- · Translated Vector Spaces / Translated Spans
- · A vector space translated by some vector p?

OneNote