

Ch5 Linear Transformation

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5.1 Linearity *Or, 'transformation'*

Function F is called **linear** if

- (1) $F(\vec{x} + \vec{y}) = F(\vec{x}) + F(\vec{y})$
- (2) $F(c\vec{x}) = cF(\vec{x})$

Linear combination:

$$\begin{bmatrix} \text{Final } x \\ \text{Final } y \end{bmatrix} = x \begin{bmatrix} \text{Transformed } \uparrow \text{'s } x \\ \text{Transformed } \uparrow \text{'s } y \end{bmatrix} + y \begin{bmatrix} \text{Transformed } \uparrow \text{'s } x \\ \text{Transformed } \uparrow \text{'s } y \end{bmatrix}$$

$$\begin{bmatrix} -1 \\ 2 \end{bmatrix} x + \begin{bmatrix} 2 \\ 2 \end{bmatrix} y$$

2x2 Matrix

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x \begin{bmatrix} a \\ c \end{bmatrix} + y \begin{bmatrix} b \\ d \end{bmatrix} = \begin{bmatrix} ax + by \\ cx + dy \end{bmatrix}$$

\uparrow coord \uparrow coord

5.2 Matrix Transformation (multiply vector by matrix)

$$y = A\vec{x}$$

\uparrow \mathbb{R}^m \uparrow \mathbb{R}^n $m \times n$ matrix

Definition 5.2.

Matrix transformation associated to A is

$$T_A(\vec{x}) := A\vec{x}.$$

Proposition 5.3. Every matrix transformation

is a linear transformation.

$$\begin{aligned} T_A(\vec{x} + \vec{y}) &= A(\vec{x} + \vec{y}) \\ &= T_A(\vec{x}) + T_A(\vec{y}) \end{aligned}$$

Theorem 5.4.

Every linear transformation is a matrix transformation.

if $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is **linear**, then $F = T_A$ where
(columns of A are $T(e_1), T(e_2), T(e_3)$ implies $T(x) = Ax$)

$$A = (F(e_1) \ F(e_2) \ \dots \ F(e_n))$$

Unit vectors

Activity 5.1

$$\begin{aligned} (1) \quad F(\vec{x}) &= 2\vec{x} \\ \text{Since } 2(\vec{x} + \vec{y}) &= 2\vec{x} + 2\vec{y} = F(\vec{x}) + F(\vec{y}) \\ 2(c\vec{x}) &= c(2\vec{x}) = cF(\vec{x}) \end{aligned}$$

\therefore Linear

$$\begin{aligned} (2) \quad G\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) &= \begin{pmatrix} x^2 \\ y^2 \end{pmatrix} \\ \text{No. } G\left(\begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \end{pmatrix}\right) &= \begin{pmatrix} (x_1 + x_2)^2 \\ (y_1 + y_2)^2 \end{pmatrix} \neq \begin{pmatrix} x_1^2 + x_2^2 \\ y_1^2 + y_2^2 \end{pmatrix} \\ G(c\begin{pmatrix} x \\ y \end{pmatrix}) &= \begin{pmatrix} (cx)^2 \\ (cy)^2 \end{pmatrix} = c^2 \begin{pmatrix} x^2 \\ y^2 \end{pmatrix} \end{aligned}$$

$$(3) \quad T\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{pmatrix} x+1 \\ y-1 \end{pmatrix}$$

$$T\left(\begin{pmatrix} x_1 + x_2 \\ y_1 + y_2 \end{pmatrix}\right) = \begin{pmatrix} (x_1 + x_2) + 1 \\ (y_1 + y_2) - 1 \end{pmatrix}$$

5.2 $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is a linear transformation.

Recall a line in \mathbb{R}^2 can be described by

$$S = \left\{ \begin{pmatrix} x \\ y \end{pmatrix} \in \mathbb{R}^2 : y = mx + b \right\}$$

Show that $F(S) := \{F(\vec{v}) : \vec{v} \in S\}$ is either a line or a point.

Activity 5.3

$$F(\vec{e}_1) = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \quad \text{and} \quad F(\vec{e}_2) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

(1) Find $F\left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right)$ and $F\left(\begin{pmatrix} 2 \\ 3 \end{pmatrix}\right)$.

Proof

Suppose that $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation. $F = T_A$.

Let A be defined as $A = (F(\vec{e}_1) \ F(\vec{e}_2) \ \dots \ F(\vec{e}_n))$

$$\begin{pmatrix} \vec{e}_1 & \vec{e}_2 & \dots & \vec{e}_n \end{pmatrix} \begin{pmatrix} \mathbb{R}^n \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix} \dots \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 1 \end{pmatrix}$$

if linear

Activity 5.4: Find the defining matrix for following linear transformation

$$(1) \quad \vec{x} \mapsto 2\vec{x}$$

$$\text{Basis of } \mathbb{R}^n \quad e_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad e_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$F(e_1) = 2e_1 = \begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}$$

$$F(e_2) = 2e_2 = \begin{pmatrix} 0 \\ 2 \\ 0 \end{pmatrix}$$

$$F(e_3) = 2e_3 = \begin{pmatrix} 0 \\ 0 \\ 2 \end{pmatrix}$$

Defining matrix A

$$A = \begin{pmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

$$(2) \quad \dots$$

Definition 5.5

- Given a matrix A .

- T_A is the **MATRIX TRANSFORMATION** correspond to matrix A .

- call $m \times n$ matrix A_F as **DEFINING MATRIX** of transformation F .

$$T(x) = Ax + b \quad (b \neq 0) \quad (\text{Affine})$$

$$T(x) = Ax \quad (\text{Linear})$$

relationship of basis and domain.

Activity 5.3 $T: \mathbb{R}^3 \rightarrow \mathbb{R}^3$

$$T\left(\begin{pmatrix} x \\ y \\ z \end{pmatrix}\right) = \begin{pmatrix} x+1 \\ y-1 \end{pmatrix}$$

Not linear transformation

- $T(0) = 0$.

- Shifts the origin \rightarrow not linear

Proof.

$$\text{We have } T(\vec{e}_1) = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$T(\vec{e}_2) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$T(\vec{e}_3) = \begin{pmatrix} -1 \\ 1 \end{pmatrix}$$

$$T(\vec{x}) = A\vec{x}$$

$$A = \begin{pmatrix} 2 & 0 & 1 \\ 0 & 0 & -1 \end{pmatrix}$$

5.3 Function Composition and the Matrix Product

$$f: A \rightarrow B \quad f \circ g \neq g \circ f$$

$$g: B \rightarrow C$$

Composite function $g \circ f: A \rightarrow C$ is defined by

$$(g \circ f)(a) = g(f(a))$$

$$T_A: \mathbb{R}^k \rightarrow \mathbb{R}^m, \vec{x} \mapsto A\vec{x}$$

$$T_B: \mathbb{R}^n \rightarrow \mathbb{R}^k, \vec{x} \mapsto B\vec{x}$$

$\therefore T_A \circ T_B: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is defined by

$$(T_A \circ T_B)(\vec{x}) = A(B\vec{x})$$

$$T_A \circ T_B = T_C \quad C = AB$$

Definition 5.6.

Let A be an $m \times k$ matrix.

Let B be a $k \times n$ matrix.

MATRIX PRODUCT of A and B is $m \times n$ matrix C .

$$T_A \circ T_B = T_C.$$

$$\text{Then } \vec{x} = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}, B = (b_1 \vec{b}_1 \dots b_n \vec{b}_n)$$

$$\text{We have } A(B\vec{x}) = A(x_1 b_1 \vec{b}_1 + x_2 b_2 \vec{b}_2 + \dots + x_n b_n \vec{b}_n)$$

$$= C\vec{x}.$$

$$(Ab_1 \vec{b}_1 \quad Ab_2 \vec{b}_2 \quad \dots \quad Ab_n \vec{b}_n)$$

$$G: \mathbb{R}^2 \rightarrow \mathbb{R}^3.$$

$$F(e_1) = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$F(e_2) = \begin{pmatrix} -1 \\ 0 \\ 0 \end{pmatrix}$$

$$A = \begin{pmatrix} 0 & -1 \\ 1 & 0 \\ 0 & 0 \end{pmatrix}$$



By Proposition 5.3, every matrix transformation is linear.
So T is a linear transformation.

Activity 5.6.

Function $H: \mathbb{R}^2 \rightarrow \mathbb{R}^3$ defined by

$$H\left(\begin{pmatrix} x \\ y \end{pmatrix}\right) = \begin{pmatrix} x+y \\ x \\ 0 \end{pmatrix}$$

$$\begin{pmatrix} x+y \\ x \\ 0 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix}$$

$$\therefore \text{We have } H(x, y) = A \begin{pmatrix} x \\ y \end{pmatrix} \text{ for } (x, y) \in \mathbb{R}^2$$

Since any transformation of the form $T(x) = Ax$ is linear,

Basically Matrix Multiplication.

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Example 5.7

$$\text{Let } A = \begin{pmatrix} 1 & 0 & 3 \\ 1 & 1 & -1 \end{pmatrix}, B = \begin{pmatrix} 1 & 2 \\ 0 & 3 \\ -1 & 1 \end{pmatrix}$$

$$\uparrow$$

$$2 \times 3$$

$$\uparrow$$

$$3 \times 2$$

$\therefore C$ is 2×2 .

5.4. Geometric Rank-Nullity

Recall $F: A \rightarrow B$

\uparrow Domain \uparrow CODOMAIN

Definition 5.10

Given a function $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$.

1. Kernel of F is subset of \mathbb{R}^n

$$\ker(F) := \{\vec{x} \in \mathbb{R}^n \mid F(\vec{x}) = \vec{0}\}$$

(i.e. all the vectors that becomes origin $\vec{0}$ after transformation)

2. Image of F is subset of \mathbb{R}^m

$$\text{im}(F) := \{\vec{y} \in \mathbb{R}^m \mid F(\vec{x}) = \vec{y} \text{ for some } \vec{x} \in \mathbb{R}^n\}$$

\uparrow Span!

$\text{Nul}(A_F) = \ker(F)$ = set of vectors that got mapped to zero

$\text{Col}(A_F) = \text{im}(F)$ = the span of its column vectors

$$\begin{bmatrix} 1 & 4 & 7 \\ 2 & 6 & 9 \end{bmatrix}$$

$$\uparrow \quad \uparrow \quad \uparrow$$

$$v_1 \quad v_2 \quad v_3$$

Activity 5.7

$$\text{Consider } F: \mathbb{R}^3 \rightarrow \mathbb{R}^2, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} x-y \\ z \end{pmatrix}$$

1. Find a vector \vec{x} in $\ker(F)$.

$$F\left(\begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 0-0 \\ 0 \end{pmatrix} = \vec{0}$$

OR

$$F\left(\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 1-0 \\ 0 \end{pmatrix} = \vec{0}$$

$$\therefore \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}, \text{ (in } \mathbb{R}^3)$$

$$\therefore \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \text{ (in } \mathbb{R}^3)$$

2. Find a vector \vec{y} in $\text{im}(F)$

we want any $(y, z) \in \mathbb{R}^2$ write as $(x-y, z) \in \mathbb{R}^2$

Choose $(y, z) = (1, 2)$

Then pick preimage = $(3, 2, 2)$

v_1, v_2, v_3

$$F\left(\begin{pmatrix} 3 \\ 2 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

↑

 $y = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$ is in $\text{im}(F)$

Activity 5.8

Show that 1. $\ker(F) = \text{Nul}(A_F)$,2. $\text{im}(F) = \text{Col}(A_F)$

* Recall,

$$\ker(F) = \{\vec{x} \in \mathbb{R}^m \mid F(\vec{x}) = \vec{0}\}$$

$$\text{Nul}(A) = \{\vec{x} \in \mathbb{R}^m \mid A\vec{x} = \vec{0}\}$$

$$\text{Since } F(\vec{x}) = A\vec{x}$$

Definition 5.11

- **RANK** of linear transformation F is the dimension of $\text{im}(F)$.
- **NULLITY** of linear transformation F is dimension of $\ker(F)$

Activity 5.9.

Find rank and nullity of $F: \mathbb{R}^3 \rightarrow \mathbb{R}^2, \begin{pmatrix} x \\ y \\ z \end{pmatrix} \mapsto \begin{pmatrix} x-y \\ z \end{pmatrix}$ • $\text{im}(F)$: To find $\text{im}(F)$, we want to find the no. of independent vectors in A_F .

$$\begin{pmatrix} 1 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} x + \begin{pmatrix} -1 \\ 0 \end{pmatrix} y + \begin{pmatrix} 0 \\ 1 \end{pmatrix} z$$

• All vectors: $\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$, only 2 are independent.

$$\text{Rank} = \dim(\text{Col}(A)) = \dim(\text{im}(F)) = 2$$

$$\text{Nullity} = \dim(\text{Nul}(A)) = \dim(\ker(F)) = \text{Number of columns of } A_F - 2 = 1$$

Pbset.

P. 5.2

Let V be a vector subspace of \mathbb{R}^n and suppose that $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is a linear transformation.Show that $F(V) = \{f(v) \mid v \in V\}$ is a vector subspace of \mathbb{R}^m .Proof ① $\vec{0} \in F(V)$

② Closed under addition

③ Closed under multiplication of scalars.

Proof. ① $\vec{0} \in V$ as V is a subspace1. Since V is a subspace, $\vec{0} \in V$.Since F is linear transformation,

$$F(\vec{0}) = \vec{0}$$

$$\vec{0} \in F(V)$$

2. Since ..., let $v_1, v_2 \in V, v_1 + v_2 \in V$.

$$F(v_1 + v_2) = F(v_1) + F(v_2) \in F(V)$$

Since T is linear transformation, $F(\vec{0}) = \vec{0}$
 $\therefore \vec{0} \in F(V)$

② Let $v_1, v_2 \in V$.

Let $F(v_1) = w_1$, $F(v_2) = w_2$.

V is subspace: $v_1 + v_2 \in V$.

$F(v_1 + v_2) = F(v_1) + F(v_2) = w_1 + w_2$

$\therefore w_1 + w_2 \in F(V)$

③ Let $v \in V$.

Let $F(v) = w$

V is subspace: $c v \in V$ (c is constant)

$F(c v) = c F(v) = c w \in F(V)$

P. 5.8

Let $F: \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation.

If $n < m$, show that F cannot be surjective.

Let $A\vec{x} = \vec{b}$

F is surjective if all its rows has a pivot.

Assume $n=2$, $m=3$. Then the transformation matrix is in form $\begin{pmatrix} * & * \\ * & * \\ * & * \end{pmatrix}$. Since each column can at most have

one pivot, there is at most 2 pivots, but we have

3 rows. \therefore Not all of the rows has a pivot.

$\therefore F$ cannot be surjective.