

Ch7 Determinant

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7.1 Determinants in \mathbb{R}^2

Definition 7.1

The unit square is subset of \mathbb{R}^2 :

$$S := \{x_1 \vec{e}_1 + x_2 \vec{e}_2 : 0 \leq x_1, x_2 \leq 1\}$$

Proposition 7.2.

Let $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear transformation.

- Then $F(S)$ is a parallelogram given by $F(\vec{e}_1)$ and $F(\vec{e}_2)$
- \mathbb{R}^2 coordinate grid transformed into a grid with axes in $F(\vec{e}_1)$ and $F(\vec{e}_2)$

Proof.

$$\begin{aligned} F(S) &= \{F(x_1 \vec{e}_1 + x_2 \vec{e}_2) : 0 \leq x_1, x_2 \leq 1\} \\ &= \{x_1 F(\vec{e}_1) + x_2 F(\vec{e}_2) : 0 \leq x_1, x_2 \leq 1\} \end{aligned}$$

Definition 7.3

An ordered basis $\{\vec{b}_1, \vec{b}_2\}$ for \mathbb{R}^2 is called

POSITIVELY ORIENTED if we can rotate \vec{b}_1 less than

180° counterclockwise to reach \vec{b}_2 . Else, basis is negatively oriented.

* Definition 7.4

Let $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear transformation.

Determinant of F , $\det(F)$, is the oriented area of $F(S)$.

For $\alpha(F(S))$ being area of $F(S)$:

$$\det(F) := \begin{cases} \alpha(F(S)) & \text{if } \{F(\vec{e}_1), F(\vec{e}_2)\} \\ -\alpha(F(S)) & \text{if } \{F(\vec{e}_1), F(\vec{e}_2)\} \\ 0 & \text{if } \alpha(F(S)) = 0 \end{cases}$$

* Proposition 7.5.

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc$$

7.2 Determinants in \mathbb{R}^3

Definition 7.6

UNIT CUBE

$$C := \{ \alpha_1 \vec{e}_1 + \alpha_2 \vec{e}_2 + \alpha_3 \vec{e}_3 : 0 \leq \alpha_1, \alpha_2, \alpha_3 \leq 1 \}$$

Definition 7.7.

 $\{\vec{b}_1, \vec{b}_2, \vec{b}_3\}$ positively oriented if follows right-hand rule.
Definition 7.8. determinant of T is oriented volume of $T(C)$.Let $v(T(C))$ be volume.

$$\det(T) := \begin{cases} v(T(C)) & \text{if } \{T(\vec{e}_1), T(\vec{e}_2), T(\vec{e}_3)\} \text{ is positively oriented} \\ -v(T(C)) & \text{if } \{T(\vec{e}_1), T(\vec{e}_2), T(\vec{e}_3)\} \text{ is negatively oriented.} \\ 0 & \text{if } v(T(C)) = 0 \end{cases}$$

Proposition 7.9.

$$\det \begin{pmatrix} c & 0 & 0 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{pmatrix} = c \det \begin{pmatrix} a_2 & a_3 \\ b_2 & b_3 \end{pmatrix}$$

Proposition 7.10

$$\det(\vec{v}_1, \vec{v}_2, \vec{v}_3) = -\det(\vec{v}_2, \vec{v}_1, \vec{v}_3)$$

Proposition 7.11 row linearity

$$\det \begin{pmatrix} \alpha & \beta & \gamma \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{pmatrix} = \det \begin{pmatrix} \alpha & 0 & 0 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{pmatrix} + \det \begin{pmatrix} 0 & \beta & 0 \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{pmatrix} + \det \begin{pmatrix} 0 & 0 & \gamma \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{pmatrix}$$

Example 7.12 Calculate determinant of 3×3 matrix

$$A = \begin{pmatrix} a & b & c \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$$

$$\det(A) = \det \begin{pmatrix} a & 0 & 0 \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} + \det \begin{pmatrix} 0 & b & 0 \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} + \det \begin{pmatrix} 0 & 0 & c \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$$

$$\begin{aligned}
 &= \det \begin{pmatrix} a & 0 & 0 \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} - \det \begin{pmatrix} b & 0 & 0 \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} + \det \begin{pmatrix} c & 0 & 0 \\ 1 & 2 & 3 \\ 4 & 3 & 6 \end{pmatrix} \\
 &= a \det \begin{pmatrix} 2 & 3 \\ 5 & 6 \end{pmatrix} - b \det \begin{pmatrix} 2 & 3 \\ 5 & 6 \end{pmatrix} + c \det \begin{pmatrix} 2 & 3 \\ 5 & 6 \end{pmatrix} \\
 &= -3a + 6b - 3c
 \end{aligned}$$

7.3 Cofactor Expansion and Determinant in \mathbb{R}^n .

Definition 7.13

- For an $n \times n$ matrix $A = (a_{ij})$
- i, j -MINOR of A is defined to be the $(n-1) \times (n-1)$ matrix of A_{ij} , with i th and j th row deleted.

Definition 7.14

Let A be $n \times n$ matrix with i, j -entry equal to a_{ij} .

$$\det(A) := a_{11} \det(A_{11}) - a_{12} \det(A_{12}) + \dots + (-1)^{n+1} a_{1n} \det(A_{1n})$$

Definition 7.16

The unit n -cube C_n is the subset of \mathbb{R}^n defined by

$$C_n = \{x_1 \vec{e}_1 + \dots + x_n \vec{e}_n : 0 \leq x_i \leq 1\}$$

Proposition 7.17

Let $F: \mathbb{R}^n \rightarrow \mathbb{R}^n$ be a linear transformation.

- Image of the unit n -cube under F is a parallelepiped in \mathbb{R}^n .

$$F(C_n) = \{x_1 F(\vec{e}_1) + \dots + x_n F(\vec{e}_n) : 0 \leq x_1, \dots, x_n\}$$

$$\text{Volume} = V(F(C_n)) = |\det(F)|$$

7.4 Properties of the Determinant

Theorem 7.18.

- Let A be an $n \times n$ matrix.
- A is only invertible if and only if $\det A \neq 0$

Lemma 7.19

Let $A = (a_{ij})$ be an $n \times n$ matrix with ij -entry equal to a_{ij} .

$$\det(A) = a_{11}\det(A_{11}) - a_{21}\det(A_{21}) + \dots + (-1)^{n+1}a_{n1}\det(A_{n1})$$

(we can perform cofactor expansion by along first column instead of row)

Theorem 7.20 Let A be an $n \times n$ matrix.(1) If B is obtained by interchanging 2 rows of A ,

$$\det(B) = -\det(A)$$

(2) If B is obtained by multiplying one row of A by a constant c ,

$$\det(B) = c\det(A)$$

(3) If B is obtained by replacing a row of A by that rowand a scalar multiple of another row of A , then

$$\det(B) = \det(A)$$

Corollary 7.21 If A is not invertible, $\det(A) = 0$ Lemma 7.22 Let E be an $n \times n$ elementary matrix,and B be any $n \times n$ matrix.

$$\det(EB) = \det(E)\det(B)$$

Proposition 7.23

$$\det(A) = \det(A^T)$$

$$\cdot \det(AB) = \det(A) \det(B)$$

P.7.3 Show that if A is not invertible,

then A^T is not invertible. Conclude that if A is not invertible, then $\det(A^T) = 0$

Let $\det(A) = 0$.

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix},$$

• Assume A is not invertible.

Then there exist $\vec{y} \neq 0$ s.t. $A\vec{y} = \vec{0}$

Taking transpose on both sides,

$$(A\vec{y})^T = \vec{0}^T$$

$$\vec{y}^T A^T = \vec{0}$$

Since $\vec{y} \neq 0$, \vec{y}^T is also not zero.

\therefore There exist non-trivial solution, thus y^T is not inv

Show that if A or B is not invertible, then AB is not invertible.

P.7.4. Let A be an invertible matrix.

$$\text{Show } \det(A^{-1}) = \frac{1}{\det(A)}$$

• Assume A is invertible.

$$AA^{-1} = I$$

$$\det(AA^{-1}) = \det(I)$$

$$\det(A) \det(A^{-1}) = \det(I)$$

$$\det(A^{-1}) = \frac{1}{\det(A)}$$

P. 7.5 True or False:

• For any $n \times n$ matrix A , $\det(-A) = -\det(A)$

• False.

$$\text{Let } A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \det(A) = 1.$$

$$-A = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}$$

$$\det(-A) = \det \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} = 1 \neq -1.$$

P. 7.9. An $n \times n$ matrix A is called skew-symmetric if $A = -A^T$.

Show that when n is odd, any $n \times n$ skew-symmetric matrix is not invertible.

$$\det A = \det(A^T)$$

$$\det A = (-1)^n \det(A^T)$$

$$\det(A) = -\det(A)$$

$$2\det A = 0$$

$$\det A = 0$$

\therefore Not invertible.

P. 8.1 (4, 5)

• Let $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear transformation which rotates every vector in \mathbb{R}^2 counterclockwise by an angle θ .

(a) Show that $A_F = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$

$$\cdot e_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \therefore F(e_1) = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}$$

$$\cdot e_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \therefore F(e_2) = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -\sin \theta \\ \cos \theta \end{pmatrix}$$

$$A_F = (F(e_1) \ F(e_2)) = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

(b) Show that A_F does not have any real eigenvalues unless θ is an integer multiple of 180° .

$$1. \det(A_F - \lambda I) = 0$$

$$\det \begin{pmatrix} \cos \theta - \lambda & -\sin \theta \\ \sin \theta & \cos \theta - \lambda \end{pmatrix}$$

$$= (\cos \theta - \lambda)(\cos \theta - \lambda) - (-\sin \theta)(\sin \theta)$$

$$= \lambda^2 - 2\lambda \cos \theta + \cos^2 \theta + \sin^2 \theta$$

$$= \lambda^2 - 2\lambda \cos \theta + 1$$

$$\Delta = (-2 \cos \theta)^2 - 4(1)(1)$$

$$= -4 \sin^2 \theta$$

$$\sin^2 \theta \geq 0, \therefore \text{only } -4 \sin^2 \theta = 0$$

$$\sin \theta = 0$$

$$\theta = k\pi.$$

P.8.2. Show that for any $n \times n$ matrix A we have $\chi_A = \chi_{A^T}$.

Conclude A and A^T has same eigen values.

$$1. \chi_{A^T} = \det(A^T - \lambda I)$$

$$= \det((A - \lambda I)^T) \quad (\text{as } (A - \lambda I)^T = A^T - \lambda I)$$

$$= \det(A - \lambda I)$$

$$= \chi_A,$$

\Rightarrow Same eigenvalue.