view_frames Result

Recorded at time: 1733369171.2319732

world

Broadcaster: /base_to_world
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: /ref_base_to_world
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

base

reference/base

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

controller_box

pedestal_feet

pedestal

right_arm_base_link

torso

reference/right_arm_base_link

reference/controller_box

reference/pedestal_feet

reference/pedestal

reference/torso

Broadcaster: /robot_state_publisher
Average rate: 38.755
Buffer length: 4.98
Most recent transform: 1733369171.213
Oldest transform: 1733369166.233

Broadcaster: /robot_ref_publisher
Average rate: 39.078
Buffer length: 4.99
Most recent transform: 1733369171.215
Oldest transform: 1733369166.225

right_l0

reference/right_l0

Broadcaster: /robot_state_publisher
Average rate: 38.755
Buffer length: 4.98
Most recent transform: 1733369171.213
Oldest transform: 1733369166.233

Broadcaster: /robot_state_publisher
Average rate: 38.755
Buffer length: 4.98
Most recent transform: 1733369171.213
Oldest transform: 1733369166.233

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_ref_publisher
Average rate: 39.078
Buffer length: 4.99
Most recent transform: 1733369171.215
Oldest transform: 1733369166.225

Broadcaster: /robot_ref_publisher
Average rate: 39.078
Buffer length: 4.99
Most recent transform: 1733369171.215
Oldest transform: 1733369166.225

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

head

right_l1

right_torso_itb

reference/head

reference/right_l1

reference/right_torso_itb

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_state_publisher
Average rate: 38.755
Buffer length: 4.98
Most recent transform: 1733369171.213
Oldest transform: 1733369166.233

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

Broadcaster: /robot_ref_publisher
Average rate: 50.191
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Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

Broadcaster: /robot_ref_publisher
Average rate: 39.078
Buffer length: 4.99
Most recent transform: 1733369171.215
Oldest transform: 1733369166.225

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

screen

head_camera

right_l1_2

right_l2

reference/screen

reference/head_camera

reference/right_l2

reference/right_l1_2

Broadcaster: /robot_state_publisher
Average rate: 38.755
Buffer length: 4.98
Most recent transform: 1733369171.213
Oldest transform: 1733369166.233

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_ref_publisher
Average rate: 39.078
Buffer length: 4.99
Most recent transform: 1733369171.215
Oldest transform: 1733369166.225

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

right_l3

right_l2_2

reference/right_l3

reference/right_l2_2

Broadcaster: /robot_state_publisher
Average rate: 38.755
Buffer length: 4.98
Most recent transform: 1733369171.213
Oldest transform: 1733369166.233

Broadcaster: /robot_ref_publisher
Average rate: 39.078
Buffer length: 4.99
Most recent transform: 1733369171.215
Oldest transform: 1733369166.225

right_l4

reference/right_l4

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_state_publisher
Average rate: 38.755
Buffer length: 4.98
Most recent transform: 1733369171.213
Oldest transform: 1733369166.233

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_ref_publisher
Average rate: 39.078
Buffer length: 4.99
Most recent transform: 1733369171.215
Oldest transform: 1733369166.225

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

right_arm_itb

right_l5

right_l4_2

reference/right_l5

reference/right_arm_itb

reference/right_l4_2

Broadcaster: /robot_state_publisher
Average rate: 38.755
Buffer length: 4.98
Most recent transform: 1733369171.213
Oldest transform: 1733369166.233

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_ref_publisher
Average rate: 39.078
Buffer length: 4.99
Most recent transform: 1733369171.215
Oldest transform: 1733369166.225

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

right_l6

right_hand_camera

right_wrist

reference/right_l6

reference/right_hand_camera

reference/right_wrist

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

right_hand

reference/right_hand

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

stp_022312TP99620_base

reference/stp_022312TP99620_base

Broadcaster: /robot_state_publisher
Average rate: 50.203
Buffer length: 4.98
Most recent transform: 1733369171.701
Oldest transform: 1733369166.722

Broadcaster: /robot_ref_publisher
Average rate: 50.191
Buffer length: 4.981
Most recent transform: 1733369171.711
Oldest transform: 1733369166.73

stp_022312TP99620_tip_1

reference/stp_022312TP99620_tip_1