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Computer-aided Design of Bio-inspired Nanoporous Silica Materials

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1 Summary

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3 Introduction

Molecular Dynamics (MD) and Monte Carlo (MC) have been powerful tools to simulate molecular interactions of surfactants in solvent systems, allowing a deeper understanding of self-assembly process of this sort of material (Need & Someone, 2025). Therefore, these structural conformations are specially useful to design bio-inspired silica materials (Patwardhan, 2011) since with the addition of silica they remain behaving as scaffolds to mesoporous or nanoporous structures that are maintained even after surfactant removal, silica oligomer polymerization and calcination (Tolbert, Firouzi, Stucky, & Chmelka, 1997). A vast range of silica materials are examples of this phenomena, such as MCM-41 as reported by Kresge and Roth (2013), HR (Jin et al., 2008), MSU-V (Tanev, Liang, & Pinnavaia, 1997) and many others, in which the self-assembly structure depend on the type of surfactant and concentration of the substances involved. Moreover, most of the experimental methods used to obtain data are based on observation and interpretation of final silica structure by using X-ray diffraction (XRD) and transmission electron microscopy (TEM), thus initial self-assembled conformations are predicted as a reflex of the final results and little is known about the mechanistic of this process. However, by using MD simulations it is possible to observe and analyse these initial steps of self-assembly and further predict, with more accuracy, properties and framework provided by surfactant (Tresset, 2009) to generate silica structures.

A major concern is that even though MD uses sophisticated software prepared to simulate enormous systems with thousands of atoms, using all capacities of hardware available, such as high-speed multi-core processors in conjunction with GPUs designed specifically to process data from arrays (Pronk et al., 2013), they hardly can achieve long time horizons and are commonly limited to a few μs depending on the size of the system. For this reason, several techniques have been developed to optimize the performance of the simulations such as coarse-grain models (Need & Someone, 2025). Briefly, the idea behind using this technique is to fit parameters of heavy atoms groups with similar properties in a bigger "bead", which includes atomic masses and electrostatic charges lumped in approximated values. For example, by merging carbon heavy atoms, that means carbon atom and its hydrogen atoms, at a lipid tail in groups of three or four since they have similar hydrophobic properties.

In order to provide topologies to GROMACS simulations several force-fields, for example MARTINI (Marrink, Risselada, Yefimov, Tieleman, & de Vries, 2007), use Lennard-Jones potentials fitted to a range of pre-defined bead types to describe coarse-grain models. Furthermore, not only intramolecular beads are possible, but also intermolecular beads can be specified, such as multiple solvent molecules merged in a single bead or ions surround by water molecules. Previous works conducted by (Pérez-Sánchez, Gomes, & Jorge, 2013) with this method recreated a model of surfactant in presence of silica with explicit water that was successful in describing rod-like self-assembly structures detected on MCM-41 materials, demonstrating the capacities of up-scaling this type of systems. Nevertheless, solvent presence demands most of the computational resources, hence implicit solvent scheme has been focus of many studies (Pronk et al., 2013).

Different concepts have been applied to develop a suitable model for implicit solvents, studies conducted by Arnarez et al. (2015) developed the Dry MARTINI force-field by modifying parameters of its predecessor, in such manner that solvent interactions became incorporated in these values and then solvent beads are no longer necessary. Another method, described by (Mirzoev & Lyubartsev, 2013) is able to recreate an implicit solvent system from interaction potentials generated from a bottom-up approach, that means by using an all-atoms simulation to generate parameters for the coarse-grain model. It is supposed that thermodynamic changes on the system, originated from solvent interaction with amphiphilic molecules, are incorporated on the approximated potentials. Therefore, changes in parameters as concentration may not affect coarse-grained model performance on recreating self-assembly structures (Mirzoev & Lyubartsev, 2014b).

The work presented on following experiments are an attempt to create a cross-link method to upscale silica crystal-liquid phase interactions (Tolbert et al., 1997) from the atomistic model to a mesoscale model with the advent of this later coarse-grain technique. The methodology applied to reach the desired model is based on the MagiC software package (Mirzoev & Lyubartsev, 2013) that in conjunction MD simulation software, in this case GROMACS (Pronk et al., 2013), will provide a suitable approximation to self-assembly of amphiphilic molecules in presence of silica. Further explanations of the process are described on Experimental Methods section. For the scope of this project, a bolaamphiphilic molecule 1,12-diaminododecane (DMDD) has been chosen as surfactant because that as seen in previous research by Tanev et al. (1997) it self-assembly in multilamellar vesicles that in presence of a silica precursor is capable of generating a mesoporous structure with remarkable properties. In order to validate this structure formation and further framework formation for silica oligomers, a coarse-grain approximation is suitable option since amphiphilic molecules interaction with

solvents can be described efficiently with tabulated Lennard-Jones potentials interactions. As a final objective at the end of this project, a implicit water coarse-grain model for DMDD will be generated and properly validated based on MD simulations and thermodynamic properties,in order to provide a good approximation to interactions with silica oligomers in a mesoscale model.

4 Theoretical Basis

This work is based on two molecular simulation techniques the former, called Molecular Dynamics, accounts for integration of Newton forces in order to describe positions and velocities of particles in the system. The latter, called Monte Carlo method, is a powerful statistical tool based on stochastic inputs to measure properties of many systems, in this case thermodynamic equilibrium of molecular systems. Following sections will describe the mechanistic behind each technique and further explain how they are used in simulation software.

4.1 Simulation Methods

4.1.1 Molecular Dynamics simulation

Molecular Dynamics is a simulation method that originates from dynamic nature of atomic interactions. Generally, a system of atoms can be treated as a multi-particle system ruled by Newton's Law (Frenkel & Smit, 2001). Considering a system with \mathcal{N} atoms for each i th particle of the system the follow differential equation:

$$m_i \frac{d^2 \vec{r}_i(t)}{dt^2} = \vec{F}_i(t) \quad (1)$$

Where $\vec{r} = (x, y, z)$ is the position vector and $F = (F_x, F_y, F_z)$ are the force components. Therefore, for this \mathcal{N} particle system, it is necessary to solve $3\mathcal{N}$ differential equations in order to fully describe it analytically at any t . Since any molecular system involves an enormous number of molecules, solving these equations analytically is impracticable and simulation methods are necessary. The derivatives terms need to be numerically calculated and as soon as simulation efficiency is a major concern, a suitable approximation to the second derivative of position is the Taylor's expansion, taking the x coordinate as an example, for a given Δt is:

$$x(t + \Delta t) = x(t) + \Delta t \frac{dx(t)}{dt} + \frac{1}{2!} \Delta t^2 \frac{d^2 x(t)}{dt^2} + \frac{1}{3!} \Delta t^3 \frac{d^3 x(t)}{dt^3} + \mathcal{O}(\Delta t^4) \quad (2)$$

$$x(t - \Delta t) = x(t) - \Delta t \frac{dx(t)}{dt} + \frac{1}{2!} \Delta t^2 \frac{d^2 x(t)}{dt^2} - \frac{1}{3!} \Delta t^3 \frac{d^3 x(t)}{dt^3} + \mathcal{O}(\Delta t^4) \quad (3)$$

$$\frac{d^2 x(t)}{dt^2} = \frac{x(t + \Delta t) - 2x(t) + x(t - \Delta t)}{\Delta t^2} + \mathcal{O}(\Delta t^2) \quad (4)$$

Hence, by neglecting the error of order $\mathcal{O}(\Delta t^2)$, it is possible to use equations Eqn.(1) and Eqn.(4) to derive the called "Verlet method" where position and velocity vectors for each i th atom on next step ($t + \Delta t$) are calculated using previous and current step:

$$\vec{r}_i(t + \Delta t) = 2\vec{r}_i(t) - \vec{r}_i(t - \Delta t) + \frac{\Delta t^2}{m_i} \vec{F}_i(t) \quad (5)$$

$$\vec{v}_i(t) = \frac{\vec{r}_i(t + \Delta t) - \vec{r}_i(t - \Delta t)}{2\Delta t} \quad (6)$$

In order to improve accuracy on Verlet method, another approach can be made by accounting a new force term in the velocity. This term is calculated from the updated position vector, and this improved velocity term is used to calculate the new position in the next step, creating a preciser step cycle with more stability(Satoh, 2010). This set of equations are called "Velocity Verlet method" and they are described as:

$$\vec{r}_i(t + \Delta t) = \vec{r}_i(t) + \vec{v}_i(t)\Delta t + \frac{\vec{F}_i(t)}{2m_i}\Delta t^2 \quad (7)$$

$$\vec{v}_i(t + \Delta t) = \vec{v}_i(t) + \frac{\vec{F}_i(t + \Delta t) + \vec{F}_i(t)}{2m_i}\Delta t \quad (8)$$

As a final variation for Verlet method one can derive the "Leap frog method", in which considers half-step when calculating the velocity term. Even though the use of this technique leads to a more

stable and accurate behaviour when compared to Verlet method, it is noticeable that velocity and position are not in the same time steps, therefore it is not possible to calculate the total energy at a given t , just kinetic or potential energy separately (Frenkel & Smit, 2001). By applying first-order derivatives with half-steps, one can obtain the following equations:

$$\vec{r}_i(t + \Delta t) = \vec{r}_i(t) + \vec{v}_i(t + \Delta t/2)\Delta t \quad (9)$$

$$\vec{v}_i(t + \Delta t/2) = \vec{v}_i(t - \Delta t/2) + \frac{\vec{F}_i(t)}{m_i}\Delta t \quad (10)$$

The force term for each step is a key factor to define whether Molecular Dynamics are realistic or not. They are strictly related to the force-field adopted to describe molecular interactions, since they provide parameters to describe Lennard-Jones potentials in which forces can be calculated at any system configuration. Eventually, as seen in innovative methods such as the used on this project, the potential values can also be provided by tables generated specifically for each molecular interaction, explanations about this technique will be given on further sections. Molecular dynamics technique enable the use of thermostats and barostats to control dynamic behaviour of temperature and pressure of the system, recreating different types of thermodynamic ensemble. Hence, at equilibrated states, system properties can be obtained as a temporal average of instantaneous values and those averages can be compared to real experimental data in order to validate simulations.

4.1.2 Monte Carlo simulation

Monte Carlo is a simulation method based on statistical probability of existence of a system at thermodynamic equilibrium. This happens when free energy reaches a minimum by calculating the energy for each particle's microscopic state. Given a system of \mathcal{N} particles, temperature T and volume V , thus it can be denoted as a canonical ensemble, it is possible to assume that the free Helmholtz energy of the system is:

$$A = U - TS \quad (11)$$

Where S is the entropy and U is the internal energy, meaning that not only a minimum in free energy can arise from a minimum in total energy, but also an increase in entropy of the system can contribute to this energy minimization. A system can be described by a group of coordinates, in this case to give a simplified idea assume a group of distance vectors $\lambda = (\vec{r}_1, \vec{r}_2, \dots, \vec{r}_{\mathcal{N}})$ from system origin. For an arbitrary λ the probability of a single particle of the system to statistically occupy that position is described by using a probability distribution function (Satoh, 2010):

$$\rho(\lambda) = \frac{\exp\left(-\frac{U(\lambda)}{kT}\right)}{\int_V \dots \int_V \exp\left(-\frac{U(\lambda)}{kT}\right) d\vec{r}_1 d\vec{r}_2 \dots d\vec{r}_{\mathcal{N}}} \quad (12)$$

Whether the system configuration is generated with considerable number of microstates that satisfies this probability, the final configuration would have a real physical meaning. But, as soon as it is almost impossible to define an analytical solution to this equation if \mathcal{N} is too large another method became necessary to use Monte Carlo simulations in molecular dynamics. The Metropolis method (Metropolis, Rosenbluth, Rosenbluth, Teller, & Teller, 1953) allowed the use of Monte Carlo technique by introducing the following concept: given 2 different microstates, the probability to change from state 1 to 2 is defined by:

$$P_{1 \leftrightarrow 2} = \begin{cases} 1 & \text{for } \frac{\rho(\lambda_2)}{\rho(\lambda_1)} \geq 1 \\ \frac{\rho(\lambda_2)}{\rho(\lambda_1)} & \text{for } \frac{\rho(\lambda_2)}{\rho(\lambda_1)} < 1 \end{cases} \quad (13)$$

Therefore, the integral term in eq.(12) vanishes and it is clear to observe that when $U(\lambda_1) \geq U(\lambda_2)$ the system will certainly change to this new microstate since it has lower energy, however in the case of $U(\lambda_1) < U(\lambda_2)$ the system has a certain probability of changing to this new microstate indicating an increase of entropy in the system. So, by applying stochastic inputs for particle displacements and acceptance values for eq.(13), with a large number of Monte Carlo steps the system will eventually reach a minimum in free energy. Moreover, when this system reaches equilibrium it is possible to calculate accurately microstate dependent properties via ensemble averages. That means with n samples of Monte Carlo steps, the average of a ξ property can be obtained by:

$$\langle \xi \rangle = \sum_{i=1}^n \frac{\xi_i}{n} \quad (14)$$

It is important to notice that Monte Carlo simulations do not consider dynamic properties of the system such as kinetic energy, and therefore only Molecular Dynamics can account such things(Satoh, 2010). Finally, now that both molecular simulation methods had been properly introduced it is possible to proceed to an overview of both simulation software used on this project. Together they can unite the benefits of both simulation methods, in order to recreate a suitable coarse-grain model for Molecular Dynamics.

4.2 Software Description

4.2.1 About GROMACS

GROMACS (**G**roningen **M**achine for **C**hemical **S**imulations) (van der Spoel et al., 2013) is a Molecular Dynamics and energy minimization software created at the University of Groningen (the Netherlands), and currently has been developed and updated by Royal Institute of Technology and Uppsala University (Sweden). GROMACS is a widely used tool in the branch of computational chemistry because it is flexible and efficient. Its flexibility comes from the capacity of simulating multiscale molecular models, from atomistic to mesoscale depending on topology described by the user. The efficiency originates from the computational optimisation, by this meaning not only that GROMACS can achieve impressive simulation speed in large system using supercomputing or clusters, but also it can run small simulations in any ordinary computers with great performance.

In order to interpret interatomic interactions, that means forces between each pair of atoms, GROMACS uses pre-defined parameters called Topologies in which the user can describe almost any molecule using force fields or tabulated potentials. Data given in this description includes information regarding atoms' type, mass and charge. Furthermore, it includes detailed description of each angle and dihedral for the molecule. There are several Force-fields available for usage depending on the desired objective of the simulation, their role is to be a database that describes interactions potential, hence their applicability is suitable to almost any system from all-atoms to coarse-grain descriptions it is just necessary for the user to describe a realistic model.

When dealing of simulations of complex systems, realism means more computational power expended trying to achieve it(Satoh, 2010), therefore a major concern is how to achieve longer time horizons without loosing precision. A good example is the Lennard-Jones potential for Van der Waals forces, used by OPLS-AA Force-field (Jorgensen, Maxwell, & Tirado-Rives, 1996), which is the one chosen for all-atomic simulations in this project. This type of potential approximation for a given atom i in relation to atom j is defined simply by two parameters ϵ and σ as it can be seen in Eq.15:

$$U_{LJ}(r_{ij}) = 4\epsilon_{ij} \left(\left(\frac{\sigma_{ij}}{r_{ij}} \right)^{12} - \left(\frac{\sigma_{ij}}{r_{ij}} \right)^6 \right) \quad (15)$$

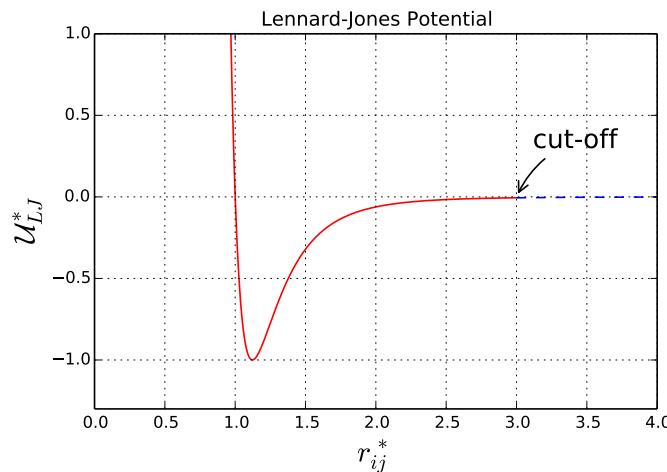


Figure 1: Example of Lennard-Jones Potential(with reduced units)

Where the forces used in Molecular Dynamics equations come from derivative of this potential for each pair of particles:

$$\vec{F}_{ij} = \nabla \mathcal{U}_{LJ}(r_{ij}) = \left(\frac{\partial \mathcal{U}_{LJ}(r_{ij})}{\partial x} \hat{x} + \frac{\partial \mathcal{U}_{LJ}(r_{ij})}{\partial y} \hat{y} + \frac{\partial \mathcal{U}_{LJ}(r_{ij})}{\partial z} \hat{z} \right) \quad (16)$$

For every simulation time-step, GROMACS recalculates bonded potentials from Topology, and non-bonded potentials from the summation of Lennard-Jones and short-range Coulomb potentials. As shown in Fig.(1) whether $r_{ij} \rightarrow \infty \Rightarrow \mathcal{U}_{LJ} \rightarrow 0$ and a similar behaviour occurs for Coulomb forces. Hence, GROMACS generates a neighbour list of atoms determined by a cut-off radius for each particle, by this means avoiding having to spend a lot of computational power calculating numbers with negligible value. Moreover, this feature allows the use of periodic boundary conditions that recreates a continuous media environment for simulation boxes bigger than two times the cut-off radius, since particles can not interact with itself.

Although speed efficiency is a concern it is not only the unique preoccupation, it is also necessary to control environment variables such as temperature and pressure, in order to maintain the simulation within physical limits and that demands computational resources. GROMACS is capable of using three types of thermostat which are Berendsen ,v-rescaling and Nosé-Hoover and three types of barostat Berendsen, Parrinello-Rahman and MTTK (van der Spoel et al., 2013). Furthermore, other computational expensive technique is the use of Particle-mesh Ewald (PME) summation method to deal with long-range electrostatic interactions, which is indispensable in ionic environments. All these tools makes GROMACS not only fast but also reliable for Molecular Dynamics simulation, and for this reason the aim of this project is to demonstrate the capacity of this software to simulate realistic multi-scale molecular models.

4.2.2 About MagiC

MagiC is software package developed by Mirzoev and Lyubartsev (2013), which is a systematic method to generate coarse-grain models from all-atomic simulations using Iterative Boltzmann Inversion (IBI) and Inverse Monte Carlo (IMC). As described in Fig.(2) method consists in a three step process, where the input is the trajectory file of an equilibrated all-atoms simulation from GROMACS, and outputs are a set of tabulated potentials and a Topology for a coarse-grained model that uses these potentials to run Molecular Dynamics simulations using GROMACS.

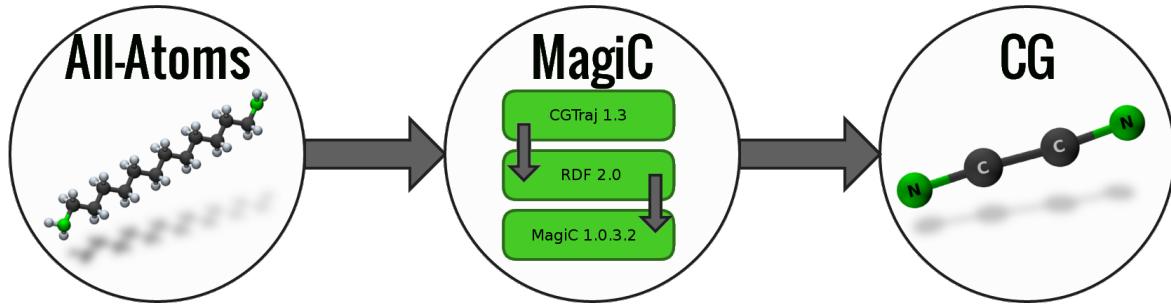


Figure 2: MagiC

The first step uses "CGtraj 1.3" (MagiC package utility written in Fortran 90) (Mirzoev & Lyubartsev, 2014a), where the trajectory of the all-atoms simulation is recalculated based on a bead mapping described by the user. Basically, it analyses the group of atoms in each bead and assign the position of this bead as the center of mass, charge as summation of all charges and mass as summation of atomic masses, thus giving as output a representation of the input system as if it was an "ideal" coarse-grain model. Next, this rewritten trajectory is used as input to rdf-2.0 (MagiC package utility written in Python) (Mirzoev & Lyubartsev, 2014a), where several reference Radial Distributions Functions are created for each bond, angle and pairwise intermolecular interaction, as specified by user. These reference RDFs in conjunction with the coarse-grain topology are the inputs to the MagiC kernel (MagiC package utility written in Fortran 90) (Mirzoev & Lyubartsev, 2014a), which is the key step of the process, where the final output might be a suitable coarse-grain model ready for GROMACS simulation.

In the kernel is where the actual inversion processes occurs, as schematised in Fig.(3). Whether using IMC or IBI, a couple of millions of Metropolis Monte Carlo steps are simulated using a set of trial potentials to create several samples of averaged thermodynamics properties. Then, these averages are applied in the equations of the chosen inversion method in order to refine the trial potentials that will be used on the next inversion step.

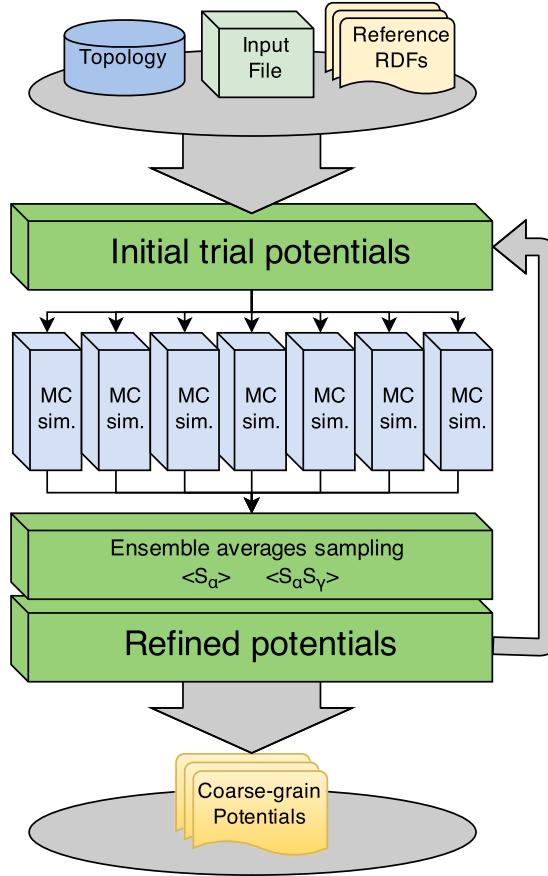


Figure 3: MagiC kernel work-flow scheme

The Iterative Boltzmann Inversion is a reasonable methodology to apply in the initials iterations, since it has fast convergence. The process derives from probability distribution function (Eq.(12)), thus for a pairwise particle interaction, the relationship between the reference RDF and Potential Mean Force (PMF) enables the use of an iterative method shown in Eq.(17) (Moore, Iacobella, & McCabe, 2014):

$$\mathcal{U}^{(i+1)}(r) = \mathcal{U}^{(i)}(r) - \eta k_B T \ln \left(\frac{\rho^{(i)}(r)}{\rho_{ref}(r)} \right) \quad (17)$$

Where η is a regulation parameter to avoid excessive variations. For a system in a canonical ensemble, temperature will be constant, hence the potential is corrected for each iteration using the $\rho_{ref}(r)$ calculated from reference RDF in comparison to $\rho^{(i)}(r)$ from RDF generated by Metropolis Monte Carlo simulation. Although this method is efficient to achieve small deviance from references, it does not guarantee that the generated potential represents one that will reproduce a behaviour similar to atomistic model because IBI does not consider cross-correlation terms between bonds and angles (Mirzoev & Lyubartsev, 2013).

Regarding the Inversion Monte Carlo process, it follows the methodology described by Lyubartsev and Laaksonen (1995). Given a Hamiltonian, that means the total energy of the system:

$$\mathcal{H}(q) = \int \mathcal{U}_\alpha \mathcal{S}_\alpha(q) d\alpha \quad (18)$$

For pair interactions, the degree of freedom q in Eq.(18) becomes the distance r between a pair of atoms. Therefore, for a real system the Hamiltonian would be the summation of an infinite set of

\mathcal{U}_α . However, a good approximation for numerical methods is to assume a cut-off radius r_{cut} , where potentials no longer have relevant value after this point. One can define a $\Delta r = \frac{r_{\text{cut}}}{M}$, obtaining M subdivisions and thus a finite set of \mathcal{U}_α in which S_α is the number of pairs within interval $[r_\alpha, (r_\alpha + \Delta r)]$. Since S_α is function of \mathcal{U} , one can derive the following Taylor expansion:

$$\Delta \langle S_\alpha \rangle = \sum_{\phi=\alpha}^M \frac{\partial \langle S_\alpha \rangle}{\partial U_\phi} \Delta U_\phi + \mathcal{O}(\Delta U_\phi^2) \quad (19)$$

$$\frac{\partial \langle S_\alpha \rangle}{\partial U_\phi} = \frac{\langle S_\alpha \rangle \langle S_\phi \rangle - \langle S_\alpha S_\phi \rangle}{k_B T} \quad (20)$$

For each inversion step k , Monte Carlos simulations are run using a set of potentials $\mathcal{U}_\alpha^{(k)}$, then as explained previously it is possible to calculate ensemble averages of the cross-correlation terms $\langle S_\alpha S_\phi \rangle^{(k)}$ and averages $\langle S_\alpha \rangle^{(k)}, \langle S_\phi \rangle^{(k)}$. At this point, the reference RDFs becomes useful for inverse Monte Carlo. Since this method deals with pairwise interactions the value of S_α and $\rho(r)$ are directly proportional following the rule $S_\alpha^* = \rho(r_\alpha) \Delta r$ (Mirzoev & Lyubartsev, 2013) because both measure the quantity of one type of coarse-grain bead in relation to another. Hence, by using $\Delta \langle S_\alpha \rangle = \langle S_\alpha \rangle^{(k)} - S_\alpha^*$ in conjunction with Eq.(19) and Eq.(20) and neglecting the error $\mathcal{O}(\Delta U^2)$ the potential correction for next step $\Delta U_\alpha^{(k)}$ can be obtained and finally potentials are updated using the following equation:

$$U_\alpha^{(k+1)} = U_\alpha^{(k)} + \Delta U_\alpha^{(k)} \quad (21)$$

Both of the previous methods described rely on a considerably large mount of Monte Carlo simulation steps. That is due to the fact that the closer the set of potentials gets to solution the harder it becomes to distinguish between statistical noise and a suitable potential correction. For his reason, MagiC has a built-in capacity of running parallel Monte Carlo simulation as it an be see on Fig.(3), which which enable the user to reach the order of billions of simulation steps in a feasible timespan. Moreover, there is not an unique solution for a given RDF (Moore et al., 2014) and eventually solution can possible diverge at a certain point. Therefore, a satisfactory result depend on analysis of all outputs from inverse steps in order to guarantee convergence. Further explanations regarding functionalities and parameters for MagiC and GROMACS will be provided the next section.

5 Methods Description

5.1 GROMACS All-Atom simulations

The experimental process of this project is divided in 3 main parts: Firstly, develop a efficient coarse-grain model and validate its use. Secondly, analyse the relationship between concentration of all-atoms simulation and concentration of coarse-grained simulation. Then finally, create and reproduce a Silica surfactant mesoscale system.

In order to maintain standard parameters for all GROMACS simulations, all-atoms simulations that were used for coarse-grained reference were run in NPT ensemble. All simulation boxes were created using genbox (GROMACS package utility), first by inserting the desired number of surfactant molecules and then adding the solvent at the adequate ratio. The molecules were designed based on OPLS-AA forcefield (Jorgensen et al., 1996) parameters. The surfactant DMDD was created with aid of co-workers and water type was TIP4P (Jorgensen, Chandrasekhar, Madura, Impey, & Klein, 1983). Moreover, no initial configuration was determined, such as a pre self-assembled system, to ensure stochastic nature of the system.

Initially, all boxes received a energy minimization step in order to avoid system blow-up deal to possible extreme potential energy spots created during box generation. That is because during random displacement of molecules some of them could overlap others and then cause a destabilization of the system. After, an equilibration step was necessary to reach desired initial temperature and pressure conditions for the MD simulation. During equilibration temperature coupling was kept at 298 K using a v-rescaling thermostat (?, ?) with time constant of 0.01 ps and pressure coupling was kept at 1 bar using a Berendsen barostat (?, ?) with time constant of 0.5 ps. The simulation was run for 200 ps with time step of 0.5 fs using leap-frog algorithm.

Regarding the concentration of surfactant in each box, four all-atom boxes were created with composition and size described in Table (1).

Table 1: Description of all-atom simulation boxes

Box	DMDD (no. Molec.)	Water (no. Molec.)	Silica (no. Molec.)	Avg. size (Å)	Concentration (mM)
B1	30	1500	-	38.2646	0.89
B2	30	670	-	31.3201	1.62
B3	45 ^a	240	-	28.2972	3.30
B4	30	670	30	???	???

^a Necessary change, otherwise box size would be too small for the experiments, however concentration is the same as a 30-160 box.

The utility of each box will be described further in each experiment section. Even though they have different structural parameters, all of them followed the same ensemble with temperature kept at 298 K by a Nosé-Hoover thermostat (?, ?) and pressure kept at 1 bar by a Parrinello-Rahman barostat (?, ?). Moreover, simulation time was also standardized. Every simulation lasted 350 ns with a time step of 1 fs using leap-frog algorithm. But for the sake of experiments using MagiC, the first 50 ns of the simulations were disregarded because during this time the system still in equilibration, and therefore that would affect reference RDF values.

5.2 Experiment 1: Model Creation

Since the main objective of this project is to probe the effectiveness of coarse-grain models generated using MagiC, this first experiment is an attempt to understand and analyse to what extent bead size influence on the process of coarse-graining. Hence, two models were proposed: Model 1 (M1) described in Fig.(4) and Model 2 (M2) described in Fig. (5).

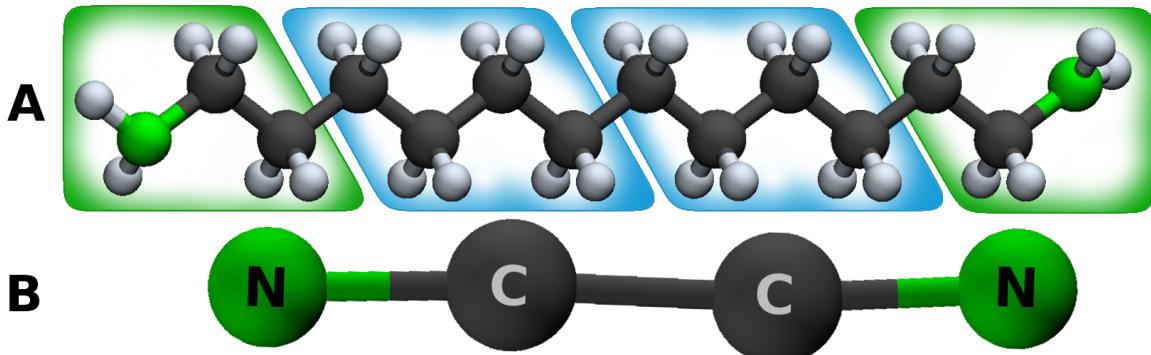


Figure 4: A) Schematic of M1 molecule split plan, Carbon atoms represented in black, Nitrogen in green and Hydrogen in gray. B)Final coarse-grain model for M1. This model aggregated the three most polar heavy atoms on the tips and four apolar heavy atoms at the center.

The differences between M1 and M2 are an effort to distinguish at different level of detail the amphiphilic nature of the DMDD. In order to avoid electrostatic interactions on the IMC process and further GROMACS simulations, the heavy atom groups (heavy atom + hydrogen) were kept together, thus final charge remain neutral in each bead. Hence, forces will only arise from Van der Waals interactions and implications of inverse process might originate from degrees of freedom deal to number of beads. The All-Atom simulation box chosen for this experiment was B1, because at this experiment concentration of reference was not a major concern, more information regarding this point is given at Experiment 2 (see Section 6.3)

In order to fully describe the system, MagiC generates potential tables for interaction between each bead. The first type of table are for each bond type, for example on M1, there are two different tables: one for N-C bond and other for C-C bond. However, as soon as the molecule is symmetric the two external N-C bonds uses the same potential table. Secondly, it generates tables for each angle type, following the symmetry rule. And finally, each type interatomic pair interaction has its own table, i.e. on M1 there are three: N-N, N-C and C-C. A more detailed description for both models is exposed in Table (2).

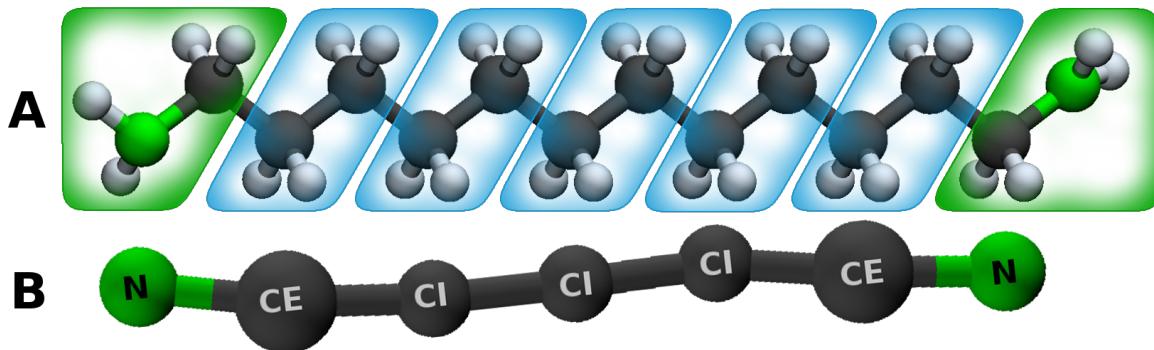


Figure 5: A) Schematic of M2 molecule split plan, Carbon atoms represented in black, Nitrogen in green and Hydrogen in gray. B)Final coarse-grain model for M2. Heavy atom were grouped pairwise in such a manner that amphiphilic parts were kept as distinct as possible. It is important to notice the necessity of two carbon bead types CE and CI

Table 2: Description of coarse-grain models

	Bonds	Angles	Interatomic
Model 1	[N-C] [C-C]	[N- \widehat{C} -C]	[N-N] [N-C] [C-C]
Model 2	[N-CE] [CE-CI] [CI-CI]	[N- \widehat{CE} -CI] [CE- \widehat{CI} -CI] [CI- \widehat{CI} -CI]	[N-N] [N-CE] [N-Cl] [CE-CE] [CE-Cl] [Cl-Cl]

During the usage of MagiC package, the model description begun at the "CGtraj" step, where not only the bead types for the model were described, but also which atoms would be inside each bead. These informations must be part of input file of "CGtraj", following the strict guidelines of MagiC Manual (Mirzoev & Lyubartsev, 2014a). In addition, it was at this moment that occurred the determination of implicit water condition, therefore during the recalculation of trajectories the water molecules were removed from the box. At the second step is where bonds, angles, and interatomic interactions were described in the input file for "rdf-2.0" utility, following as well MagiC Manual guidelines (Mirzoev & Lyubartsev, 2014a). That is because at this point MagiC generated reference RDF's used in inversion process for each potential table. Additional information regarding model description in input files for M1 and M2 can be found on Appendix (see Section 10).

Once reference RDFs and a Topology were specified the inversion step started. The parameters of each inversion step were based on work done by Mirzoev and Lyubartsev (2014b), in which similarly to this project also analyses the self-assembly of amphiphilic molecules. Nevertheless, considering that DMDD owns a much less complex molecular structure, the number of Monte Carlo simulation steps were considerably modified for each model. The simulations were run in parallel using up to 24 cores. Table (5.2) exposes the specific number of steps per core and whether it used IBI or IMC method for inversion. The ensemble averages were calculated every 1000 Monte Carlo steps, after equilibration. Since the water is implicit, the dielectric constant for Monte Carlo simulations was set to experimental dielectric constant of water at 298 K and 1 bar which is $\epsilon = 78$ (? , ?).

After each inversion step MagiC generates RDF based on ensemble averages calculated during Monte Carlo simulations and then it calculates the deviance between reference RDFs and inversion RDFs. When the deviance reached the desired convergence value, the potentials and topology were exported to GROMACS format. In order to compare both models to the atomistic model, a reproduction test was done using the same parameters of all-atom boxes, with the exception of dielectric constant that was changed to $\epsilon = 78$ and specification of each potential table required for GROMACS Simulation. Furthermore, since the charges of all beads is null, PME long-range electrostatics were replaced by cut-off scheme which increased simulation speed and cut-off was increased to $R_{cut} = 1.8 \text{ nm}$. An example of reproduction test input parameters can be found on Appendix (see Section 10).

Finally regarding up-scaling tests, all simulations were made with the same machine using up to 8 MPI threads, depending on the size of the system. All values were obtained from the prediction made by "mdrun" (GROMACS package utility) (van der Spoel et al., 2013), which provides an estimated

Table 3: Inversion Process description for M1 and M2

	N_{Inv}	10	10	10	5		
M1	Method	IBI	IMC	IMC	IMC		
	N_{Cores}	8	8	8	8		
	N_{MCe}	3000000	3750000	5625000	7500000		
	N_{MC}	12000000	15000000	22500000	30000000		
	N_{Avg}	72000	90000	135000	180000		
M2	N_{Inv}	10	10	10	5	5	14
	Method	IBI	IMC	IMC	IMC	IMC	IMC
	N_{Cores}	24	24	24	24	24	24
	N_{MCe}	1000000	10000000	20000000	30000000	40000000	30000000
	N_{MC}	4000000	30000000	60000000	90000000	120000000	250000000
	N_{Avg}	72000	480000	960000	1440000	1920000	5280000

average of simulation speed, however it is important to consider that it may vary throughout the whole simulation. The simulation parameters were the same as the reproduction tests, however now the simulations were run using a higher timestep of 20 fs for M1 and 10 fs for M2.

5.3 Experiment 2: Concentration Analysis

Subsequently, this second experiment has two main objectives, both related to concentration of DMDD in the system. The former objective is focused mainly on influence of concentration variations over the inverse steps, that means how the complexity of the self-assembly structure affects convergence during IBI and IMC. The latter objective is to understand the relationship between the variation of DMDD concentration in the all-atom reference system and its effects in the self-assembly behaviour of the coarse-grain model chosen. Moreover, it will be an attempt to confirm the assumption that implicit water coarse-grain models can assume multiple concentrations, independently of the concentration chosen in the all-atoms reference.

This assumption derives from the concept that implicit water models can only assume an NVT ensemble, because due to the absence of solvent, pressure has no physical meaning in these systems. It is supposed that the entropy from free energy (see Eq.(11)) that comes partially from solvent interaction is lumped into the potential obtained using the inversion process. However, differently from temperature it is yet clear to what extent concentration has influence over entropy. Hence, in this case just by varying the size of simulation box, the implicit water system should approximately behave as if it was on a different concentration.

The experiment begins with the development of two new coarse-grain models based on M1 from the previous experiment. However, at this moment the all-atoms box's concentrations were increased to $C_{B2} = 1.62 \text{ mM}$ and $C_{B3} = 3.30 \text{ mM}$, thus the Intermediate Concentration Model (M_I) and High Concentration Model (M_H) were created based on those concentrations respectively. Furthermore, for this experiment, M1 which has the lowest concentration will now be denominated as Low Concentration Model (M_L).

A complete description regarding the Inversion process for both latter models is given in Table (4), showing the peculiarities of each one. To be more specific, in order to evaluate the efficiency of inversion method for different concentrations, M_I followed almost the same process as like M_L with the exception of number inverse steps and Monte Carlo simulations. But, in the other hand, M_H had two modifications: the former was the inclusion of a higher number of DMDD molecules in the simulation box and the latter was a new technique adopted to optimize the Inversion process. The first alteration was an inevitable consequence of the increasing concentration, because otherwise the number of molecules in the all-atom box would not be enough to fulfil the minimum requirements of box size to the adopted cut-off radius $R_{cut} = 1.3 \text{ nm}$. The second alteration in the process of model creation was on the initial phase of inversion, because instead of using IBI to approximate suitable initial trial potentials, we used as a basis the final potential obtained for M_L . Further explanations regarding this technique are shown in the Results and Discussion section (See Section 6.3.1).

After, with the three models, a comparison test was made in order to observe whether the systems behave similarly with the same box size, that means concentration. Nevertheless, since the surfactant self-assembly simulations were using coarse-grained models, the system had been up-scaled. Each simulation box contained 1000 molecules of Coarse-grained DMDD and the size of the box's edge was

Table 4: Inversion Process description for M_I and M_H

M_I	N_{Inv}	10	10	10	5	10	5	5	5	9
	Method	IBI	IMC	IMC	IMC	IMC	IMC	IMC	IMC	IMC
	N_{Cores}	24	24	24	24	24	24	24	24	24
	N_{MCe}	1000000	1250000	1875000	2500000	10000000	20000000	30000000	40000000	50000000
	N_{MC}	4000000	5000000	7500000	10000000	30000000	60000000	80000000	100000000	150000000
	N_{Avg}	72000	90000	135000	180000	480000	960000	1200000	1440000	2400000

M_H	N_{Inv}	(No IBI) Initial trial potentials extracted from M1	10	10	5	10	3
	Method		IMC	IMC	IMC	IMC	IMC
	N_{Cores}		8	8	8	8	8
	N_{MCe}		10000000	20000000	30000000	33000000	40000000
	N_{MC}		30000000	60000000	90000000	100000000	120000000
	N_{Avg}		160000	320000	480000	536000	640000

determined by rescaling average box size from Table (1) using the following equation:

$$L_{CG} = \sqrt[3]{\frac{N_{CG} L_{AA}^3}{N_{AA}}} \quad (22)$$

where N is number of molecule and L is the edge side. Full description of all nine simulation boxes is given in Table (5). All simulation parameters were exactly the same as used in Experiment 1 up-scaling simulations, but now the simulations were run until the moment that self-assembly structure had appeared to achieve a stable configuration.

Table 5: Description of coarse-grain simulation boxes

Box	$B_{L@L}$	$B_{I@L}$	$B_{H@L}$	$B_{L@I}$	$B_{I@I}$	$B_{H@I}$	$B_{L@H}$	$B_{I@H}$	$B_{H@H}$
Model	M_L	M_I	M_H	M_L	M_I	M_H	M_L	M_I	M_H
Size (nm)	12.3147	12.3147	12.3147	10.08	10.08	10.08	7.9556	7.9556	7.9556
Concentration (mM)	0.89	0.89	0.89	1.62	1.62	1.62	3.30	3.30	3.30
Time (ns)									

6 Results and Discussion

6.1 GROMACS simulations

Regarding the All-Atom simulations, it is interesting to highlight the different types of self-assembled structures obtained in each concentration, all of them having its own observable peculiarities. In order to obtain a cohesive comparison basis between themselves and their coarse-grain models, each one of the simulation boxes received its characterization based on their periodicity and Radial Distribution Function.

As a initial approach, a qualitative evaluation of the simulations is provided in Fig.(6). With the aid of periodic replicas, this image reveals that only at a high concentration (6c) it became possible to form a complete layer in all periodic directions. Contrastingly, the other two boxes only showed periodicity in one of the directions, perpendicular the normal vector of the formed layer. Concerning the dynamic behaviour of both systems, it is observable that this structure remain stable during all simulation and the layer kept constantly rotating around the periodic axis, although meanwhile the high concentration layer seldom presented any rotation.

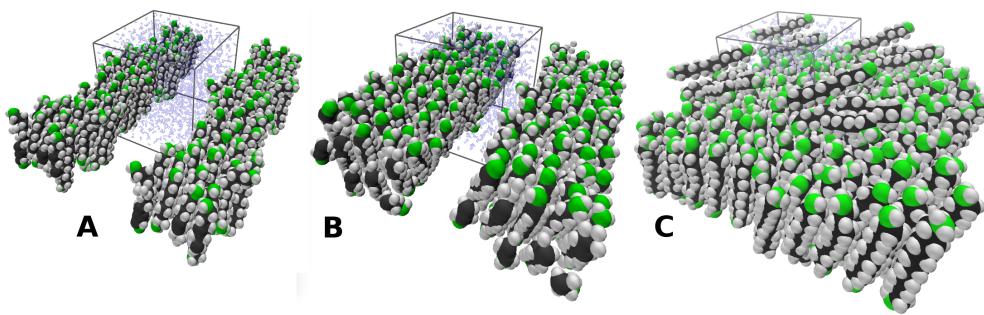


Figure 6: Snapshot of simulation boxes with periodic replicas. a) box at low concentration (B1), b) box intermediate concentration (B2) and c) box at high concentration (B3). The original images are the ones located inside the grid box surrounded by water. Nitrogen atoms are represented in green, Carbon in black, Hydrogen in gray and water molecules in transparent blue.

Next, another characteristic of the system is the Radial Distribution Function. The RDF of N-N interactions are a great representatives of the system because the N atoms, which are the polar heads, can provide informations about the position of each molecule in relation their neighbours. In this case, as it can be seen in Fig.(7), the RDFs of all boxes are similar since the aggregation phenomena inquires that proximity between polar and apolar parts, remains at a distance where free energy is the lowest. The different values to the peaks, does not means that there are more N heads within a given radius. This value varies according to the bulk density of the box because the RDF values are normalized, that means a higher concentration implies in a higher number of atoms within a given range therefore, a lower normalized peak.

As a final consideration, it is possible to observe that the peaks of the high concentration box are located in a slightly distinct position, and that may be a consequence of the lack of space inside the box. Moreover it seems that there is an ideal concentration between Intermediate and High concentration where one complete periodic layer should be formed without leftover molecules. A single layer is the desirable configuration since in a real system seldom will present any non-aggregated molecule. Therefore, for future experiments including silica this concentration will be adopted.

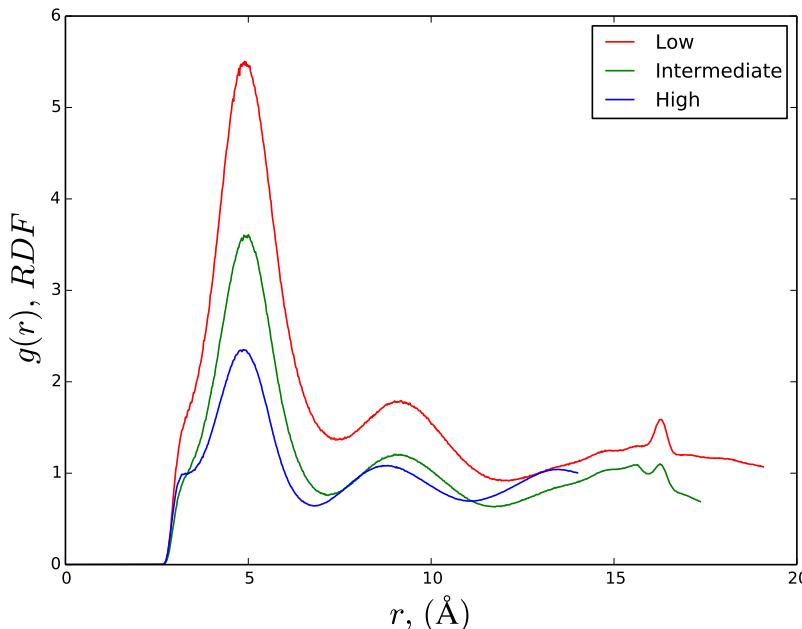


Figure 7: Radial distribution function between N-N atoms.

6.2 Experiment 1: Model Creation

6.2.1 Convergence Analysis

The Coarse-grain method adopted in this project rely deeply on visual and numerical analysis of the convergence during Inversion process. For all experiments each inversion step was validated by comparing it with previous steps and with the behaviour observed in atomistic simulations. There is not any guarantee that the set of potentials generated after each step will necessarily reproduce a physically meaningful system. That is because these potentials are made to reproduce the RDF obtained after inversion, and since the configuration of the system is a probabilistic event there is more than one way to represent a given RDF. Therefore, the smaller the deviation from reference RDFs, the greater the odds that the potential set will reproduce a behaviour with acceptable reliability. A good example of this phenomena in shown in Fig.(8) were the deviance between reference RDF and Reproduction test RDF is numerically low, however it is very clear visually that the system is not reflecting the expected result. After extensive trials with all models, it was verified that an acceptable value for deviances was any sum below 0.025. In order to proceed beneath this amount, it would require an excessive number of Monte Carlo simulations which might be unnecessary, since at this levels all models reproduced plausible results. Hence, before focusing on the analysis of the final coarse-grain model it is important to make an overview upon the whole Inversion process for both models.

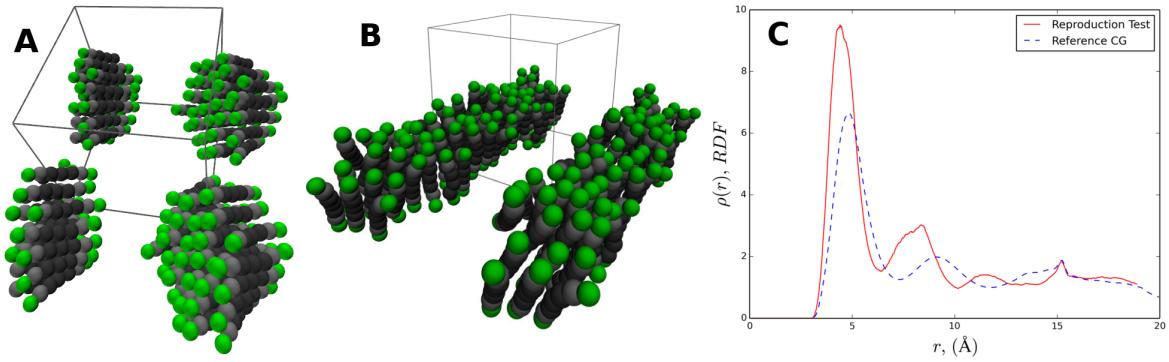


Figure 8: Demonstration of a qualitative evaluation of convergence based on comparison between expected result and trial simulation. A) Snapshot of a equilibrium state after a long simulation time using M2 with poorly converged potentials B) Reference Coarse-grain from CGtraj. Periodic replicas are provided to improve visualization. C) RDFs representing each system (Deviance = 0.52504)

Starting with M1, it is possible to observe in Fig.(9) that the process was very smooth. Both graphics refers to N-N head interactions which as explained provides a good representation of DMDD behaviour. The trial potentials generated after each iteration went directly to a specific region, therefore meaning that the desired curve should be located somewhere within that area. The deviation graph provided a numerical basis to predict if it was necessary to increase the number of Monte Carlo steps. The sign for that was whenever the error fluctuation started to drift around a certain value, meaning that potential conversion had been affected by statistical noise.

The RDF progression graph had shown a topical behaviour observed in all inversion processes, which is the presence of three distinct convergence phases. In M1's case, during the initial phase (under 13 steps) the RDF rapidly converged to a shape very similar to the reference, but looking at the potential curves it is clear that they were far from the final result. During the second phase (between 13 and 21 steps), the potential curves began to adopt the same aspect of the final curve, however the deviation increased or stagnated at a point whilst the RDF peaks and valleys became more sharp. Then finally the deviation suddenly started to decrease, consequently the RDFs and potentials began to converge to the desired region in a very slow pace. Even though for M1 these signs are not very clear, for other models such as M_1 this behaviour is well defined (See Section 6.3).

Subsequently, Fig. (10) presents a similar overview for M2. It is important to keep in mind that even though they have the same name, the N beads are completely different for each model. Therefore there are no similarities between those potential curves, nevertheless the RDFs should be similar because the center of mass of both beads are very near. A key feature of this model is that it was the one who required the largest amount of Monte Carlo simulations for the Inversion steps. Just as

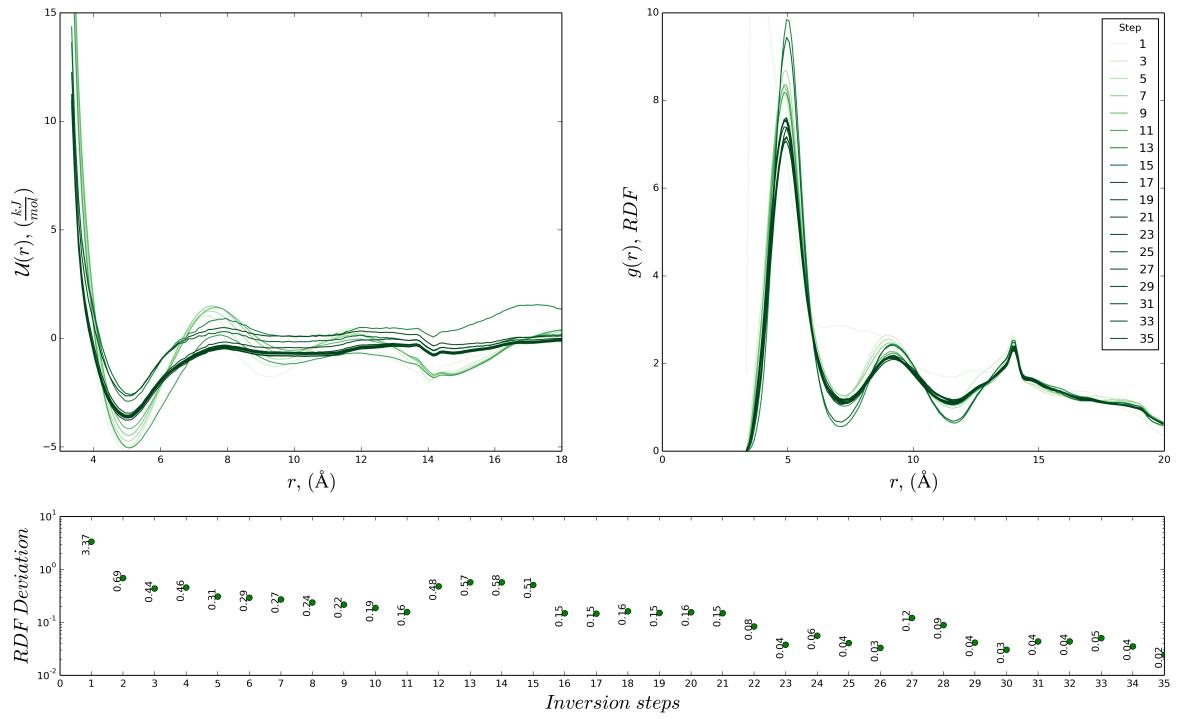


Figure 9: Graphical representation of the inversion process for M1. Graph 1 (top left) show potential progression at certain steps. Graph 2 (top right) show RDF progression at the same steps as the potential. Both graphs are representing N-N interactions and equal colors represent at the same step furthermore, the darker the line color the higher the step. Graph 3 (bottom) shows the root mean square deviation between reference RDF and RDF of a given step (for all interactions). Notice that this graph is using logarithmic scale.

shown in Table (5.2), some steps demanded over 6.4 billion steps in order to avoid statistical noise, thus taking a much longer time to reach errors at desired values.

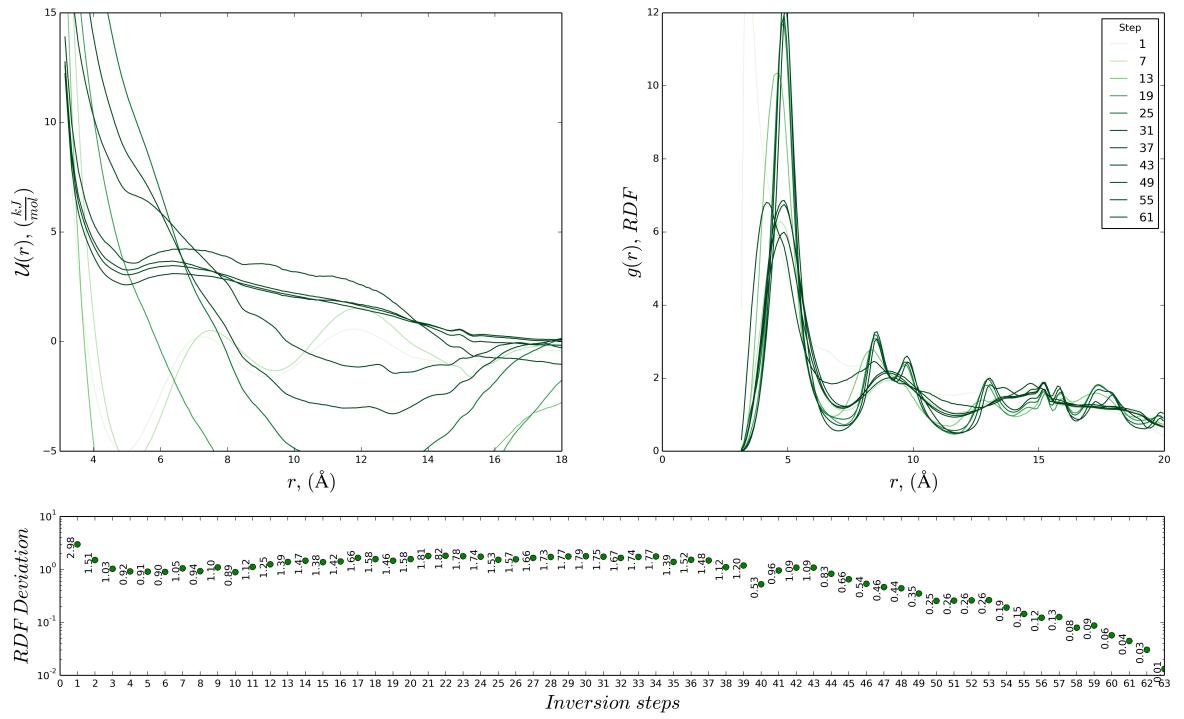


Figure 10: Graphical representation of the inversion process for M2. Graph 1 (top left) show potential progression at certain steps. Graph 2 (top right) show RDF progression at the same steps as the potential. Both graphs are representing N-N interactions and equal colors represent at the same step furthermore, the darker the line color the higher the step. Graph 3 (bottom) shows the root mean square deviation between reference RDF and RDF of a given step (for all interactions). Notice that this graph is using logarithmic scale.

Once again, three phases of convergence were present during the process, and at this time they are clearer to visualize graphically. The shape of the deviance curve reveals the first phase, where potential are far from convergence region, but the error is decreasing. Between steps 7 and 30 approximately, the deviance diverged considerably while potentials assumed a position within a characteristic region, indicating a phase two behaviour. Lastly, both graphics began to slowly converge to the final aspect until desired deviance value was reached.

6.2.2 Reproduction Tests

The efficiency of both models can be evaluated by making a side by side comparison between reproduction test results. Figures (11) and (12) promptly provide not only a quantitative, but also a qualitative validation both models' capacity of representing the atomistic system. It is important to notice that the RDFs should reproduce exactly the same RDF as the reference however, at some points they mismatch. This fact is directly related to two factors: level of convergence and cut-off radius adopted.

Firstly since M2 is a more detailed model, as expected the RDF aspect is more similar to the atomic RDF. Secondly as soon as the deviance for M1 is higher, the reproduction test RDF showed a greater disparity from reference principally for long-range interactions. Both simulations were run using a $R_{cut} = 1.8 \text{ nm}$. Then based those observations, for the level of convergence factor it is supposable that if M1 had had a lower deviance it would reproduce a finer result. However, it is not necessarily a general rule because coarse-grain models may loose information deal to the level of detail of the model. Even though it requires much more computational resources, adopting a finer model such as M2 might enable a lower deviance values, where as a more lumped model such as M1 could drift indefinitely through statistical noise. Nevertheless, the simulation boxes reveals that the layer formed in both cases are qualitatively similar, therefore the loss of detail in M1 is tolerable.

Regarding the influence of the cut-off radius, the simulation analysis using different Cut-offs in M2 demonstrated that long range interactions are important for coarse-grain models. Figure (13) provides

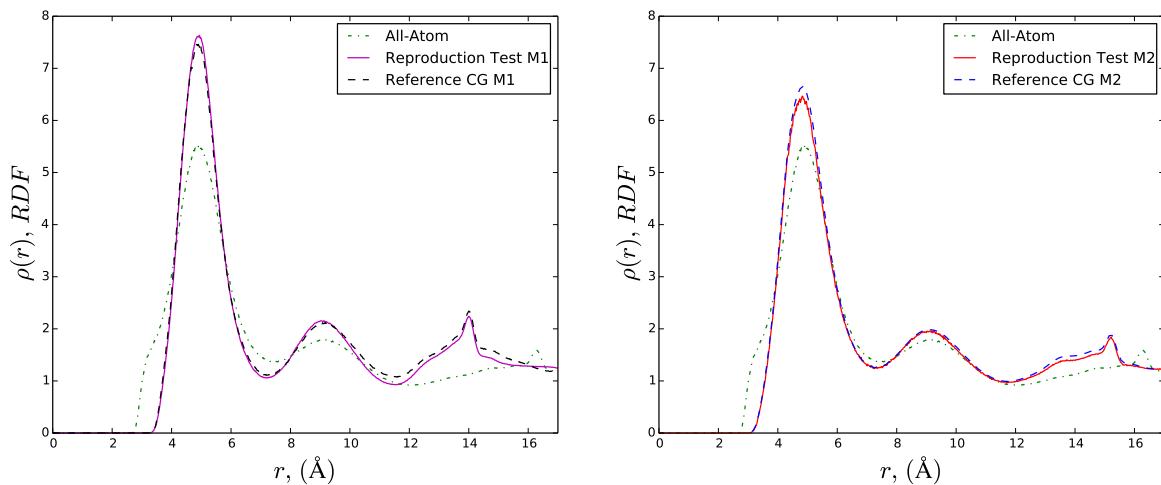


Figure 11: Radial distribution function between N-N beads/atoms. Left graph representing M1 and right graph representing M2

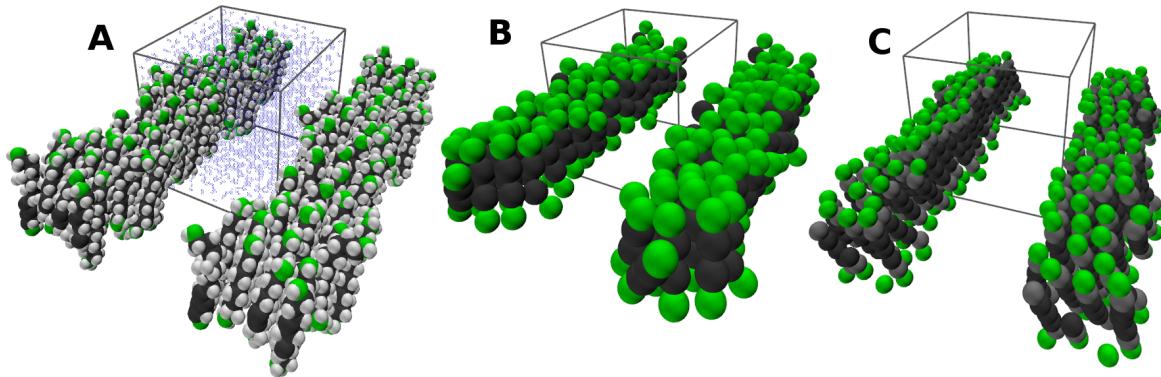


Figure 12: Snapshot of simulation boxes with periodic replicas. A) All-Atom reference at low concentration (B1), B) M1 reproduction test and c) M2 reproduction test.

a brief example about to what extent R_{cut} can influence the system's behaviour. Hence, differently from All-Atoms simulations long-range interatomic interactions carries a major responsibility regarding self-assembled structures, and the adoption of a short cut-off will cause loss of important information thus reproducing unrealistic results.

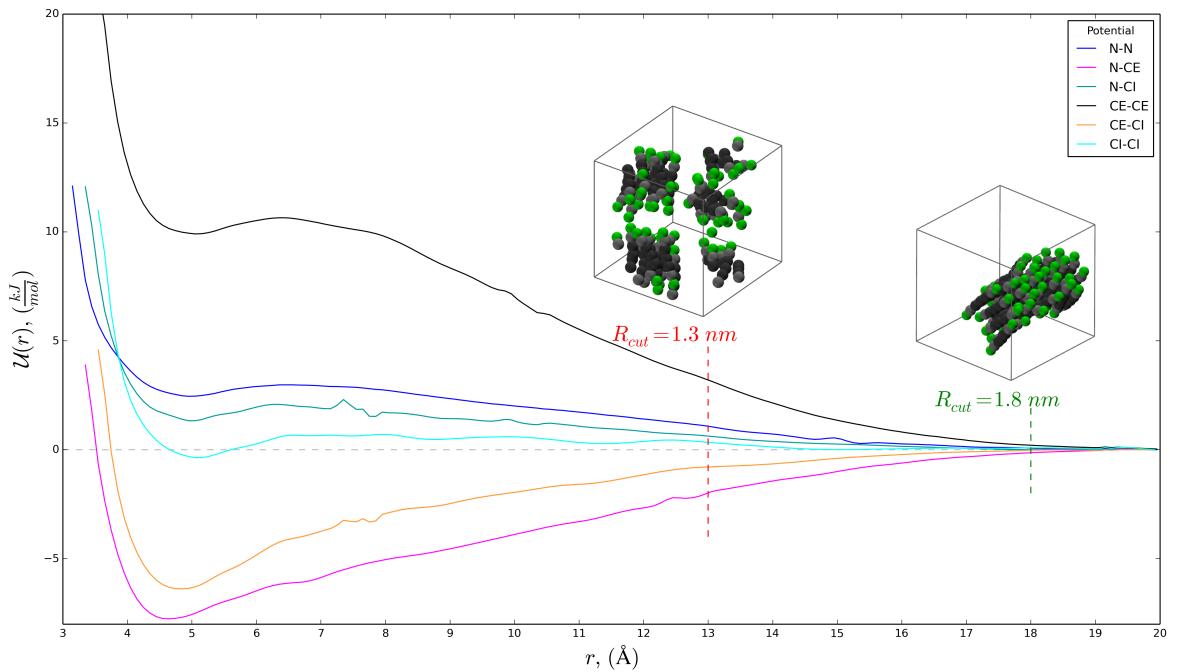


Figure 13: Graphical representation of the potential cut-off radius influence over simulation. Each box is using the respective cut-off. For the simulation any point after the dashed lines will be considered zero.

6.2.3 System up-scaling

A major concern for coarse-grain models is that even though they are made be a good approximation of atomic models, they should be designed in such a manner that the system can be up-scaled. Simulation speed and system size need to be optimized as much as possible without excessive information loss deal to lack of level of detail. In order to improve simulation performance, the time-step for each model was readjusted since it is related to the bond size. The movement of one bead in relation to its bonded pair must not exceed maximum bond distance. Therefore, a lower level of detail result in an increased bond size enabling the use of bigger time-steps. Both models proposed for this experiment were able to breed reasonable results from reproduction test, then the last criteria to evaluate which is the most suitable model are the up-scaling capacities. Table (6) shows a comparison of multiple system sizes and respective simulation speed.

Table 6: System up-scaling for M1 and M2

Number of Molecules	100	1000	5000	10000	20000
Simul. speed for M1	9086 ns/day	985 ns/day	235 ns/day	133 ns/day	67 ns/day
Simul. speed for M2	1458 ns/day	208 ns/day	62 ns/day	33 ns/day	15 ns/day

Decisively, M1 was the model chosen for further experiments since it seems to be in all cases much more efficient when up-scaling than M2. Although M2 is able to reproduce finer results, the error committed by using M1 can be neglected for the benefit of simulation speed. Moreover, the Inversion process presented a smoother behaviour requiring lesser amounts of Monte Carlo simulations.

6.3 Experiment 2: Concentration Analysis

6.3.1 Systematic Replication

A valuable advantage of using MagiC Coarse-grain method is that once a model is fully described it becomes simple to replicate it using different references. The systematic procedure uses the same structural description to recreate a new model. Nevertheless, minor changes still necessary in the input files for the tools such as, the number of molecules in the system (solvent and solute), trajectory files from the new All-atom simulation and modifications in simulation box size.

However, the experiment proposed in this section revealed that major differences emerged during the Inversion process. The use of higher concentrations of surfactant in the reference simulation increased drastically the computational effort to obtain the set of potentials. Beginning with M_I , by observing Figure (14) and crossing with data provided in Table (4), the previous statement is readily confirmed. Moreover, the three phase behaviour is very evident throughout the process. Another important fact is that during later steps even though the number of Monte Carlo simulations was increased greatly, the deviation remained drifting around a certain region. This could indicate that this model probably reached its maximum level of detail, thus hardly precision would get any higher.

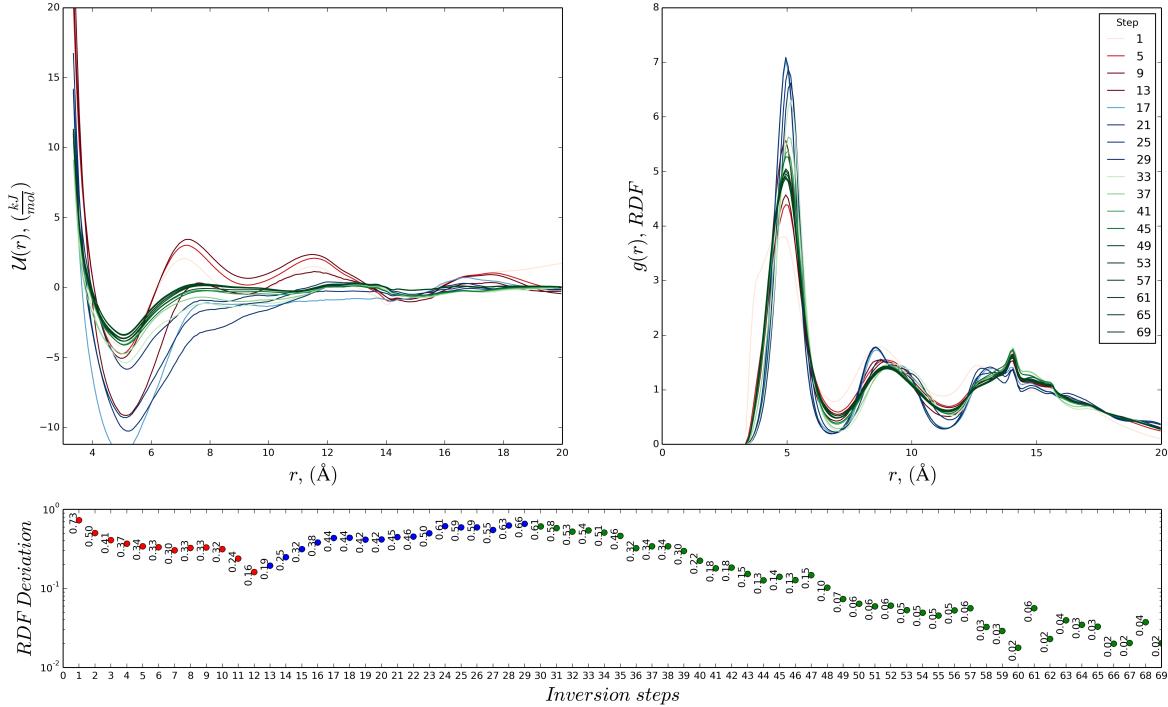


Figure 14: Graphical representation of the inversion process for M_I . Graph 1 (top left) show potential progression at certain steps. Graph 2 (top right) show RDF progression at the same steps as the potential. Both graphs are representing N-N interactions and equal colors represent at the same step furthermore, the darker the line color the higher the step. Red lines indicate phase one, blue lines indicate phase two and green lines indicate phase three. Graph 3 (bottom) shows the root mean square deviation between reference RDF and RDF of a given step (for all interactions). Notice that this graph is using logarithmic scale.

In the case of the high concentration model, the increased complexity demanded modifications to standard procedure because, even with numerous attempts, the Inversion process for M_H model kept diverging indefinitely during phase two. By comparing potential plots of M_L and M_I , it is possible to assume that potential for M_H should be located within the same region. Hence, by setting the initial trial potentials for M_H as being the final potentials of M_L the Inversion process simply skipped phase one and jumped directly to a convergent phase two. As demonstrated in Figure (15), the whole process was considerably smooth and seldom the deviance strayed significantly.

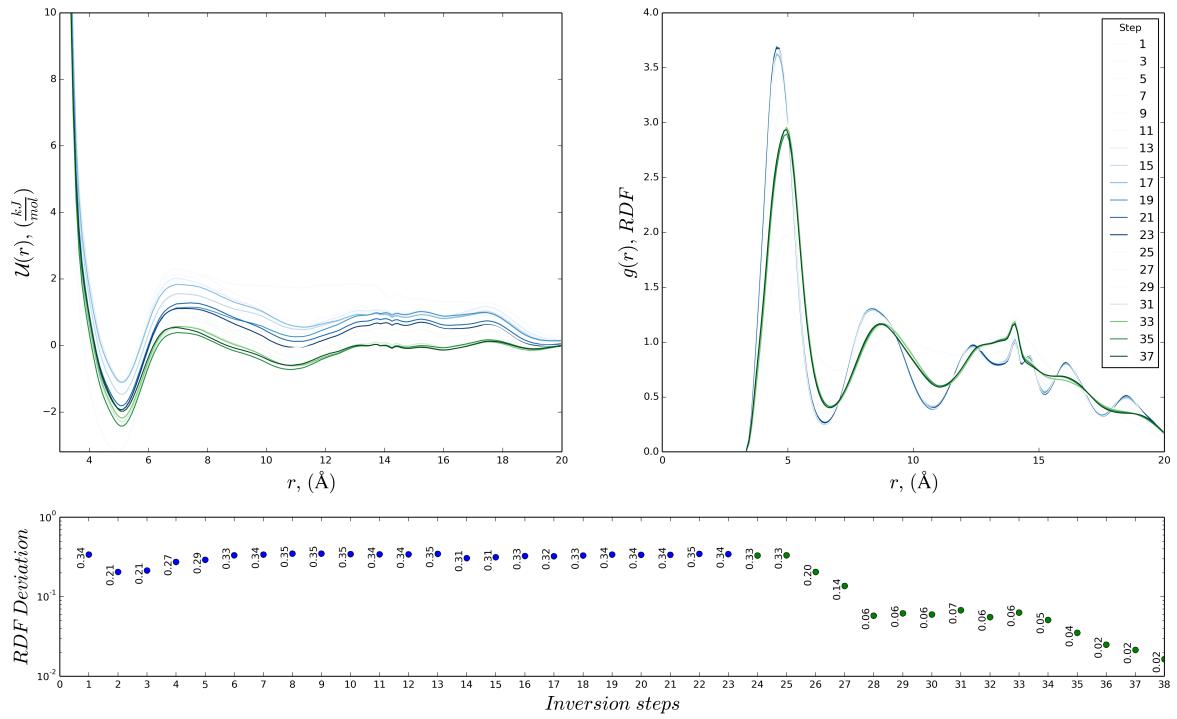


Figure 15: Graphical representation of the inversion process for M_I . Graph 1 (top left) show potential progression at certain steps. Graph 2 (top right) show RDF progression at the same steps as the potential. Both graphs are representing N-N interactions and equal colors represent at the same step furthermore, the darker the line color the higher the step. Blue lines indicate phase two and green lines indicate phase three. Graph 3 (bottom) shows the root mean square deviation between reference RDF and RDF of a given step (for all interactions). Notice that this graph is using logarithmic scale.

Therefore, this phenomena indicates that it might be possible to derive potentials for complex system just by adopting a gradual procedure. For further experiments with silica where intermolecular iterations will increase drastically, this technique should be a useful tool to deal with divergent Inversion processes. It is important to keep in mind that this method still need a deeper analysis in order to probe its validation, because it may not be applicable in other cases. However, this analysis is out of the scope of this project and will be evaluated in future studies.

6.3.2 Potential Comparison

In atomic models the Lennard-Jones potentials only accounts for short range intermolecular interactions because surfactant's atoms seldom interact with each other. Therefore, long-range interaction occurs via a solvent which carries the received forces through solvent media until it reaches other molecules. However for an implicit water coarse-grain model these forces must be included in each bead interaction. With use of different concentrations, the set of potentials obtained for each model revealed interesting features regarding this phenomena. As showed in Figure (16) the long-range potentials presented more regions of low energy rather than the initial first pit. Hence, these regions will be responsible for the self-assembly structures, which means for example, that M_H will always tend to aggregate in more well structured and rigid structures. That is because the low energy regions are deeper and limited within a shorter region, but in the other hand the other models present wider regions which allows a more flexible structure. This is better illustrated by the C-C potential, however it occurs in all the others.

For instance, the intramolecular interactions are quite similar with the exception of the angular potential. It seem that for M_H angular positions smaller than 120° the potential energy starts to increase drastically meaning that the molecules will rarely present these angles. This characteristic implies that molecules will occupy less space in the structure formed, therefore the structure will be more compact when compared to the other models.

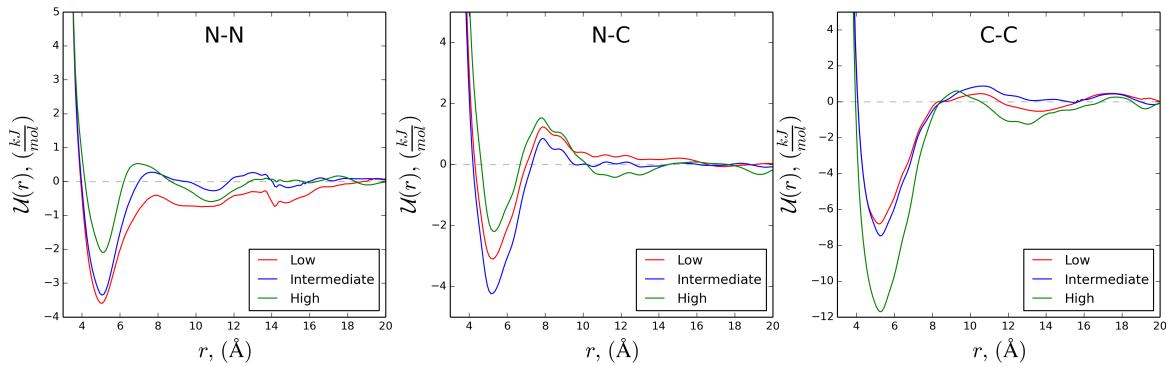


Figure 16: Comparison between Intermolecular potentials for different concentrations. The color shown in the label indicates which model the curve refers. The title in the top indicates which bead types will have these potentials

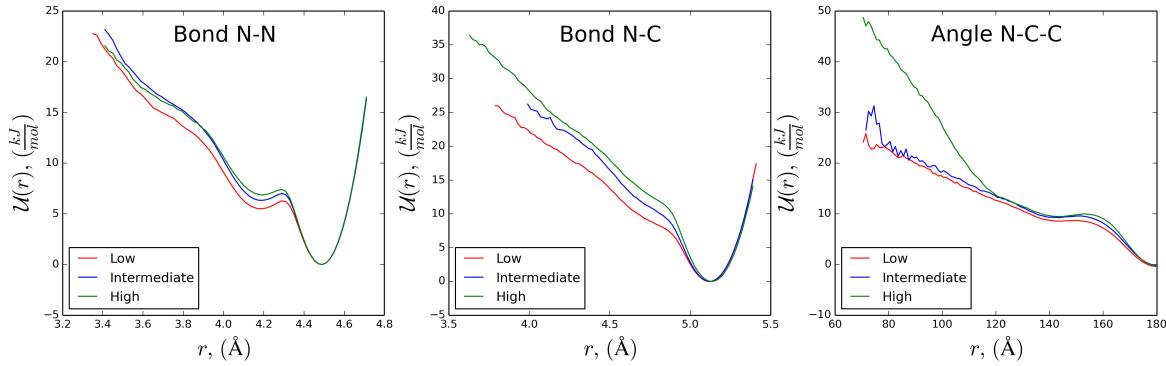


Figure 17: Comparison between Intramolecular potentials for different concentrations. The color shown in the label indicates which model the curve refers. The title in the top indicates which bead types will have these potentials

6.3.3 Interchangeability Test

The final procedure proposed for this project is an attempt to make a cross-comparison to evaluate the capacities of each model at different concentrations. For this the following nine simulations were run until the system equilibrates in a certain configuration. In case the models were interchangeable, the expected result should be self-assembled structures with similar layout.

The first test used low concentration for the simulations, so Box A in Figure (18) is the reference. Due to the lack of molecules in the system the final structure was similar to a vesicle which is an efficient way to reduce contact between solvent and the apolar part. It is noticeable that it is not a complete vesicle, instead the transversal cut of the aggregate reveals that several short crossed planes were the preferred structure. In the other cases, M_I formed a tube like periodic structure and M_H formed a complete "tetrahedral" vesicle with well defined planes.

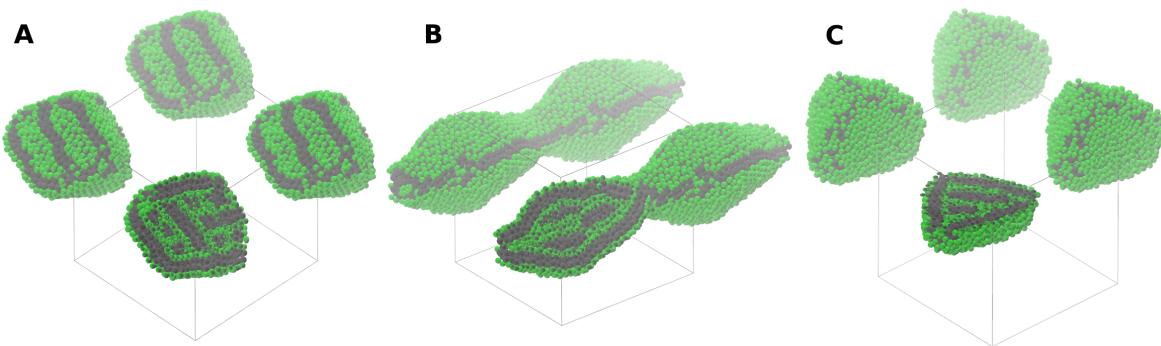


Figure 18: InterLow

Secondly, the intermediate concentration test possible is the one that revealed the real nature of each model. In figure 19 it is observable that all three models presented a periodic interconnected cylindrical structure. In the case of M_L and M_I , the stable configuration shown bridge like interconnections which seemed to not only maintain the structure but at the same time leave space to solvent flow through it. Notwithstanding, M_H preferred a complete plane to interconnect the cylinders blocking solvent flow through the membrane. Furthermore, the cutting planes expose that inside the cylindrical structure M_L kept forming randomly distributed short planes while the others attempted to complete the structure with another concentric cylinder like aggregate.

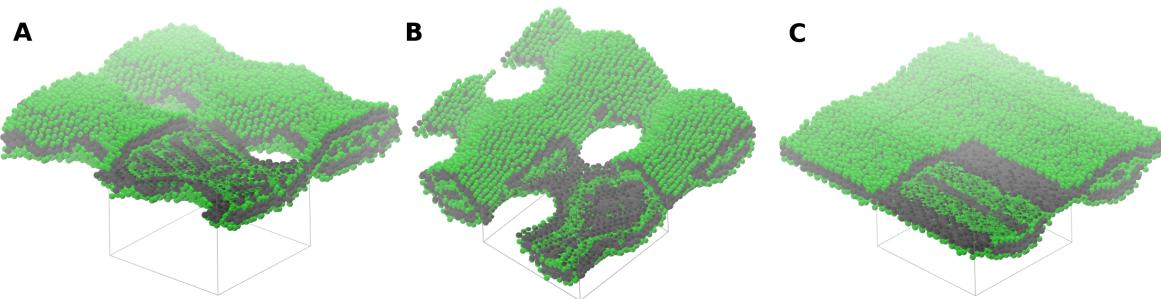


Figure 19: InterI

Lastly, the high concentration test induced complete periodic planes in all cases. Even for M_L which in all other cases preferentially formed short planes, at this concentration stabilized forming long planar lattice structures. Contrastingly, instead of a mesh the other two models favoured parallel planes. Another noticeable feature for M_L and M_H shown in Figure (20) is the existence of a interplanar region with high density of surfactant arranged in alternative directions. However, for M_H case there is only one direction for all planes and as expected, for M_L they appear to be randomly distributed. Exceptionally, M_I does not present this region forming three planes instead.

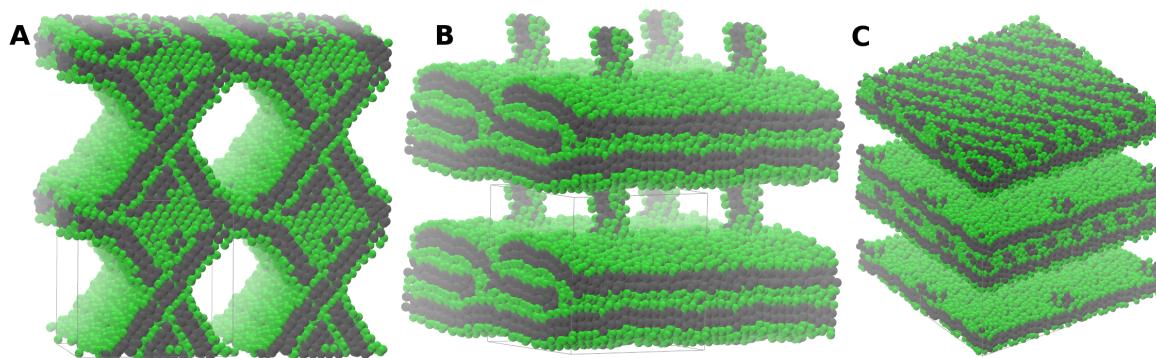


Figure 20: InterHigh

Generally, M_L and M_I

7 Conclusion

What did you really see from the results?
 There was any bad assumption that is contestable?
 What will be the next step to your research?

Due to the enormous discrepancy between number of Monte Carlo steps per Inversion step required for M2 and M1, it is possible to conclude that there is direct relationship between model complexity and effort necessary to obtain a potential set.

8 Nomenclature

\mathcal{H}	Hamiltonian
k_B	Boltzmann's Constant
C_n	Molar concentration of species n ($ mM$)

9 References

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10 Appendix