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# MULTIDIMENSIONAL EXTENSION OF BUFFON'S NEEDLE PROBLEM

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A PREPRINT

Alexander Choi  
alexander.e.choi@gmail.com

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## ABSTRACT

Consider a line segment randomly placed on a two-dimensional plane ruled with a set of regularly spaced parallel lines. The classical Buffon's needle problem asks what the probability is that the line segment intersects at least 1 of these lines. This paper extends this problem by considering a line segment randomly placed in  $\mathbb{R}^D$  and its probability of intersection with a set of regularly spaced parallel hyperplanes.

**Keywords** Buffon's needle problem · Geometric Probability

## 1 Introduction

Given  $D \in \mathbb{N}_{>0}$  and  $N \in [1, 2, \dots, D]$ , consider a grid on  $\mathbb{R}^D$  formed by  $N$  orthogonal sets of regularly spaced hyperplanes. Each set of hyperplanes has a potentially unique spacing of  $S_i$ . A line segment of length  $l \in \mathbb{R}^+$  is randomly located in the space such that one of its end points,  $P_0$ , is uniformly distributed across the entire domain. The line segments orientation is distributed such that when considering  $P_0$  as the center of a  $(D - 1)$ -sphere of radius  $l$ , the other point,  $P_1$ , is uniformly distributed on the surface of that hypersphere. This line segment may intersect with  $C \in \mathbb{N}$  unique hyperplanes. This paper studies the probability of the line segment intersecting more than  $c$  hyperplanes,  $P(C > c | l, D, N, S)$ . From there, solutions for crossing less than  $c$  hyperplanes and exactly  $c$  hyperplanes can be derived.

As an example, the classical Buffon's needle problem would be  $P(C > 0 | l, 2, 1, S)$ . Laplace's extension would be represented as  $P(C > 0 | l, 2, 2, S)$ .

The orientation of the line segment can be represented using spherical coordinates of a  $(D - 1)$ -sphere.

$$x_1 = r \cos \phi_1 \tag{1}$$

$$x_2 = r \sin \phi_1 \cos \phi_2 \tag{2}$$

$$\vdots \tag{3}$$

$$x_{n-1} = r \sin \phi_1 \dots \sin \phi_{D-2} \cos \phi_{D-1} \tag{4}$$

$$x_n = r \sin \phi_1 \dots \sin \phi_{D-2} \sin \phi_{D-1} \tag{5}$$

$$\vec{y} = \vec{x} + P_0 \tag{6}$$

There are several symmetries which simplify the problem. Translational symmetry of the grid of hyperplanes allows us to consider the domain of  $P_0$  to be  $P_0 \in [0, S_i]^D$  as the origin can be moved to any point on the grid.

## 2

## 3 Headings: first level

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## 3.1 Headings: second level

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$$\xi_{ij}(t) = P(x_t = i, x_{t+1} = j | y, v, w; \theta) = \frac{\alpha_i(t) a_{ij}^{w_t} \beta_j(t+1) b_j^{v_{t+1}}(y_{t+1})}{\sum_{i=1}^N \sum_{j=1}^N \alpha_i(t) a_{ij}^{w_t} \beta_j(t+1) b_j^{v_{t+1}}(y_{t+1})} \quad (7)$$

## 3.1.1 Headings: third level

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## 4 Examples of citations, figures, tables, references

## 4.1 Citations

Citations use natbib. The documentation may be found at

<http://mirrors.ctan.org/macros/latex/contrib/natbib/natnotes.pdf>

Here is an example usage of the two main commands (`citet` and `citep`): Some people thought a thing [Kour and Saabne, 2014a, Hadash et al., 2018] but other people thought something else [Kour and Saabne, 2014b]. Many people have speculated that if we knew exactly why Kour and Saabne [2014b] thought this...

## 4.2 Figures

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<sup>1</sup>Sample of the first footnote.



Figure 1: Sample figure caption.

Table 1: Sample table title

Part		
Name	Description	Size ( $\mu\text{m}$ )
Dendrite	Input terminal	$\sim 100$
Axon	Output terminal	$\sim 10$
Soma	Cell body	up to $10^6$

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### 4.3 Tables

See awesome Table 1.

The documentation for booktabs (‘Publication quality tables in LaTeX’) is available from:

<https://www.ctan.org/pkg/booktabs>

### 4.4 Lists

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- consectetur adipiscing elit.
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