

AGUSTÍN GABRIEL YABO

Industrial Automation and Control Engineer
PhD Candidate at Inria Sophia Antipolis - Méditerranée

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ACADEMIC EXPERIENCE

PhD Candidate

Biocore / McTao, Inria Sophia Antipolis - Méditerranée

📅 Sep 2018 – Dec 2021 📍 Nice, France

- Investigated optimal control strategies for synthesizing artificial metabolites in bacteria through growth rate regulation [1, 2, 3, 4], and designed model-predictive control loops for its production in industrial setups [5]. Examples in the [ct-gallery](#).
- Different applications of computer science and systems theory to biological problems [6, 7, 8, 9]. Examples in the [ct-gallery](#).
- DCME activities: teaching and supervising the practical sessions (TD) of the courses
 - Statistics and R (MAM3)
 - Time series (MAM4)of the *Applied mathematics and modeling* engineering degree at *Polytech Nice Sophia* (Sophia Antipolis, France).

Intern

Ctrl-A, Inria Grenoble - Rhône Alpes

📅 Feb 2018 – Jun 2018 📍 Grenoble, France

- Design and validation of control-oriented system models for autonomic computing and self-management of High Performance Computing systems [10].
- Explore novel control strategies for autonomic resource management through optimal and predictive control approaches in real grid computing systems [11].

Research assistant

Science & Technology Department, National University of Quilmes

📅 July 2014 – Jul 2017 📍 Buenos Aires, Argentina

- Developed real-time computer vision algorithms for vehicle tracking, measuring traffic flow parameters and detecting traffic jams in Python [12].
- Implemented machine learning techniques for vehicle classification and statistical analysis of traffic flow [13].
- Worked on dynamical modeling and numerical simulation of arthropods' visual motion-sensitive neurons for studying and controlling their visuomotor behaviours [15, 14].

Teaching assistant

Neural Networks / Control Systems, National University of Quilmes

📅 Mar 2015 – Jul 2017 📍 Buenos Aires, Argentina

Prepared class exercises and activities focused on:

- automatic control systems design, modelling and simulation of dynamical systems and signal processing using MATLAB.
- solving clustering, regression and classification problems through machine learning techniques using MATLAB/Python.

WORK EXPERIENCE

Project Engineer

R&D Department, G&L Group S.A.

📅 2015 – 2017 📍 Buenos Aires, Argentina

- Provided IT solutions (e.g. machine learning, computer vision, automation, control systems and IT infrastructure) and consulting services to companies and clients.
- Participated in domestic non-profit technological projects in cooperation with the Ministry of Science, Technology and Productive Innovation (Argentina).

Industrial Automation Engineer

Automation Department, Secin S.A.

📅 2013 – 2014 📍 Buenos Aires, Argentina

- Developed, implemented, tested and troubleshooted automation systems and control loops through Siemens programmable controllers.
- Acquired an overall understanding of manufacturing processes, as well as industrial instrumentation equipment.

Platform Analyst

IT Department, ICBC Argentina S.A.

📅 2012 – 2013 📍 Buenos Aires, Argentina

- Designed and programmed algorithms and scripts for automating IT processes.
- Acquired general knowledge of big-scale IT infrastructures, and implemented automated tasks on repetitive processes.

INTERESTS

Control systems Systems biology
Optimal control Computer vision
Machine learning Coding

SKILLS

Python Julia Matlab C C++ LaTeX
Assembler SQL Java OpenCV PHP
Smalltalk LUA JS VBScript

PUBLICATIONS

Conference Proceedings

[2] • **Yabo, A.** and J.L. Gouzé. “Optimizing bacterial resource allocation: metabolite production in continuous bioreactors”. In: *21th IFAC World Congress (Berlin, Germany)*. 2020.

[3] • **Yabo, A.,** J.B. Caillaud, and J.L. Gouzé. “Singular regimes for the maximization of metabolite production”. In: *The 58th Conference on Decision and Control (IEEE CDC 2019) (Nice, France) (accepted for publication)*. 2019.

[4] • **Yabo, A.,** J.B. Caillaud, and J.L. Gouzé. “Bacterial growth strategies as Optimal Control problems: maximizing metabolite production”. In: *The 19th French-German-Swiss conference on Optimization (FGS’2019) (Nice, France)*. 2019.

[5] • **Yabo, A.,** J.B. Caillaud, and J.L. Gouzé. “Hierarchical MPC applied to bacterial resource allocation and metabolite synthesis (accepted for publication)”. In: *The 60th IEEE conference on Decision and Control (Austin, Texas, USA)*. 2021.

[8] • N. Augier and **Yabo, A.** “Time-optimal control of piecewise affine bistable gene-regulatory networks: preliminary results”. In: *7th IFAC Conference on Analysis and Design of Hybrid Systems (Brussels, Belgium)*. 2021.

[9] • C. Djuikem, **Yabo, A.,** F. Grogard, and S Touzeau. “Mathematical modelling and optimal control of the seasonal coffee leaf rust propagation”. In: *7th IFAC Conference on Analysis and Design of Hybrid Systems (Brussels, Belgium)*. 2021.

[10] • E. Stahl, **Yabo, A.,** O. Richard, B. Bzeznik, B. Robu, and E. Rutten. “Towards a control-theory approach for minimizing unused grid resources”. In: *The 1st Autonomous Infrastructure for Science Workshop (AI-Science’18) (Tempe, AZ, United States)*. 2018.

[11] • **Yabo, A.,** O. Richard, B. Bzeznik, B. Robu, and E. Rutten. “A control-theory approach for cluster autonomic management: maximizing usage while avoiding overload”. In: *The 3rd IEEE Conference on Control Technology and Application (IEEE CCTA 2019) (Hong Kong, China)*. 2019.

[12] • D. Oliva, **Yabo, A.,** L. Garcia, S. Arroyo, and F. Safar. “Implementation of a traffic flow measurement and traffic jam detection system in highways”. In: *Argentine Symposium on Artificial Intelligence (ASAI 2015)-JAIIO 44 (Rosario, Argentina)*. 2015.

[13] • **Yabo, A.,** S. Arroyo, F. Safar, and D. Oliva. “Vehicle classification and speed estimation using computer vision techniques”. In: *XXV Argentine Congress on Automatic Control (AADECA 2016) (Buenos Aires, Argentina)*. 2016.

[15] • **Yabo, A.,** J. Carbone, S. Ibañez, D. Tomsic, and D. Oliva. “Wide-field stimulation system for measuring of visuomotor behaviors in arthropods”. In: *XXIX Annual Meeting of the Argentine Society for Research in Neuroscience (SAN 2014) (Córdoba, Argentina)*. 2014.

LANGUAGES

English	●●●●●
Fluent - IELTS Band 7.5	
Spanish	●●●●●
Mother tongue	
French	●●●●●
Fluent	
Chinese	●●●●●
HSK Level 2	

Journal Articles

[1] • **Yabo, A.,** J.B. Caillaud, and J.L. Gouzé. “Optimal bacterial resource allocation: metabolite production in continuous bioreactors”. In: *Mathematical Biosciences and Engineering* 17.6 (2020), pp. 7074–7100.

[6] • N. Augier and **Yabo, A.** “Time-optimal control of piecewise affine bistable gene-regulatory networks (accepted for publication)”. In: *International Journal of Robust and Nonlinear Control* (2021).

[7] • **Yabo, A.,** J.B. Caillaud, J.L. Gouzé, Hidde de Jong, and Francis Mairé. “Dynamical analysis and optimization of a generalized resource allocation model of microbial growth (accepted for publication)”. In: *SIAM Journal on Applied Dynamical Systems* (2021).

[14] • J. Carbone, **Yabo, A.,** and D. Oliva. “Characterization and modelling of looming-sensitive neurons in the crab *Neohelice*”. In: *Journal of Comparative Physiology A* (2018), pp. 1–17.

GRANTS

2018	EDSTIC PhD funding PhD funding (10 grants per year). Granted by Université Côte d’Azur (Nice, France).
2017	LabEx PERSYVAL-Lab Master M2 scholarship program (10 grants per year). Granted by LabEx PERSYVAL-Lab and Université Grenoble Alpes (Grenoble, France).
2016	University and Transport Merit-based research scholarship for research assistants. Granted by the Ministry of Education National University of Quilmes (Buenos Aires, Argentina).
2015	SAI Research Subsidy Program Research support subsidy for undergraduate students. Granted by National University of Quilmes (Buenos Aires, Argentina).
2014	Santander Ibero-American Grants Exchange scholarship for a 1 semester stay in Spain. Granted by Santander Bank (Spain) and National University of Quilmes (Buenos Aires, Argentina).
2013	CONAHEC Student Exchange Program Short-stay exchange scholarship. Granted by CONAHEC and National University of Quilmes (Buenos Aires, Argentina).