

codegen development memo

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1 Gallina

1.1 Gallina Syntax

$t = x$	variable
c	constant
C	constructor
T	type
$\lambda x:T. t$	abstraction
$t u$	application
let $x := t : T$ in u	let-in
match t_0 with $(C_i \Rightarrow t_i)_{i=1\dots h}$ end	conditional
fix $(f_i/k_i : T_i := t_i)_{i=1\dots h}$ for f_j	fixpoint

Note:

- u represents a term as t .
 y, z , and f represent a variable as x .
 U represents a type as T .
- We write $(\dots((t u_1) u_2) \dots u_n)$ as $t u_1 \dots u_n$.
- k is an integer.
 k_i for fixpoint specify the decreasing argument for f_i .
- If it is unambiguous, we omit type annotations for the sake of simplicity. We also omit k_i in fixpoints if they are not used.
- We omitted the elimination predicate (**as-in-return** clause of **match**-expression). It is not used in reductions.
- **match**-branches t_i are functions that take the constructor members (constructor arguments without inductive type parameters). This formalism is taken from CIC [1].
- We omitted the detail of the types. Actual Gallina permits any Gallina term which evaluates to a type.

1.2 Gallina Conversion Rules

$$\begin{aligned}
\text{beta: } & E[\Gamma] \vdash ((\lambda x. t) u) \triangleright t\{x/u\} \\
\text{delta-local: } & \frac{(x := t) \in \Gamma}{E[\Gamma] \vdash x \triangleright t} \\
\text{delta-global: } & \frac{(c := t) \in E}{E[\Gamma] \vdash c \triangleright t} \\
\text{zeta: } & E[\Gamma] \vdash \text{let } x := t \text{ in } u \triangleright u\{x/t\} \\
\text{iota-match: } & \frac{E[\Gamma] \vdash C_j u_1 \dots u_{p+m} : T \quad p \text{ is the number of parameters of the inductive type } T}{E[\Gamma] \vdash \text{match } (C_j u_1 \dots u_{p+m}) \text{ with } (C_i \Rightarrow t_i)_{i=1\dots h} \text{ end} \triangleright t_j u_{p+1} \dots u_{p+m}} \\
\text{iota-fix: } & \frac{u_{k_j} = C u'_1 \dots u'_m}{E[\Gamma] \vdash (\text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_j) u_1 \dots u_{k_j} \triangleright t_j\{f_k/\text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_k\}_{k=1\dots h} u_1 \dots u_{k_j}} \\
\text{eta expansion: } & \frac{E[\Gamma] \vdash t : \forall x:T. U}{E[\Gamma] \vdash t \triangleright \lambda x:T. (t x)}
\end{aligned}$$

Note:

- The rules shown here are reductions, except the eta expansion.
- $t\{x/u\}$ means a term in which x in term t is replaced by u . This notation is taken from the Coq reference manual [1].
- Variables cannot conflict because Coq uses de Bruijn's indexes to represent variables.
- E is a global environment which is a list of global assumptions ($c:T$), global definitions ($c := t:T$), and inductive definitions ($\text{Ind } [p] (\Gamma_I := \Gamma_C)$).
- Γ is a local context which is a list of local assumptions ($x:T$) and local definitions ($x := t:T$). The local assumptions represent variables bounded by outer abstractions and fixpoints. The local definitions represent variables bounded by outer let-in.
- If it is unambiguous, we omit type annotations in these definitions for the sake of simplicity.
- Iota-match reduces `match @cons nat 1 nil with (nil \Rightarrow t_1) (cons \Rightarrow t_2) end` to t_2 1 nil because `list` has one parameter ($p = 1$) and `cons` has two members ($m = 2$).

2 CodeGen

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 - C Code Generation

3 Convertible Transformations

3.1 Inlining

3.2 Strip Cast

3.3 Eta Expansion for Function Bodies

We apply eta-expansion to function bodies of top-level functions and fix-bounded functions. This makes beta-var applicable to the bodies.

3.4 V-Normalization

3.4.1 V-Reductions

$$\begin{aligned}
 \text{zeta-arg: } & \frac{E[\Gamma] \vdash t_i : T_i \quad t_0 \text{ is not an application} \quad t_i \text{ is not a variable} \quad x_i \text{ is a fresh variable}}{E[\Gamma] \vdash t_0 x_1 \dots x_{i-1} t_i t_{i+1} \dots t_n \triangleright \text{let } x_i := t_i : T_i \text{ in } t_0 x_1 \dots x_{i-1} x_i t_{i+1} \dots t_n} \\
 \text{zeta-item: } & \frac{E[\Gamma] \vdash t_0 : T_0 \quad t_0 \text{ is not a variable} \quad x_0 \text{ is a fresh variable}}{E[\Gamma] \vdash \text{match } t_0 \text{ with } (C_i \Rightarrow t_i)_{i=1\dots h} \text{ end} \\
 & \quad \triangleright \text{let } x_0 := t_0 : T_0 \text{ in match } x_0 \text{ with } (C_i \Rightarrow t_i)_{i=1\dots h} \text{ end}}
 \end{aligned}$$

3.4.2 V-Normal Form

V-normal form restricts Gallina terms that (1) application arguments and (2) match items to variables.

$$\begin{aligned}
 t = & x \mid c \mid C \mid T \mid \lambda x:T. t \mid \text{let } x := t : T \text{ in } u \\
 & \mid \text{fix } (f_i/k_i : T_i := t_i)_{i=1\dots h} \text{ for } f_j \\
 & \mid t x \quad \leftarrow (1) \\
 & \mid \text{match } x \text{ with } (C_i \Rightarrow t_i)_{i=1\dots h} \text{ end} \quad \leftarrow (2)
 \end{aligned}$$

3.5 S-Normalization

$$\begin{aligned}
 \text{beta-var: } & \frac{0 < n \quad E[\Gamma] \vdash (\lambda x. t) y_1 \dots y_n : T \quad T \text{ is an inductive type}}{E[\Gamma] \vdash (\lambda x. t) y_1 \dots y_n \triangleright t\{x/y_1\} y_2 \dots y_n} \\
 \text{delta-var: } & \frac{(x := y) \in \Gamma}{E[\Gamma] \vdash x \triangleright y} \\
 \text{delta-fun: } & \frac{0 \leq p \quad 0 < q \quad (f := t x_1 \dots x_p) \in \Gamma \quad t \text{ is one of } x, c, C, \lambda x. u, \text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_j}{E[\Gamma] \vdash f y_1 \dots y_q \triangleright t x_1 \dots x_p y_1 \dots y_q} \\
 \text{zeta-flat: } & E[\Gamma] \vdash \text{let } y := (\text{let } x := t_1 \text{ in } t_2) \text{ in } t_0 \triangleright \text{let } x := t_1 \text{ in } (\text{let } y := t_2 \text{ in } t_0) \\
 \text{zeta-app: } & E[\Gamma] \vdash (\text{let } x_0 := t \text{ in } u) x_1 \dots x_n \triangleright \text{let } x_0 := t \text{ in } (u x_1 \dots x_n) \\
 \text{iota-match-var: } & \frac{(x := C_j y_1 \dots y_{p+m} : T) \in \Gamma \quad p \text{ is the number of parameters of the inductive type } T}{E[\Gamma] \vdash \text{match } x \text{ with } (C_i \Rightarrow t_i)_{i=1\dots h} \text{ end} \triangleright t_j y_{p+1} \dots y_{p+m}} \\
 & \quad (x_{k_j} := C y_1 \dots y_m) \in \Gamma \quad f'_1 \dots f'_h \text{ are fresh variables} \\
 \text{iota-fix-var: } & \frac{E[\Gamma] \vdash (\text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_j) x_1 \dots x_n : T \quad T \text{ is an inductive type}}{E[\Gamma] \vdash (\text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_j) x_1 \dots x_n \\
 & \quad \triangleright \text{let } f'_1 := \text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_1 \text{ in } \dots \\
 & \quad \text{let } f'_h := \text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_h \text{ in } \\
 & \quad t_j\{f_k/f'_k\}_{k=1\dots h} x_1 \dots x_n} \\
 & \quad (x_{k_j} := C y_1 \dots y_m) \in \Gamma \\
 & \quad (f'_1 := \text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_1) \in \Gamma \quad \dots \quad (f'_h := \text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_h) \in \Gamma \\
 \text{iota-fix-var': } & \frac{E[\Gamma] \vdash (\text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_j) x_1 \dots x_n : T \quad T \text{ is an inductive type}}{E[\Gamma] \vdash (\text{fix } (f_i/k_i := t_i)_{i=1\dots h} \text{ for } f_j) x_1 \dots x_n \triangleright t_j\{f_k/f'_k\}_{k=1\dots h} x_1 \dots x_n}
 \end{aligned}$$

3.6 Type Normalization

3.7 Static Argument Normalization

3.8 Unused let-in Deletion

$$\text{zeta-del: } \frac{x \text{ does not occur in } u \quad x \text{ is not linear} \quad \text{FV}(t) \text{ does not contain linear variable}}{E[\Gamma] \vdash \text{let } x := t \text{ in } u \triangleright u}$$

Note:

- $\text{FV}(t)$ means the free variables of t .

3.9 Call Site Replacement

3.10 Argument Completion

Argument completion removes partial applications by applying eta expansions.

- $F[t]$ considers t to be a top-level function or a closure-generating expression. F transforms t to be a nested abstraction expression that takes all arguments. Fixpoint expressions are allowed outside or between the abstractions.
- $\text{BR}[t]_{m,q}$ transforms a branch of a match expression into a nested abstraction expression that takes constructor members. Fixpoint expressions are not allowed.
- $E[t / x_1 \dots x_p]_q$ is a term convertible with $t x_1 \dots x_p$ that does not contain a partial application. $E[t / x_1 \dots x_p]_q$ traverses t while tracking the arguments for t to find closure-generating expressions. The number of arguments given to t is $p + q$. The first p arguments are $x_1 \dots x_p$ and they can be the argument of beta-var redex. The last q arguments cannot be the argument of beta-var redex.

$$F[t] = \begin{cases} \lambda x. F[u] & t = \lambda x. u \\ \text{fix } (f_i := F[t_i])_{i=1\dots h} \text{ for } f_j & t = \text{fix } (f_i := t_i)_{i=1\dots h} \text{ for } f_j \\ \lambda x_1 \dots \lambda x_m. E[t / x_1 \dots x_m]_0 & \text{otherwise (eta expansion)} \end{cases}$$

where $t : T_1 \rightarrow \dots \rightarrow T_m \rightarrow T_0$

T_0 is an inductive type

$x_1 \dots x_m$ are fresh variables

$$\text{BR}[t]_{m,q} = \begin{cases} E[t /]_q & m = 0 \\ \lambda x. \text{BR}[u]_{m-1,q} & (m > 0) \wedge (t = \lambda x. u) \\ \lambda x_1 \dots \lambda x_m. E[t / x_1 \dots x_m]_q & \text{otherwise (eta expansion)} \end{cases}$$

where $x_1 \dots x_m$ are fresh variables

$$E[t / x_1 \dots x_p]_q = \begin{cases} x & (t = x) \wedge (p = q = 0) \\ x x_1 \dots x_p & (t = x) \wedge \neg(p = q = 0) \wedge (r = 0) \\ F[x x_1 \dots x_p] & (t = x) \wedge \neg(p = q = 0) \wedge (r > 0) \\ t x_1 \dots x_p & ((t = c) \vee (t = C)) \wedge (r = 0) \\ F[t x_1 \dots x_p] & ((t = c) \vee (t = C)) \wedge (r > 0) \\ E[u\{x/x_1\} / x_2 \dots x_p]_q & (t = \lambda x. u) \wedge (p > 0) \wedge (r = 0) \quad (\text{beta-var}) \\ (\lambda x. E[u /]_{p+q-1}) x_1 \dots x_p & (t = \lambda x. u) \wedge ((p = 0) \wedge (r = 0)) \\ F[t x_1 \dots x_p] & (t = \lambda x. u) \wedge (r > 0) \\ E[u / x_0 x_1 \dots x_p]_q & t = u x_0 \\ \text{let } x := E[t_1 /]_0 \text{ in } E[t_2 / x_1 \dots x_p]_q & t = \text{let } x := t_1 \text{ in } t_2 \quad (\text{zeta-app}) \\ \text{match } x \text{ with } (C_i \Rightarrow \text{BR}[t_i]_{\text{NM}_{C_i}, p+q})_{i=1\dots h} \text{ end } x_1 \dots x_p & t = \text{match } x \text{ with } (C_i \Rightarrow t_i)_{i=1\dots h} \text{ end} \\ (\text{fix } (f_i := F[t_i])_{i=1\dots h} \text{ for } f_j) x_1 \dots x_p & (t = \text{fix } (f_i := t_i)_{i=1\dots h} \text{ for } f_j) \wedge (r = 0) \\ F[t x_1 \dots x_p] & (t = \text{fix } (f_i := t_i)_{i=1\dots h} \text{ for } f_j) \wedge (r > 0) \end{cases}$$

where $t : T_1 \rightarrow \dots \rightarrow T_p \rightarrow T_{p+1} \rightarrow \dots \rightarrow T_{p+q} \rightarrow T_{p+q+1} \rightarrow \dots \rightarrow T_{p+q+r} \rightarrow T_0$
 T_0 is an inductive type

Note:

- This transformation assumes t is not dependently typed: no type terms and no dependent **match**-expressions.
- NM_C is the number of the members of the constructor C (the number of arguments without the parameters for the inductive type):
 $NM_C = m$ if $C : T_1 \rightarrow \dots \rightarrow T_p \rightarrow T_{p+1} \rightarrow \dots \rightarrow T_{p+m} \rightarrow T_0$ and T_0 is an inductive type which has p parameters.

3.11 Move Match Argument

$$\text{match-app: } \frac{E[\Gamma] \vdash z : T}{E[\Gamma] \vdash \text{match } x \text{ as } x' \text{ in } I \dots y_1 \dots y_{NI_I} \text{ return } T \rightarrow P \ y_1 \dots y_{NI_I} \ x' \text{ with } (C_i \ x_{i1} \dots x_{iNM_{C_i}} \Rightarrow t_i)_{i=1\dots h} \text{ end } z \triangleright \text{match } x \text{ as } x' \text{ in } I \dots y_1 \dots y_{NI_I} \text{ return } P \ y_1 \dots y_{NI_I} \ x' \text{ with } (C_i \ x_{i1} \dots x_{iNM_{C_i}} \Rightarrow t_i \ z)_{i=1\dots h} \text{ end}}$$

beta-var and zeta-app are also applied.

Note:

- match-app is not convertible
- NI_I is the number of the indexes of the inductive type I (the number of arguments without the parameters for the inductive type):
 $NI_I = m$ if $I : T_1 \rightarrow \dots \rightarrow T_p \rightarrow T_{p+1} \rightarrow \dots \rightarrow T_{p+m} \rightarrow S$ and S is a sort.

3.12 Borrow Check

We define two judgements $E[\Gamma'] \vdash t \mid B$ and $E[\Gamma'] \vdash t \mid (L, B^{\text{used}}, B^{\text{result}})$ for borrow check. Γ' is an annotated local context. It is a list of $(x^B : T)$ or $(x^B := t : T)$. The variable x is annotated with a borrow information B . B is a set of pair of borrow type and linear variable, such as $\{(T_1, x_1), \dots\}$. B^{used} and B^{result} are also borrow information. L is a set of linear variables. T is the type of t .

We omit $: T$ in a rule which does not use T .

The borrow information $B = \{(T_1, x_1), \dots\}$ represents a linear variable x_i is used via borrow type T_i . $(x^{\{(T', y)\}} : T) \in \Gamma'$ represents x may contain a value of type T' which is a (part of) content of the linear variable y .

$E[\Gamma'] \vdash t \mid B$ means a function t may use linear variables via borrow B .

$E[\Gamma'] \vdash t \mid (L, B^{\text{used}}, B^{\text{result}})$ means an expression t (1) consumes linear variables L , (2) may use linear values via borrow B^{used} , (3) result value may contain linear values via borrow B^{result} .

For example, assume linear list **lseq**, borrow list **bseq** which has constructors **bnil** and **bcons**, borrow function **borrow** : **lseq** **nat** \rightarrow **bseq** **nat**. In a code fragment

let $y := \text{borrow } x \text{ in match } y \text{ with bnill} \Rightarrow \text{true} \mid \text{bcons } h \ t \Rightarrow \text{false} \text{ end}$ contains variables $x : \text{lseq nat}$, $y : \text{bseq nat}$, $h : \text{nat}$, and $t : \text{bseq nat}$. y and t contain a **bseq nat** value borrowed from x . It is represented as $y^{\{(bseq \text{ nat}, x)\}} : \text{bseq nat}$ and $t^{\{(bseq \text{ nat}, x)\}} : \text{bseq nat}$. The type of h is **nat**. Since **nat** is not a borrow type, h lives even after x is consumed.

$$\begin{array}{l}
\text{borrow-lvar: } \frac{(x^B:T) \in \Gamma' \quad x \text{ is linear}}{E[\Gamma'] \vdash x \mid (\{x\}, B, B)} \\
\text{borrow-var: } \frac{(x^B:T) \in \Gamma' \quad x \text{ is not linear}}{E[\Gamma'] \vdash x \mid (\emptyset, B, B)} \\
\text{borrow-constant: } \frac{c \text{ is not a borrow function}}{E[\Gamma'] \vdash c \mid (\emptyset, \emptyset, \emptyset)} \\
\text{borrow-ctor: } E[\Gamma'] \vdash C \mid (\emptyset, \emptyset, \emptyset) \\
\\
\begin{array}{c}
E[\Gamma'] \vdash t_1 \mid (L_1, B_1^{\text{used}}, B_1^{\text{result}}) \\
E[\Gamma' :: (x^{B_1^{\text{result}}}:T) := t_1:T] \vdash t_2 \mid (L_2, B_2^{\text{used}}, B_2^{\text{result}}) \\
L_1 \cap L_2 = \emptyset \\
x \text{ is linear} \rightarrow x \in L_2 \\
L_1 \cap B_2^{\text{used}} = \emptyset
\end{array} \\
\text{borrow-letin: } \frac{E[\Gamma'] \vdash \text{let } x := t_1 : T \text{ in } t_2 \mid (L_1 \cup L_2 - \{x\}, B_1^{\text{used}} \cup B_2^{\text{used}} - \{x\}, B_2^{\text{result}} - \{x\})}{E[\Gamma'] \vdash t_0 \mid (L_0, B_0^{\text{used}}, B_0^{\text{result}})} \\
\begin{array}{c}
B_{ij} = B_0^{\text{result}} \text{ filtered with the type of } x_{ij} \\
\Gamma'_i = (x_{i1}^{B_{i1}}:T_{i1}) :: \dots :: (x_{i \text{NM}_{C_i}}^{B_{i \text{NM}_{C_i}}}:T_{i \text{NM}_{C_i}}) \\
E[\Gamma' :: \Gamma'_i] \vdash t_i \mid (L_i, B_i^{\text{used}}, B_i^{\text{result}}) \\
L_i^{\text{M}} = L_i \cap \{x_{i1}, \dots, x_{i \text{NM}_{C_i}}\} \quad L_i^{\text{F}} = L_i - \{x_{i1}, \dots, x_{i \text{NM}_{C_i}}\} \\
L_i^{\text{M}} = \{x_{ij} \mid 1 \leq j \leq \text{NM}_{C_i} \wedge x_{ij} \text{ is linear}\} \quad L_1^{\text{F}} = \dots = L_h^{\text{F}} \quad L_0 \cap L_1^{\text{F}} = \emptyset \\
B_i^{\text{used}} = B_1^{\text{used}} - \{x_{i1}, \dots, x_{i \text{NM}_{C_i}}\} \quad B_i^{\text{result}} = B_1^{\text{result}} - \{x_{i1}, \dots, x_{i \text{NM}_{C_i}}\} \\
B^{\text{used}} = B_1^{\text{used}} \cup \dots \cup B_h^{\text{used}} \quad B^{\text{result}} = B_1^{\text{result}} \cup \dots \cup B_h^{\text{result}} \quad L_0 \cap B^{\text{used}} = \emptyset
\end{array} \\
\text{borrow-match: } \frac{E[\Gamma'] \vdash \text{match } t_0 \text{ with } (C_i \ x_{i1} \dots x_{i \text{NM}_{C_i}} \Rightarrow t_i)_{i=1..h} \text{ end} \mid (L_0 \cup L_1^{\text{F}}, B_0^{\text{used}} \cup B^{\text{used}}, B^{\text{result}})}{E[\Gamma'] \vdash t_0 \mid (L_0, B_0^{\text{used}}, B_0^{\text{result}})} \\
\text{borrow-var-app: } \frac{(x_0^B:T') \in \Gamma' \quad \text{APP}(\Gamma', B, x_1 \dots x_n, T, L, B^{\text{used}}, B^{\text{result}})}{E[\Gamma'] \vdash x_0 \ x_1 \dots x_n : T \mid (L, B^{\text{used}}, B^{\text{result}})} \\
\text{borrow-constant-app: } \frac{c \text{ is not a borrow function} \quad \text{APP}(\Gamma', \emptyset, x_1 \dots x_n, T, L, B^{\text{used}}, B^{\text{result}})}{E[\Gamma'] \vdash c \ x_1 \dots x_n : T \mid (L, B^{\text{used}}, B^{\text{result}})} \\
\text{borrow-ctor-app: } \frac{\text{APP}(\Gamma', \emptyset, x_1 \dots x_n, T, L, B^{\text{used}}, B^{\text{result}})}{E[\Gamma'] \vdash C \ x_1 \dots x_n : T \mid (L, B^{\text{used}}, B^{\text{result}})} \\
\text{borrow-fix-app: } \frac{E[\Gamma'] \vdash \text{fix } (f_i := t_i)_{i=1..h} \text{ for } f_j \mid B \quad \text{APP}(\Gamma', B, x_1 \dots x_n, T, L, B^{\text{used}}, B^{\text{result}})}{E[\Gamma'] \vdash (\text{fix } (f_i := t_i)_{i=1..h} \text{ for } f_j) \ x_1 \dots x_n : T \mid (L, B^{\text{used}}, B^{\text{result}})} \\
\begin{array}{c}
c \text{ is a borrow function} \\
E[\Gamma'] \vdash c : T^{\text{arg}} \rightarrow T^{\text{result}} \quad T^{\text{arg}} \text{ is a linear type} \quad T^{\text{result}} \text{ is a borrow type} \\
T^{\text{result}} \text{ does not contain function} \\
\{T_1, \dots, T_n\} \text{ is a set of borrow types contained in } T^{\text{result}}
\end{array} \\
\text{borrow-borrow: } \frac{B = \{(T_1, x), \dots, (T_n, x)\}}{E[\Gamma'] \vdash c \ x \mid (\emptyset, B, B)} \\
\text{borrow-fix-clo: } \frac{E[\Gamma'] \vdash \text{fix } (f_i := t_i)_{i=1..h} \text{ for } f_j \mid B}{E[\Gamma'] \vdash \text{fix } (f_i := t_i)_{i=1..h} \text{ for } f_j \mid (\emptyset, B, B)} \\
\text{borrow-abs-clo: } \frac{E[\Gamma'] \vdash \lambda x. t \mid B}{E[\Gamma'] \vdash \lambda x. t \mid (\emptyset, B, B)}
\end{array}$$

$$\begin{array}{c}
t \text{ is not an abstraction} \\
t \text{ is not a fixpoint} \\
E[\Gamma' :: (x_1^\emptyset:T_1) :: \dots :: (x_n^\emptyset:T_n)] \vdash t : T \mid (L, B^{\text{used}}, B^{\text{result}}) \\
\{x_i \mid 1 \leq i \leq n \wedge x_i \text{ is linear}\} = L \\
\text{borrow-abs-fun: } \frac{B' = (B^{\text{used}} - \{x_1, \dots, x_n\}) \text{ filtered with the type of } T}{E[\Gamma'] \vdash \lambda x_1:T_1. \dots \lambda x_n:T_n. t \mid B'} \\
t \text{ is a fixpoint} \\
E[\Gamma' :: (x_1^\emptyset:T_1) :: \dots :: (x_n^\emptyset:T_n)] \vdash t \mid B \\
\forall 1 \leq i \leq n, x_i \text{ is not linear} \\
\text{borrow-abs-fix: } \frac{E[\Gamma'] \vdash \lambda x_1:T_1. \dots \lambda x_n:T_n. t \mid B}{E[\Gamma' :: (f_1^\emptyset:T_1) :: \dots :: (f_h^\emptyset:T_h)] \vdash t_i \mid B_i} \\
B = B_1 \cup \dots \cup B_h \\
\text{borrow-fix-fun: } \frac{B = B_1 \cup \dots \cup B_h}{E[\Gamma'] \vdash \text{fix}(f_i : T_i := t_i)_{i=1\dots h} \text{ for } f_j \mid B}
\end{array}$$

$$\begin{aligned}
& \text{APP}(\Gamma', B, x_1 \dots x_n, T, L, B^{\text{used}}, B^{\text{result}}) \\
& = 1 \leq n \\
& \wedge \forall 1 \leq i \leq n, \forall 1 \leq j \leq n, (i \neq j \rightarrow \neg(x_i = x_j \wedge x_i \text{ is linear})) \\
& \wedge L = \{x_i \mid 1 \leq i \leq n \wedge x_i \text{ is linear}\} \\
& \wedge B^{\text{used}} = B \cup \{B' \mid 1 \leq i \leq n \wedge (x_i^{B'} : T') \in \Gamma'\} \\
& \wedge B^{\text{result}} = B^{\text{used}} \text{ filtered with the type } T \\
& \wedge B^{\text{used}} \cap L = \emptyset
\end{aligned}$$

We mix borrow information and set of variables in set-operations. Assume $L = \{x_1, \dots, x_n\}$ and $B = \{(T_1, y_1), \dots, (T_m, y_m)\}$.

$$\begin{aligned}
B \cap L &= L \cap B = \{(T_i, y_i) \in B \mid 1 \leq i \leq m, y_i \in L\} \\
B - L &= \{(T_i, y_i) \in B \mid 1 \leq i \leq m, y_i \notin L\}
\end{aligned}$$

Note:

- borrow-fix-fun annotates $f_1^\emptyset \dots f_n^\emptyset$. This is not correct because $f_1 \dots f_n$ may refer borrowed values via free variables in $\text{fix}(f_i : T_i := t_i)_{i=1\dots h} \text{ for } f_j$. However, it is harmless because corresponding linear value cannot be consumed in the fix-term.

3.13 C Variable Allocation

$$\begin{aligned}
x &: \text{Gallina variable} \\
v &: \text{C variable} \\
V &= \text{empty} \mid x \mapsto v \mid V; V
\end{aligned}$$

- $\text{CV}[t / x_1 \dots x_n]_V$ is the variable mapping of the variables declared in t .
- $x_1 \dots x_n$ are arguments for t .
- V is the variable mapping for variables declared outside.

$$\text{CV}[\![t / x_1 \dots x_n]\!]_V = \begin{cases} \text{empty} & (t = x) \vee (t = c) \vee (t = C) \vee (t = T) \\ \text{CV}[\![u /]\!]_{V;M}; M & (t = \lambda x. u) \wedge (n = 0) \quad \text{where } M = x \mapsto v \\ \text{CV}[\![u / x_2 \dots x_n]\!]_{V;M}; M & (t = \lambda x. u) \wedge (n > 0) \quad \text{where } M = x \mapsto V(x_1) \\ \text{CV}[\![u / x_0 x_1 \dots x_n]\!]_V & t = u x_0 \\ \text{CV}[\![t_1 /]\!]_V; \text{CV}[\![t_2 / x_1 \dots x_n]\!]_{V;M}; M & t = \text{let } x := t_1 \text{ in } t_2 \quad \text{where } M = x \mapsto v \\ (\text{CV}[\![t_1 / x_1 \dots x_n]\!]_{V;M_1}; \dots; & t = \text{match } x \text{ with } (C_i \Rightarrow \lambda y_{i1} \dots \lambda y_{i \text{NM}_{C_i}}. t_i)_{i=1 \dots h} \text{ end} \\ \text{CV}[\![t_h / x_1 \dots x_n]\!]_{V;M_h}; & \text{where } M_i = y_{i1} \mapsto v_{i1}; \dots; y_{i \text{NM}_{C_i}} \mapsto v_{i \text{NM}_{C_i}} \\ M_1; \dots; M_h) & \\ \text{CV}[\![t_1 /]\!]_{V;M}; \dots; \text{CV}[\![t_h /]\!]_{V;M}; M & t = \text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j \\ & \text{where } M = f_1 \mapsto v_1; \dots; f_h \mapsto v_h \end{cases}$$

where v, v_i, v_{ij} are fresh C variables

Note: We consider Gallina variables unique.

4 C Code Generation

4.1 The Gallina Subset For C Code Generation

$$\begin{array}{c}
\frac{E[\Gamma] \vdash_b x \quad E[\Gamma] \vdash_b c \quad E[\Gamma] \vdash_b C}{E[\Gamma] \vdash_b t \quad E[\Gamma] \vdash x : T \quad T \text{ is a non-dependent inductive type}} \\
\frac{E[\Gamma] \vdash_b t x}{E[\Gamma] \vdash_b \text{let } x := t : T \text{ in } u} \\
\frac{E[\Gamma] \vdash_b t \quad E[\Gamma :: (x := t : T)] \vdash_b u \quad T \text{ is a non-dependent inductive type}}{E[\Gamma] \vdash_b \text{let } x := t : T \text{ in } u} \\
\frac{E[\Gamma] \vdash x : T \quad T \text{ is a non-dependent inductive type with } p \text{ parameters: } I u_1 \dots u_p}{E[\Gamma] \vdash C_i u_1 \dots u_p : T_{i1} \rightarrow \dots \rightarrow T_{i \text{NM}_{C_i}} \rightarrow T \quad T_{ij} \text{ are non-dependent inductive types}} \\
\frac{E[\Gamma :: (y_{i1} : T_{i1}) :: \dots :: (y_{i \text{NM}_{C_i}} : T_{i \text{NM}_{C_i}})] \vdash_b t_i}{E[\Gamma] \vdash_b \text{match } x \text{ with } (C_i \Rightarrow \lambda y_{i1} \dots \lambda y_{i \text{NM}_{C_i}}. t_i)_{i=1 \dots h} \text{ end}} \\
\frac{E[\Gamma :: (x : T)] \vdash_b t \quad T \text{ is a non-dependent inductive type}}{E[\Gamma] \vdash_b \lambda x : T. t} \\
\frac{E[\Gamma] \vdash_f \text{fix } (f_i : T_i := t_i)_{i=1 \dots h} \text{ for } f_j}{E[\Gamma] \vdash_b \text{fix } (f_i : T_i := t_i)_{i=1 \dots h} \text{ for } f_j} \\
\\
\frac{E[\Gamma] \vdash t : T \quad T \text{ is a non-dependent inductive type} \quad E[\Gamma] \vdash_b t}{E[\Gamma] \vdash_f t} \\
\frac{E[\Gamma :: (x : T)] \vdash_f t \quad T \text{ is a non-dependent inductive type}}{E[\Gamma] \vdash_f \lambda x : T. t} \\
\frac{E[\Gamma :: (f_1 : T_1) :: \dots :: (f_h : T_h)] \vdash_f t_i}{E[\Gamma] \vdash_f \text{fix } (f_i : T_i := t_i)_{i=1 \dots h} \text{ for } f_j}
\end{array}$$

4.2 Detection of Inlinable Fixpoints

We detect inlinable fixpoints. “Inlinable fixpoint” means a fixpoint, $\text{fix } (f_i / k_i := t_i)_{i=1 \dots h} \text{ for } f_j$, which all application to f_i is located at the tail positions of $f_1 \dots f_h$. In this case, the continuation of the applications to $f_1 \dots f_h$ in $\text{let } x := (\text{fix } (f_i / k_i := t_i)_{i=1 \dots h} \text{ for } f_j) x_1 \dots x_n \text{ in } u$ are always $\text{let } x := \square \text{ in } u$. Thus, we can translate the tail positions of $f_1 \dots f_h$ to (1) assignments to the arguments of f_i and $\text{goto } f_i$ for application to f_i and (2) assignment to x and $\text{goto } u$ otherwise. This translation is equivalent to inlining a recursive function, which means generating a loop at a non-tail position.

$\text{TR}[\![t]\!]_n$ is the first element of $\text{RNT}[\![t]\!]_n$. $(R, N, T) = \text{RNT}[\![t]\!]_n$ classify variables in t assuming that it is called with n arguments as $t\ x_1 \dots x_n$:

R : tail-recursive fixpoint bounded functions that do not need to be real functions

N : free variables at non-tail positions of t

T : free variables at tail positions of t

“tail position” is extended to the function position of the application at a tail position.

R distinguishes fixpoint bounded functions translatable without actual functions (but with **goto**) or not.

$$\text{TR}[\![t]\!]_n = R \quad \text{where} \quad (R, N, T) = \text{RNT}[\![t]\!]_n$$

$$\text{RNT}[\![t]\!]_n =$$

$$\left\{ \begin{array}{ll} (\emptyset, \emptyset, \{x\}) & t = x \\ (\emptyset, \emptyset, \emptyset) & (t = c) \vee (t = C) \\ (R, N \cup \{x\}, T) & t = u\ x \quad \text{where} \quad (R, N, T) = \text{RNT}[\![u]\!]_{n+1} \\ (R_1 \cup R_2, N_1 \cup T_1 \cup N_2 - \{x\}, T_2 - \{x\}) & t = \text{let } x := t_1 \text{ in } t_2 \\ & \text{where } (R_1, N_1, T_1) = \text{RNT}[\![t_1]\!]_0 \quad (R_2, N_2, T_2) = \text{RNT}[\![t_2]\!]_n \\ (\bigcup_{i=1}^h R_i, \bigcup_{i=1}^h N_i, \bigcup_{i=1}^h T_i) & t = \text{match } x \text{ with } (C_i \Rightarrow t_i)_{i=1\dots h} \text{ end} \\ & \text{where } (R_i, N_i, T_i) = \text{RNT}[\![t_i]\!]_{n+\text{NM}_{C_i}} \\ (R, N - \{x\}, T - \{x\}) & (t = \lambda x. u) \wedge (n > 0) \quad \text{where} \quad (R, N, T) = \text{RNT}[\![u]\!]_{n-1} \\ (R, (N \cup T) - \{x\}, \emptyset) & (t = \lambda x. u) \wedge (n = 0) \quad \text{where} \quad (R, N, T) = \text{RNT}[\![u]\!]_{\text{NA}_u} \quad (\text{closure}) \\ (\bigcup_{i=1}^h R_i \cup \{f_1, \dots, f_h\}, & (t = \text{fix } (f_i := t_i)_{i=1\dots h} \text{ for } f_j) \\ \bigcup_{i=1}^h N_i - \{f_1, \dots, f_h\}, & \wedge (n = \text{NA}_t) \wedge (\bigcup_{i=1}^h N_i \cap \{f_1, \dots, f_h\} = \emptyset) \\ \bigcup_{i=1}^h T_i - \{f_1, \dots, f_h\}) & \text{where } (R_i, N_i, T_i) = \text{RNT}[\![t_i]\!]_{\text{NA}_{t_i}} \\ (\bigcup_{i=1}^h R_i, & (t = \text{fix } (f_i := t_i)_{i=1\dots h} \text{ for } f_j) \quad (\text{real function, maybe closure}) \\ \bigcup_{i=1}^h (N_i \cup T_i) - \{f_1, \dots, f_h\}, & \wedge \neg((n = \text{NA}_t) \wedge (\bigcup_{i=1}^h N_i \cap \{f_1, \dots, f_h\} = \emptyset)) \\ \emptyset) & \text{where } (R_i, N_i, T_i) = \text{RNT}[\![t_i]\!]_{\text{NA}_{t_i}} \end{array} \right.$$

Note:

- NA_t is the number of arguments of t : $\text{NA}_t = m$ if $t : T_1 \rightarrow \dots \rightarrow T_m \rightarrow T_0$ and T_0 is an inductive type.
- The variables in t are unique. Codegen uses de Bruijn’s indexes for N and T ; the variables renamed by Section 3.13 for R .
- x of **match** x **with** $(C_i \Rightarrow t_i)_{i=1\dots h}$ **end** is not counted because x is not a function and does not affect the final result.

4.3 Top-Level Functions Detection

If a fixpoint needs recursive call in C, we need a real C function for it. Codegen detects such fixpoints by simulating A_K and B_K in Section 4.5 and Section 4.6 to collect application of fixpoint-bounded functions.

4.4 Outer-Variable

4.5 Translation to C for a Non-Tail Position

$A_K[\![t / x_1 \dots x_n]\!]$ generates C code for $t\ x_1 \dots x_n$ in a non-tail position. The result expression is passed to K .

$K(e) = “v = e;”$ in simple situations.

$A_K \llbracket x / \rrbracket = K(“x”)$	
$A_K \llbracket x / x_1 \dots x_n \rrbracket = “\text{passign}(\text{fvars}' \llbracket x \rrbracket, x_1 \dots x_n)$	$(n > 0) \wedge x$ is bounded by a fixpoint \wedge
$\quad \text{goto entry } x;”$	$x \in TR$
$A_K \llbracket x / x_1 \dots x_n \rrbracket = K(“x(y_1, \dots, y_o, x_1, \dots, x_n)”)$	$(n > 0) \wedge x$ is bounded by a fixpoint \wedge
	$x \notin TR$
$A_K \llbracket c / x_1 \dots x_n \rrbracket = K(“c(x_1, \dots, x_n)”)$	$n \geq 0$
$A_K \llbracket C / x_1 \dots x_n \rrbracket = K(“C(x_1, \dots, x_n)”)$	$n \geq 0$
$A_K \llbracket t x_0 / x_1 \dots x_n \rrbracket = A_K \llbracket t / x_0 x_1 \dots x_n \rrbracket$	
$A_K \llbracket \text{let } x := t_1 \text{ in } t_2 / x_1 \dots x_n \rrbracket = “A_{K'} \llbracket t_1 / \rrbracket$	where $K'(e) = “x = e;”$
$\quad A_K \llbracket t_2 / x_1 \dots x_n \rrbracket”$	
$A_K \llbracket \lambda x. t / x_1 x_2 \dots x_n \rrbracket = A_K \llbracket t / x_2 \dots x_n \rrbracket$	$(x \text{ and } x_1 \text{ are mapped to the same C variable})$
$A_K \llbracket \text{match } x \text{ with } (C_i \Rightarrow \lambda y_{i1} \dots \lambda y_{i \text{NM}_{C_i}} \cdot t_i)_{i=1 \dots h} \text{ end}$	where $x : T$
$\quad / x_1 \dots x_n \rrbracket =$	
$\quad “\text{switch } (swfunc_T(x)) \{$	
$\quad \dots$	
$\quad \text{caselabel}_{C_i} : \quad y_{i1} = \text{get_member}_{C_{i1}}(x); \dots;$	
$\quad \quad y_{i \text{NM}_{C_i}} = \text{get_member}_{C_i \text{NM}_{C_i}}(x);$	
$\quad \quad \text{linear_dealloc}_T(x);$	
$\quad \quad A_K \llbracket t_i / x_1 \dots x_n \rrbracket$	
$\quad \quad \text{break};$	
$\quad \dots$	
$\quad \}”$	
$A_K \llbracket \text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j / x_1 \dots x_n \rrbracket =$	$f_j \in TR$
$\quad “\text{passign}(\text{fvars} \llbracket t_j \rrbracket, x_1 \dots x_n)$	where
$\quad \text{GENBODY}_{K'}^{\text{AT}} \llbracket \text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j \rrbracket$	$K'(e) = \begin{cases} K(e) & K(e) \text{ contains } \text{goto} \\ “K(e) & \text{otherwise} \\ \text{goto exit-}f_j;” & \end{cases}$
$\quad \text{exit-}f_j;”$	
$A_K \llbracket \text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j / x_1 \dots x_n \rrbracket =$	$f_j \notin TR$
$\quad “K(f_j(y_1, \dots, y_o, x_1, \dots, x_n))$	
$\quad \text{goto skip-}f_j;$	
$\quad \text{GENBODY}^{\text{AN}} \llbracket \text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j \rrbracket$	
$\quad \text{skip-}f_j;”$	

Note:

- “...” means a string. A string can contain characters in typewriter font and expressions starting in italic or roman font. The former is preserved as-is. The latter embeds the value of the expression (with name translation from Gallina to C).
- Gallina types, constants, and constructors have corresponding (user-configurable) C names and they are implicitly translated. Gallina variables are translated by the mapping defined in Section 3.13.
- $TR = \text{TR} \llbracket t \rrbracket_n$ where the translating function is defined as **Definition** $c := t$ and t is an n -arguments function.
- $swfunc_T$, $caselabel_{C_i}$, and $get_member_{C_{ij}}$ are defined by a user to translate **match**-expressions for the inductive type T .
- $\text{passign}(y_1 \dots y_n, x_1 \dots x_n)$ is a parallel assignment. It is translated to a sequence of assignments to assign $x_1 \dots x_n$ into $y_1 \dots y_n$. It may require temporary variables.

- y_1, \dots, y_o are the outer variables of the fixpoint.
- We do not define $A_K[\lambda x. t /]$ because we do not support closures yet.
- Actual Codegen generates $\text{GENBODY}^{\text{AN}}[\![\]\!]$ in a different position to avoid the label `skip- f_j` and `goto- f_j` .
- $\text{linear_dealloc}_T(x)$ is the deallocation function for the linear type T . It is empty for unrestricted types.

4.6 Translation to C for a Tail Position

$B_K[t / x_1 \dots x_n]$ generates C code for $t x_1 \dots x_n$ in a tail position. The result expression is passed to K . $K(e) = \text{"return } e; \text{"}$ in simple situations.

$$\begin{aligned}
B_K[x /] &= K(\text{"x"}) \\
B_K[x / x_1 \dots x_n] &= \text{"passign(fvars'[\![x]\!], } x_1 \dots x_n \text{)"} & (n > 0) \wedge x \text{ is bounded by a fixpoint} \\
&\quad \text{goto entry_x;"} \\
B_K[c / x_1 \dots x_n] &= K(\text{"c(x}_1, \dots, x_n)\text{"}) & n \geq 0 \\
B_K[C / x_1 \dots x_n] &= K(\text{"C(x}_1, \dots, x_n)\text{"}) & n \geq 0 \\
B_K[t x_0 / x_1 \dots x_n] &= B_K[t / x_0 x_1 \dots x_n] \\
B_K[\text{let } x := t_1 \text{ in } t_2 / x_1 \dots x_n] &= \text{"A}_{K'}[\![t_1 /]\!] & \text{where } K'(e) = \text{"x = e;"} \\
&\quad B_K[\![t_2 / x_1 \dots x_n]\!] \\
B_K[\lambda x. t / x_1 x_2 \dots x_n] &= B_K[t / x_2 \dots x_n] & (x \text{ and } x_1 \text{ are mapped to the same C variable)} \\
B_K[\text{match } x \text{ with } (C_i \Rightarrow \lambda y_{i1} \dots \lambda y_{i \text{NM}_{C_i}} \cdot t_i)_{i=1 \dots h} \text{ end}] &= \text{where } x : T \\
&\quad / x_1 \dots x_n] = \\
&\quad \text{"switch (swfunc}_T(x)) \{ \\
&\quad \dots \\
&\quad \text{caselabel}_{C_i} : \quad y_{i1} = \text{get_member}_{C_{i1}}(x); \dots; \\
&\quad \quad y_{i \text{NM}_{C_i}} = \text{get_member}_{C_i \text{NM}_{C_i}}(x); \\
&\quad \quad \text{linear_dealloc}_T(x); \\
&\quad \quad B_K[\![t_i / x_1 \dots x_n]\!] \\
&\quad \dots \\
&\quad \} \text{"} \\
B_K[\text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j / x_1 \dots x_n] &= \\
&\quad \text{"passign(fvars[\![t_j]\!], } x_1 \dots x_n \text{)"} \\
&\quad \text{GENBODY}_K^B[\text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j] \text{"}
\end{aligned}$$

Note:

- We do not define $B_K[\lambda x. t /]$ because a tail position cannot be a function after the argument completion.

4.7 Auxiliary Functions for Translation to C

$$\begin{aligned}
\text{fvars}[\![t]\!] &= \begin{cases} \text{"x; fvars}[\![u]\!]" & t = \lambda x. u \\ \text{fvars}[\![t_j]\!] & t = \text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j \\ \text{"} & \text{otherwise} \end{cases} \\
\text{fvars}'[\![f_i]\!] &= \text{fvars}[\![t_i]\!] \quad \text{for functions bounded by } \text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j \\
\text{GENBODY}_K^{\text{AT}}[\![t]\!] &= \begin{cases} \text{GENBODY}_K^{\text{AT}}[\![u]\!] & t = \lambda x. u \\ \text{"entry_f}_i : \text{GENBODY}_K^{\text{AT}}[\![t_i]\!]" & t = \text{fix } (f_i := t_i)_{i=1 \dots h} \text{ for } f_j \\ \quad \text{for } i = j, 1, \dots, (j-1), (j+1), \dots, h & \\ \text{A}_K[\![t /]\!] & \text{otherwise} \end{cases}
\end{aligned}$$

$$\begin{aligned}
\text{GENBODY}^{\text{AN}}[t] &= \begin{cases} \text{GENBODY}^{\text{AN}}[u] & t = \lambda x. u \\ \text{"entry-}f_i\text{: GENBODY}^{\text{AN}}[t_i]\text{"} & t = \text{fix}(f_i := t_i)_{i=1\dots h} \text{ for } f_j \\ \text{for } i = 1, \dots, h & \\ B_K[t /] & \text{otherwise} \end{cases} \\
&\quad \text{where} \\
&\quad t : T \\
&\quad K(e) = \text{"*(T*)ret = e; return;"} \\
\text{GENBODY}_K^{\text{B}}[t] &= \begin{cases} \text{GENBODY}_K^{\text{B}}[u] & t = \lambda x. u \\ \text{"entry-}f_i\text{: GENBODY}_K^{\text{B}}[t_i]\text{"} & t = \text{fix}(f_i := t_i)_{i=1\dots h} \text{ for } f_j \\ \text{for } i = j, 1, \dots, (j-1), (j+1), \dots, h & \\ B_K[t /] & \text{otherwise} \end{cases}
\end{aligned}$$

Note:

- `fvars` and `fvars'` returns a list of variables: $x_1; \dots; x_n$. For simplicity, we omit “;” if not ambiguous.
- “ $g(i)$ ” for $i = j_1, \dots, j_n$ means “ $g(j_1) \dots g(j_n)$ ”.

4.8 Translation for a Top-Level Function which is Translated to Multiple C Functions

$\text{GENFUN}^{\text{M}}[c]$ translates the function (constant) c with one or more auxiliary functions. We assume c is defined as **Definition** $c := t$. The auxiliary functions $f_1 \dots f_n$ are fixpoint bounded functions in t which are invoked as functions. We assume the types of them:

$$\begin{aligned}
c &: T_{01} \rightarrow \dots \rightarrow T_{0m_0} \rightarrow T_{00} \\
f_i &: T_{i1} \rightarrow \dots \rightarrow T_{im_i} \rightarrow T_{i0} \quad i = 1 \dots n
\end{aligned}$$

where T_{i0} are inductive types ($i = 0 \dots n$)

The formal arguments of c are $x_{01} \dots x_{0m_0} = \text{fvars}[t]$ and the formal arguments of f_i are $x_{i1} \dots x_{im_i} = \text{fvars}'[f_i]$.

f_i invocation in C needs extra arguments, $y_{i1}:U_{i1} \dots y_{io_i}:U_{io_i}$, addition to the actual arguments in Gallina application because the free variables of the fixpoint should also be passed. If the free variables contain a function bounded by an outer fixpoint, the function itself is not passed but the free variables of the outer fixpoint are also passed. We iterate it until no fixpoint functions.

$$\text{GENFUN}^{\text{M}}[c] = \text{"enum_entries}[c] \text{ arg_structdefs}[c] \text{ forward_decl}[c] \text{ entry_functions}[c] \text{ body_function}[c]\text{"}$$

$$\text{enum_entries}[c] = \text{"enum enum_func_c \{func_c, func_f_1, \dots, func_f_n\};"}\text{"}$$

$$\text{arg_structdefs}[c] = \text{"main_structdef}[c] \text{ aux_structdef}[c]_1 \dots \text{aux_structdef}[c]_n\text{"}$$

$$\text{main_structdef}[c] = \text{"struct arg_c \{ T_{01} arg1; \dots; T_{0m_0} argm_0; \};"}\text{"}$$

$$\text{aux_structdef}[c]_i = \text{"struct arg_f_i \{ U_{i1} outer1; \dots; U_{io_i} outero_i; T_{i1} arg1; \dots; T_{im_i} argm_i; \};"}\text{"}$$

$$\text{forward_decl}[c] = \text{"static void body_function_c(enum enum_func_c g, void *arg, void *ret);"}\text{"}$$

$$\text{entry_functions}[c] = \text{"main_function}[c] \text{ aux_function}[c]_1 \dots \text{aux_function}[c]_n\text{"}$$

$$\begin{aligned}
\text{main_function}[c] &= \text{"static T_{00} c(T_{01} x_{01}, \dots, T_{0m_0} x_{0m_0}) \{ } \\
&\quad \text{struct arg_c arg} = \{x_{01}, \dots, x_{0m_0}\}; T_{00} \text{ ret;} \\
&\quad \text{body_function_c(func_c, \&arg, \&ret); return ret;} \\
&\quad \} \text{"}
\end{aligned}$$

```

aux_function[[c]]i = “static Ti0 fi(Ui1 yi1, ..., Uioi yioi, Ti1 xi1, ..., Timi ximi) {
    struct arg_fi arg = {yi1, ..., yioi, xi1, ..., ximi}; Ti0 ret;
    body_function_c(func_fi, &arg, &ret); return ret;
}”

```

```

body_function[[c]] = “static void body_function_c(enum enum_func_c g, void *arg, void *ret) {
    decls
    switch (g) { aux_case[[c]]1 ... aux_case[[c]]n main_case[[c]] }
    GENBODYBK[[t]]
}”

```

```

aux_case[[c]]i = “case func_fi:
    yi1 = ((struct arg_fi *)arg)->outer1; ...; yioi = ((struct arg_fi *)arg)->outeroi;
    xi1 = ((struct arg_fi *)arg)->arg1; ...; ximi = ((struct arg_fi *)arg)->argmi;
    goto entry_fi;”

```

```

main_case[[c]] = “default::
    x01 = ((struct arg_c *)arg)->arg1; ...; x0m0 = ((struct arg_c *)arg)->argm0;”

```

where *decls* is local variable declarations for variables used in GENBODY^B_K[[t]].

$K(e) = “*(T_{00}*)ret = e; return;”$

4.9 Translation for a Top-Level Function which is Translated to a Single C Function

GENFUN^S[[c]] translates the function (constant) *c* to a single C function.

```

GENFUNS[[c]] = “static T0 c(fargs'[[t]]) { decls GENBODYBK[[t]] }”

```

where *c* is defined as **Definition** $c : T_1 \rightarrow \dots \rightarrow T_n \rightarrow T_0 := t$.

*T*₀ is an inductive type

decls is local variable declarations for variables used in GENBODY^B_K[[t]] excluding fargs[[t]].

$K(e) = “return e;”$

$$\text{fargs}[[t]] = \begin{cases} “T\ x, \text{fargs}[[u]]” & t = \lambda x:T. u \\ \text{fargs}[[t_j]] & t = \text{fix}(f_i := t_i)_{i=1\dots h} \text{ for } f_j \\ “” & \text{otherwise} \end{cases}$$

fargs'[[t]] = fargs[[t]] without the trailing comma

4.10 Translation for Top-Level Function

$$\text{GENFUN}[[c]] = \begin{cases} \text{GENFUN}^M[[c]] & t \text{ needs multiple functions} \\ \text{GENFUN}^S[[c]] & \text{otherwise} \end{cases}$$

where *c* is defined as **Definition** $c := t$.

References

- [1] The Coq Development Team. The coq reference manual: Release 8.12.0. 2020.