Solving Ordinary Differential Equations (ODEs) using Python

Simple differential equations can be solved numerically using the Euler-Cromer method, but more complicated differential equations may require a more sophisticated method. The scipy library for Python contains numerous functions for scientific computing and data analysis. It includes the function odeint for numerically solving sets of first-order, ordinary differential equations (ODEs) using a sophisticated algorithm. Any set of differential equations can be written in the required form. The example below calculates the solution to the following second-order differential equation,

$$\frac{d^2y}{dt^2} = ay + b\frac{dy}{dt}.$$

It can be rewritten as the following two first-order differential equations,

$$\frac{dy}{dt} = y'$$
 and $\frac{dy'}{dt} = ay + by'$.

Notice that the first of these equations is really just a definition. In Python, the function y and its derivative y' will be part of elements of an array. The function y will be the first element y[0] (remember that the lowest index of an array is zero, not one) and the derivative y' will be the second element y[1]. In this case, you can think of the index as how many derivatives are taken of the function. In this notation, the differential equiations are

$$\frac{dy[0]}{dt} = y[1]$$
 and $\frac{dy[2]}{dt} = ay[0] + by[1]$.

The odeint function requires a function (called deriv in the example below) that will return the first derivative of each of element in the array. In other words, the first element returned is dy[0]/dt and the second element is dy[1]/dt, which are both functions of y[0] and y[1]. You must also provide initial values for y[0] and y[1] which are placed in the array yinit in the example below. Finally, the values of the times at which solutions are desired are provided in the array time.

```
from scipy import odeint
from pylab import * # for plotting commands

def deriv(y,t): # return derivatives of the array y
    a = -2.0
    b = -0.1
    return array([ y[1], a*y[0]+b*y[1] ])

time = linspace(0.0,10.0,1000)
yinit = array([0.0005,0.2]) # initial values
y = odeint(deriv,yinit,time)

figure()
plot(time,y[:,0]) # y[:,0] is the first column of y
xlabel('t')
ylabel('y')
show()
```

Note that odeint returns the values of both the function y[0] = y and its derivative y[1] = y' at each time. In the example above, the function is plotted versus the time.

For a second example, suppose that you want to solve the following coupled, second-order differential equations,

$$\frac{d^2x}{dt^2} = ay$$
 and $\frac{d^2y}{dt^2} = b + c\frac{dx}{dt}$.

In order to rewrite these equations as a set of first-order differential equations, start by defining

$$\frac{dx}{dt} = x'$$
 and $\frac{dy}{dt} = y'$.

The original equations can be written as

$$\frac{dx'}{dt} = ay$$
 and $\frac{dy'}{dt} = b + cx'$.

To use odeint, the four first-order equations must be written as elements of an array. If we make the definitions,

$$z[0] = x$$
, $z[1] = x'$, $z[2] = y$, and $z[3] = y'$,

then the four equations become

$$\frac{dz[0]}{dt} = z[1], \quad \frac{dz[1]}{dt} = az[2], \quad \frac{dz[2]}{dt} = z[3], \text{ and } \frac{dz[3]}{dt} = b + cz[1].$$

These equations are now in a form necessary for the derivative function, which would be an array with four elements. Notice that the index of the array is not the number of derivatives of a single function in this case.

Exercise:

An example of a differential equation that exhibits chaotic behavior is

$$\frac{d^3x}{dt^3} = -2.017 \frac{d^2x}{dt^2} + \left(\frac{dx}{dt}\right)^2 - x.$$

- (a) Write the differential equation as a set of *first-order* differential equations.
- (b) Modify the example program to solve the equations with the initial conditions of x = 0, dx/dt = 0, and $d^2x/dt^2 = 1$.
- (c) Plot the results for t from 0 to 100.

Additional documentation is available at:

http://docs.scipy.org/doc/scipy/reference/generated/scipy.integrate.odeint.html http://docs.scipy.org/doc/scipy/reference/tutorial/integrate.html