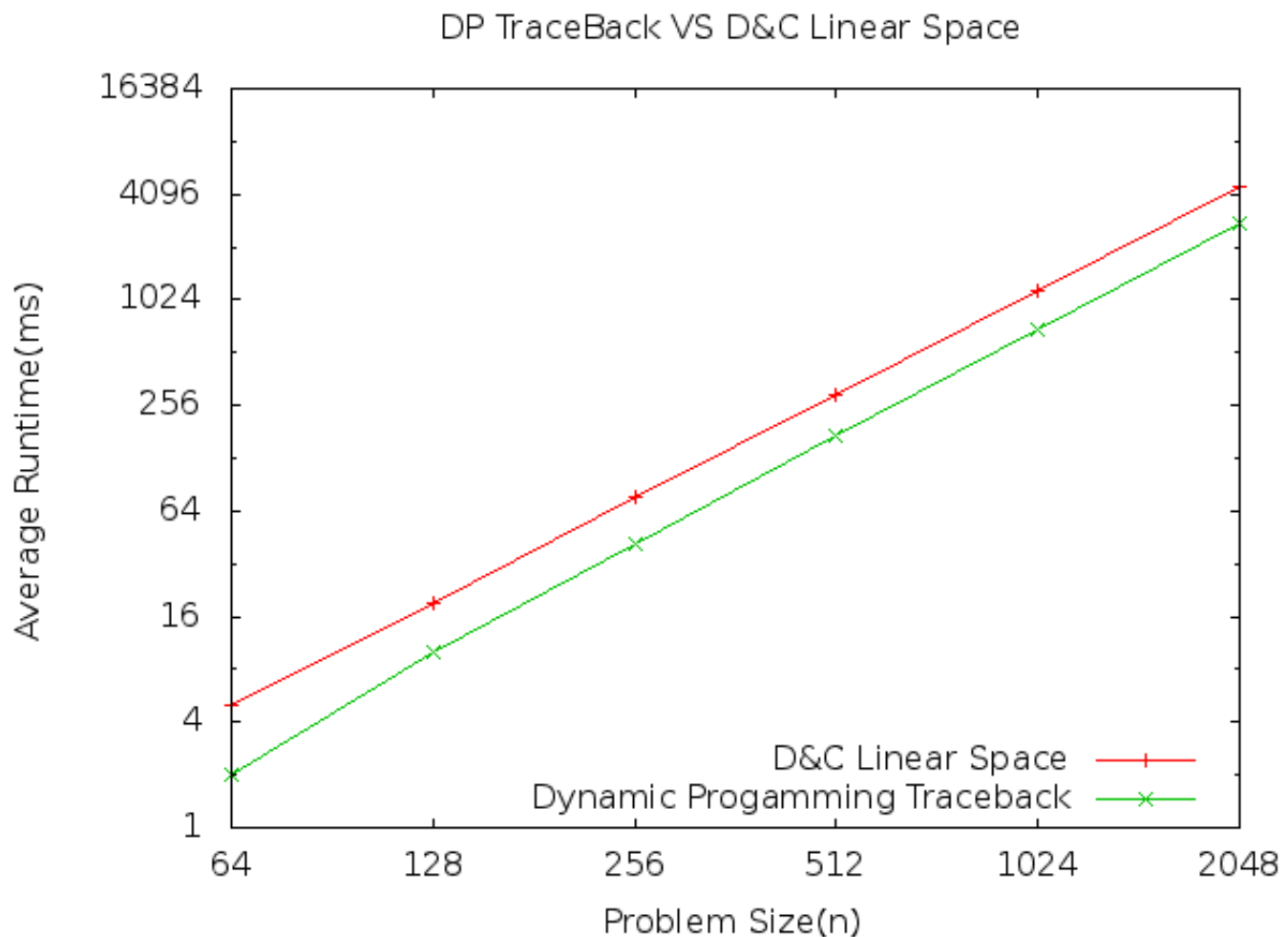


Assignment 2 - Knapsack

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This assignment compares the **Dynamic Programming Traceback** method with the **Divide and Conquer Linear-Space** algorithm. We know that the Dynamic Programming method is faster but it takes a lot of space. We are trying to use the Divide and Conquer method to get those same results with a linear space algorithm. We have designed it to take about two times as long but it is in n space instead of n^2 space.

Here are the results. I used problem sizes from 64 to as much as I can increasing the problem size by two.



This plots the average runtime vs problems size (Number of items available). I averaged the run times over 30 runs. The actual data can be found in the file dynamicVSlinear.

What is the difference between the lines?

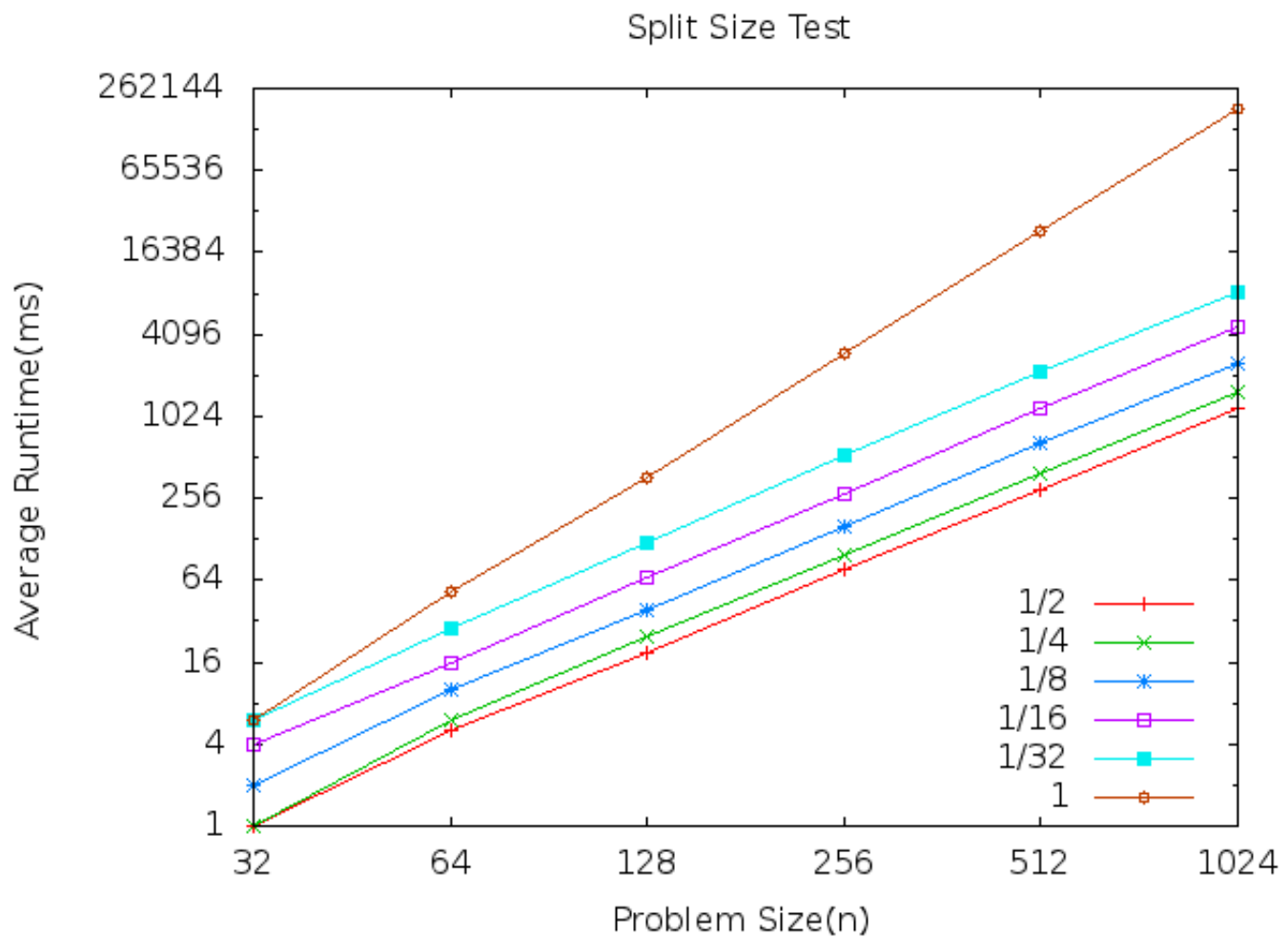
As we can see from the lines on the graph, the D&C Linear Space algorithm is taking very close to **twice as long**. This is exactly what we had hoped to see from our algorithm analysis!

How much larger problems can you solve with the D&C compared to the original algorithm?

We can solve a problem that is much larger. With the dynamic programming we can only solve a problem of about size $\sqrt{\text{memory}}$. With the D&C we can now solve a problem that is about $\text{memory}/4$. We can't go quite to those sizes because we can't completely max out our memory and there is some overhead but the difference between size $\sqrt{\text{memory}}$ and $\text{memory}/4$ is huge!

How is the runtime affected by splitting the problem into different sizes?

I also compared the split size on the recursion to see if it is better to always split the problem in half. It tests where the problem is still split in two but it is split where one side is $n \times k$ and the other is $n \times (1-k)$. Where $k = 1/2, 1/4, 1/8, 1/16, 1/32, 1$. This is a test to see what difference it makes when we split the problem.



It is very interesting to note that the difference between the different splits is a **constant** factor. Except $k=1$. This seems to be exponential. So splitting the problem even if the split is small makes a big difference on the runtime!