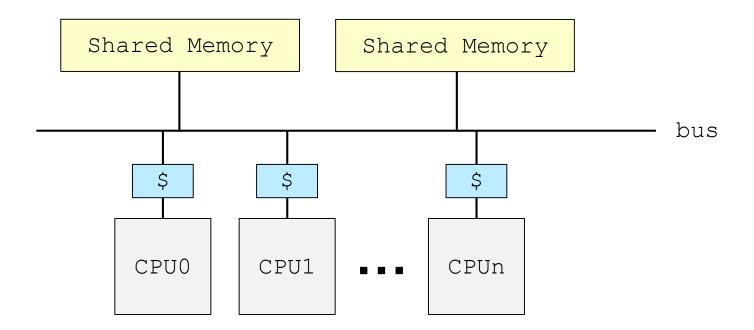
Running Programs on a System

Advanced Process Scheduling

SMP Scheduling

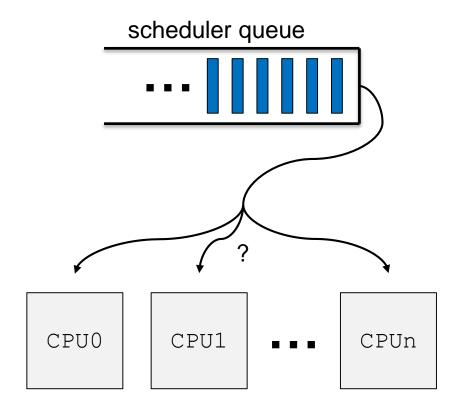
Symmetric Multiprocessor (SMP)

- Multiprocessor with shared memory
 - limited number of homogeneous CPUs with private cache
 - equal/similar access time to shared memory



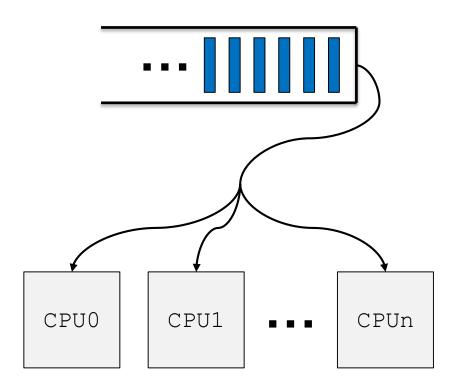
Multiprocessor Scheduling

How should tasks get distributed?



Global Queue

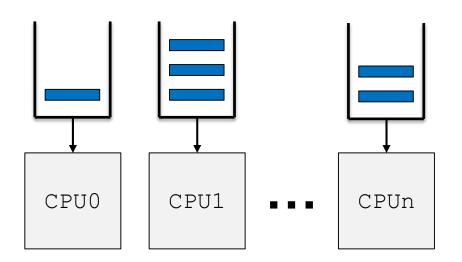
- each core runs his own scheduler
- global queue shared data structure



- + fairness
- + CPU utilization
- scalability
- cache locality

Local (per-CPU) Queue

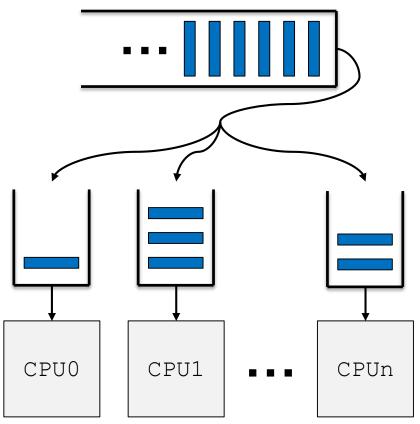
- each core runs his own scheduler
- local queue private data structure
- static assignment of processes to CPUs



- + scalability
- + cache locality
- + simplicity
- load balancing

Local (per-CPU) Queue with Load Balancing

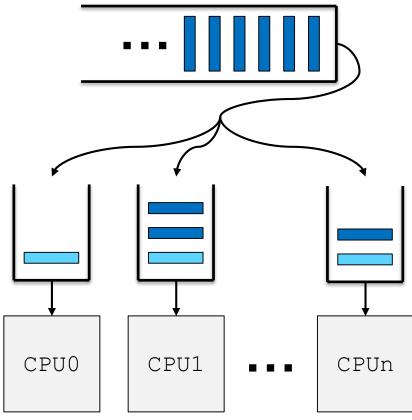
- hybrid approach between global & local queues
- schedule locally, balance globally
- processor affinity



- + best of both worlds
- complexity

Gang Scheduling

- parallel tasks may need coordination and should be scheduled simultaneously
- local scheduler queue does not act independently
- global context switch



History of the Linux Scheduler

History of the Linux Scheduler

Original Scheduler Linux 1.0 (1995)

- circular runqueue
- round robin scheduling

O(N) Scheduler Linux 2.4 (2001) epochs and timeslices

complexity O(N)

Scheduling Classes Linux 2.2 (1999) rt, non-rt, non-preemptable, normal scheduling classes support for SMP epoch and task selection

> O(1) Scheduler Linux 2.6 (2003)

- run queues that allow task selection in O(1)
- lots of heuristics to determine a task's CPU/IO-boundness

Completely Fair Scheduler (CFS) Linux 2.6.23 (2008)

- models an ideal, precise multitasking CPU on real hardware
- completely fair balancing of processor time between tasks

The O(N) Scheduler

- timeslice: assigned to each task at the beginning of an epoch
 - depends on priority and unused timeslice in last epoch
 - fork(): parent/child share remaining timeslice (each gets half)
- epoch: scheduling "generation"
 - initialization: sum of all timeslices
 - end of epoch: no ready-to-run tasks has timeslice > 0
- goodness(): selection of next task to run

```
max_goodness = 0
max_t = idle_task

foreach runnable task t
  if ((g = goodness(t)) > max_goodness)
    max_goodness = g
    max_t = t

dispatch(max t)
```

The O(N) Scheduler

issues

- does not scale well
 - epoch calculation: O(# tasks)
 - task selection: O(# runnable tasks)
- favors I/O bound tasks
 - maybe okay for server, less so for desktops
- predefined minimal quantum is too long
 - long latency under high system load
- weak support for real-time processes

The O(1) Scheduler

two main ideas

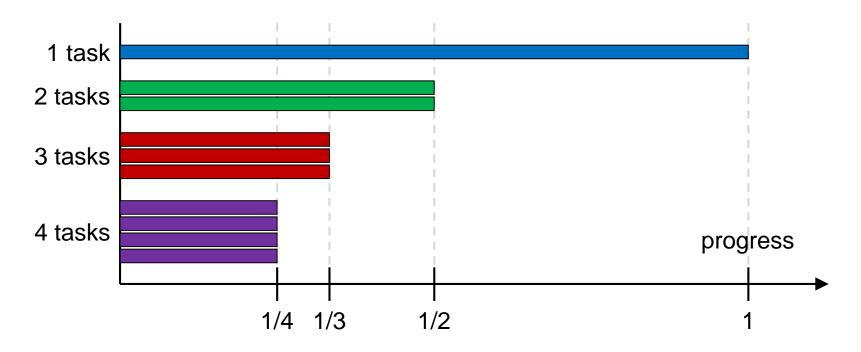
- active and expired runqueues
 - active runqueue: tasks with timeslice > 0
 - expired: tasks that have expired their timeslice
 - ▶ active → expired: task moved when timeslice reaches 0
 - new timeslice is computed upon insertion into expired
 - ▶ active runqueue empty → array swap
- pair of (active, expired) runqueues per priority level
 - scheduling: pick first task from first non-empty active runqueue of highest priority level → O(1)

The O(1) Scheduler

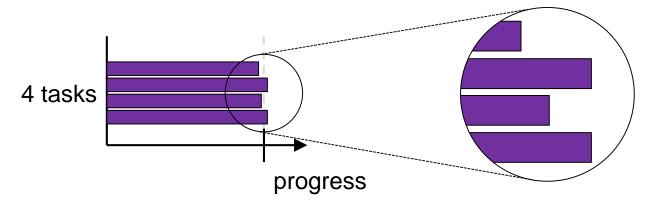
issues

- heuristics to determine CPU- resp. I/O-boundness of task
 - complex and error-prone
 - permitted attacks on the scheduler

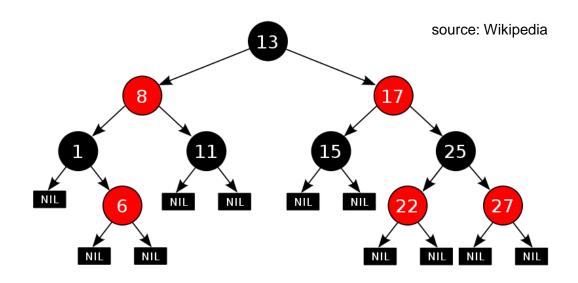
- Models an ideal, precise multitasking CPU
 - simultaneous process of tasks infinitesimally small timeslices, no task switching overhead
 - n runnable tasks progress uniformly at 1/nth of the CPU speed



- Each task's (of equal priority) timeslice = 1/n of the default task latency
 - task latency = maximum wait time
 - default: 20ms
 - lower bound timeslice (default: 4ms) may force increasing the task latency
 - priorities modeled with proportional sharing
- Selection of next task to run = pick task with minimum runtime so far
 - runtime accounting: vruntime (nanosecond granularity)



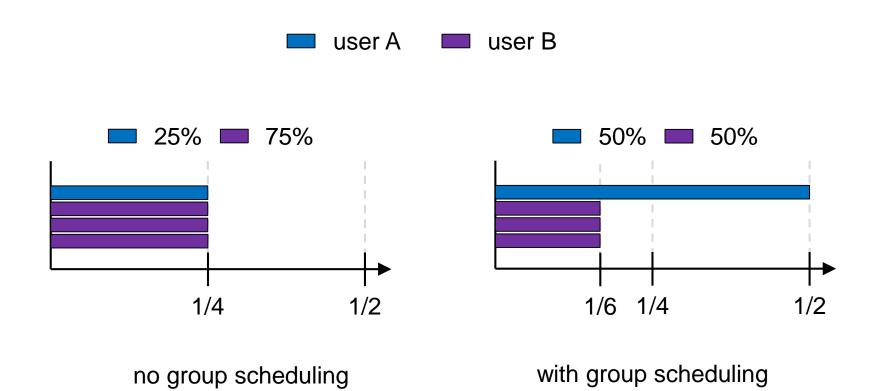
- Efficiently finding the task with minimum runtime
 - red-black tree
 - insertion & deletion: O(log N), find minimum: O(1)
 - ordered by runtime
 - task with minimum runtime is always left-most node



highest need of CPU

lowest need of CPU

- Group Scheduling
 - divide CPU time equally between groups instead of tasks



- Load balancing
 - active balancing periodically pull tasks over from busiest CPU
 - idle balancing as soon as there is no runnable task
 - migrated only if average idle time > migration cost