

35.6

We begin by re writing the system of equations as matrix multiplication (also let $\kappa = L$)

$$m \ddot{x}_1 = (-K - L)x_1 + Lx_2$$

$$m \ddot{x}_2 = (-K - L)x_2 + Lx_1$$

is encoded by

$$m \frac{d^2}{dt^2} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} -K-L & L \\ L & -K-L \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

we then make the ansatz that

$$\begin{bmatrix} x_1(t) \\ x_2(t) \end{bmatrix} = \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} e^{rt}, \text{ thus}$$

$$mr^2 \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} = \begin{bmatrix} -K-L & L \\ L & -K-L \end{bmatrix} \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} \quad (1)$$

and thus this substitution works if

$$M = \begin{bmatrix} -K-L & L \\ L & -K-L \end{bmatrix} \text{ has eigenvector } \begin{bmatrix} A_1 \\ A_2 \end{bmatrix} \text{ and eigenvalue } mr^2$$

We can find the eigenvalues by solving

$$\det \begin{pmatrix} -K-L-\lambda & L \\ L & -K-L-\lambda \end{pmatrix} = 0$$

for λ :

$$(-K-L-\lambda)^2 - L^2 = 0$$

implies

$$\lambda = -L - K \pm L = -K, -K - 2L$$

In order for our ansatz to hold, we must provide that
by setting that

$$mr^2 = \lambda \Rightarrow r = i\sqrt{\frac{K}{m}} \text{ or } r = \sqrt{\frac{K+2L}{m}}$$

Plugging in these r into (1), ^{and substituting where suitable,} we get that

$$L \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ A_2 \end{bmatrix} = 0 \Rightarrow \lambda = -k \Rightarrow \text{eigenvector} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{and for } \lambda = \text{MARK} - 2L, L \begin{bmatrix} -1 & -1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ A_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \Rightarrow \text{eigenvector} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$