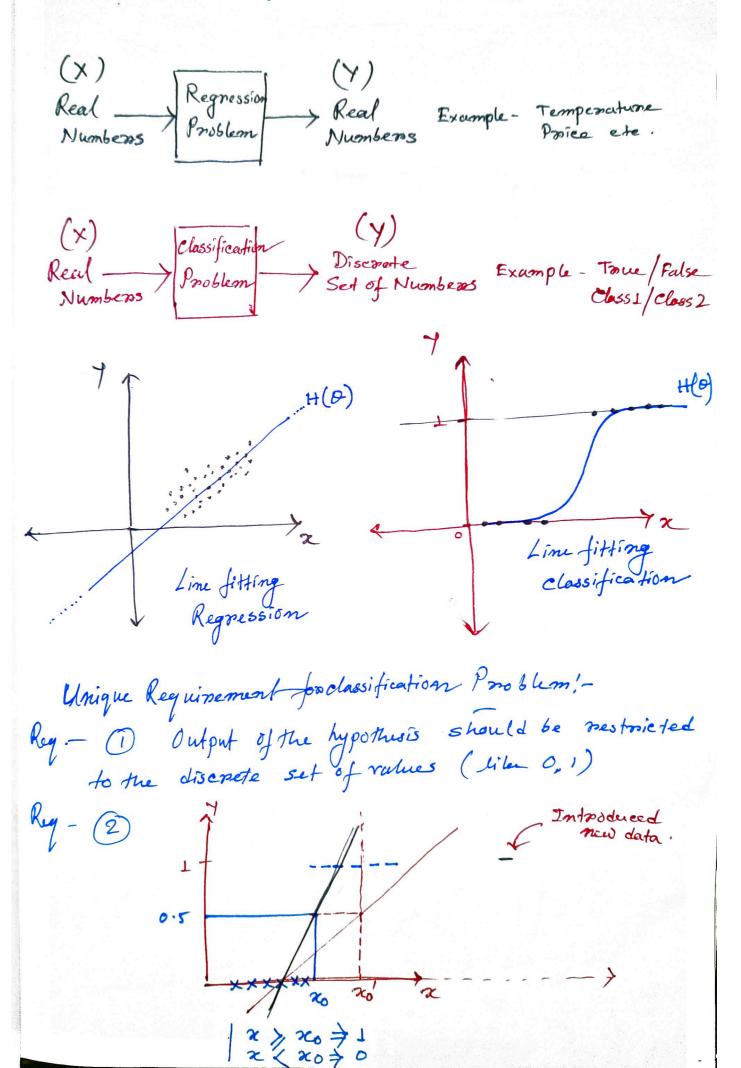
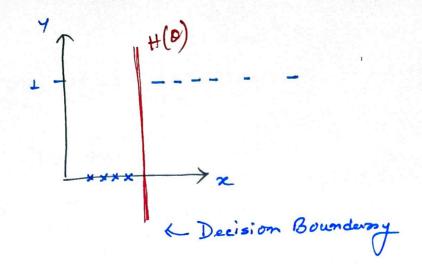
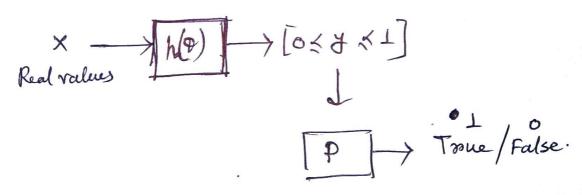
Regnession Vs Classification





So, unlike Regnession line, that passes through the points minimizing the distance from the duta points, for classification problem we will search for a Decision line/plane to separate different classes of duta."

So we need to develop a function like.



Sigmoid Function / Logistic function

$$g(z) = \frac{1}{1+e^{-z}}$$

For linear Regnassion

J = mx. on.

y = 0, x, + 82 x2 + 03 x3 + ... & n7ny + 8n.

= OTX [vectorized form]

Now passing output of L.R to Logisticfn. -

 $J = g(o^T x) = \frac{1}{1 + o^{-o^T x}}$

··· 0 x g(8 x) x 1

Now Let us interpret g(QTX) is the estimated probability of y=1 for given x. i.e . P(y=1/x) = ho(x) = g(otx)

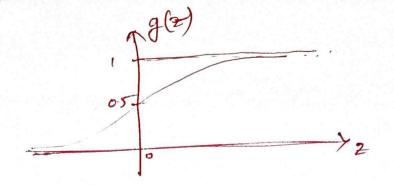
we know, y is either 0 or 1

P(y=1/x,0)+P(y=0/x,0) 21

P($y=0/x, \theta$) = 1- P($y=1/x, \theta$)
As we need to give the ofp as 0 on L (possible of value)

Let say if P(y21/20) > 0.5 => Y21 if P(y=1/2,8) < 0.5 => y=0

10(2) 1, 0.5 output y21



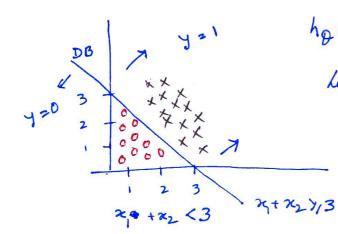
we predict 721

9(2) 1/0-5

Similarly

When 2 / 0

Otx (0 we predict y=0.



ho(x) = q (80+8,x,+8,x2)

let us assume we leaven the

Papameters like

$$\theta_0 = -3$$
, $\theta_1 = 1$, $\theta_2 = 1$

then, $\theta = \begin{bmatrix} -3 \\ 1 \end{bmatrix}$

To predict y = 1 ho(2) 7,0.5 > 8TX 7,000

-3+x1+x2 710

21+ x2 71 = 3

Non linears Decision Boundary
$$h_{\theta}(x) = g(\theta_{8} + \theta_{1}x_{1} + \theta_{2}x_{2} + \theta_{3}x_{1}^{2} + \theta_{4}x_{2}^{2})$$

Predictly=1) if.

-1 + 2/+ 2/10 2/+ 2/11

Equation of circle.

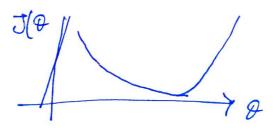
Cost Function

Linean Regnession Cost function-

$$J(\theta) = \frac{1}{m} \sum_{i>j} \frac{1}{2} \left(h_{Q}(x^{i}) - y^{i} \right)^{2}$$

and we mud to minimize $J(\theta)$ to find out the parameters is $\theta = \theta_0, \theta_1, \dots \theta_m$.

- I Remember we used numerical method called Gradient Descent to find out the minima value of $J(\theta)/\theta_0, \theta_1 \cdot \theta_n$.
- + To Remember Gradient Descent algorithm
 Wolld converge if J(8) vs & is a convex
 curre. like.



If we try to use linear regression Cost function for logistic regression it can be shown that the resultant cost function won't be convex any more. So we need to find out a new cost function for logistic Regression.

5(0)

Logistic Regression Cost Function $Cost(h_{\theta}(x), y) = \frac{3}{2} - log(h_{\theta}(x)) if y=1 \to 0$ - log(1-h_{\theta}(x)) if y=0.70 Plot -1 desmos: com/calculatos. We are only interested for the segment of 251 from Plot-1 for a date x; if we predict Ji=0 ie k(s) hg(x) =0 we can see the cost approaches to os and if diel (ie. conrect prediction) cost + 0 From Plot-2 for a data x: if we predict y: 21 ie ho(x)=1 we can see the cost approaches to or and for yizo (ie. correct prediction) cot to. Combining 29-1 & 5-2.

Cost (ho(x), y) = y * - log (ho(x)) - (1-y) log (1-ho(x))

This cost of n is convex in nature

So the Cost for logistic regression—
$$J(\theta) = \frac{1}{m} \sum_{i \ge 1}^{\infty} Cost(h_{\theta}(x_{i}), y_{i})$$

$$= \frac{1}{m} \sum_{i \ge 1}^{\infty} J_{\theta}(h_{\theta}(x_{i})) + (1 - y_{i}) \log(1 - h_{\theta}(x_{i}))$$
So we need to \rightarrow

No we need to
$$\rightarrow$$

minimize $(J(a))$ to get the a s

To minimize the &J(D) we would use G.D.

$$\frac{\partial j_{i+j}}{\partial y_{i}} = \frac{\partial j}{\partial y_{i}} - \frac{\partial j}{\partial y_{i}} = \frac{\partial j}{\partial y_{i}} = \frac{\partial j}{\partial y_{i}} \left(h_{0}(x^{i}) - y^{i} \right) x_{j}^{i}$$

$$\frac{1}{2} = 8j - \frac{1}{m} \sum_{i=1}^{m} (h_{0}(z^{i}) - y^{i}) \chi_{j}^{i}$$