

Splitting of Meshes in Image-Space

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Introduction

The main purpose of 3D computergraphics is to represent image data. To make these data examinable, user interaction becomes an important part. Hence, the user should be able to translate, rotate and scale the 3D object. With the complexity of the object, the desire to examine just parts of it rises. The examination and analysis of the objects' inner structures can also be of interest. That leads to the a complex problem that needs to be solved: How can we reveal the inner sturctures? By simply removing the outer structures, the context would also get lost that could be important for scientific findings. Hence, the idea is to reveal the point of interest whilst keeping the context. Therefor, several scientific approaches exist. One idea is to simply raise the opacity of the outer structures. For example to reveal a brain, the approach would be to simply raise the opacity of the scull and the skin respectively for making the parts of secondary interest semi-transparent. Another approach is to cut out parts of the outer structure of the object so that no information gets lost and still the inside would be fully visible. A different approach are so called explosion views that unfold the inside by breaking the outer struktures into multiple parts and shifting those apart whilst keeping the point of interest in the center.

This paper will examine several approaches to reveal inner structures of complex 3D models retaining the context to be able to examine the object in respect of its surroundings. TOEDIT In section BLA you will learn how to BLA and BLA BLA

Analysis of existing approaches

2.1 Literature studies

Exploring volume data is a complex task. Every research has different points or regions of interest (ROI) and the methods to reveal those regions depend on the purpose of the study. Hence, regions are classified by their *degree-of-interest* (DOI) [8]. A high DOI means a region is of high interest, a low DOI stands for a region of secondary interest.

There are tree main methods for revealing inner structures of an object:

- Transparency/Ghosted views
- Cut-away views
- Explosion views

Transparency/Ghosted views

These techniques do not discard any data points but let them vanish to a certain degree. Hence it lowers the opacity of certain data points. For example, the opacity of the outer structure of an object is decreased so that the inner structure is revealed [3].

Ghosting is often used in combination with cut-away views. This would mean that the region cut out is replaced by faded duplicate of the original. Features such as edges are attempted to be preserved. Therefor the *ghost* stands for the original region before cutting [1].

Increasing the transparency of occluding parts makes ROIs visible but at the same time makes it difficult to distinguish the several semi-transparent layers and identify their spatial composition [7].

Bruckner and Gröller [1] use a ghost object explicitly to preserve the context of illustrations. When the user defines a ROI, several transformations can be applied to it while at the original position, a faded version of the ROI will be visible.

In their work, Bruckner and Gröller describe a method with weighted membership functions of

background, ghost and selection respectively to define the color of the resulting illustration. The opacity for a point p will be determined by the grade of membership in the union of all sets.

Cut-away views

Cut-away views, also called cutaways, reveal ROIs that are occluded by objects of secondary interest. The latter are cut out in order to make the ROI visible [1] [2] [3] [6]. Omitting the occluding regions increases comprehension of spatial relationships between the components. Also, the position and orientation of ROIs are shown in context of their surrounding structures [7].

Methodology

3.1 Plug-ins in VolumeShop

VolumeShop is an interactive hardware-accelerated application for direct volume illustration [1]. It is designed for developers to have maximum flexibility for visualization research. Its objects can be dynamically created and accessed [9].

Plug-ins are functionally independent and can be dynamically loaded. One main advantage in development is that the application does not need to be closed when a plug-in is recompiled.

Properties

The complete state of a plug-in is defined by its properties which constitute the plug-ins' functionality [9]. A plug-in can be easily created with the following command.

An example for an integer property in the range [0,255]:

For extended functionality there is the possibility of linking properties. The change of a property causes linked properties to change as well.

Creating links in the GUI: [FIGURE] Creating links programmatically:

```
// Link property "MyProperty" to property "LinkedProperty"
PropertyContainer::Link myLink(pTargetObject,"LinkedProperty");
GetPlugin().SetPropertyLink("MyProperty",myLink);
```

Observers

Observers allow tracking changes in properties or other objects. Notifications are being bound to member functions with the class 'ModifiedObserver'. This class notifies changes from multiple

objects of different types [9]. An example for using observers:

```
// usually a class member
ModifiedObsever myObserver;

// typically in plugin constructur
// connect observer to member function
myObserver.connect(this,&MyPlugin::changed);

// add observer to objects we want to track
GetPlugin().GetProperty("MyProperty1").addObsever(&myObserver);
GetPlugin().GetProperty("MyProperty2").addObsever(&myObserver);

// notification handler
void changed(const Variant & object, const Observable::Event & event)
{
    // handle changes, e.g., trigger re-render
    GetPlugin().update();
}
```

For this work the display() function is of most importance. It is responsible for the rendering.

Languages

The plug-ins are written in C++ using OpenGL that is a successful cross-platform graphics application programming interface (API) for 2D and 3D computer graphics [5]. For shading and texturing OpenGL Shading Language (GLSL) is used [9].

3.2 Concept of Shaders

In GLSL there are four different shaders:

- Vertex shader
- Fragment shader
- Geometry shader
- Tessellation shader

The two basic shaders, vertex shader and fragment shader, will be described in detail in the following section.

In 3D computer graphics objects are described with a set of polygon surface patches and are

called 'polygonal mesh' or simply 'mesh'. Each polygon has several vertices, edges and faces [4]. With GLSL the shading of the polygons can be modified directly, replacing the default shading function of OpenGL.

Vertex shader

The vertex data is taken as input. A single vertex can consist of several attributes include position, color and normals.

The vertex shader can perform tasks such as [5]:

- transforming vertex positions
- transforming the normal vectors and normalizing them
- generating and transforming texture coordinates
- applying light models such as ambient, diffuse and specular per vertex
- computing color

Fragment shader

After the vertices have been transformed into the viewplane they are rasterized. The result are fragments which contain information about screen coordinates, depth, color, texture coordinates and so on. The value of the pixel color is determined by interpolation of the vertex colors. The fragment shader can perform tasks such as [5]:

- applying light values
- computing shadows
- adding complex texture(e.g. Bump Mapping)

Suggested implementation

In this section a step by step approach to reveal inner structures of a mesh will be discussed. First a plane needs to be defined that represents the position and direction of the cut. To retain interactivity, several parameters in the VolumeShop interface are available to translate, rotate and scale the plane. The color and opacity of the plane should be adaptable to not occlude parts of the mesh. For the mesh splitting an offset is defined that indicates how far the two halfs of the mesh shall be apart from the plane. The larger the gap the better the insight into the model. The splitting itself is no real translation of the two halfs, but the model is rendered twice at different positions in space parallel to the plane. The final step is shading of the models' surface as well as the back facing triangles. The latter will be shaded with a different color, but with the same amount of lighting to create the illusion of depth.

4.1 Definition of the plane

A plane in this context is a square of infinite size. It is used as a visual help to define where the mesh will be cut.

To be able to intervene with VolumeShop, it is necessary to provide properties to set the translation, rotation, and scale vectors as well as the color. Each property requires a name and a type. Here an example of a property named "Plane Translation Vector" of the type Vector (in this case vec3):

```
GetPlugin().GetProperty("Plane Translation Vector").require(
    Variant::TypeVector(Vector(0.0f, 0.0f, 0.0f)));
```

To apply changes made in the interface immediately, an observer for the property has to be added:

```
GetPlugin().GetProperty("Plane Translation Vector").addObserver
   (&m_modVariantObserver);
```

Before drawing the plane, the Viewing Transformation Matrix is loaded. This matrix is for tranforming the coordinates from world space into viewing space.[BOOK: Hearn, Baker] Then the plane is being adjusted by its affine transformations. All passed parameters are of the type 'float' and taken from the user input.

The commands in OpenGL:

```
glTranslatef(vecPlaneTranslation.GetX(), vecPlaneTranslation.
    GetY(), vecPlaneTranslation.GetZ());
glRotatef(vecPlaneRotationAngle, vecPlaneRotation.GetX(),
    vecPlaneRotation.GetY(), vecPlaneRotation.GetZ());
glScalef(vecPlaneScaling.GetX(), vecPlaneScaling.GetY(),
    vecPlaneScaling.GetZ());
```

The color of the plane is handed over from the input panel, normalized, and passed on to the renderer. In VolumeShop, this can be easily archieved by calling the function 'GetNormalized<ColorChannel>()'.

```
glColor4f(vecPlaneColor.GetNormalizedRed(), vecPlaneColor.
   GetNormalizedGreen(), vecPlaneColor.GetNormalizedBlue(),
   vecPlaneColor.GetNormalizedAlpha());
```

OpenGL supports several basic graphics primitives by default. For the plane a quad is required that looks like the following [5]:

```
glBegin(GL_QUADS);
    glNormal3f(0, 0, 1);
    glVertex3f(-1, -1, 0);
    glVertex3f( 1, -1, 0);
    glVertex3f( 1, 1, 0);
    glVertex3f(-1, 1, 0);
glVertex3f(-1, 1, 0);
```

As stated above our plane will be indefinite, but for the purpose as a visual helper it is displayed from -1 to 1 as a default. Note that the plane is also scaleable for bigger meshes.

The result should look like [FIGURE].

4.2 Splitting the mesh

The splitting offset is again implemented as a interface parameter. If the parameter is set to '0.0f' the mesh does not seem to be split. The larger the value of the offset the bigger the distance between the two halfs of the mesh.

Note that of course an observer needs to be added as well. (REF 4.1.)

Rotation of the planes' normal vector

The normal of the plane has been defined with '(0.0, 0.0, 1.0)', but regarding that the normal vector is still located in the object space of the plane, it needs to be transformed into the same space as the mesh. This is being done by rotating the normal by the same amount as the plane is rotated in the interface.

The following code reveals the rotation matrix regarding the interface inputs.

Of course, the rotation matix could also be calculated using the generally known formulas [5]:

x-roll:

$$R_x(\beta) = \begin{pmatrix} 1 & 0 & 0 & 0\\ 0 & \cos(\beta) & -\sin(\beta) & 0\\ 0 & \sin(\beta) & \cos(\beta) & 0\\ 0 & 0 & 0 & 1 \end{pmatrix}$$
(4.1)

y-roll:

$$R_y(\beta) = \begin{pmatrix} \cos(\beta) & 0 & \sin(\beta) & 0\\ 0 & 1 & 0 & 0\\ -\sin(\beta) & 0 & \cos(\beta) & 0\\ 0 & 0 & 0 & 1 \end{pmatrix}$$
(4.2)

z-roll:

$$R_z(\beta) = \begin{pmatrix} \cos(\beta) & -\sin(\beta) & 0 & 0\\ \sin(\beta) & \cos(\beta) & 0 & 0\\ 0 & 0 & 1 & 0\\ 0 & 0 & 0 & 1 \end{pmatrix}$$
(4.3)

However, it should be considered that 3D rotation matrices do not commute [5], so the order of multiplication matters. For details on matrix multiplication and applying affine transformations please look up the referenced literature. [5] [4]

Next the rotated normal vector should be multiplied with the modelview matrix to get the vector in modelview space before the it is normalized. After normalization the normal vector has a value between 0 and 1.

```
planeNormal.normalize();
```

Translating the mesh

After the light calculations the mesh is translated by the value of the offset in the direction of the normal vector. The command in OpenGL for translation is 'glTranslatef'. Before the mesh is rendered the shader needs to be bound.

```
Vector meshTranslation = planeNormal * offset;
glTranslatef(meshTranslation.GetX(), meshTranslation.GetY(),
    meshTranslation.GetZ());
m_shaShader.bind();
renderMesh(*pMesh);
m_shaShader.release();
```

As stated above the mesh is rendered twice to create the illusion of a mesh that is dragged apart. So the mesh needs to be rendered again with a translation in the opposite direction.

In VolumeShop, the two meshes displayed with a plane in between. The distance of the meshes is twice the offset [FIGURE].

Discarding dispensable pixel

To eliminte the pixels from the other side of the plane of each mesh respectively, it has to be determined on which side of the plane a pixel lies.

The computation is performed in the fragment shader.

The dot product of the plane normal and the vertex position minus a point on the plane states if the vertex is in front of or behind the plane. If the resulting value is smaller or equal to zero, the point is behind the plane and should not be drawn. Before the mesh is rendered, the normal of the plane as well as a point on the plane must be passed to the shader as uniforms. For the first half of the mesh the normal vector is untouched, for the second one converted. The point on the plane has to be determined in respect of the plane translation.

Definition of the plane normal and point on the plane as uniforms:

```
glUniform3f(m_shaShader.GetUniformLocation("planeNormal"),
    planeNormal.GetX(), planeNormal.GetY(), planeNormal.GetZ());
glUniform3f(m_shaShader.GetUniformLocation("planePoint"),
    vecPlaneTranslation.GetX(), vecPlaneTranslation.GetY(),
    vecPlaneTranslation.GetZ());
```

The fragment shader discards the points behind the plane:

```
float dotProduct = dot((vertexPosition - pointOnPlane),
    planeNormal);

if(dotProduct <= 0.0) {
        discard;
}</pre>
```

4.3 Shading the mesh

The back faces of the mesh still have the same color as the front faces, what makes it look unreal. Therefor the back faces have to be shaded in a different color. OpenGL has a function to check if the fragment is front facing:

```
if(!gl_FrontFacing) {
     gl_FragColor = vec4(1.0, 0.0, 0.0, 1.0) //shades all
     inner facing vertices red
}
```

Using the phong shading model for the back facing fragments

To add the impression of depth, lighting of the back facing fragments is being done with the phong shading model [4].

```
void directionalLight(in gl_LightSourceParameters light, in vec
   3 N, in vec3 V, in float shininess, inout vec4 ambient,
   inout vec4 diffuse, inout vec4 specular)
{
   vec3 L = normalize(light.position.xyz);

   float nDotL = dot(N, L);

   if (nDotL > 0.0)
   {
      vec3 H = normalize(light.halfVector.xyz);

      float pf = pow(max(dot(N,H), 0.0), shininess);

      diffuse += light.diffuse * nDotL;
      specular += light.specular * pf;
   }

   ambient += light.ambient;
}

void main()
{
   vec3 v = normalize(vVertexPosition);
   vec3 n = normalize(vVertexNormal);
   if(!gl_FrontFacing) {
```

Critical reflection

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