

Red-Blue Computation

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Motivation

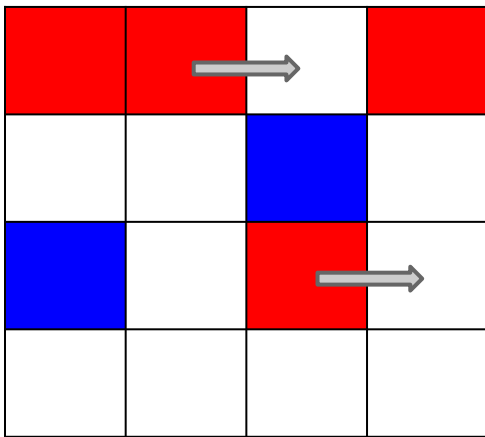
Red/Blue is a fairly simple case study we looked at early in the semester.

- Opportunity to see real speed-up on parallel code
- Apply OpenMP and Pthreads knowledge

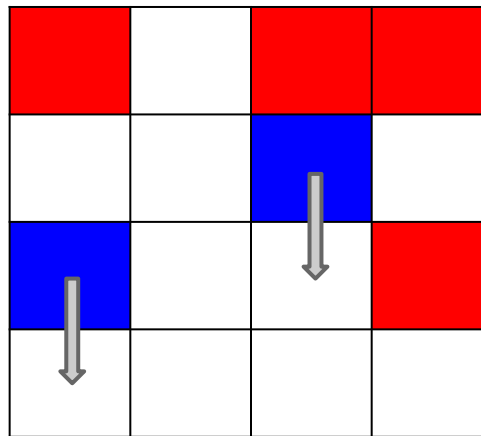
Two-Stage Computation

1. Red squares may move to the right into an empty (white) square
2. Blue squares may move down into an empty (white) square

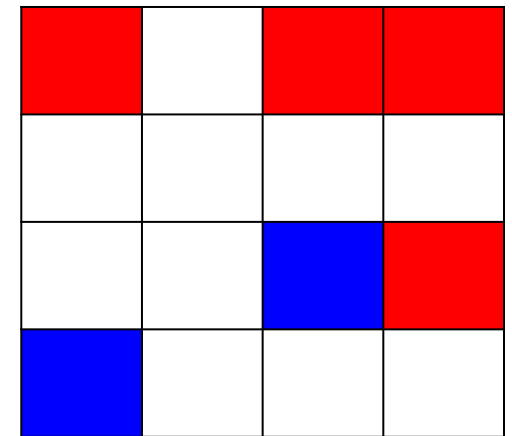
Original



Red Step



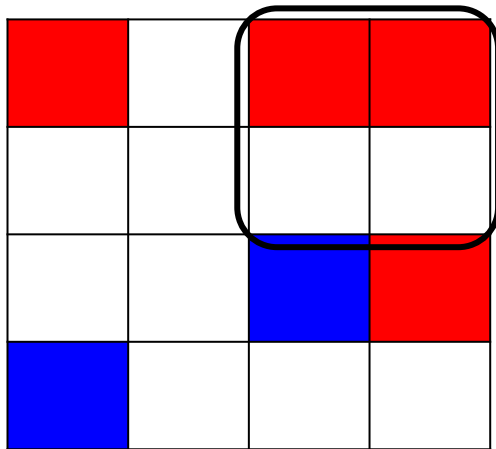
Blue Step



Notice that it does not move recursively -- only one of the reds in the first row moved.

Convergence

1. Split the grid into NxN tiles
2. Compute % for each color in a given tile
3. If that % reaches a threshold, we're done, otherwise, keep stepping



Converges (2x2 tiles and .5 convergence value)

Algorithm Summary (Sequential)

```
read_grid();  
while(true) {  
    if (converges()) break;  
    iterate_red(); // nested for loop  
    iterate_blue(); // nested for loop  
}
```

Parallelization Difficulties and Strategies

Problems:

- Partition boundaries (blue moves into vacated red square)
- Save previous iteration (all moves work from previous iteration)

Solutions:

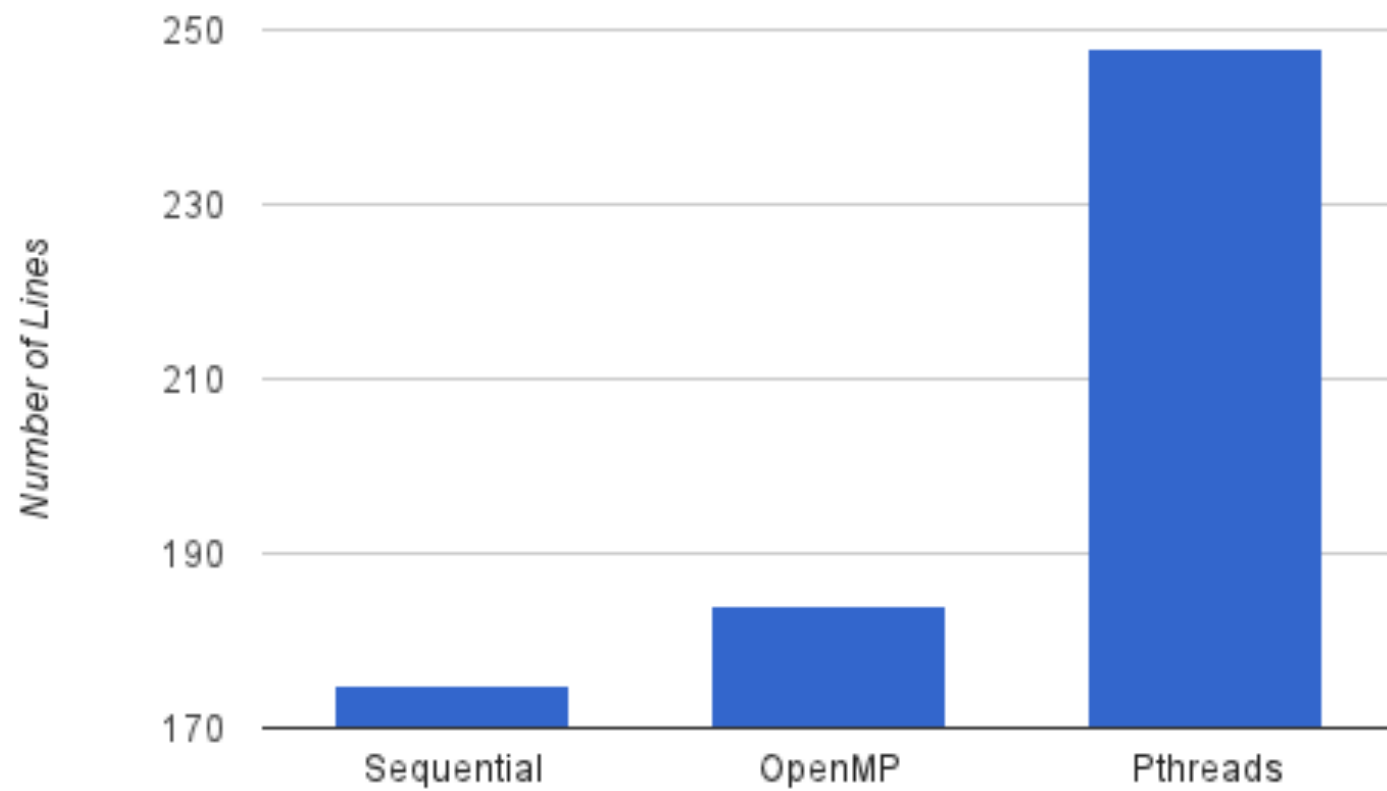
- Two different grids, iterate from one to the other
 - Eliminates boundary issues and thread synchronization
- Barrier between each iteration

OMP vs Pthreads

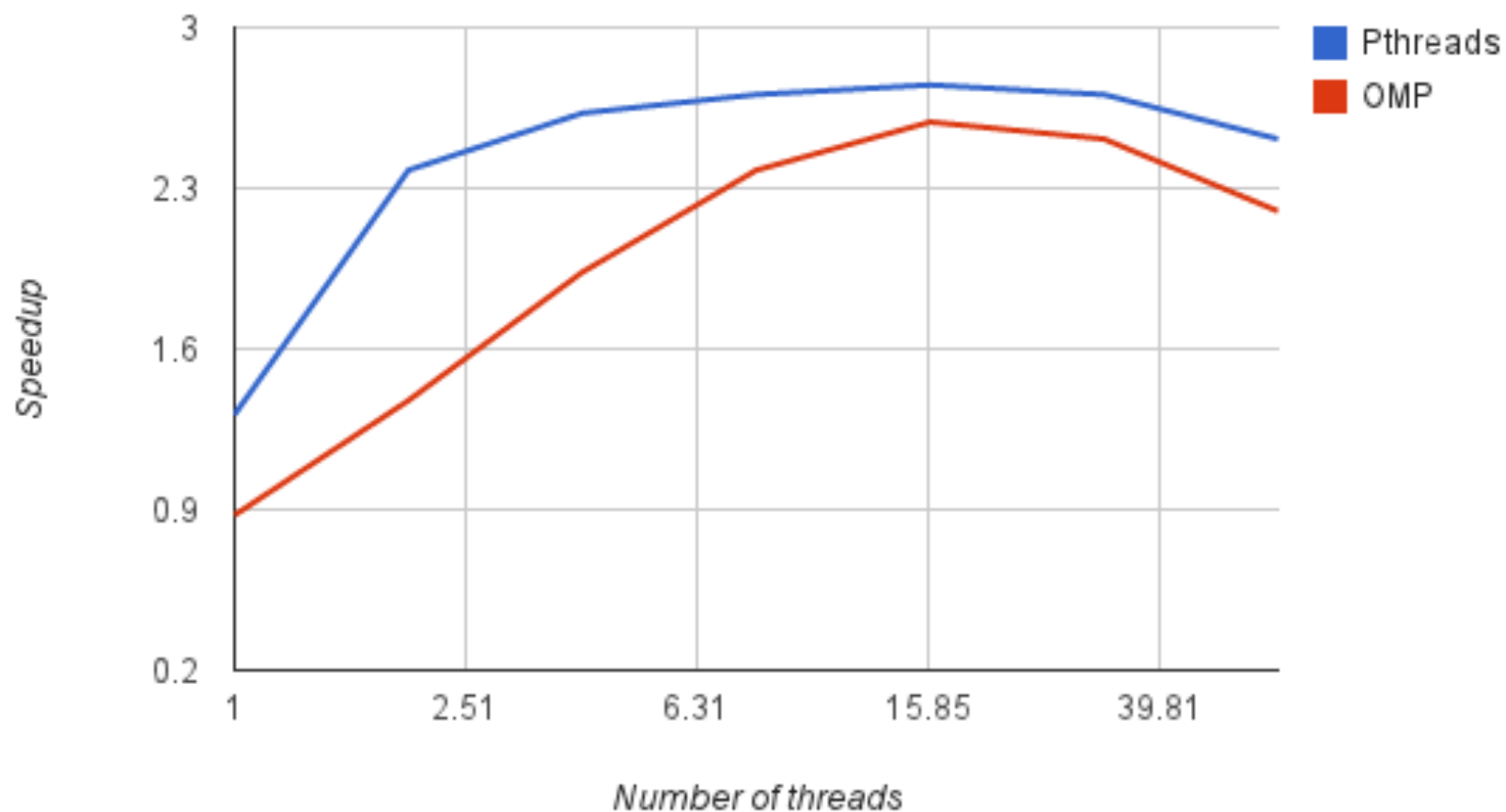
OpenMP does all partitioning for us. Add `#pragma omp parallel for` and we're done.

Pthreads requires manual partitioning, but is more optimizable as a result.

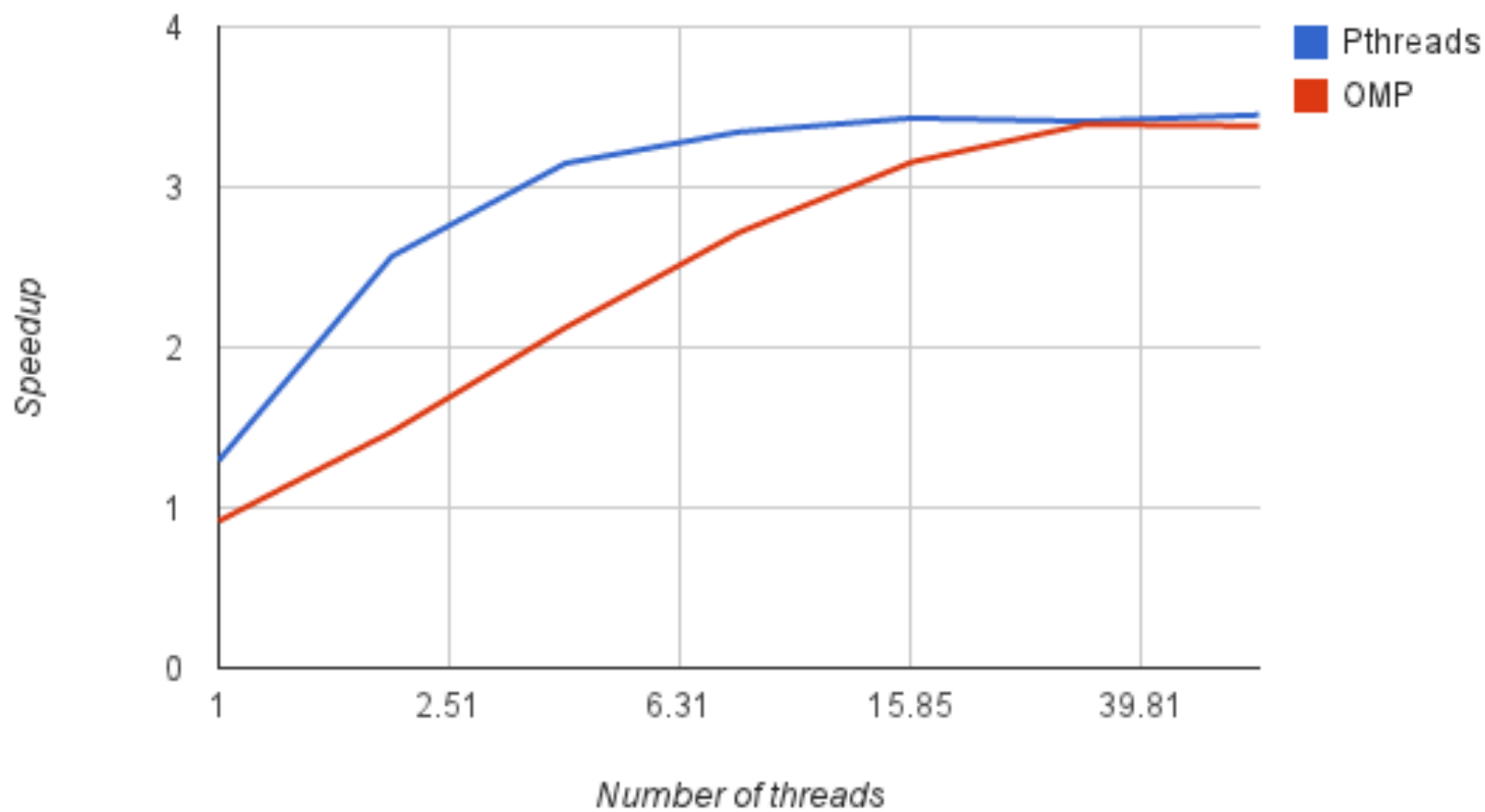
Program Complexity



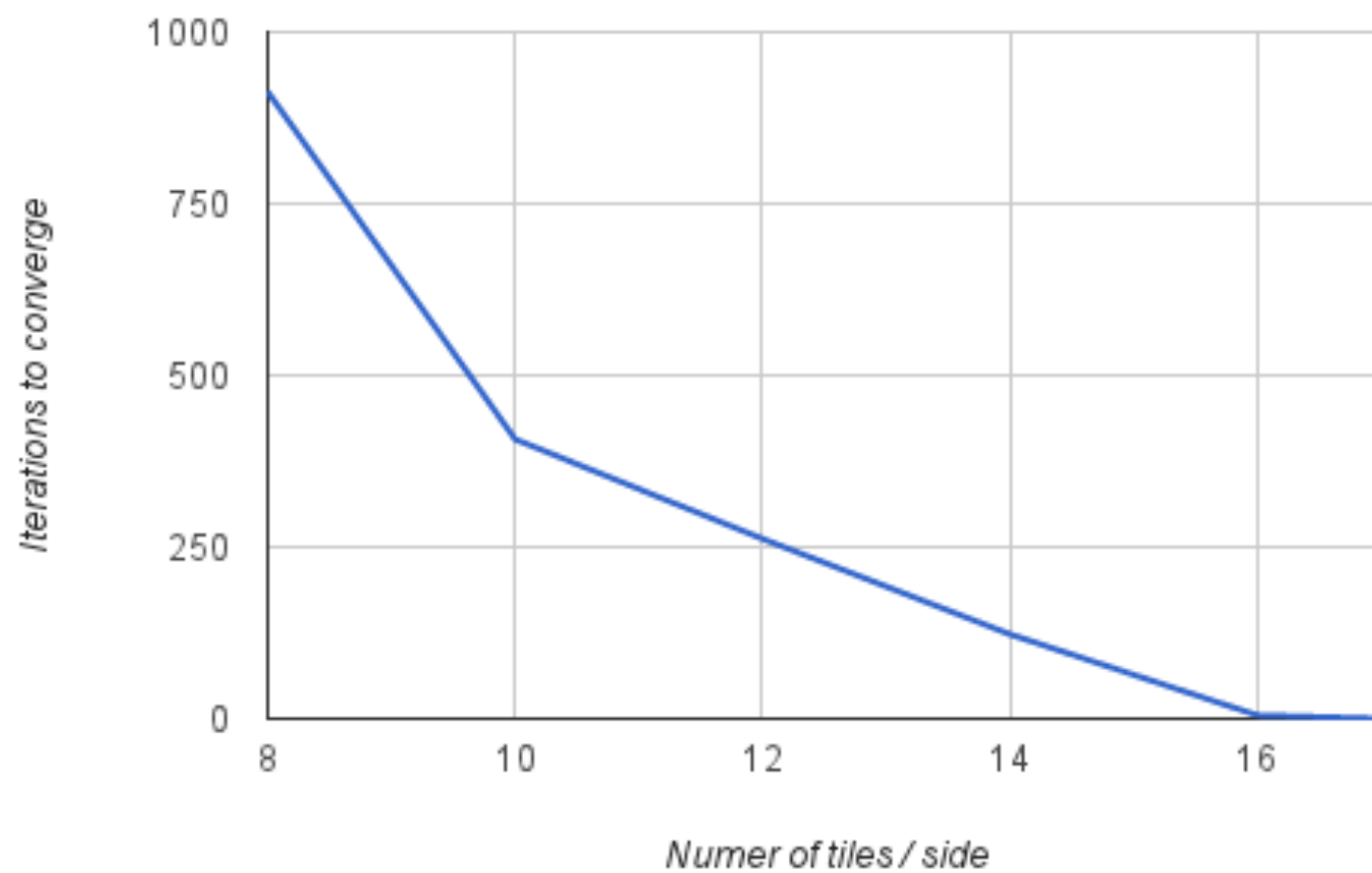
512x512, 16% Convergence, 8 tiles/side, 913 itr



4096x4096, 12.7% Converge, 8 tiles/side, 62 ltr



Convergence Rate, 512x512, 16% Converge



Conclusion

- Drastic speedups with both OMP and Pthreads
- Concrete example of drawbacks and advantages of Pthreads vs OMP
 - Complexity for Speedup
- Concrete examples of how one size doesn't fit all
 - Number of threads
 - Size of problem