$\begin{bmatrix} (1.0\sin\left(\theta_{1}\right)\cos\left(\theta_{2}\right)+1.0\sin\left(\theta_{2}\right)\cos\left(\theta_{1}\right))\sin\left(\theta_{5}\right)+(-1.0\left(-1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right)+\cos\left(\theta_{1}\right)\cos\left(\theta_{2}\right))\sin\left(\theta_{3}\right)\sin\left(\theta_{4}\right)+(-1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right)+\cos\left(\theta_{1}\right)\cos\left(\theta_{2}\right))\cos\left(\theta_{3}\right)\cos\left(\theta_{4}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right)-1.0\cos\left(\theta_{1}\right)\cos\left(\theta_{2}\right))\sin\left(\theta_{5}\right)+(-1.0\left(\sin\left(\theta_{1}\right)\cos\left(\theta_{2}\right)+\sin\left(\theta_{2}\right)\cos\left(\theta_{1}\right))\sin\left(\theta_{3}\right)\sin\left(\theta_{4}\right)+(-1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right)+\cos\left(\theta_{1}\right)\cos\left(\theta_{3}\right)\cos\left(\theta_{4}\right))\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right)-1.0\cos\left(\theta_{1}\right)\cos\left(\theta_{2}\right)\sin\left(\theta_{5}\right)+(-1.0\sin\left(\theta_{1}\right)\cos\left(\theta_{2}\right)+\sin\left(\theta_{2}\right)\cos\left(\theta_{3}\right)\sin\left(\theta_{4}\right)+(-1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right)+\cos\left(\theta_{1}\right)\cos\left(\theta_{3}\right)\cos\left(\theta_{4}\right)\\ (1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right)-1.0\cos\left(\theta_{1}\right)\cos\left(\theta_{2}\right)\sin\left(\theta_{5}\right)+(-1.0\sin\left(\theta_{1}\right)\cos\left(\theta_{2}\right)+\sin\left(\theta_{2}\right)\cos\left(\theta_{1}\right)\sin\left(\theta_{2}\right)+\sin\left(\theta_{2}\right)\cos\left(\theta_{3}\right)\cos\left(\theta_{4}\right)\\ (1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right)-1.0\cos\left(\theta_{1}\right)\cos\left(\theta_{2}\right)\sin\left(\theta_{5}\right)+(-1.0\sin\left(\theta_{1}\right)\cos\left(\theta_{2}\right)+\sin\left(\theta_{2}\right)\cos\left(\theta_{3}\right)\cos\left(\theta_{4}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{4}\right)+1.0\sin\left(\theta_{4}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{4}\right)+1.0\sin\left(\theta_{4}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{4}\right)+1.0\sin\left(\theta_{4}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{4}\right)+1.0\sin\left(\theta_{4}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{4}\right)+1.0\sin\left(\theta_{4}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{4}\right)+1.0\sin\left(\theta_{4}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{4}\right)+1.0\sin\left(\theta_{4}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{5}\right)+1.0\sin\left(\theta_{5}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{5}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{3}\right)\cos\left(\theta_{5}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{5}\right)\cos\left(\theta_{5}\right)\cos\left(\theta_{5}\right)\\ (1.0\sin\left(\theta_{5}\right)\cos\left(\theta_{5}\right)\cos\left(\theta_{5}\right)$	$(1.0 \sin{(\theta_1)} \cos{(\theta_2)} + 1.0 \sin{(\theta_2)} \cos{(\theta_1)}) \cos{(\theta_5)} - 1.0 (-1.0 (-1.0 \sin{(\theta_1)} \sin{(\theta_2)} + \cos{(\theta_1)} \cos{(\theta_2)}) \sin{(\theta_3)} \sin{(\theta_4)} + (-1.0 \sin{(\theta_1)} \sin{(\theta_2)} + \cos{(\theta_1)} \cos{(\theta_2)}) \cos{(\theta_3)} \cos{(\theta_4)}) \sin{(\theta_5)} \cos{(\theta_5)} - 1.0 (-1.0 (\sin{(\theta_1)} \cos{(\theta_2)} + \sin{(\theta_2)} \cos{(\theta_1)}) \sin{(\theta_3)} \sin{(\theta_4)} + (\sin{(\theta_1)} \cos{(\theta_2)} + \sin{(\theta_2)} \cos{(\theta_1)}) \cos{(\theta_3)} \cos{(\theta_4)}) \sin{(\theta_5)} \cos{(\theta_5)} - 1.0 (1.0 \sin{(\theta_3)} \cos{(\theta_4)} + 1.0 \sin{(\theta_4)} \cos{(\theta_3)}) \sin{(\theta_5)} \cos{(\theta_5)} - 1.0 (1.0 \sin{(\theta_3)} \cos{(\theta_4)} + 1.0 \sin{(\theta_4)} \cos{(\theta_3)}) \sin{(\theta_5)} \cos{(\theta_5)} (\theta_$	1.0 $(-1.0 \sin(\theta_1) \sin(\theta_2) + \cos(\theta_1) \cos(\theta_2)) \sin(\theta_3) \cos(\theta_4) + 1.0 (-1.0 \sin(\theta_1) \sin(\theta_2) + \cos(\theta_1) \cos(\theta_2)) \sin(\theta_4) \cos(\theta_3)$ 1.0 $(\sin(\theta_1) \cos(\theta_2) + \sin(\theta_2) \cos(\theta_1)) \sin(\theta_3) \cos(\theta_4) + 1.0 (\sin(\theta_1) \cos(\theta_2) + \sin(\theta_2) \cos(\theta_1)) \sin(\theta_4) \cos(\theta_3)$ 1.0 $\sin(\theta_3) \sin(\theta_4) - 1.0 \cos(\theta_3) \cos(\theta_4)$	$10.0\left(-1.0\sin{(\theta_1)}\sin{(\theta_2)} + \cos{(\theta_1)}\cos{(\theta_2)}\right)\sin{(\theta_3)}\cos{(\theta_4)} + 10.0\left(-1.0\sin{(\theta_1)}\sin{(\theta_2)} + \cos{(\theta_1)}\cos{(\theta_2)}\right)\sin{(\theta_4)}\cos{(\theta_2)} + 5.74\left(-1.0\sin{(\theta_1)}\sin{(\theta_2)} + \cos{(\theta_1)}\cos{(\theta_2)}\right)\cos{(\theta_3)} - 9.15\sin{(\theta_1)}\sin{(\theta_2)} + 9.15\cos{(\theta_1)}\cos{(\theta_2)} + 9.28\cos{(\theta_1)}\cos{(\theta_2)} + 9.28\cos{(\theta_1)}\cos{(\theta_2)}\cos{(\theta_2)} + \sin{(\theta_2)}\cos{(\theta_2)}$
$\begin{bmatrix} -1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right) + \cos\left(\theta_{1}\right)\cos\left(\theta_{2}\right) & 0 & 1.0\sin\left(\theta_{1}\right)\cos\left(\theta_{2}\right) + 1.0\sin\left(\theta_{2}\right)\cos\left(\theta_{1}\right) & -9.15\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right) + 9.15\cos\left(\theta_{1}\right)\cos\left(\theta_{2}\right) + 9.28\cos\left(\theta_{1}\right) \\ \sin\left(\theta_{1}\right)\cos\left(\theta_{2}\right) + \sin\left(\theta_{2}\right)\cos\left(\theta_{1}\right) & 0 & 1.0\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right) - 1.0\cos\left(\theta_{1}\right)\cos\left(\theta_{2}\right) & 9.15\sin\left(\theta_{1}\right)\sin\left(\theta_{2}\right) + 9.28\sin\left(\theta_{1}\right) + 9.15\sin\left(\theta_{2}\right)\cos\left(\theta_{1}\right) \\ 0.0 & 1.0 & 0.0 & 16.39 \\ 0.0 & 0.0 & 0.0 & 1.0 \end{bmatrix}$ $\begin{bmatrix} 0.22 & 0.0 & 0.97 & 9.75 \\ 0.97 & 0.0 & -0.22 & 14.1 \\ 0.0 & 1.0 & 0.0 & 16.39 \\ 0.0 & 0.0 & 0.0 & 1.0 \end{bmatrix}$			