

Marvok-Chain Model for Unbounded Key Propagation

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1 Three Children Model

In this case we let the number of children $m = 3$. Following the approach for the $m = 2$ case, we now define the following sets S_1 , S_2 , S_3 , S_4 , and S_5 .

- S_1 = The number of nodes with 3 children
- S_2 = The number of nodes with 2 children
- S_3 = The number of nodes with 1 children
- S_4 = The number of nodes with 0 children
- S_5 = The number of nodes that are not connected

In a network with n nodes, we can see that $\sum_{i=1}^5 S_i = n$.

Now we examine the change of the network state at each epoch, where a node is assumed to only obtain one new child node connection in an epoch. To capture this behavior, we define the following variables D_2 , D_3 , and D_4 to be the number of new nodes connected from nodes in sets S_2 , S_3 , and S_4 , respectively. Using this information, the transfer equations clearly generalize to:

$$\begin{aligned} S_1 &\rightarrow S_1 + D_2 \\ S_2 &\rightarrow S_2 - D_2 + D_3 \\ S_3 &\rightarrow S_3 - D_3 + D_4 \\ S_4 &\rightarrow S_4 + D_2 + D_3 \\ S_5 &\rightarrow S_5 - D_2 - D_3 - D_4 \end{aligned}$$

Clearly, the initial state of the network is $S^* = (S_1, S_2, S_3, S_4, S_5) = (0, 0, 0, 1, n - 1)$. Using the aforementioned transfer equations we can represent this state as $S^* = (D_2, D_3 - D_2, D_4 - D_3, 1 + D_2 + D_3, n - 1 - D_2 - D_3 - D_4)$. Therefore, we can represent the state of the network using a three-dimensional vector $D_k = (D_1, D_2, D_3)$.

If we now consider transitions in the state of the network by some vector $\bar{h} = (i, j, k)$, where the transition is defined as $D + \bar{h} = (D_2 + i, D_3 + j, D_4 + k)$, as well as the transfer equations used to define the network state evolution, we come up with the following constraints for \bar{h}

Based on the transfer equations, we can also define the following constraints for the network state.

$$0 \leq i \leq D_3 - D_2 \tag{1}$$

$$0 \leq j \leq D_4 - D_3 \tag{2}$$

$$0 \leq k \leq 1 + D_2 + D_3 \tag{3}$$

$$i + j + k \leq n - 1 - D_2 - D_3 - D_4 \tag{4}$$

With these constraints, we conclude that the network can evolve along any vector path bounded by these constraints and the line $D_2 + D_3 + D_4 = 1$, which is the point where all nodes have the key. A visual depiction of the unconstrained and partly constrained network state space is shown in Figures 1 and 1.

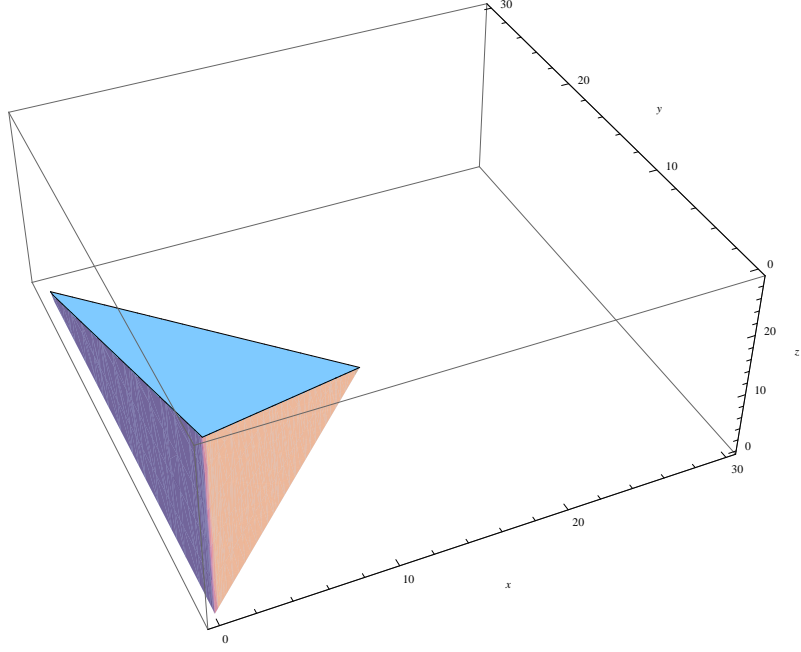


Figure 1: Plot of the network space without constraints, where x , y , and z are D_2 , D_3 , and D_4 , respectively.

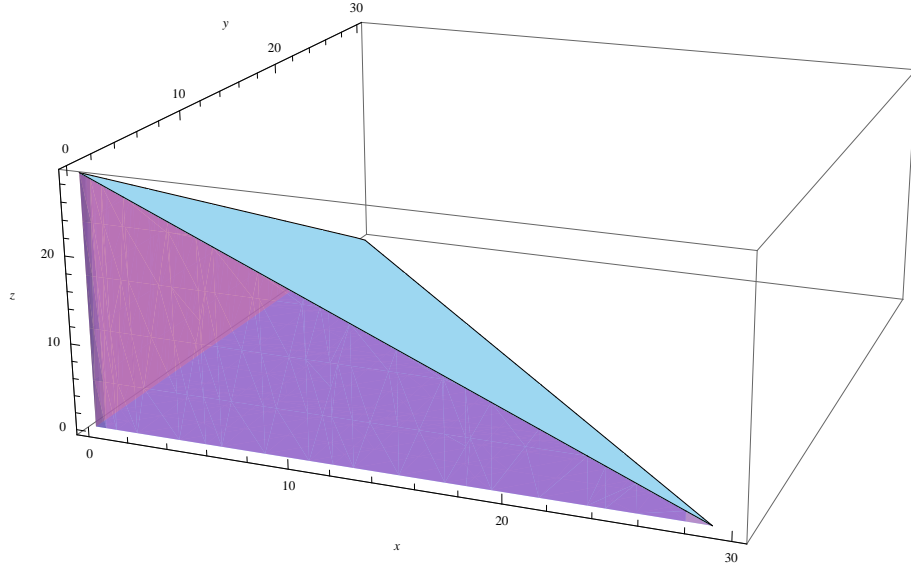


Figure 2: Plot of the network space under constraint 1, where x , y , and z are D_2 , D_3 , and D_4 , respectively.

With a constrained network state space, we can now define the expected time for a key to be distributed, $E(T_D)$, by assigning a probability $P_D(\bar{h})$ to each possible network state transition. In particular, we have the following.

$$P_D(\bar{h}) = \Pr[D_{s+1} = D + \bar{h} | D_s = D]$$

In this context, D_s is the state of the network at state s (i.e. after s epochs). We can now define $E(T_D)$ as follows,

$$E(T_D) = \frac{1}{1 - P_D(\bar{h}^*)} [1 + \sum_{\bar{h} \in A_{D_s}} P_D(\bar{h}) \times E(T_{D+\bar{h}})],$$

where $A_{D_s} = \{(i, j, k) | 0 < i + j + k \leq n - 1 - D_2 - D_3 - D_4, 0 \leq i \leq D_3 - D_2, 0 \leq j \leq D_4 - D_3, 0 \leq k \leq 1 + D_2 + D_3\}$.

From this point, we refer to the original proof of the correctness of this equation. No further work must be done

2 Generalized Model

Following the approach for the $m = 3$ case, we can generalize the this model to $m \geq 4$ as follows.

1. Define network state sets $S_1, S_2, \dots, S_{m+1}, S_{m+2}$, and also define network state variables D_2, \dots, D_m, D_{m+1} .
2. Generalize the transfer equations to the following.

$$\begin{aligned} S_1 &\rightarrow S_1 + D_2 \\ S_2 &\rightarrow S_2 - D_2 + D_3 \\ S_i &\rightarrow S_i - D_i + D_{i+1} \\ S_{m+1} &\rightarrow S_{m+1} + \sum_{k=2}^m D_k \\ S_{m+2} &\rightarrow S_{m+1} - \left(\sum_{k=2}^{m+1} D_k \right) \end{aligned}$$

3. Represent the network state space in terms of all D_i variables, thus resulting in a m -dimensional network state space.