

PRACTICE SESSION 2

EXERCISE 3

Given the system

$$\begin{cases} x(t+1) = \frac{1}{2}x(t) + 2u(t) \\ y(t) = 3x(t) \end{cases}$$

$$F = \frac{1}{2} \quad G = 2 \quad H = 3 \quad D = 0$$

(a) Compute the first 5 samples of the impulse response

Method I: Directly from the system of difference equations

$$u(t) = \begin{cases} 1 & t=0 \\ 0 & t \neq 0 \end{cases}$$

$$x(0) = x_0 = 0$$

If it is not specified
consider the initial
state equal to zero

t	x(t)	y(t)
0	$x(0) = 0$	$y(0) = 3x(0) = 0$
1	$x(1) = \frac{1}{2}x(0) + 2\overset{1}{u}(0) = 2$	$y(1) = 3x(1) = 6$
2	$x(2) = \frac{1}{2}x(1) + 2\cancel{u}(1) = 1$	$y(2) = 3x(2) = 3$
3	$x(3) = \frac{1}{2}x(2) + 2\cancel{u}(2) = \frac{1}{2}$	$y(3) = 3x(3) = \frac{3}{2}$
4	$x(4) = \frac{1}{2}x(3) + 2\cancel{u}(3) = \frac{1}{4}$	$y(4) = 3x(4) = \frac{3}{4}$
5	$x(5) = \frac{1}{2}x(4) + 2\cancel{u}(4) = \frac{1}{8}$	$y(5) = 3x(5) = \frac{3}{8}$

$$w(0) = 0 \quad w(1) = 6 \quad w(2) = 3 \quad w(3) = \frac{3}{2} \quad w(4) = \frac{3}{4} \quad w(5) = \frac{3}{8}$$

Method IV: Geometric series trick

First of all we need to compute the transfer function

$$W(z) = H(zI - F)^{-1}G + D$$

$$\begin{aligned} W(z) &= 3\left(z - \frac{1}{2}\right)^{-1}2 = \frac{6}{z - \frac{1}{2}} = \frac{6z^{-1}}{1 - \frac{1}{2}z^{-1}} = \\ &= 6z^{-1} \left(\frac{1}{1 - \frac{1}{2}z^{-1}} \right) = 6z^{-1} \left(\sum_{k=0}^{\infty} \left(\frac{1}{2}z^{-1}\right)^k \right) = \\ &= 6z^{-1} \left(1 + \frac{1}{2}z^{-1} + \frac{1}{4}z^{-2} + \frac{1}{8}z^{-3} + \frac{1}{16}z^{-4} + \dots \right) = \\ &= 6z^{-1} + 3z^{-2} + \frac{3}{2}z^{-3} + \frac{3}{4}z^{-4} + \frac{3}{8}z^{-5} + \dots = \end{aligned}$$

$$w(0) = 0 \quad w(1) = 6 \quad w(2) = 3 \quad w(3) = \frac{3}{2} \quad w(4) = \frac{3}{4} \quad w(5) = \frac{3}{8}$$

- ⑥ Compute the 2nd order Henkel Matrix and check that it is not full rank, and justify it.

$$H_2 = \begin{bmatrix} w(1) & w(2) \\ w(2) & w(3) \end{bmatrix} = \begin{bmatrix} 6 & 3 \\ 3 & 3/2 \end{bmatrix}$$

$H_2(2,:) = \frac{1}{2} H_2(1,:)$ \rightarrow since the two rows are not linearly independent H_2 is not full rank.

$$H_2 = \begin{bmatrix} 6 & 3 \\ 3 & 3/2 \end{bmatrix} \quad \text{rank}(H_2) < 2$$

Justification: Consider the Henkel matrix of order i
 if $i > m \Rightarrow \text{rank}(H_i) = m$
 in our case $i = 2$ $m = 1 \Rightarrow \text{rank}(H_2) = 1$

- ⑦ Identify the system matrices using the GSD method

STEP 1: Identify the system order m

in this case we already know that $m = 1$

STEP 2: Build H_{m+1}

$$H_2 = \begin{bmatrix} 6 & 3 \\ 3 & 3/2 \end{bmatrix}$$

STEP 3: Find a factorization of $H_{m+1} = O_{m+1} R_{m+1}$

$$\begin{array}{ll} O_{m+1} \quad (m+1) \times (m) & \rightarrow \text{in our case } 2 \times 1 \\ R_{m+1} \quad (m) \times (m+1) & \rightarrow \text{in our case } 1 \times 2 \end{array}$$

$$\begin{bmatrix} 1 \\ \frac{1}{2} \end{bmatrix}_{O_{m+1}} \begin{bmatrix} 6 & 3 \end{bmatrix}_{R_{m+1}} = \begin{bmatrix} 6 & 3 \\ 3 & 3/2 \end{bmatrix}$$

- put m independent rows of H_{m+1} in R_{m+1}
- Fill the rows of O_{m+1} such that $H_{m+1} = O_{m+1} R_{m+1}$

STEP a: matrix extraction $\hat{F}, \hat{G}, \hat{H}, \hat{D}$

$$\hat{F} = O_{m+1}(1:m, :)^{-1} O_{m+1}(2:m+1, :) = (1)^{-1} \frac{1}{2} = \frac{1}{2}$$

$$\hat{G} = R_{m+1}(:, 1) = 6$$

$$\hat{H} = O_{m+1}(1, :) = 1$$

$\hat{D} = 0$ (since the system is strictly proper)

$$\begin{array}{ll} \hat{F} = \frac{1}{2} & \hat{G} = 6 \\ \hat{H} = 1 & \hat{D} = 0 \end{array}$$

Remark: we have found a different but equivalent state space representation.

(d) Compute the transfer function starting from the identified matrices

$$\begin{aligned} \hat{W}(z) &= \hat{H}(zI - \hat{F})^{-1} \hat{G} + \hat{D} = \\ &= 1 \left(z - \frac{1}{2} \right)^{-1} 6 = \frac{6}{z - \frac{1}{2}} = \frac{6z^{-1}}{1 - \frac{1}{2}z^{-1}} \end{aligned}$$

$$\hat{W}(z) = \frac{6z^{-1}}{1 - \frac{1}{2}z^{-1}}$$

the transfer function is the same, the I/O relationship is maintained

EXERCISE 4

Given the transfer function

$$W(z) = \frac{(z+2)}{(z+\frac{1}{2})(z+2)}$$

REMARK ZERO-POLE CANCELLATION

$$W_1(z) = \frac{(z+2)}{(z+\frac{1}{2})(z+2)}$$

$$W_2(z) = \frac{1}{z+\frac{1}{2}}$$

W_1 and W_2 represents the same I/O relationship.

$$W_1(z) = \frac{z+2}{(z+\frac{1}{2})(z+2)} = \frac{z+2}{z^2 + \frac{5}{2}z + 1} \quad \leftarrow 2^{\text{nd}} \text{ order unstable system}$$

$$W_2(z) = \frac{1}{z+\frac{1}{2}}$$

$\leftarrow 1^{\text{st}} \text{ order stable system}$

WRONG CONCLUSION

DO NOT CANCEL NUMERATOR-DENOMINATOR COMMON-TERMS!

(a) Compute the state space system in control form

$$W(z) = \frac{z+2}{z^2 + \frac{5}{2}z + 1}$$

$$b_0 = 1 \quad b_1 = 2$$

$$a_1 = \frac{5}{2} \quad a_2 = 1$$

$$F = \begin{bmatrix} 0 & 1 \\ -1 & -\frac{5}{2} \end{bmatrix} \quad G = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$H = \begin{bmatrix} 2 & 1 \end{bmatrix} \quad D = \begin{bmatrix} 0 \end{bmatrix}$$

(b) Check observability and Reachability

$$m=2 \rightarrow \mathcal{O} = \begin{bmatrix} H \\ HF \end{bmatrix} \quad \mathcal{R} = \begin{bmatrix} G & FG \end{bmatrix}$$

$$\mathcal{O}(1,:) = \begin{bmatrix} 2 & 1 \end{bmatrix}$$

$$\mathcal{O}(2,:) = \begin{bmatrix} 2 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ -1 & -\frac{5}{2} \end{bmatrix} = \begin{bmatrix} -1 & -\frac{1}{2} \end{bmatrix}$$

$$\mathcal{O} = \begin{bmatrix} 2 & 1 \\ -1 & -\frac{1}{2} \end{bmatrix} \rightarrow \text{the two rows are not linearly independent}$$

$$\mathcal{O}(2,:) = -\frac{1}{2} \mathcal{O}(1,:)$$

$$\text{rank}(O) < 2 \rightarrow$$

The system S is not observable

$$Q(:,1) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$Q(:,2) = \begin{bmatrix} 0 & 1 \\ -1 & -\frac{5}{2} \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ -\frac{5}{2} \end{bmatrix}$$

$$Q = \begin{bmatrix} 0 & 1 \\ 1 & -\frac{5}{2} \end{bmatrix}$$

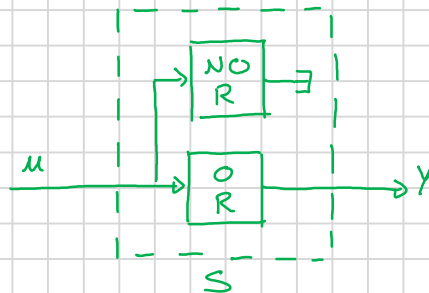
All the rows are linearly independent

$$\text{rank}(Q) = 2 \rightarrow$$

The system S is reachable

A zero-pole cancellation corresponds to a hidden part of the systems: something that the I/O representation cannot catch.

In this case there is a nonobservable part



$w(z)$ represents just the reachable and observable part of the system

③ Compute the first 4 samples of the Impulse Response and plot the state and output evolution.

We have to use method I:

$$\begin{cases} x_1(t+1) = x_2(t) \\ x_2(t+1) = -x_1(t) - \frac{5}{2}x_2(t) + u(t) \\ y(t) = 2x_1(t) + x_2(t) \end{cases}$$

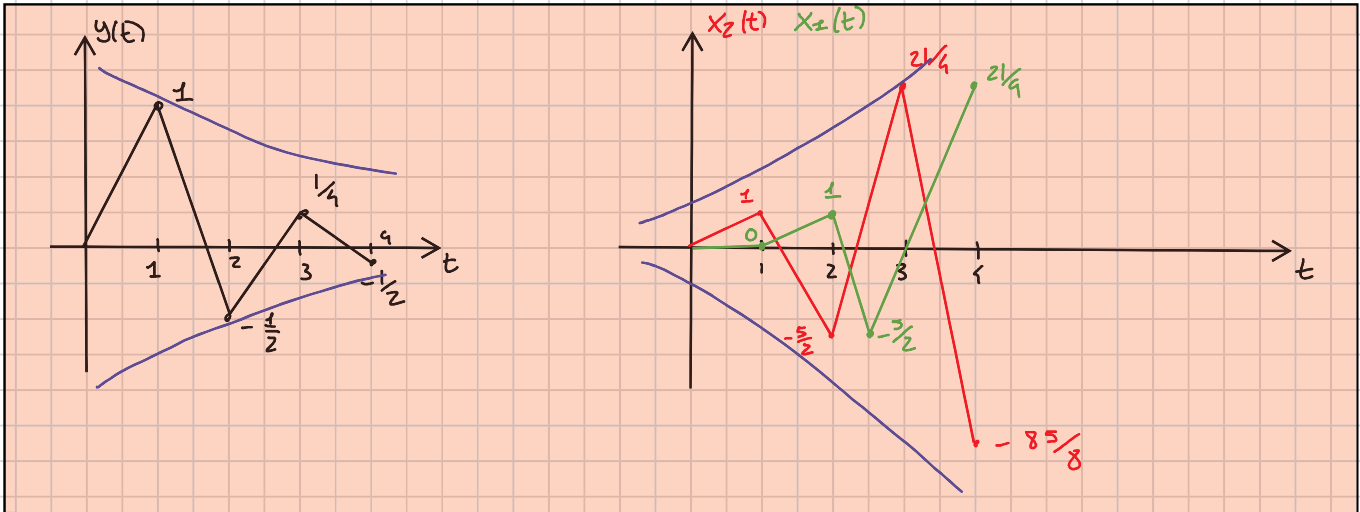
$$u(t) = \begin{cases} 1 & t=0 \\ 0 & t \neq 0 \end{cases}$$

$$x(0) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

t	x(t)	y(t)
0	$x_1(0) = 0$ $x_2(0) = 0$	$y(0) = 2x_1(0) + x_2(0) = 0$
1	$x_1(1) = x_2(0) = 0$ $x_2(1) = -x_1(0) - \frac{5}{2}x_2(0) + \underbrace{u(0)}_1 = 1$	$y(1) = 2x_1(1) + x_2(1) = 1$
2	$x_1(2) = x_2(1) = 1$ $x_2(2) = -x_1(1) - \frac{5}{2}x_2(1) + \cancel{u(1)} = -\frac{5}{2}$	$y(2) = 2x_1(2) + x_2(2) = -\frac{1}{2}$

$$\begin{array}{l|l}
 3 & \begin{array}{l} x_1(3) = x_2(2) = -\frac{5}{2} \\ x_2(3) = -x_1(2) - \frac{5}{2}x_2(2) + u(2) = 2\frac{1}{4} \end{array} & y(3) = 2x_1(3) + x_2(3) = \frac{1}{4} \\
 4 & \begin{array}{l} x_1(4) = x_2(3) = 2\frac{1}{4} \\ x_2(4) = -x_1(3) - \frac{5}{2}x_2(3) + u(3) = -\frac{85}{8} \end{array} & y(4) = 2x_1(4) + x_2(4) = -\frac{1}{8}
 \end{array}$$

$$w(0) = 0 \quad w(1) = 1 \quad w(2) = -\frac{1}{2} \quad w(3) = \frac{1}{4} \quad w(4) = -\frac{1}{8}$$



Remark: Looking at the I/O relationship the system seems to be stable, but the states diverge then there is an internal instability.

d) Identify the matrices using the ASID method

STEP 1: Identify the system order

$$\lceil \text{rank}(H_i) = m \quad \forall i \geq m \quad m \text{ is the system order}$$

$$\left. \begin{array}{l} \text{rank}(H_m) = m \\ \text{rank}(H_{m+1}) = m \end{array} \right\} \text{ the rank stops increasing}$$

$$H_1 = w(1) = 1 \quad \text{rank}(H_1) = 1$$

$$H_2 = \begin{bmatrix} w(1) & w(2) \\ w(2) & w(3) \end{bmatrix} = \begin{bmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{4} \end{bmatrix} \quad \begin{array}{l} H_2(2,:) = -\frac{1}{2} H_2(1,:) \\ \text{rank}(H_2) = 1 \end{array}$$

$$\begin{array}{l} \text{rank}(H_1) = 1 \\ \text{rank}(H_2) = 1 \end{array} \rightarrow m = 1$$

STEP 2 Build H_{m+1}

$$H_2 = \begin{bmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{4} \end{bmatrix}$$

STEP 3: Find a factorization of $H_{m+1} = \Theta_{m+1} Q_{m+1}$

$$\begin{bmatrix} 1 \\ -\frac{1}{2} \end{bmatrix}_{\Theta_2} \begin{bmatrix} 1 & -\frac{1}{2} \end{bmatrix}_{Q_2} = \begin{bmatrix} 1 & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{4} \end{bmatrix}_{H_2}$$

- Put m independent rows of H_{m+1} in Q_{m+1}
- Fill the rows of Θ_{m+1} such that $\Theta_{m+1} Q_{m+1} = H_{m+1}$

STEP 4: matrix Extraction

$$\hat{F} = \Theta_{m+1}(1:m,:)^{-1} \Theta_{m+1}(2:m+1,:) = (1)^{-1} \left(-\frac{1}{2}\right) = -\frac{1}{2}$$

$$\hat{G} = Q_{m+1}(:,1) = 1$$

$$\hat{H} = \Theta_{m+1}(1,:) = 1$$

$$\hat{D} = 0 \quad \text{strictly proper system } (w(0)=0)$$

$$\hat{F} = -\frac{1}{2} \quad \hat{G} = 1 \quad \hat{H} = 1 \quad \hat{D} = 0$$

② Compute the transfer function starting from the identified matrices

$$\hat{W}(z) = \hat{H}(zI - \hat{F})^{-1} \hat{G} + \hat{D} = \frac{1}{z + \frac{1}{2}}$$

→ it represents just the reachable and observable part.

EXERCISE 5

Given the impulse response

$$w(0)=0 \quad w(1)=0 \quad w(2)=2 \quad w(3)=0 \quad w(4)=1 \quad w(5)=0$$

(a) Identify the system order

$$H_1 = w(1) = 0 \quad \text{rank}(H_1) = 0$$

$$H_2 = \begin{bmatrix} 0 & 2 \\ 2 & 0 \end{bmatrix} \quad \text{rank}(H_2) = 2$$

$$H_3 = \begin{bmatrix} 0 & 2 & 0 \\ 2 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} \quad H_3(3,:) = \frac{1}{2} H_3(1,:) \rightarrow \text{rank}(H_3) = 2$$

$$\text{rank}(H_2)=2 \quad \text{rank}(H_3)=2 \rightarrow \boxed{m=2}$$

(b) Compute the transfer function

$$\text{IR} \rightarrow \hat{F} \hat{G} \rightarrow \hat{W}(z)$$

STEP 1: Identify the system order

$$m=2 \quad \text{from question (a)}$$

STEP 2: Build H_{m+1}

$$H_3 = \begin{bmatrix} 0 & 2 & 0 \\ 2 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

STEP 3: Find a factorization $H_{m+1} = Q_{m+1} R_{m+1}$

$$\underbrace{\begin{bmatrix} 1 & 0 \\ 0 & 1 \\ \frac{1}{2} & 0 \end{bmatrix}}_{Q_2} \underbrace{\begin{bmatrix} 0 & 2 & 0 \\ 2 & 0 & 1 \end{bmatrix}}_{R_3} = \underbrace{\begin{bmatrix} 0 & 2 & 0 \\ 2 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}}_{H_3}$$

• put m independent rows of H_{m+1} in R_{m+1}

STEP 4: Matrix extraction

$$\hat{F} = Q_{m+1}(1:m, :)^{-1} Q_{m+1}(2:m+1, :) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}^{-1} \begin{bmatrix} 0 & 1 \\ \frac{1}{2} & 0 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ \frac{1}{2} & 0 \end{bmatrix}$$

$$\hat{G} = Q_{m+1}(:, 1) = \begin{bmatrix} 0 \\ 2 \end{bmatrix}$$

$$\hat{H} = \mathcal{O}_{m \times 1}(1, :) = \begin{bmatrix} 1 & 0 \end{bmatrix}$$

$$\hat{D} = 0 \quad \text{strictly proper system } (\omega(0)=0)$$

$$\hat{W}(z) = \hat{H}(zI - \hat{F})^{-1} \hat{G} + \hat{D}$$

$$(zI - \hat{F}) = \begin{bmatrix} z & -1 \\ -\frac{1}{2} & z \end{bmatrix} \quad (zI - \hat{F})^{-1} = \frac{1}{z^2 - \frac{1}{2}} \begin{bmatrix} z & 1 \\ \frac{1}{2} & z \end{bmatrix}$$

$$\begin{aligned} \hat{W}(z) &= \frac{1}{z^2 - \frac{1}{2}} \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} z & 1 \\ \frac{1}{2} & z \end{bmatrix} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \\ &= \frac{1}{z^2 - \frac{1}{2}} \begin{bmatrix} z & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \frac{2}{z^2 - \frac{1}{2}} \end{aligned}$$

$$\hat{W}(z) = \frac{2}{z^2 - \frac{1}{2}}$$

© Compute the first 4 samples of the Impulse response
Method II: matrix multiplication formula

$$w(t) = \begin{cases} 0 & t=0 \\ HF^{t-1}G & t \geq 1 \end{cases}$$

it is valid only for strictly proper systems

$$w(0) = 0$$

$$w(1) = HG = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = 0$$

$$w(2) = HFG = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ \frac{1}{2} & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \overset{HF}{\boxed{\begin{bmatrix} 0 & 1 \end{bmatrix}}} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = 2$$

$$w(3) = HF^2G = HF \cdot FG = \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ \frac{1}{2} & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \overset{HF^2}{\boxed{\begin{bmatrix} \frac{1}{2} & 0 \end{bmatrix}}} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = 0$$

$$w(4) = HF^3G = \begin{bmatrix} \frac{1}{2} & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ \frac{1}{2} & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 0 & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 0 \\ 2 \end{bmatrix} = 1$$

$$w(0) = 0 \quad w(1) = 0 \quad w(2) = 2 \quad w(3) = 0 \quad w(4) = 1$$