Syntax Analysis of Non-Deterministic Grammars Earley (Tabular) Method

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A GENERAL SYNTAX ANALYSIS METHOD – EARLEY (TABULAR)

The *Earley* method (also called *tabular* method) deals with any grammar type, even ambiguous, but we fully apply it only to non-deterministic grammars

It builds in parallel all the possible derivations of the string prefix scanned so far

Earley is similar to *ELR*, but it does not use the stack; instead, it uses a vector of sets, which efficiently represents stacks that have common parts

It resembles closely the implementation of the *ELR* deterministic *PDA* by means of a vectored stack

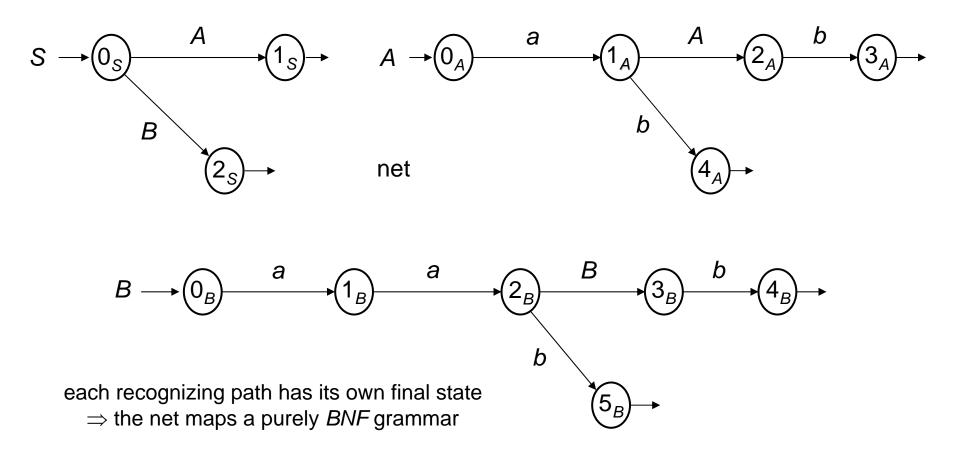
It simulates a non-deterministic pushdown analyzer, but with a polynomial time complexity

Notice that also the *ELR* method simulates parallel analysis threads, but only until reduction time

The Earley algorithm has variants without or with look-ahead, but here for simplicity look-ahead is not used

EXAMPLE – a grammar not LR (k)

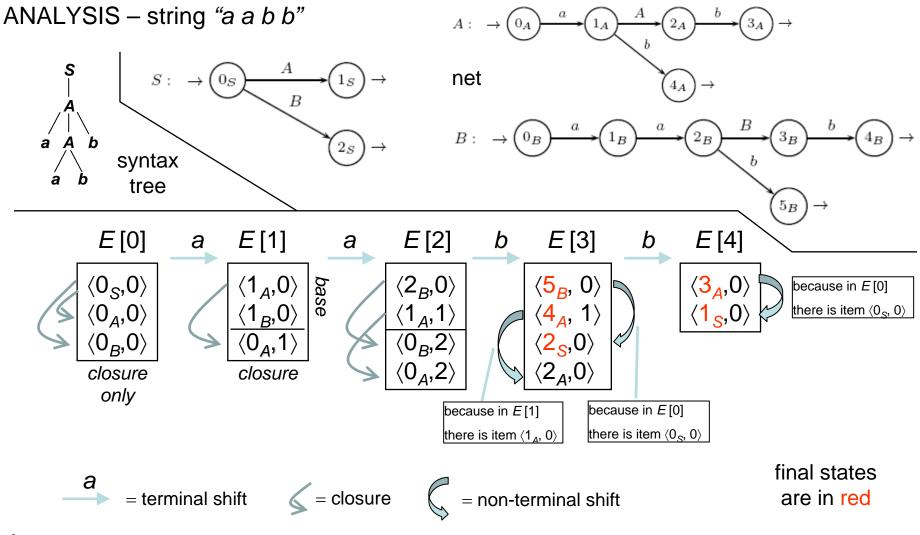
$$\begin{bmatrix}
L = \{a^n b^n \mid n \ge 1\} \cup \{a^{2n} b^n \mid n \ge 1\} \\
S \to A \mid B \quad A \to aAb \mid ab \quad B \to aaBb \mid aab
\end{bmatrix}$$



series 14

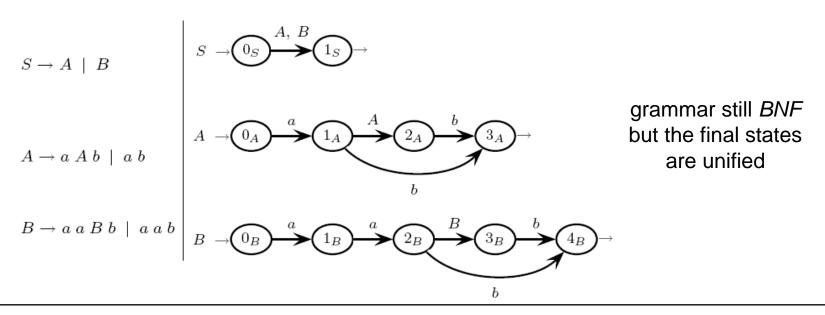
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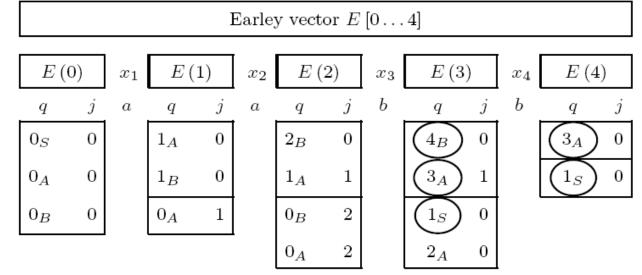
pp. 3 / 15



If the string were "a a b", it would be accepted because $\langle 2_S, 0 \rangle \in E$ [3] and 2_S is final for M_S But it is the string "a a b b" that is accepted, because $\langle 1_S, 0 \rangle \in E$ [4] and 1_S is final for M_S Besides deciding if it holds $x \in L$, the algorithm decides also for all the prefixes of string x

SAME LANGUAGE AS BEFORE BUT WITH A NOT *ELR* (*k*) GRAMMAR





pp. 5 / 15

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ALGORITHM – the Earley (tabular) recognizer

The algorithm builds a vector E[0 ... n] of n = |x| elements Each element E[i] is a set of items (or pairs) $\langle s, j \rangle$ like the items in the LR stack, but without look-ahead The vector E contains all the analysis threads in a compacted form, i.e., the common parts are shared

We define the move types that are found in the steps of the algorithm

terminal shift scanning: there are at most *n* shifts, one per each character in *x*

closure same as the closure in LR

non-terminal shift same as the non-terminal shift in LR

completion = closure + non-terminal shift, possibly repeated two or more times

call *i* the *current position*, the max index value *i* such that the set *E* [*i*] is not empty

do

```
TerminalShift(E, i)
                                - - with index 1 \le i \le n
- - loop that computes the terminal shift operation
- - for each preceding pair that shifts on terminal x_i
for (each pair \langle p, j \rangle \in E[i-1] and q \in Q s.t. p \xrightarrow{x_i} q) do
      add pair \langle q, j \rangle to element E[i]
end for
- - analyze the terminal string x for possible acceptance
- - define the Earley vector E[0...n] with |x| = n \ge 0
E[0] := \{ \langle 0_S, 0 \rangle \}
                                     - - initialize the first elem. E [0]
for i := 1 to n do
                                     - - initialize all elem.s E[1 \dots n]
      E[i] := \emptyset
end for
Completion(E, 0)
                                      - - complete the first elem. E[0]
i := 1
- - while the vector is not finished and the previous elem. is not empty
while (i \le n \land E[i-1] \ne \emptyset) do

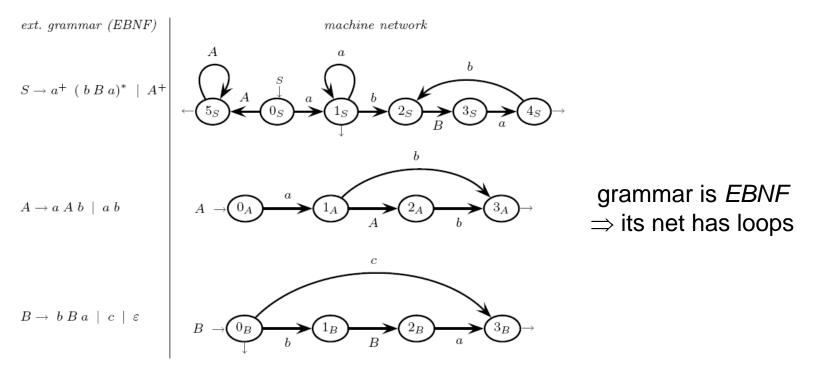
ightharpoonup TerminalShift (E, i)
                                     - - put into the current elem. E[i]
       Completion(E, i)
                                - - complete the current elem. E[i]
       i + +
end while
                                                                 Earley
```

```
Completion(E, i)
                               - - with index 0 \le i \le n
      - - loop that computes the closure operation
      - - for each pair that launches machine M_X
     for (each pair \langle p, j \rangle \in E[i] and X, q \in V, Q s.t. p \xrightarrow{X} q) do
            add pair \langle 0_X, i \rangle to element E[i]
                                                              closure
     end for
     - - nested loops that compute the nonterminal shift operation
     - - for each final pair that enables a shift on nonterminal X
     for (each pair \langle f, j \rangle \in E[i] and X \in V such that f \in F_X) do
            - - for each pair that shifts on nonterminal X
            for (each pair \langle p, l \rangle \in E[j] and q \in Q s.t. p \xrightarrow{X} q) do
                  add pair \langle q, l \rangle to element E[i]
            end for
                                                 non-terminal shift
      end for
while
         (some pair has been added)
```

every string character x_{i+1} is examined only once in the scanning the machine input head is one-way and there is not backtracking.

string x is accepted if and only if item $\langle f_S, 0 \rangle \in E[n]$ $f_S \in F_S$ is a final state for machine S series 14 Form. Lang. & Comp. pp. 7 / 15

MORE COMPLEX EXAMPLE WITH A NON-DETRMINISTIC GRAMMAR (not *ELR* (1))

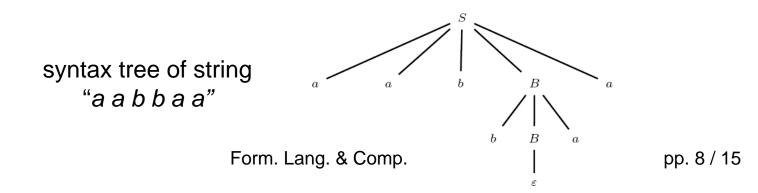


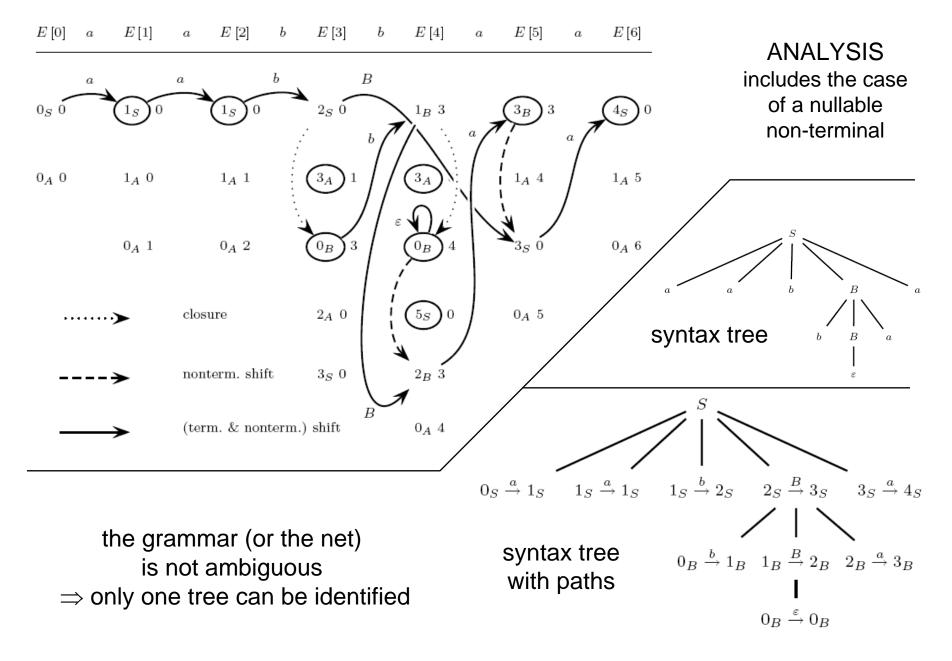
NON-DETERMINISM: if

series 14

- the adjacent substrings of a and b have the same length
- there is not any character c

Then the string deep structure can be determined only at the end of the scanning





WORST-CASE ASYMPTOTIC COMPLEXITY OF EARLEY

Let $n \ge 1$ be the length of the string to be analyzed

space complexity = size of the Earley vector

= # of sets E [j] \times max size of an element

$$= O(n^2)$$
 is quadratic

time compexity = # of terminal shifts + # of closures + # of nonterminal shifts

 $= O(n^3)$ is cubic

So in general Earley is polynomial, though it is not linear

Special case: n=0 (null string), then both complexities are constant, as only closure is used and is limited by the number of states k, which is a constant; anyway, the complexity is still polynomial

In most practical cases with applicative grammars (or machine nets), Earley performs better than above and approaches a linear behaviour

RECONSTRUCTION OF THE SYNTAX TREE

(for non-ambiguous grammars only)

The recursive procedure BuildTree (BT) builds the one tree starting from vector E

BT has four parameters: nonterminal X, subtree root, with $X \in V$

final state of machine M_X

integer i, substring left position

integer j, substring right position

BT returns:

the (sub)tree of the derivation $X \Rightarrow^* x_{i+1}, \dots x_j$

that has root X

Initial call $BT(S, f_S, 0, n)$

INITIALIZATION AND MAIN OPERATIONS

 $BuildTree\ (X,\ f,\ j,\ i)$

- -- X is a nonterminal, f is a final state of M_X and $0 \le j \le i \le n$
- - return as parenthesized string the syntax tree rooted at node X
- - node X will have a list \mathcal{C} of terminal and nonterminal child nodes
- - either list \mathcal{C} will remain empty or it will be filled from right to left

$$\mathcal{C} := \varepsilon$$

- - set to ε the list \mathcal{C} of child nodes of X

$$q := f$$

- - set to f the state q in machine M_X

$$k := i$$

- - set to i the index k of vector E

In its recostruction loop, function *BT* performs the following operations:

- scanning the vector E backwards by iterating the while loop
- rebuilding terminal and non-terminal shift moves
- identifying the child nodes of the same parent node
- recursively calling itself if set *E*[*i*] contains a pair from non-terminal shift
- ⇒ the recursive call builds the subtree of the shifted non-terminal

- - walk back the sequence of term. & nonterm. shift oper.s in M_X

while $(q \neq 0_X)$ do -- while current state q is not initial

SYNTAX TREE **RECONSTRUCTION LOOP**

terminal

shift

- - try to backwards recover a terminal shift move $p \stackrel{x_k}{\rightarrow} q$, i.e.,
- - check if node X has terminal x_k as its current child leaf

(a) if
$$\begin{pmatrix} \exists h = k-1 \ \exists p \in Q_X \text{ such that } \\ \langle p, j \rangle \in E[h] \land \text{ net has } p \xrightarrow{x_k} q \end{pmatrix}$$
 then $\mathcal{C} := x_k \cdot \mathcal{C}$ -- concatenate leaf x_k to list \mathcal{C} end if

- - try to backwards recover a nonterm. shift oper. $p \xrightarrow{Y} q$, i.e.,
- - check if node X has nonterm. Y as its current child node

(b) if
$$\left(\exists Y \in V \ \exists e \in F_Y \ \exists h \ j \leq h \leq k \leq i \ \exists p \in Q_X \ \text{s.t.} \right)$$
 then $\left(\langle e, h \rangle \in E[k] \ \land \ \langle p, j \rangle \in E[h] \ \land \ \text{net has } p \xrightarrow{Y} q \right)$

- - recursively build the subtree of the derivation:
- $--Y \stackrel{\pm}{=} x_{h+1} \dots x_k \text{ if } h < k \text{ or } Y \stackrel{\pm}{=} \varepsilon \text{ if } h = k$
- - and concatenate to list \mathcal{C} the subtree of node Y

$$C := BuildTree (Y, e, h, k) \cdot C$$

end if

- - shift the current state q back to p q := p

k := h- - drag the current index k back to h

end while

return $(\mathcal{C})_X$ - - return the tree rooted at node $X \square$ non-ambiguous grammar ⇒ deterministic reconstruction

non-terminal

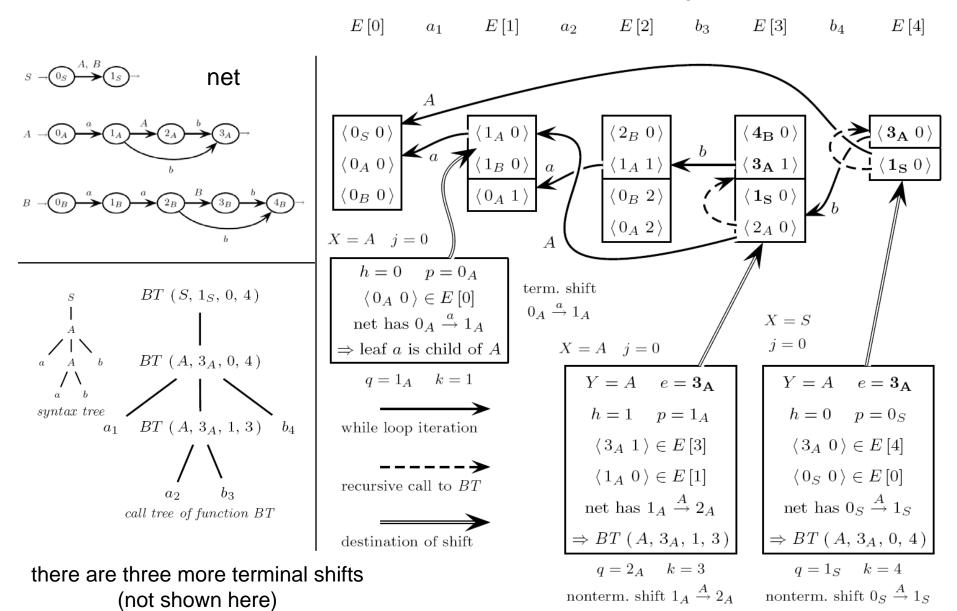
shift

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pp. 13 / 15

ANALYSIS AND TREE CONSTRUCTION - string "a a b b"



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pp. 14 / 15

WORST-CASE COMPLEXITY OF BUILDTREE

Since the grammar is supposed to be not ambiguous, the tree size is linear, so the time complexity of *BT* is also cubic (like Earley)

Extending *BT* to ambiguous grammars is possible as well, but to efficiently represent all the trees a Sparse Tree Forest (*STF*) is necessary, which is a graph type more general than a tree (not considered here)

OPTIMIZATION OF THE EARLEY METHOD BY USING LOOK-AHEAD

The items in the sets E[i] of the Earley vector E can be extended by including look-ahead, computed as it is done in the ELR(1) method

By siding a look-ahead to each item, the Earley algorithm avoids to put into the sets E [i] items that correspond to choices doomed to failure. This way however, for some grammars the number of items may increase rather than decrease. So the advantage of using look-ahead in Earley is controversial

At present the most efficient implementations of Earley do not use look-ahead