## Remote Triggered FPGA based Automation System

## **Table of Contents:**

- 1. Introduction
  - ▲ Need & Inspiration for building such a system
  - ▲ Brief System Description
  - 2. Usage Scenarios
    - ∆ Usage Diagram with Sequence
    - △ Brief Description of the different steps
      - ▲ Screenshots of the different steps
  - 3.System Overview
    - ▲ System Block Diagram
    - A Briefly explain all parts and the technology used behind each of them
      - △ Give details of server setup & directories where files reside/are created
  - 4.Detailed Workflow
    - ▲ Refer back to Usage Diagram from Chapter 2 above
    - ▲ Describe what action each 'user step' results in
      - △ Provide with details of the files/functions/scripts etc.
  - ▲ Dedicated section on programming, running & extracting data from the FPGA hardware 5.Future Work
    - ▲ Possible Enhancements & Additions
  - 6.References

# **Chapter One:**

### Introduction

### Need & Inspiration for building such a system

Simulation does not give the feel of running the designs on an actual FPGA system. So if a system is built such that the user can run his design and check his output for various inputs on the actual system without actually having the system with him i.e. he accesses the FPGA based system remotely, then most of the users' work will be simplified.

But the design cannot be implemented until the designer compiles, synthesizes then assigns pins to the board for which he needs to know the board details. All this becomes tedious. This can be simplified if the user is just asked to provide with his design file and the test vectors and rest of the part is automated.

Thus bringing us to the Remote Triggered FPGA based Automation system. Such kind of system is developed under WEL Virtual labs with the help of Altera DE2-70 board.

### **Block diagram:**

#### GUI based Front-end for User

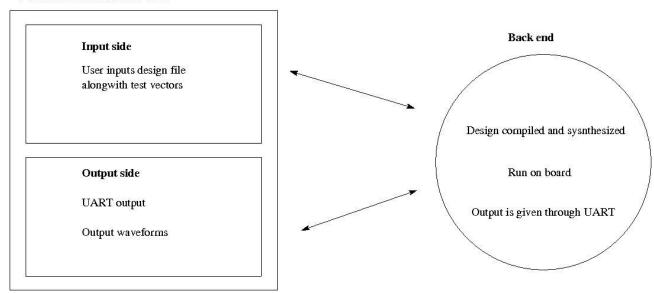


Fig. 1.1 – Basic block diagram of Remote triggered FPGA based automation system

### Basic working of this system

- Remote user uploads the design file (eg.: user\_design.v) in specified format along with test vectors.
- An FSM system is invoked which will automate the process.
- This FSM will take the user design along with the test vectors and generate the output and send it through UART from which the output waveforms can be generated.
- This FSM will be responsible to produce output corresponding to each test vector input.

The following gives a better idea of this FSM system:

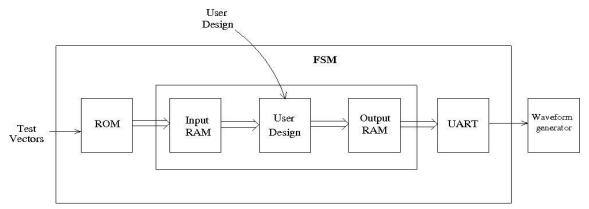


Fig. 1.2 - FSM system

- This Automation FSM system is designed using Verilog HDL and will thus have the Verilog modules ROM.v, INPUT\_RAM.v, USER\_DESIGN\_WRAPPED.v, OUTPUT\_RAM.v, UART.v and FSM.v. Named as per the blocks shown in fig. 1.2.
- FSM.v will act as a top-level module which instantiates all other Verilog modules depending on the FSM design.

## **Chapter Two:**

### **Usage Scenario**

• User will access the website of "Remote triggered FPGA based automation system" (http://59.181.142.81/fpga/automation.php)



Fig. 2.1 – Webpage of "Remote triggered FPGA based automation system"

• The user will upload his design by clicking on "Upload Verilog File"

### Step 1: Upload Design Under Test Verilog File

**Upload Verilog File** 

Fig. 2.2 – Upload Design file (.v)

• After uploading the design file, the system checks for 1-bit input ports and lists options for the user to select the clock pin.

#### Step 1: Upload Design Under Test Verilog File



Fig. 2.3 – Select the appropriate clock pin and click on "Set clock pin" button

- The user has to give appropriate test vector input for the corresponding clock.
- User can provide the input for maximum 256 clock cycles.

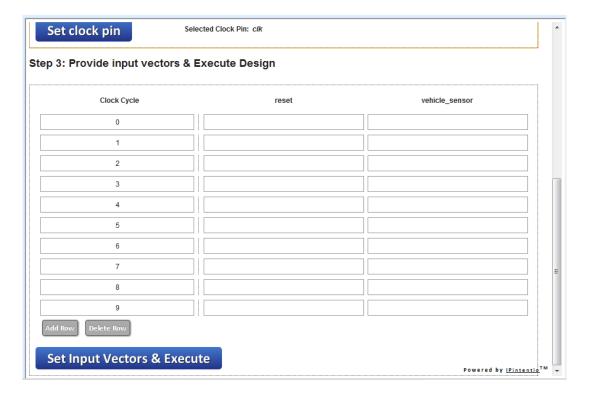


Fig. 2.4 – Step appearing after pressing "Set clock pin"

- The user may opt out from giving an input if the input is just repeating for some number of clock cycles where the system will take the value as the value of previous clock cycle but user will have to give the input where the input is changing.
- User can add and delete rows, if required, and can extend upto maximum a total of 256 rows.

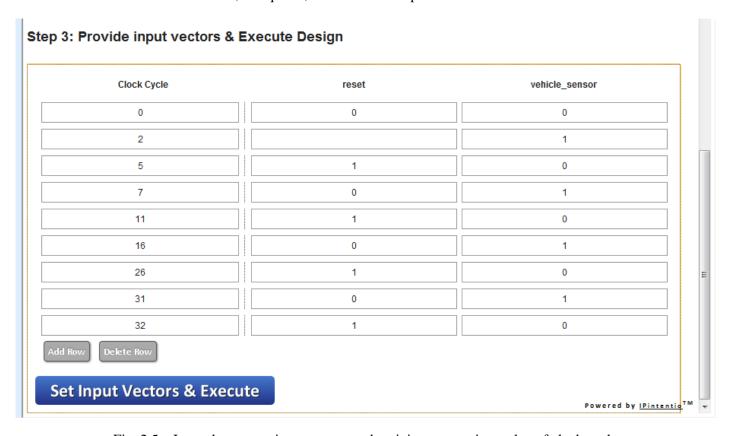


Fig. 2.5 – Input the appropriate test vectors by giving appropriate value of clock cycle and press "Set Input Vectors & Execute" button

- These inputs along with the clock pin are combined together to form a 16-bit where the rest of the bits are zeros.
- The files INPUT\_RAM.c, OUTPUT\_RAM.c, ROM.c USER\_DESIGN\_WRAPPER.c, FSM.c are called the configuration files.
- The input\_width and the no. of inputs are supplied to file INPUT\_RAM.c by the user to generate INPUT\_RAM.v.
- The output\_width and no. of outputs (same as no. of inputs) are supplied by the user to file OUTPUT\_RAM.c to generate OUTPUT\_RAM.v.
- The input\_width, output\_width and no. of inputs are supplied by the user to file OUTPUT\_RAM.c to generate FSM.v
- The test\_vectors supplied by the user (as described in fig. 2.5) are read by the ROM.c along with the input\_width and no. of inputs to generate ROM.v file.
- The user\_design.v file is read by the USER\_DESIGN\_WRAPPER.c file along with input\_width and output\_width to generate USER\_DESIGN\_WRAPPED.v file. This file instantiates module of user\_design.v.



Fig. 2.6 - User clicks on "Set Input Vectors & Execute"

- This will generate board files which will take-in various inputs and convert all .c files to .v files (mentioned above).
- After all the .v files are generated, all the modules are compiled, synthesized and then pin
  assignment is done according to the device family of the Altera DE2-70 board in the Quartus II
  software in shell mode.
- To simplify this procedure, TCL script has been written which will create follow all the procedure of:
  - 1. Creating a project
  - 2. Selecting device family
  - 3. Defining top-level module and adding all automated FSM design
  - 4. Assigning pins of input, output, clk and reset to the Altera DE2-70 board
  - 5. Compile, synthesize and execute (execute means running the design on board)
- The TCL script is shown below:

#### TCL script.tcl:

```
load_package flow
```

package require ::quartus::flow

```
# Assign family, device, and top-level file
set_global_assignment -name FAMILY CycloneII
set_global_assignment -name DEVICE EP2C70F896C6
set_global_assignment -name VERILOG_FILE final.v
set_global_assignment -name VERILOG_FILE input_ram_dual.v
set_global_assignment -name VERILOG_FILE output_ram_dual.v
set_global_assignment -name VERILOG_FILE up_counter.v
set_global_assignment -name VERILOG_FILE baud_gen.v
set_global_assignment -name VERILOG_FILE rom3.v
set_global_assignment -name VERILOG_FILE uart_rx.v
```

```
set_global_assignment -name VERILOG_FILE uart_tx.v
set_global_assignment -name VERILOG_FILE uart_tx.v
set_global_assignment -name TOP_LEVEL_ENTITY final

# Assign pins
set_location_assignment -to clk Pin_AD15
set_location_assignment -to glbl_rst Pin_AA23
set_location_assignment -to start Pin_AB26
set_location_assignment PIN_E21 -to ser_out

#compile the project
execute_flow -compile
qexec quartus_pgm -l
exec quartus_pgm --mode=jtag --cable=USB-Blaster --operation=p\;counter1.sof

#close project
project_close
```

- The system is configured such that the output is given to the UART.
- A script is written which will take-in this UART output from the DE2-70 board and interpret it in an 8-bit format. So the rest of the bits other than the output buts in the 8-bits are assigned zero.
- This 8-bit output is then converted in VCD format and is made available to the user for download.
- A log is also displayed which is actually the compilation report of quartus.

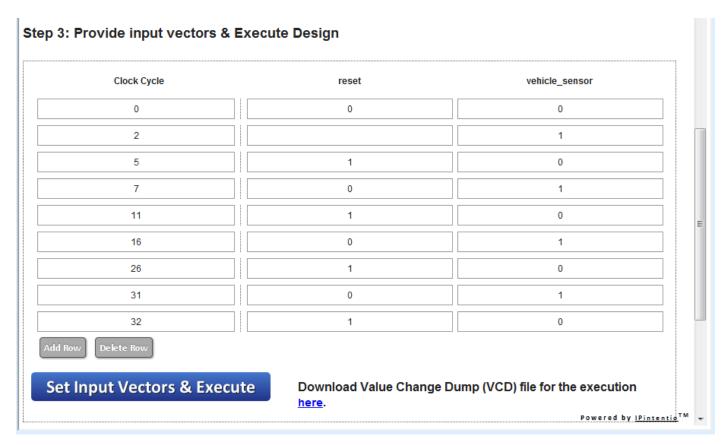


Fig. 2.7 – VCD file ready for download

- Please check at the end of the log for possible error.
- If no error then download the VCD file.

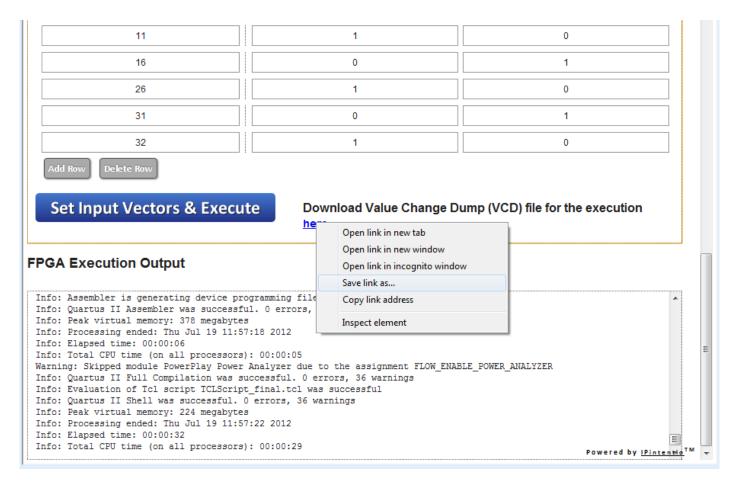


Fig. 2.8 – Download VCD file if no error

- This VCD file can then be viewed on the GTKWave waveform viewer and is illustrated below.
- Goto File>Open New Tab

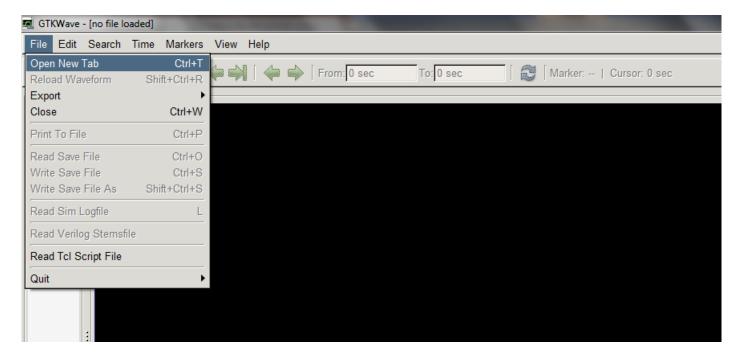


Fig. 2.8 – Open GTKWave waveform viewer (refer to GTKWave installation manual provided)

• Select the file from the directory in which .vcd file is saved.

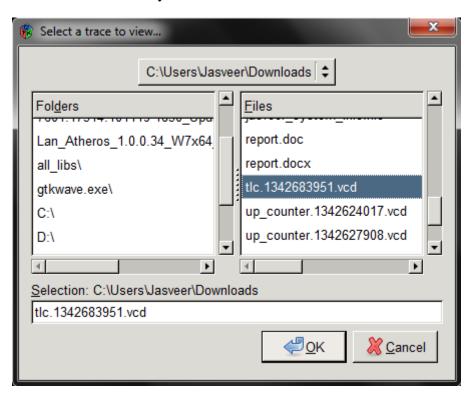


Fig. 2.9 – Select vcd file to be viewed

• The top level module name is now displayed on the top left pane of the GTKWave window.

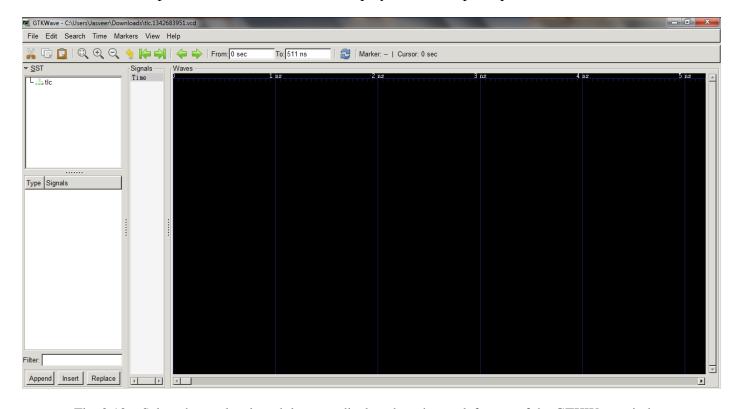


Fig. 2.10 – Select the top level module name displayed on the top left pane of the GTKWave window

• After selecting the top level module name displayed on the top left pane of the GTKWave window, the signals can be seen on the bottom left pane of the GTKWave window.

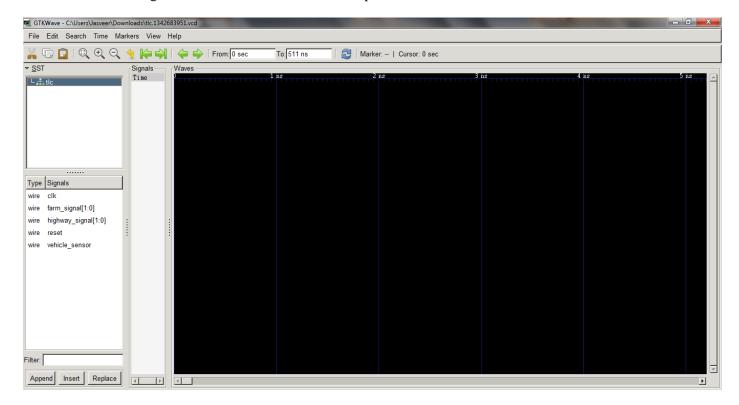


Fig. 2.11 – Open GTKWave waveform viewer (refer to GTKWave installation manual provided)

• Select all of the signals and press the button Append.

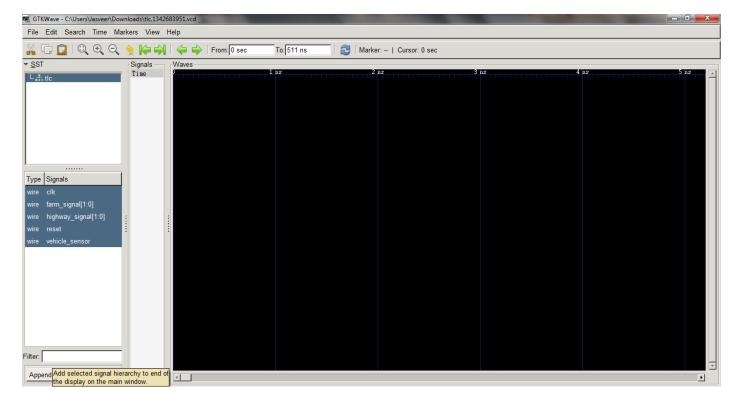


Fig. 2.12 – Select all of them and press append

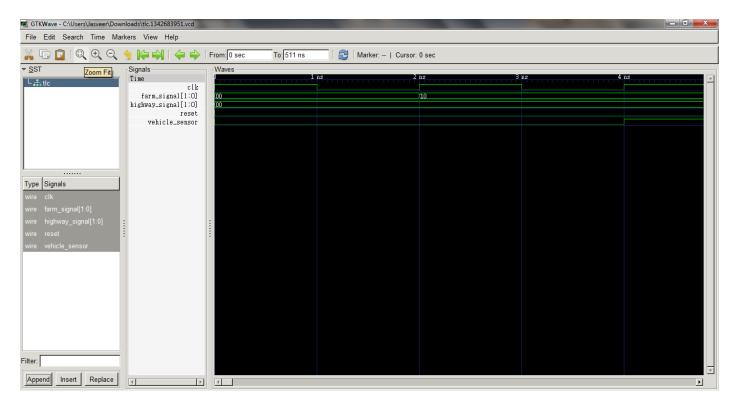


Fig. 2.12 – The waveform can be seen now

- Use the button, called Zoom-fit to see the whole 256 clock cycles on your screen.
- Use the button, called Zoom-in to see larger view i.e. less no. of cycles on your screen.
- Use the button, called Zoom-out to see the large no. of cycles on your screen.

# **Constraints:**

- The user can see maximum upto 256 clock cycles.
- Total of all input pins cannot be more than 16.
- Total of all the output pins cannot be more than 8.