Numerical Schemes for Scalar One-Dimensional Conservation Laws

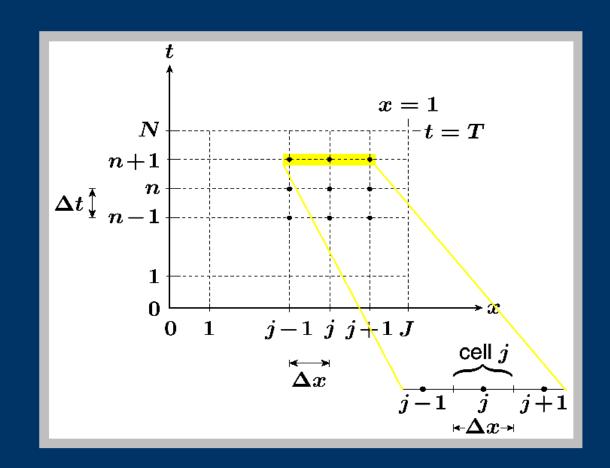
Lecture 12

Finite Volume Discretization

Computational Cells

$$x_j = j\Delta x$$

$$t^n = n\Delta t$$



Finite Volume Discretization

Cell averages

We think of \hat{u}_{j}^{n} as representing cell averages

$$egin{aligned} \hat{m{u}}_j^n &pprox rac{1}{\Delta x} \int_{x_{j-rac{1}{2}}}^{x_{j+rac{1}{2}}} m{u}(x,t^n) \ dx \end{aligned}$$

Definition

Conservative Methods

Applying integral form of conservation law to a cell j

$$rac{d}{dt} \int_{x_{j-rac{1}{2}}}^{x_{j+rac{1}{2}}} u \, dx = - \left[f(u(x_{j+rac{1}{2}},t)) - f(u(x_{j-rac{1}{2}},t))
ight]$$

suggests

$$rac{\hat{oldsymbol{u}}_j^{n+1} - \hat{oldsymbol{u}}_j^n}{\Delta t} \Delta x = -\left(F_{j+rac{1}{2}}^n - F_{j-rac{1}{2}}^n
ight)$$

$$\Rightarrow \quad \left| oldsymbol{\hat{u}}_j^{n+1} = oldsymbol{\hat{u}}_j^n - rac{\Delta t}{\Delta x} \left(F_{j+rac{1}{2}}^n - F_{j-rac{1}{2}}^n
ight)
ight|$$

Numerical Flux function

Conservative Methods

$$F_{j+rac{1}{2}}\equiv F\left(\hat{u}_{j-l},\hat{u}_{j-l+1},\ldots,\hat{u}_{j},\ldots,\hat{u}_{j+r}
ight)$$

and F is a numerical flux function of l+r+1 arguments that satisfies the following consistency condition

$$F(u,u,\ldots,u,u)=f(u)$$

$$j \stackrel{\longleftarrow}{-\ell} \quad \cdots \quad j-1 \qquad j \stackrel{\longleftarrow}{j+rac{1}{2}} j+1 \qquad \cdots \qquad j+r$$

Lax-Wendroff Theorem

If the solution of a conservative numerical scheme converges as $\Delta x \to 0$ with $\frac{\Delta t}{\Delta x}$ fixed, then it converges to a weak solution of the conservation law.

N1

shock capturing schemes are possible

N2

Lax-Wendroff Theorem

Shock Capturing

In the exact problem:

$$rac{d}{dt}\int_{x_0}^{x_J} u \; dx = -(f_0 - f_J)$$

A conservative numerical scheme satisfies an analogous discrete condition:

N3

$$egin{aligned} rac{\Delta x}{\Delta t} \sum_{j=0}^{J} (\hat{m{u}}_j^{n+1} - \hat{m{u}}_j^n) &= -\sum_{j=0}^{J} \left(F_{j+rac{1}{2}} - F_{j-rac{1}{2}}
ight) \ &= -\left(F_{J+rac{1}{2}} - F_{-rac{1}{2}}
ight) \end{aligned}$$

First Order Upwind

Linear Advection Equation...

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0$$
 $a \text{ constant } > 0$

$$oldsymbol{\hat{u}_j^{n+1}} = oldsymbol{\hat{u}_j^n} - rac{\Delta t}{\Delta x} \left(F_{j+rac{1}{2}}^{UP} - F_{j-rac{1}{2}}^{UP}
ight)$$

Let
$$F_{j+rac{1}{2}}^{UP}\equiv a\; m{\hat{u}_j} \quad \left(F_{j-rac{1}{2}}^{UP}=a\; m{\hat{u}_{j-1}}
ight)$$

$$\hat{m{u}}_j^{n+1} = \hat{m{u}}_j^n - rac{\Delta t \ a}{\Delta x} (\hat{m{u}}_j - \hat{m{u}}_{j-1})$$

First Order Upwind

...Linear Advection Equation...

What about a < 0?

We can write,

$$\hat{oldsymbol{u}}_j^{n+1} = \hat{oldsymbol{u}}_j^n - rac{a\Delta t}{\Delta x} \left\{ egin{array}{ll} \hat{oldsymbol{u}}_j^n - \hat{oldsymbol{u}}_{j-1}^n & a > 0 \ \hat{oldsymbol{u}}_{j+1}^n - \hat{oldsymbol{u}}_j^n & a < 0 \end{array}
ight.$$

or

$$\hat{u}_{j}^{n+1} = \hat{u}_{j}^{n} - rac{a\Delta t}{2\Delta x}ig(\hat{u}_{j+1}^{n} - \hat{u}_{j-1}^{n}ig) + rac{|a|\Delta t}{2\Delta x}ig(\hat{u}_{j+1}^{n} - 2\hat{u}_{j}^{n} + \hat{u}_{j-1}^{n}ig)$$

First Order Upwind

...Linear Advection Equation

In conservative form:

$$\hat{oldsymbol{u}}_j^{n+1} = \hat{oldsymbol{u}}_j^n - rac{oldsymbol{\Delta} t}{oldsymbol{\Delta} oldsymbol{x}} \left(F_{j+rac{1}{2}}^{UPn} - F_{j-rac{1}{2}}^{UPn}
ight)$$

$$oxed{F_{j+rac{1}{2}}^{UP}=rac{1}{2}a(\hat{u}_{j+1}+\hat{u}_{j})-rac{1}{2}|a|(\hat{u}_{j+1}-\hat{u}_{j})}$$

$$F_{j+rac{1}{2}}^{UP}=a\hat{u}_{j}$$

$$egin{aligned} F_{j+rac{1}{2}}^{UP} &= a\hat{u}_j \ F_{j+rac{1}{2}}^{UP} &= a\hat{u}_{j+1} \end{aligned}$$

First Order Upwind

Nonlinear Case

In the nonlinear case,

$$\frac{\partial u}{\partial t} + \frac{\partial f(u)}{\partial x} = 0$$

the flux becomes

N4

$$igg|F_{j+rac{1}{2}}^{UP} = rac{1}{2}ig(\hat{f}_{j+1} + \hat{f}_{j}ig) - rac{1}{2}|\hat{a}_{j+rac{1}{2}}|\left(\hat{u}_{j+1} - \hat{u}_{j}
ight)$$

$$oldsymbol{\hat{a}}_{j+rac{1}{2}} = egin{cases} rac{\hat{f}_{j+1}-\hat{f}_{j}}{\hat{u}_{j+1}-\hat{u}_{j}} & ext{if} & \hat{oldsymbol{u}}_{j+1}
eq \hat{oldsymbol{u}}_{j} \ f'(\hat{oldsymbol{u}}_{j}) & ext{if} & \hat{oldsymbol{u}}_{j+1} = \hat{oldsymbol{u}}_{j} \end{cases}$$

Lax-Wendroff

Conservative Methods

$$F_{j+rac{1}{2}}^{LW} = rac{1}{2}\,\left(\hat{f}_{j+1} + \hat{f}_{j}
ight) - rac{1}{2}\,\,\hat{a}_{j+rac{1}{2}}^{2}\,rac{\Delta t}{\Delta x}\left(\hat{u}_{j+1} - \hat{u}_{j}
ight)$$

For the linear equation

$$\hat{u}_{j}^{n+1} = \hat{u}_{j} - rac{C}{2} \left(\hat{u}_{j+1}^{n} - \hat{u}_{j-1}^{n}
ight) + rac{C^{2}}{2} \left(\hat{u}_{j+1}^{n} - 2\hat{u}_{j}^{n} + \hat{u}_{j-1}^{n}
ight)$$
 $C = a\Delta x/\Delta t$

Beam-Warming

Conservative Methods

$$egin{split} F^{BW}_{j+rac{1}{2}} &= rac{1}{4} \left(-\hat{f}_{j+2} + 3\hat{f}_{j+1} + 3\hat{f}_j - \hat{f}_{j-1}
ight) - \hat{a}^2_{j+rac{1}{2}} rac{\Delta x}{4\Delta t} \left(\hat{u}_{j+2} - \hat{u}_{j+1} + \hat{u}_j - \hat{u}_{j-1}
ight) \ &- rac{s_{j+rac{1}{2}}}{4} \left(-\hat{f}_{j+2} + 3\hat{f}_{j+1} - 3\hat{f}_j + \hat{f}_{j-1}
ight) + s_{j+rac{1}{2}} a^2_{j+rac{1}{2}} rac{\Delta t}{4\Delta x} \left(\hat{u}_{j+2} - \hat{u}_{j+1} - \hat{u}_j + \hat{u}_{j-1}
ight) \end{split}$$

$$s_{j+rac{1}{2}}=a_{j+rac{1}{2}}/|a_{j+rac{1}{2}}|$$

For the linear equation

$$egin{aligned} \hat{u}_{j}^{n+1} &= \hat{u}_{j}^{n} - rac{C}{2} \left(3\hat{u}_{j}^{n} - 4\hat{u}_{j-1}^{n} + \hat{u}_{j-2}^{n}
ight) + rac{C^{2}}{2} \left(\hat{u}_{j}^{n} - 2\hat{u}_{j-1}^{n} + \hat{u}_{j-2}^{n}
ight) & a > 0 \ \hat{u}_{j}^{n+1} &= \hat{u}_{j}^{n} - rac{C}{2} \left(-3\hat{u}_{j}^{n} + 4\hat{u}_{j+1}^{n} - \hat{u}_{j+2}^{n}
ight) + rac{C^{2}}{2} \left(\hat{u}_{j+2}^{n} - 2\hat{u}_{j+1}^{n} + \hat{u}_{j}^{n}
ight) & a < 0 \end{aligned}$$

Entropy Solutions

Methods

Conservative

Do these schemes converge to the entropy satisfying solution?

EXAMPLE:

Consider a non-physical solution to Burgers' equation:

$$u(x,t) = egin{cases} 1 & x \geq 0 \ -1 & x < 0 \end{cases}$$

i.e.
$$\hat{u}_j^n$$
 is either 1 or $-1 \ \Rightarrow \ f_j = \frac{1}{2} \ \ orall j$

Entropy Solutions

Example

First order upwind:

$$F_{j+rac{1}{2}}^{UP} = rac{1}{2} \left(\hat{f}_{j+1} + \hat{f}_{j}
ight) - rac{1}{2} |\hat{a}_{j+rac{1}{2}}| \left(\hat{u}_{j+1} - \hat{u}_{j}
ight)$$

Since either $\hat{a}_{j+\frac{1}{2}}$ or $\hat{u}_{j+1} - \hat{u}_{j}$ is zero orall j

$$\Rightarrow$$
 $F_{j+rac{1}{2}}^{UP}=rac{1}{2}$ $orall j \Rightarrow$ $F_{j+rac{1}{2}}^{UP}-F_{j-rac{1}{2}}^{UP}=0$ $orall j$

$$\Rightarrow \hat{u}_j^{n+1} = \hat{u}_j^n$$

The entropy-violating solution is preserved

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Monotone Schemes

Entropy Satisfying Schemes

If a scheme can be written in the form

$$\hat{oldsymbol{u}}_{j}^{n+1} = H\left(\hat{oldsymbol{u}}_{j-l}^{n}, \hat{oldsymbol{u}}_{j-l+1}^{n}, \ldots, \hat{oldsymbol{u}}_{j}^{n}, \ldots, \hat{oldsymbol{u}}_{j+r}^{n}
ight)$$

with
$$rac{oldsymbol{\partial H}}{oldsymbol{\partial u_i}} \geq \mathbf{0}$$
 $i = j - l, \ldots, j, \ldots, j + r,$

then the scheme is monotone and is

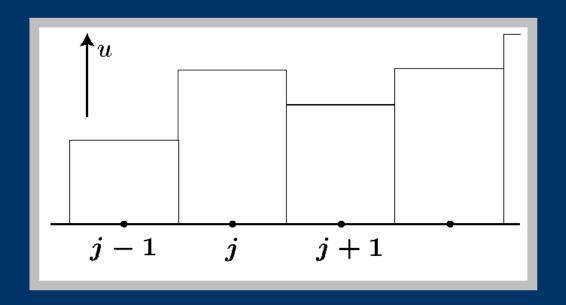
- entropy satisfying
- at most first order accurate

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Entropy Satisfying Schemes

Monotone Schemes

Godunov's Method...



Assume piecewise constant solution over each cell. Compute interface flux by solving interface (Riemann) problem exactly.

Entropy Satisfying Schemes

Monotone Schemes

...Godunov's Method...

$$egin{aligned} F_{j+rac{1}{2}}^{Gn} &= f\left(u(x_{j+rac{1}{2}}, t^{n+})
ight) \ &= egin{cases} \min_{u \in [u_j, u_{j+1}]} f(u) & u_j < u_{j+1} \ \max_{u \in [u_j, u_{j+1}]} f(u) & u_j > u_{j+1} \end{cases} \end{aligned}$$

Then,

$$oxed{\hat{u}_j^{n+1} = \hat{u}_j^n - rac{\Delta t}{\Delta x} \Big(F_{j+rac{1}{2}}^{Gn} - F_{j-rac{1}{2}}^{Gn}\Big)}$$

Entropy Satisfying Schemes

Monotone Schemes

...Godunov's Method

Applied to Burgers' equation

$$F_{j+rac{1}{2}}^G = egin{cases} rac{1}{2} \hat{u}_{j+1}^2 & \hat{u}_j, \hat{u}_{j+1} < 0 \ rac{1}{2} \hat{u}_j^2 & \hat{u}_j, \hat{u}_{j+1} > 0 \ 0 & \hat{u}_j < 0 < \hat{u}_{j+1} & ext{(expansion)} \ rac{1}{2} \hat{u}_j^2 & \hat{u}_j > 0 > \hat{u}_{j+1} & rac{1}{2} (\hat{u}_{j+1} + \hat{u}_j) > 0 \ rac{1}{2} \hat{u}_{j+1}^2 & \hat{u}_j > 0 > \hat{u}_{j+1} & rac{1}{2} (\hat{u}_{j+1} + \hat{u}_j) < 0 \end{cases}$$

E-Schemes

Entropy Satisfying Schemes

If the numerical flux $F_{j+\frac{1}{2}}$ satisfies

$$\mathsf{sign}(\hat{oldsymbol{u}}_{j+1}^n - \hat{oldsymbol{u}}_j^n)(F_{j+rac{1}{2}}^n - f(oldsymbol{u})) \leq \mathbf{0} \quad orall oldsymbol{u} \in [\hat{oldsymbol{u}}_j, \hat{oldsymbol{u}}_{j+1}]$$

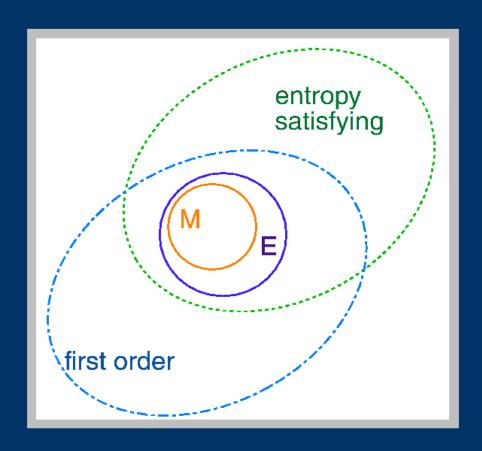
An E-scheme is

- entropy satisfying
- at most first order accurate

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Entropy Satisfying Schemes

Summary



Motivation

TVD Methods

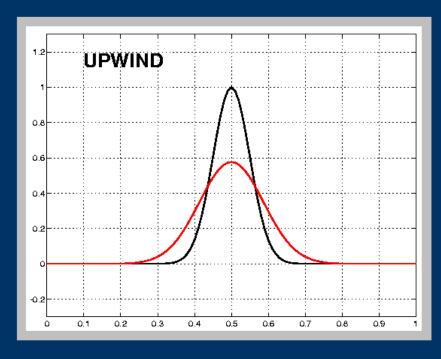
First order schemes give poor resolution but can be made to produce entropy satisfying and non-oscillatory solutions

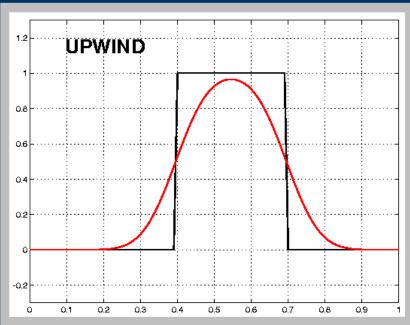
Higher order schemes (at least the ones we have seen so far) produce non-entropy satisfying and oscillatory solutions.

Good criterion to design "high order" oscillation free schemes is based on the **Total Variation** of the solution.

First Order Upwind

TVD Methods

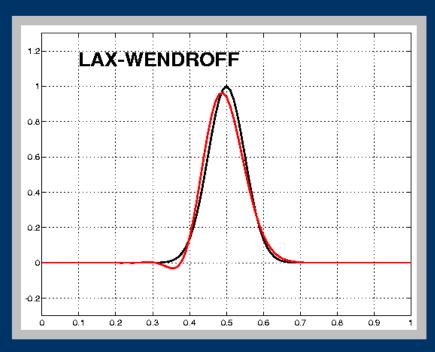


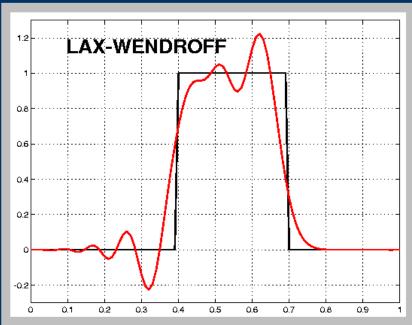


 $J=100, \ \Delta x=1/100, \ C=0.5, \ N=200$

Lax-Wendroff

TVD Methods





 $J=100, \ \Delta x=1/100, \ C=0.5, \ N=200$

Definition

TVD Methods

Total Variation of the discrete solution

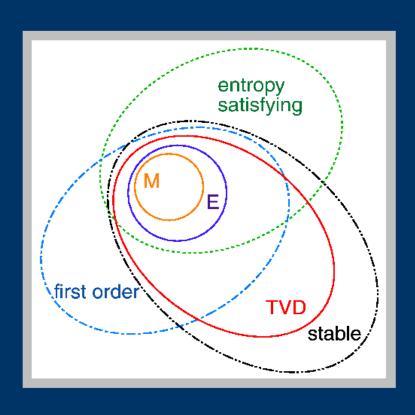
$$TV(\hat{oldsymbol{u}}^n) = \sum_{j} \left| \hat{oldsymbol{u}}_{j+1}^n - \hat{oldsymbol{u}}_{j}^n
ight|$$

If new extrema are generated $TV(\hat{u})$ will increase.

$$TV(\hat{oldsymbol{u}}^{n+1}) \leq TV(\hat{oldsymbol{u}}^n)$$

Total Variation Diminishing Schemes

Some Properties



- All E-Schemes are TVD
- Conservative TVD Schemes
 - → Converge to weak solutions

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Conditions for TVD schemes

TVD Methods

If a scheme is written in the form

$$\hat{m{u}}_{j}^{n+1} = \hat{m{u}}_{j}^{n} + D_{j+rac{1}{2}} \Delta \hat{m{u}}_{j+rac{1}{2}}^{n} - C_{j-rac{1}{2}} \Delta \hat{m{u}}_{j-rac{1}{2}}^{n}$$

$$oldsymbol{\Delta} \hat{u}_{j+rac{1}{2}} = \hat{u}_{j+1} - \hat{u}_{j}$$

it is TVD iff

$$egin{array}{ccc} C_{j+rac{1}{2}} & \geq 0 \ D_{j+rac{1}{2}} & \geq 0 \ C_{j+rac{1}{2}} + D_{j+rac{1}{2}} \leq 1 \end{array}$$

Example: Upwind

Upwind scheme for linear equation, a > 0:

$$oxed{u_j^{n+1} = u_j^n - rac{a\Delta t}{\Delta x} ig(u_j^n - u_{j-1}^nig)}$$

$$C_{j-rac{1}{2}}=rac{a\Delta t}{\Delta x}; \qquad D_{j+rac{1}{2}}=0$$

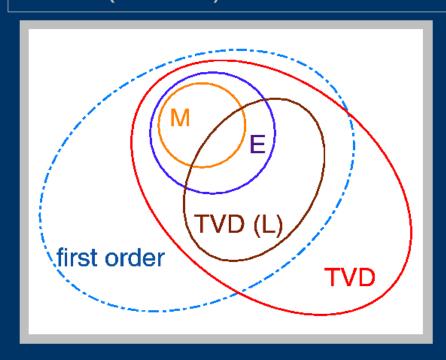
$$C_{j-rac{1}{2}}=rac{a\Delta t}{\Delta x}\leq 1$$

Stability-like condition!

Godunov's Theorem

TVD Methods

No second or higher order accurate constant coefficient (linear) scheme can be TVD.



→ Higher order TVD schemes must be non-linear

Consider the linear equation

$$\frac{\partial u}{\partial t} + a \frac{\partial u}{\partial x} = 0 \qquad a > 0$$

First order upwind (Godunov) scheme is

$$egin{align} \hat{m{u}}_j^{n+1} &= \hat{m{u}}_j^n - m{C} \left(\hat{m{u}}_j^n - \hat{m{u}}_{j-1}^n
ight) \ m{C} &= rac{m{a}m{\Delta}t}{m{\Delta}m{x}} \end{split}$$

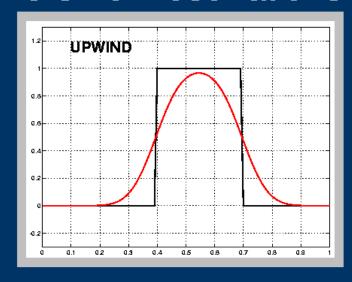
Oscillation free but smeared solutions.

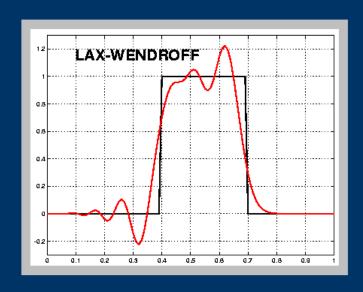
TVD Methods

Lax-Wendroff

$$\hat{m{u}}_{j}^{n+1} = \hat{m{u}}_{j}^{n} - rac{m{C}}{2} \left(\hat{m{u}}_{j+1}^{n} - \hat{m{u}}_{j-1}^{n}
ight) + rac{m{C}^{z}}{2} \left(\hat{m{u}}_{j+1}^{n} - 2\hat{m{u}}_{j}^{n} + \hat{m{u}}_{j-1}^{n}
ight)$$

Suffers from oscillations.





TVD Methods

Anti-diffusion

Re-write the Lax-Wendroff scheme:

$$\hat{u}_j^{n+1} = \underbrace{\hat{u}_j^n - C\left(\hat{u}_j^n - \hat{u}_{j-1}^n\right)}_{ ext{first order upwind}} - \underbrace{\frac{1}{2}C(1-C)\left(\hat{u}_{j+1}^n - 2\hat{u}_j^n + \hat{u}_{j-1}^n\right)}_{ ext{anti-diffusive flux}}$$
 $F_{j+rac{1}{2}}^{LW} = a\hat{u}_j + rac{a}{2}\left(1-C\right)\left(\hat{u}_{j+1} - \hat{u}_j
ight)$

Introduce flux limiter $\phi_{j+\frac{1}{2}}$:

$$F_{j+rac{1}{2}}^{TVD} = a\hat{u}_j + rac{a}{2}\left(1-C
ight)\phi_{j+rac{1}{2}}\left(\hat{u}_{j+1} - \hat{u}_j
ight)$$

TVD Methods

Flux Limiters...

$$egin{align} \hat{m{u}}_{j}^{n+1} &= \hat{m{u}}_{j}^{n} - C\left(\hat{m{u}}_{j}^{n} - \hat{m{u}}_{j-1}^{n}
ight) \ &- rac{1}{2}C(1-C)\left[m{\phi}_{j+rac{1}{2}}\left(\hat{m{u}}_{j+1}^{n} - \hat{m{u}}_{j}^{n}
ight) - m{\phi}_{j-rac{1}{2}}\left(\hat{m{u}}_{j}^{n} - \hat{m{u}}_{j-1}^{n}
ight)
ight] \end{split}$$

If
$$\phi_j = \phi_{j-1} = 1 \Rightarrow \text{Lax-Wendroff (not TVD)}$$

If $\phi_j = \phi_{j-1} = 0 \Rightarrow \text{Upwind (TVD)}$

Choose the limiter as close as possible to 1 but enforcing TVD conditions

TVD Methods

...Flux Limiters...

Re-write

$$egin{aligned} \hat{u}_{j}^{n+1} &= \hat{u}_{j}^{n} - C\Delta\hat{u}_{j-rac{1}{2}} - rac{1}{2}C(1-C)(\phi_{j+rac{1}{2}}\Delta\hat{u}_{j+rac{1}{2}} - \phi_{j-rac{1}{2}}\Delta\hat{u}_{j-rac{1}{2}}) \ &= u_{j}^{n} - C\left\{1 + rac{1}{2}(1-C)\left[rac{\phi_{j+rac{1}{2}}}{r_{j+rac{1}{2}}} - \phi_{j-rac{1}{2}}
ight]
ight\}\Delta\hat{u}_{j-rac{1}{2}} \ &\qquad \qquad r_{j+rac{1}{2}} = \Delta\hat{u}_{j-rac{1}{2}}/\Delta\hat{u}_{j+rac{1}{2}} \end{aligned}$$

Recall the TVD test:

$$\hat{u}_{j}^{n+1} = \hat{u}_{j}^{n} + D_{j+rac{1}{2}}\Delta\hat{u}_{j+rac{1}{2}}^{n} - C_{j-rac{1}{2}}\Delta\hat{u}_{j-rac{1}{2}}^{n}$$

TVD Methods

...Flux Limiters

Take

$$C_{j+rac{1}{2}} = C \left\{ 1 + rac{1}{2} (1-C) \left[rac{\phi_{j+rac{1}{2}}}{r_{j+rac{1}{2}}} - \phi_{j-rac{1}{2}}
ight]
ight\}$$

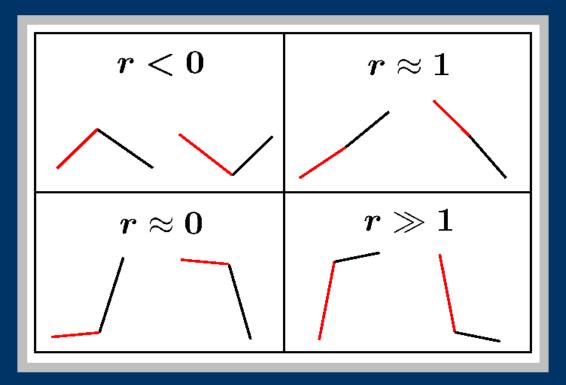
$$D_{j+\frac{1}{2}}=0$$

TVD criterion
$$\Rightarrow$$
 $0 \le C_{j+\frac{1}{2}} \le 1$

TVD Methods

Smoothness Monitor

Choose $\phi_{j+\frac{1}{2}}$ to be function of $r_{j+\frac{1}{2}}$



High Resolution Schemes

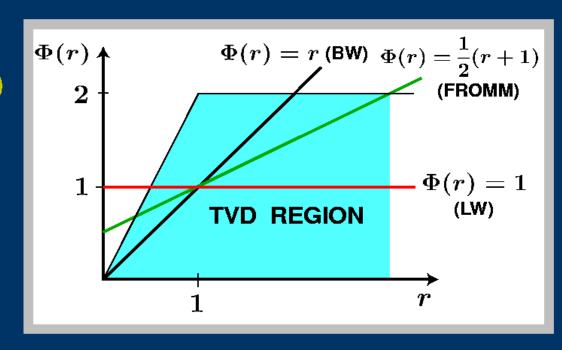
TVD region

It can be seen that the above TVD conditions are satisfied if

$$\phi(r)=0$$
 $r\leq 0$

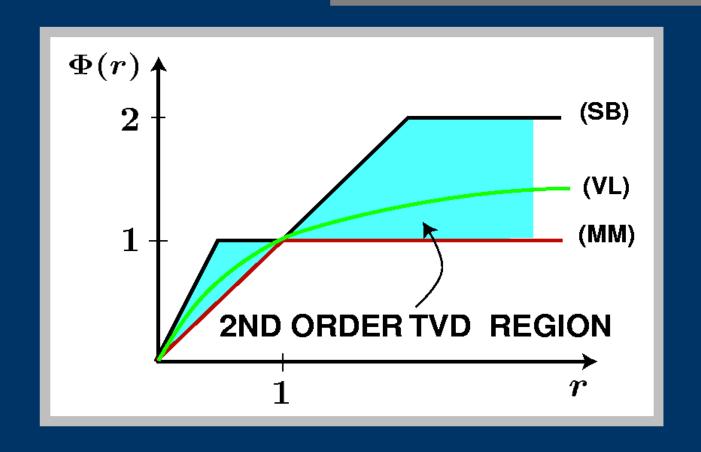
$$\mathbf{0} \leq rac{oldsymbol{\phi(r)}}{oldsymbol{r}} \leq \mathbf{2}$$

$$0 \le \phi(r) \le 2$$



High Resolution Schemes

2nd Order TVD Region



TVD Methods

Popular Choices

$$\mathsf{Minmod}\ \phi(r) = \max(\mathbf{0}, \min(\mathbf{1}, r))$$

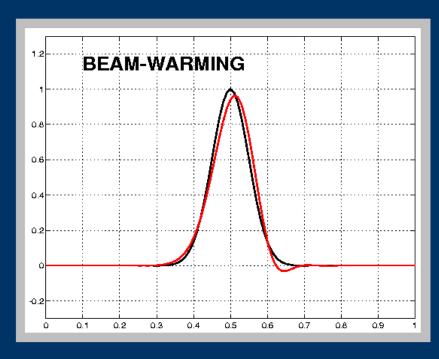
Superbee
$$\phi(r) = \max(0, \min(2r, 1), \min(r, 2))$$

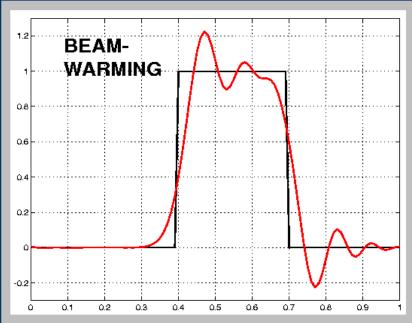
Van Leer
$$\phi(r) = \frac{r + |r|}{1 + |r|}$$

All produce **second order** schemes when the solution is smooth, and reduce to **upwind** at **discontinuities**.

High Resolution Schemes

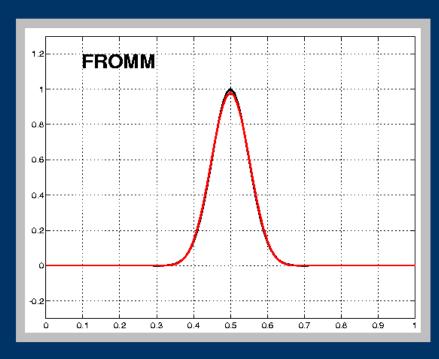
Examples...

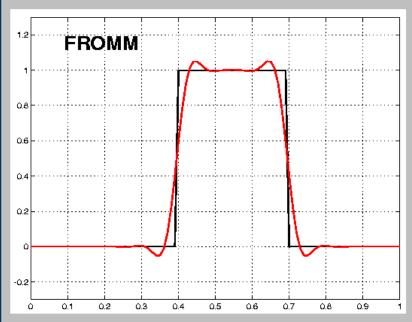




High Resolution Schemes

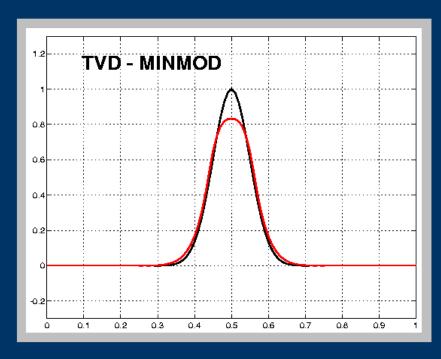
...Examples...

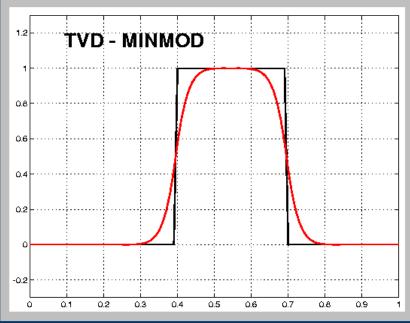




High Resolution Schemes

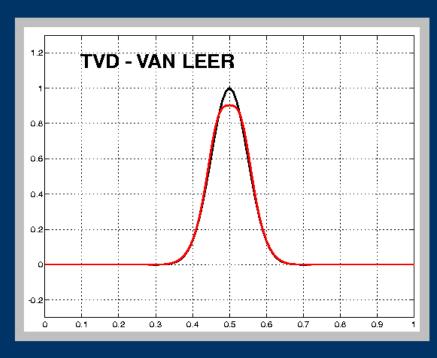
...Examples...

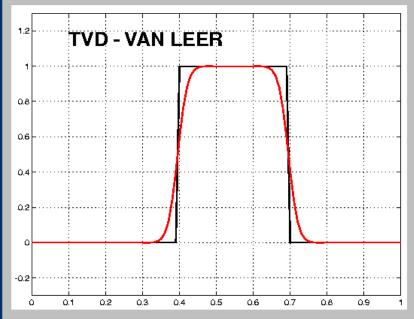




High Resolution Schemes

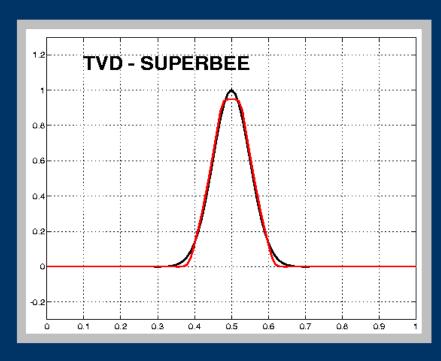
...Examples...

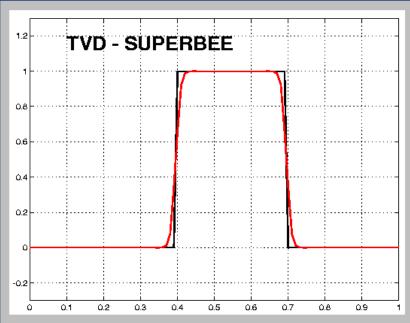




High Resolution Schemes

...Examples





High Resolution Schemes

Non-linear extension

For a non-linear conservation law the formulation of flux limiters is extended to allow both positive and negative wave speeds