Finite Difference Discretization of Elliptic Equations: FD Formulas and Multidimensional Problems

Lecture 4

Problem Definition

Given l+r+1 distinct points $(x_{-l},x_{-l+1},\ldots,x_0,\ldots,x_r)$, find the weights δ_j^m such that

$$\left.rac{d^m v}{dx^m}
ight|_{x=x_0}pprox \sum_{j=-l}^r \delta_j^m v_j$$

is of optimal order of accuracy.

N1

Two approaches:

- Lagrange interpolation
- Undetermined coefficients

Lagrange interpolation

Lagrange polynomials

$$L_j(x) = rac{(x-x_{-l})\cdots(x-x_{j-1})(x-x_{j+1})\cdots(x-x_r)}{(x_j-x_{-l})\cdots(x_j-x_{j-1})(x_j-x_{j+1})\cdots(x_j-x_r)}$$

Lagrange interpolant

$$\hat{v}(x) = \sum_{j=-l}^r L_j(x) v_j$$

Lagrange interpolation

Approximate

$$\left.rac{d^m v}{dx^m}
ight|_{x=x_0}pprox \left.rac{d^m \widehat{v}}{dx^m}
ight|_{x=x_0}=\sum_{j=-l}^r \left.rac{d^m L_j}{dx^m}
ight|_{x=x_0}v_j$$

Therefore,

$$\left. \delta_j^m = rac{d^m L_j}{dx^m}
ight|_{x=x_0}$$
 .

Lagrange interpolation

Example...

Set
$$l = r = 1$$
, (x_{j-1}, x_j, x_{j+1})

Second order Lagrange interpolant

$$\hat{v}(x) = rac{(x-x_j)(x-x_{j+1})}{(x_{j-1}-x_j)(x_{j-1}-x_{j+1})} \, v_{j-1} \, + \, rac{(x-x_{j-1})(x-x_{j+1})}{(x_j-x_{j-1})(x_j-x_{j+1})} \, v_j \, + \,$$

$$rac{(x-x_{j-1})(x-x_{j})}{(x_{j+1}-x_{j-1})(x_{j+1}-x_{j})}\,v_{j+1}$$

Lagrange interpolation

...Example...

Assuming a uniform grid

m = 1 (First derivative)

Lagrange interpolation

...Example

$$m = 2$$
 (Second derivative)

$$\delta_{j-1}^2$$
 δ_j^2 δ_{j+1}^2

$$\frac{1}{\Delta x^2}$$
 $-\frac{2}{\Delta x^2}$ $\frac{1}{\Delta x^2}$ Centered

N2

Undetermined coefficients

Finite Difference Formulas

Start from

$$\left.rac{d^m v}{dx^m}
ight|_{x=x_i}pprox \sum_{j=-l}^r \delta_j^m v_j \;.$$

Insert Taylor expansions for v_j about $x = x_i$

$$v_j = v_0 + v_0'(x_j - x_i) + rac{1}{2}v_0''(x_j - x_i)^2 + \ldots,$$

determine coefficients δ_j^m to maximize accuracy.

Undetermined coefficients

Example...

$$m=2, l=r=1, i=0,$$
 (uniform spacing Δx)

$$egin{aligned} v_0'' &= \delta_{-1}^2 (v_0 - \Delta x v_0' + rac{\Delta x^2}{2} v_0'' - rac{\Delta x^3}{6} v_0''' + rac{\Delta x^4}{24} v_0^{(4)} + \ldots) \ &+ \delta_0^2 \quad v_0 \ &+ \delta_1^2 (v_0 + \Delta x v_0' + rac{\Delta x^2}{2} v_0'' + rac{\Delta x^3}{6} v_0''' + rac{\Delta x^4}{24} v_0^{(4)} + \ldots) \end{aligned}$$

Undetermined coefficients

...Example

Equating coefficients of $v_0^{(k)}$

$$k=0 \Rightarrow \delta_{-1}^2+\delta_0^2+\delta_1^2=0$$

$$k=1 \; \Rightarrow \; \Delta x (\delta_1^2 - \delta_{-1}^2) = 0$$

$$k=2 \; \Rightarrow \; rac{\Delta x^2}{2}(\delta_1^2+\delta_{-1}^2)=1$$

Solve,

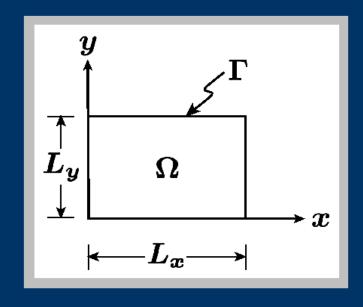
$$\delta_{-1}^2 = rac{1}{\Delta x^2}, \quad \delta_0^2 = -rac{2}{\Delta x^2}, \quad \delta_1^2 = rac{1}{\Delta x^2}$$

N3 N4

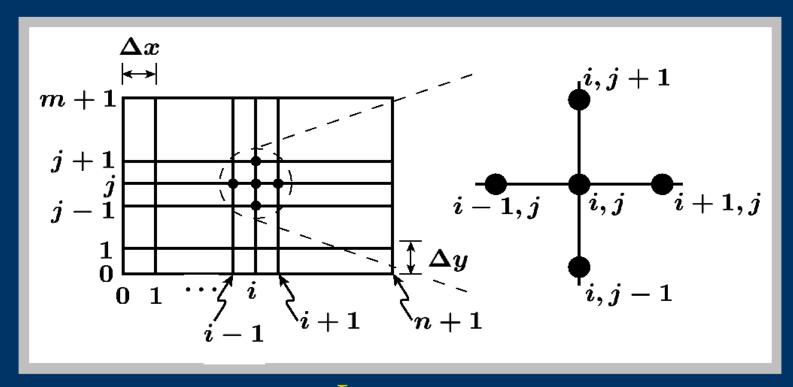
Definition

$$-
abla^2 u(x,y) = f(x,y)$$
 in Ω $u=0$ on Γ

$$abla^{2}\equivrac{oldsymbol{\partial}^{2}}{oldsymbol{\partial}oldsymbol{x}^{2}}+rac{oldsymbol{\partial}^{2}}{oldsymbol{\partial}oldsymbol{y}^{2}}, \qquad f\in\mathcal{C}^{0}$$



Discretization



$$\Delta x = rac{L_x}{n+1}$$
, $\Delta y = rac{L_y}{m+1}$, $x_i = i\Delta x$, $y_j = j\Delta y$

Approximation

For example ...

$$\left. rac{\partial^2 v}{\partial x^2}
ight|_{i,j} pprox rac{v_{i+1,j} - 2v_{i,j} + v_{i-1,j}}{\Delta x^2}$$

$$\left. rac{\partial^2 v}{\partial y^2}
ight|_{i,j} pprox rac{v_{i,j+1} - 2v_{i,j} + v_{i,j-1}}{\Delta y^2}$$

for Δx , Δy small

Equations

$$-u_{xx}-u_{yy}=f$$
 suggests ...

$$-rac{\hat{m{u}}_{i+1,j} - m{2}\hat{m{u}}_{i,j} + \hat{m{u}}_{i-1,j}}{\Delta x^2} - rac{\hat{m{u}}_{i,j+1} - m{2}\hat{m{u}}_{i,j} + \hat{m{u}}_{i,j-1}}{\Delta y^2} = \hat{m{f}}_{i,j}$$

$$egin{aligned} \hat{u}_{0,j} &= \hat{u}_{n,j} = 0 & 1 \leq j \leq m \ \hat{u}_{i,0} &= \hat{u}_{i,m} = 0 & 1 \leq i \leq n \end{aligned}$$

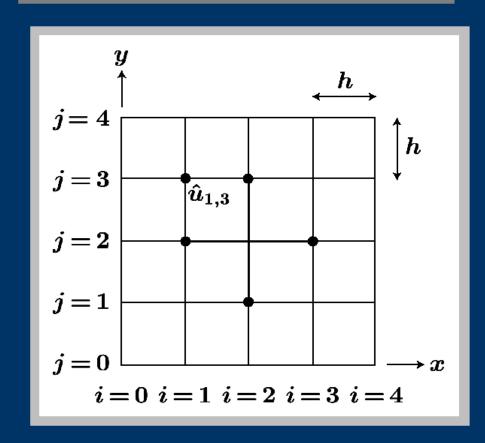
$$\Rightarrow \quad \left| A \hat{oldsymbol{u}} = \hat{oldsymbol{f}}
ight|$$

Equations

Example...

$$n=m=3$$

$$\Delta x = \Delta y = h$$



Equations

...Example

Equations

Numbering

$$egin{aligned} \hat{oldsymbol{u}}_{11} \ \hat{oldsymbol{u}}_{n1} \ \hat{oldsymbol{u}} = egin{pmatrix} \hat{oldsymbol{u}}_{11} \ \hat{oldsymbol{v}}_{n1} \ \hat{oldsymbol{f}} \ \hat{oldsymbol{f}}_{n1} \ \hat{oldsymbol{f}} \ \hat{oldsymbol{f}}_{n1} \ \hat{oldsymbol{f}} \ \hat{oldsymbol{f}}_{n1} \ \hat{oldsymbol{f}} \ \hat{oldsymbol{f}}_{nm} \end{pmatrix} \end{aligned}$$

(i,j) becomes component $\overline{(jm+i)}$

Equations

Block Matrix...

$$A = egin{pmatrix} A_x + 2I_y & -I_y & 0 & \cdots & 0 \ -I_y & A_x + 2I_y & -I_y & \cdots & dots \ 0 & \cdots & \cdots & dots & 0 \ dots & \cdots & -I_y & A_x + 2I_y & -I_y \ 0 & \cdots & 0 & -I_y & A_x + 2I_y \end{pmatrix}$$

Block $(m \times m)$ tridiagonal matrix

$$A_x, I_y$$
: $(n imes n)$, A : $(nm imes nm)$

Equations

...Block Matrix

Block Definitions

$$A_x = rac{1}{\Delta x^2} egin{pmatrix} 2 & -1 & 0 & \cdots & 0 \ -1 & 2 & -1 & \cdots & dots \ 0 & \cdots & \cdots & dots & 0 \ dots & \cdots & -1 & 2 & -1 \ 0 & \cdots & 0 & -1 & 2 \end{pmatrix}, \;\; I_y = rac{1}{\Delta y^2} egin{pmatrix} 1 & 0 & 0 & \cdots & 0 \ 0 & 1 & 0 & \cdots & dots \ 0 & \cdots & \cdots & dots & 0 \ dots & \cdots & 0 & 1 & 0 \ 0 & \cdots & 0 & 0 & 1 \end{pmatrix}$$

A has a banded structure

Bandwidth : 2n + 1

Equations

SPD Property

$$\underline{v}^T A \underline{v} = \sum_{i=1}^{n+1} \sum_{j=1}^{m+1} [rac{1}{\Delta x^2} (v_{ij} - v_{i-1,j})^2 + rac{1}{\Delta y^2} (v_{ij} - v_{i,j-1})^2]$$

Hence $v^T A v \ge 0$, for any $v \ne 0$ (A is SPD)

$$A\hat{\underline{u}}=\hat{f}:\hat{\underline{u}}$$
 exists and is unique

Error Analysis

Truncation Error

$$egin{aligned} & -rac{u(x_{i+1},y_j)-2u(x_i,y_j)+u(x_{i-1},y_j)}{\Delta x^2} \ & -rac{u(x_i,y_{j+1})-2u(x_i,y_j)+u(x_i,y_{j-1})}{\Delta y^2} = f(x_i,y_j) \ & -rac{\Delta x^2}{12}rac{\partial^4 u}{\partial x^4}(x_i+ heta_i^x\Delta x,y_j)-rac{\Delta y^2}{12}rac{\partial^4 u}{\partial y^4}(x_i,y_j+ heta_j^y\Delta y)}{ au_{i,j}} \end{aligned}$$

For
$$u \in \mathcal{C}^4$$

$$ig| au_{i,j} \sim \mathcal{O}(\Delta x^2, \Delta y^2)ig|$$

for all i, j

Error Analysis

 $\|\cdot\|_{\infty}$ Stability

It can be shown that

$$\|oldsymbol{A}^{-1}\|_{\infty} \leq rac{1}{8}$$

Ingredients:

- Positivity of the coefficients of A⁻¹
- Bound on the maximum row sum

Error Analysis

∥ · **∥**_∞ Convergence

Error equation
$$A\underline{e} = \underline{\tau} \Rightarrow |\underline{e} = A^{-1}\underline{\tau}|$$

$$egin{aligned} \|\underline{e}\|_{\infty} &= \|A^{-1}\underline{ au}\|_{\infty} \leq \|A^{-1}\|_{\infty} \ \| au\|_{\infty} \leq rac{1}{8} \| au\|_{\infty} \end{aligned} \ &\leq rac{1}{96} (\Delta x^2 \max_{(x,y) \in \Omega} |u_x^{(4)}| + \Delta y^2 \max_{(x,y) \in \Omega} |u_y^{(4)}|) \end{aligned}$$

$$\textbf{If} \;\; \boldsymbol{u} \in \mathcal{C}^4 \quad ||\underline{\boldsymbol{e}}||_{\infty} \sim \mathcal{O}(\boldsymbol{\Delta x^2}, \boldsymbol{\Delta y^2})$$

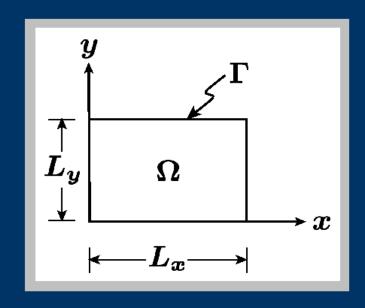
Statement

$$-
abla^2 oldsymbol{u} = oldsymbol{\lambda} oldsymbol{u} \quad ext{in} \quad oldsymbol{\Omega} \ oldsymbol{u} = oldsymbol{0} \quad ext{on} \quad oldsymbol{\Gamma}$$

Assume (for simplicity)

$$L_x = L_y = 1$$

Solutions $(u(x,y), \lambda)$



Exact Solution

Eigenvalues

$$u^{k,l}(x,y) = \sin(k\pi x)\sin(l\pi y)$$

$$-
abla^2 u^{k,l} = (k^2 \pi^2 + l^2 \pi^2) \ u^{k,l}$$

Eigenvectors

$$\lambda^{k,l}=k^2\pi^2+l^2\pi^2, \qquad k,l=1,\ldots$$

Discrete Problem

Eigenvectors

$$oxed{A \hat{oldsymbol{u}} = \hat{oldsymbol{\lambda}} \hat{oldsymbol{u}}} \;\; \Rightarrow \;\; (oldsymbol{u}^{k,l},\, \hat{oldsymbol{\lambda}}^{k,l})$$

$$egin{aligned} u_{i,j}^{k,l} &= \sin(k\pi x_i) \; \sin(l\pi y_j) \ &= \sin(k\pi i\Delta x) \; \sin(l\pi j\Delta y) \ &= \sin(rac{k\pi i}{n+1}) \; \sin(rac{l\pi j}{m+1}) \ &k,i=1,\ldots,n \quad l,j=1,\ldots,m \end{aligned}$$

Discrete Problem

Eigenvalues

$$\hat{oldsymbol{\lambda}}^{k,l} = rac{2}{\Delta x}\{1-\cos(k\pi\Delta x)\} + rac{2}{\Delta y}\{1-\cos(l\pi\Delta y)\}$$

Low Modes

$$oldsymbol{\Delta x}, oldsymbol{\Delta y}
ightarrow oldsymbol{0} \ (oldsymbol{k}, oldsymbol{l} \ ext{fixed})$$

$$egin{aligned} \hat{\lambda}^{k,l} &= k^2\pi^2 + l^2\pi^2 \ &+ \mathcal{O}(\Delta x^2, \Delta y^2) \end{aligned}$$

High Modes

$$kpprox n,\, lpprox m$$

$$\hat{\lambda}^{k,l} = 4(n+1)^2 + 4(m+1)^2$$

as
$$\Delta x, \Delta y
ightarrow 0$$

Condition Number of A

$$\kappa_A
ightarrow rac{4n^2+4m^2}{2\pi^2}$$
 as $\Delta x, \Delta y
ightarrow 0$

If $m{m} pprox m{n}$

$$\kappa_A
ightarrow rac{4n^2}{\pi^2}$$

grows (in ¹R²) as number of grid points.

(better than in 1D, relatively speaking !!)

Link to $-\nabla^2 u = f$

∥·∥ Error Estimate

Error equation
$$A \underline{e} = \underline{ au} \; \Rightarrow \overline{\; \underline{e} = A^{-1} \underline{ au} \;}$$

Error equation
$$\underline{A}\underline{e} = \underline{\tau} \Rightarrow \underline{\underline{e}} = \underline{A}^{-1}\underline{\tau}$$

$$||\underline{e}||_2 = ||A^{-1}\underline{\tau}||_2 \le ||A^{-1}||_2 \, ||\tau||_2 \le \frac{1}{\hat{\lambda}^{1,1}} ||\tau||_2$$

$$\|(\Delta x \Delta y)^{1/2}\|\underline{e}\|_2 \leq rac{1}{\hat{oldsymbol{\lambda}}^{1,1}} (\Delta x \Delta y)^{1/2}\|\underline{ au}\|_2$$

$$\Rightarrow \qquad ||\underline{e}|| \leq rac{1}{\hat{oldsymbol{\lambda}}^{1,1}}||\underline{ au}|| \sim \mathcal{O}(\Delta x^2, \Delta y^2)$$

Discrete Fourier Solution

Poisson Problem 2D

$$A ext{ is SPD} \Rightarrow A = Z\Lambda Z^T$$

- Λ diagonal matrix of eigenvalues $(nm \times nm)$
- Z is matrix of eigenvectors $(nm \times nm)$

$$egin{aligned} egin{aligned} egin{aligned} \hat{oldsymbol{u}}^{1,1} \; \hat{oldsymbol{u}}^{2,1} & \hat{oldsymbol{u}}^{n,m} \end{pmatrix} \ egin{aligned} egin{aligned} \hat{oldsymbol{u}}^{1,1} \; \hat{oldsymbol{u}}^{2,1} & & \hat{oldsymbol{u}}^{n,m} \end{pmatrix} \ & \downarrow & & \downarrow & & \downarrow \ & \downarrow & & \downarrow & & \downarrow \end{pmatrix} \end{aligned}$$

Poisson Problem 2D

Discrete Fourier Solution

$$m{Z}m{\Lambda}m{Z}^Tm{\hat{u}} = m{\hat{f}} \quad \Rightarrow \quad m{Z}^Tm{\hat{u}} = m{\Lambda}^{-1}m{Z}^Tm{\hat{f}} \quad m{\hat{u}} = m{Z}m{\Lambda}^{-1}m{Z}^Tm{\hat{f}}$$

ALGORITHM

1.
$$\underline{\hat{f}}^* = Z^T \underline{\hat{f}}$$
2. $\underline{\hat{u}}^* = \Lambda^{-1} \underline{\hat{f}}^*$
3. $\underline{\hat{u}} = Z \underline{\hat{u}}^*$

Still cost is $\mathcal{O}(n^4)$ $(n \approx m)$... BUT ...

Discrete Fourier Solution

Poisson Problem 2D

• Matrix multiplications can be reorganized (tensor product evaluation) N5 $\Rightarrow \mathcal{O}(n^3)$

• $\underline{\hat{f}}^* = Z^T \underline{\hat{f}}$ ($\underline{\hat{u}} = Z \underline{\hat{u}}^*$) is a (Inverse) Discrete Fourier Transform

Using FFT

$$\Rightarrow \mathcal{O}(n^2 \log n)$$

Poisson Problem 2D

Non-Rectangular Domains

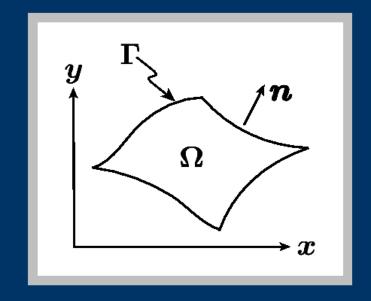
We are interested in solving

$$-
abla^2 u = f$$
 in Ω

$$u=g$$
 on Γ_D

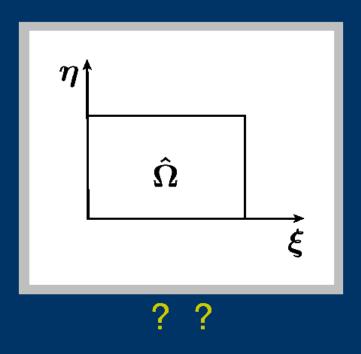
$$rac{\partial u}{\partial n} = h$$
 on $\Gamma_N = \Gamma ackslash \Gamma_D$

where f, g, and h are given.

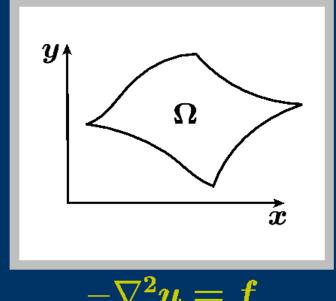


Poisson Problem 2D

Mapping



$$egin{array}{c} x = x(\xi,\eta) \ y = y(\xi,\eta) \ \longrightarrow \end{array}$$



$$-
abla^2 u = f$$

Can we determine an equivalent problem to be solved on Ω ?

Poisson Problem 2D

Transformed equations...

How do we evaluate terms ξ_x , η_x , ξ_y , and η_y ?

Poisson Problem 2D

...Transformed equations...

$$egin{aligned} oldsymbol{\xi} & = oldsymbol{\xi}(x,y) \ oldsymbol{\eta} & = oldsymbol{\eta}(x,y) \ oldsymbol{d}oldsymbol{\eta} & = egin{pmatrix} oldsymbol{\xi}_x & oldsymbol{\xi}_y \ oldsymbol{\eta}_x & oldsymbol{\eta}_y \end{pmatrix} egin{pmatrix} oldsymbol{d}x \ oldsymbol{d}y \end{pmatrix} \end{aligned}$$

$$egin{aligned} oldsymbol{\xi} & = oldsymbol{\xi}(x,y) & x = x(oldsymbol{\xi},\eta) \ \eta & = \eta(x,y) & y = y(oldsymbol{\xi},\eta) \ doldsymbol{\xi} & = egin{pmatrix} oldsymbol{\xi}_x & oldsymbol{\xi}_y \ \eta_x & \eta_y \end{pmatrix} egin{pmatrix} dx \ dy \end{pmatrix} & = egin{pmatrix} x_{oldsymbol{\xi}} & x_{\eta} \ y_{oldsymbol{\xi}} & y_{\eta} \end{pmatrix} egin{pmatrix} doldsymbol{\xi} \ d\eta \end{pmatrix} \end{aligned}$$

$$\phi = egin{pmatrix} oldsymbol{\xi}_x & oldsymbol{\xi}_y \ oldsymbol{\eta}_x & oldsymbol{\xi}_y \end{pmatrix} = egin{pmatrix} oldsymbol{x}_{\xi} & oldsymbol{x}_{\eta} \ oldsymbol{y}_{\xi} & oldsymbol{y}_{\eta} \end{pmatrix}^{-1} = rac{1}{J} egin{pmatrix} oldsymbol{y}_{\eta} & -oldsymbol{x}_{\eta} \ -oldsymbol{y}_{\xi} & oldsymbol{x}_{\xi} \end{pmatrix}^{-1}$$

$$oldsymbol{J} = x_{oldsymbol{\xi}} y_{oldsymbol{\eta}} - x_{oldsymbol{\eta}} y_{oldsymbol{\xi}}$$

Poisson Problem 2D

...Transformed equations...

$$egin{align} u_x &= rac{1}{J} \left(y_\eta u_\xi - y_\xi u_\eta
ight) \ u_y &= rac{1}{J} \left(-x_\eta u_\xi + x_\xi u_\eta
ight) \ \end{align}$$

and
$$u_{xx}=rac{\partial}{\partial x}\left(u_{x}
ight)=\left(\xi_{x}rac{\partial}{\partial \xi}+\eta_{x}rac{\partial}{\partial \eta}
ight)u_{x}\ =rac{1}{J}\left(y_{\eta}rac{\partial}{\partial \xi}-y_{\xi}rac{\partial}{\partial \eta}
ight)u_{x}\ =\ldots$$

$$u_{yy}=\dots$$

Poisson Problem 2D

...Transformed equations

Finally,
$$-(u_{xx} + u_{yy}) = f$$
, becomes

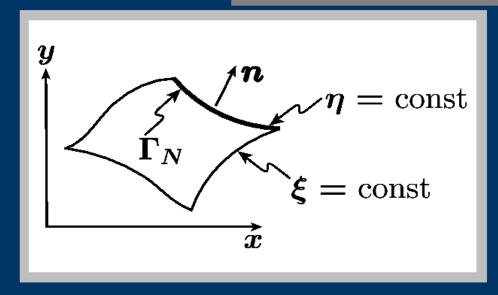
$$igg| rac{-1}{J^2} \left(a \ u_{\xi \xi} - 2b \ u_{\xi \eta} + c \ u_{\eta \eta} + d \ u_{\eta} + e \ u_{\xi}
ight) = f$$

a, b, c, d, and e depend on the mapping.

$$egin{aligned} a &= x_\eta^2 + y_\eta^2 & e &= rac{x_\eta eta - y_\eta lpha}{J} & lpha &= a x_{\xi \xi} - 2 b x_{\xi \eta} + c x_{\eta \eta} \ b &= x_\xi x_\eta + y_\xi y_\eta & d &= rac{y_\xi lpha - x_\xi eta}{J} & eta &= a y_{\xi \xi} - 2 b y_{\xi \eta} + c y_{\eta \eta} \ c &= x_\xi^2 + y_\xi^2 \end{aligned}$$

Poisson Problem 2D

Normal Derivatives...



$$m{n}=(m{n}^x,m{n}^y)$$
 is parallel to $ablam{\eta}$ (or $ablam{\xi}$); e.g., on Γ_N

$$m{n} = rac{1}{\sqrt{\eta_x^2 + \eta_y^2}} \left(\eta_x, \eta_y
ight) = rac{1}{\sqrt{x_{m{\xi}}^2 + y_{m{\xi}}^2}} \left(-y_{m{\xi}}, x_{m{\xi}}
ight)$$

Poisson Problem 2D

Normal Derivatives...

Thus,

$$egin{align} rac{\partial u}{\partial n} &= u_x n^x + u_y n^y \ &= rac{1}{J} \left[\left(y_\eta n^x - x_\eta n^y
ight) u_\xi
ight. \ &+ \left(- y_\xi n^x + x_\xi n^5 y
ight) u_\eta
ight] \end{aligned}$$

with
$$(n^x,n^y)=rac{1}{\sqrt{x_{\xi}^2+y_{\xi}^2}}\,(-y_{\xi},x_{\xi}).$$