Li Dongda

Gender: Male

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Education

School of Automation and Information Engineering

Xi'an University of Technology

09/2011-06/2015

B.S., major in <u>Automation</u> Advisor: <u>Yingming YI</u>

Specialized courses included automatic control theory, signal and system analysis, motion control technology, computer control technology, sensor technology, C++ language, embedded system, circuit theory, etc.

Research Experience

Research Assistant 03/2019-Present

Cyberspace Institute of Advanced Technology

Guangzhou University Supervisors: Zhaoquan Gu

Research Area: Reinforcement learning, Neural Combinatorial Optimization, Meta-learning

Research Assistant 10/2018-01/2019

Shenzhen Institutes of Advanced Technology

Chinese Academy of Sciences Supervisors: Chengzhong Xu

Research Area: Reinforcement learning, Neural Combinatorial Optimization

Research Assistant 08/2016-05/2017

The Department of Compute Science

The University of HongKong

Supervisors: Francis C.M. Lau, Yuexuan Wang and Heming Cui

Research Area: Robotic Network, Wireless Sensor Network, Internet of Things

Research Assistant 07/2016-07/2017

Unmanned Aerial Vehicle Autonomous Control Institute

Beijing Institute of Technology

Supervisor: Defu Lin

Research Area: Unmanned Aerial Vehicle Control System, Navigation System, Data Fusion

Research Interests

Robotic Control and Navigation, Reinforcement learning

Publications

- ▶ Dongda Li, Zhaoquan Gu, Yuexuan Wang, Changwei Ren, Francis C.M. Lau, One model packs thousands of items with Recurrent Conditional Query Learning, Knowledge-Based Systems, 2021, 107683, ISSN 0950-7051,
- Zhaoquan Gu, Dongda Li, Nadra Guizani, Xiaojiang Du, Zhihong Tian. An Aerial Computing Assisted Architecture for Large-Scale Sensor Networks. IEEE Communications Magazine. In press.
- Tong Shen, Yuexuan Wang, Zhaoquan Gu, Dongda Li, Zhen Cao, Heming Cui, Francis C.M. Lau. Alano: An Efficient Neighbor Discovery Algorithm In An Energy-Restricted Large-Scale Network. IEEE International Conference on Mobile Ad-hoc and Sensor Systems. 2018
- Dongda Li, Yuexuan Wang, Zhaoquan Gu, Tong Shen, Tianhao Wei, Yongqin Fu, Heming Cui, Mingli Song, Francis C. M. Lau. Adler: A Resilient, High-Performance and Energy-Efficient UAV-Enabled Sensor System.http://www.cs.hku.hk/research/techreps/document/TR-2018-01.pdf. 2018-01

Professional Services

Guest reviewer, IEEE Journal on Selected Areas in Communications (JSAC); Guest reviewer, IEEE International Conference on Intelligent Robots and Systems (IROS);

Research Projects:

◆ Research on Collaborative Analysis and Autonomous Decision Technology for Intelligent Manufacturing Big Data. National Key R&D Program of China (No.2018YFB1004003).

05/2018-04/2021

◆ UAV-Enabled Sensor System
◆ MBZIRC-2017 International Robotic Competition (Champion)
◆ Autonomous takeoff and landing of the intelligent quadrotor(Thesis)
12/2014-06/2015

Professional skills

- ◆ Familiar with statistic learning theory and practice;
- Familiar with the principle of inertial navigation, integrated navigation algorithm and application;
- ◆ Familiar with Robot operating system(ROS) programming and application;
- ◆ Master the C / C + +/Python language, data structure, with good code preparation habits;
- Master the Linux system programming;
- ◆ Familiar with GIT and Academic Writing:

Language skills

Chinese: native language English: IELTS 7.0

Awards

Champion	Mohamed Bin Zayed International Robotics Challenge (MBZIRC) 2017.	03/2017
Grand Prize	The eighth Shaanxi province outstanding graduation design	06/2015
Second Prize Xi'an University of Technology, 2014 Emerson "CONSIDER IT SOLVED"		08/2014
First Prize The 21st session of the "Innovation Prix" science and technology competition		11/2012