

UNREAL ENGINE Exploring Al Depth Estimation

in Compositing

Al Depth Map

- 1. Generate depthmap from video using Google Colab
- 2. Depthn procedural garbage matte
- 3. Depthmap to generate Normal map for relighting in UE



1. Depthmap from Colab



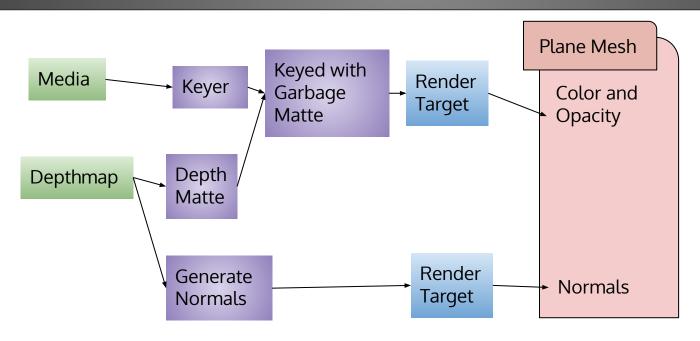
https://github.com/dpredie/Midasv2 1 small-TFLite-Inference

```
(Colab for video files!)

• Google Colaboratory notebook is now available. [July 2021] Open in Colab
```

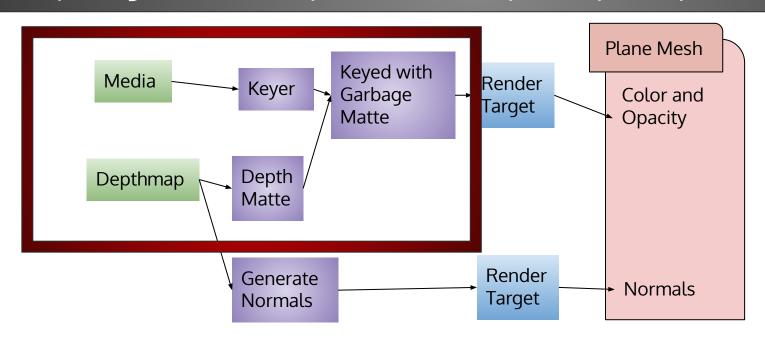
2 & 3. Compositing Overview





2. Procedural Garbage Matte

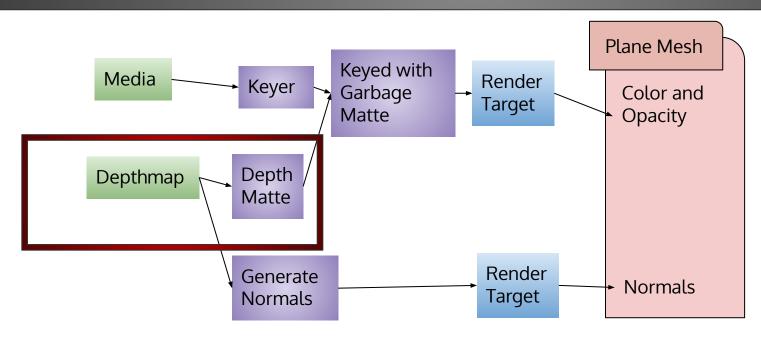




2. Procedural Garbage Matte



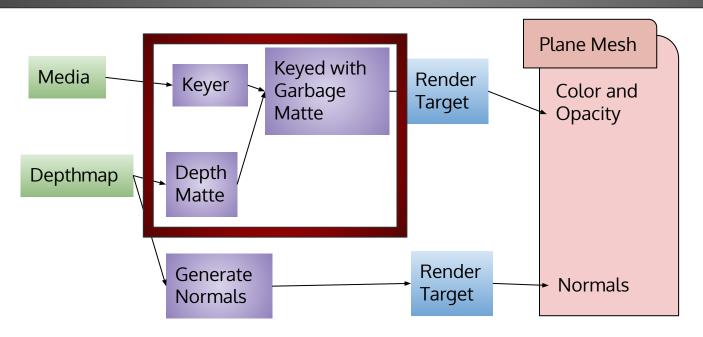
M_DepthMatting



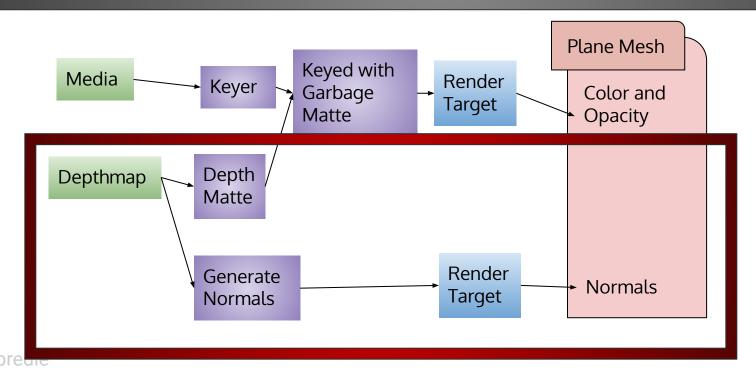
2. Procedural Garbage Matte



M_Passthrough, M_DepthMatteComp

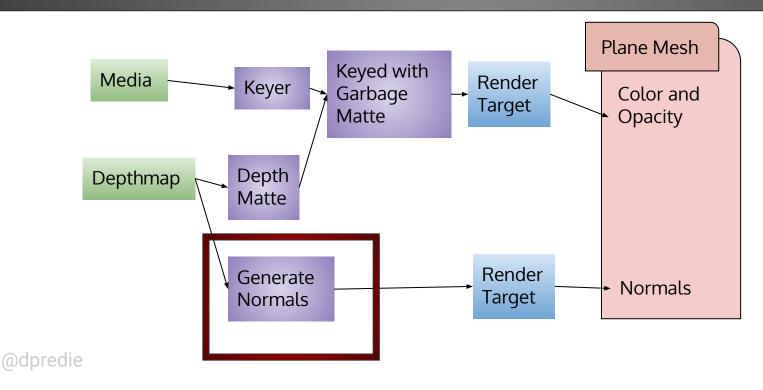






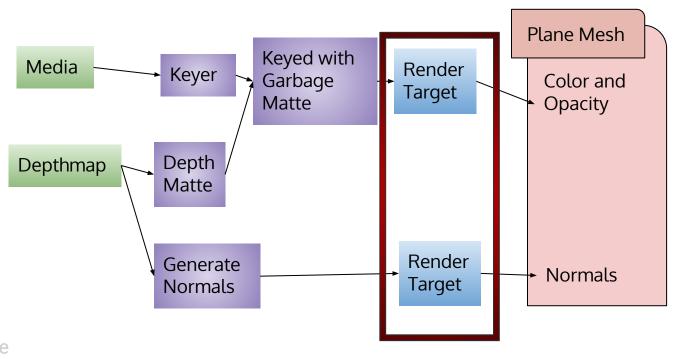


M_RescaleDepth, M_BlurDepth, M_NormalFromDepth



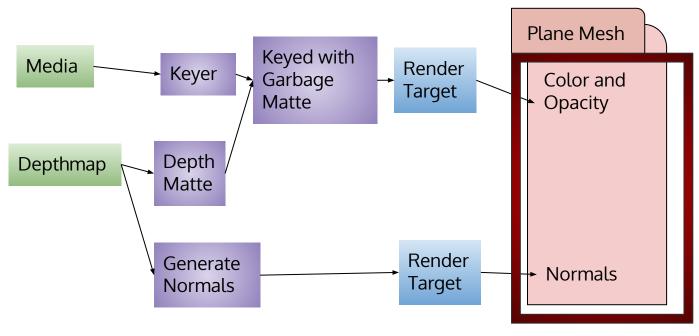


Output to RT_Keyed, RT_ReNormal



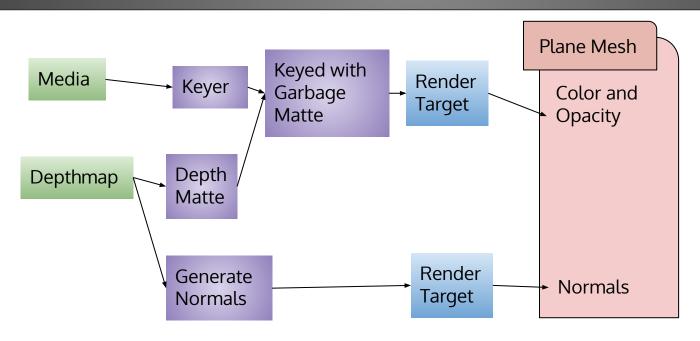


Plane Material: M_DepthMapPlane



2 & 3. Compositing Overview





Limitations

- Not Panacea (can't fix bad lighting)
- 2. Quality, Resolution, and Processing time of Depthmap relies on trained model & source video

Future Search

- 1. Realtime solution (balance between quality and FPS)
- 2. Absolute Distance to camera (meters) instead of relative values

Credits

- Ibai Gorodoro: forked Ibai's implementation of "Small Midas TFLite inference" to create the Colab notebook
 - https://www.youtube.com/watch?v=e161_IZps9c
- 3dsf for discussion on Midas & Depth networks
 - https://www.youtube.com/channel/UC1Sb4I_gCkSRE1JDMAmn2Wg
- Andy Blondin: how to sync different Media Texture using sequencer
 - https://www.youtube.com/channel/UCa1s9Zc1YxGUTIENQ0Nmyrg