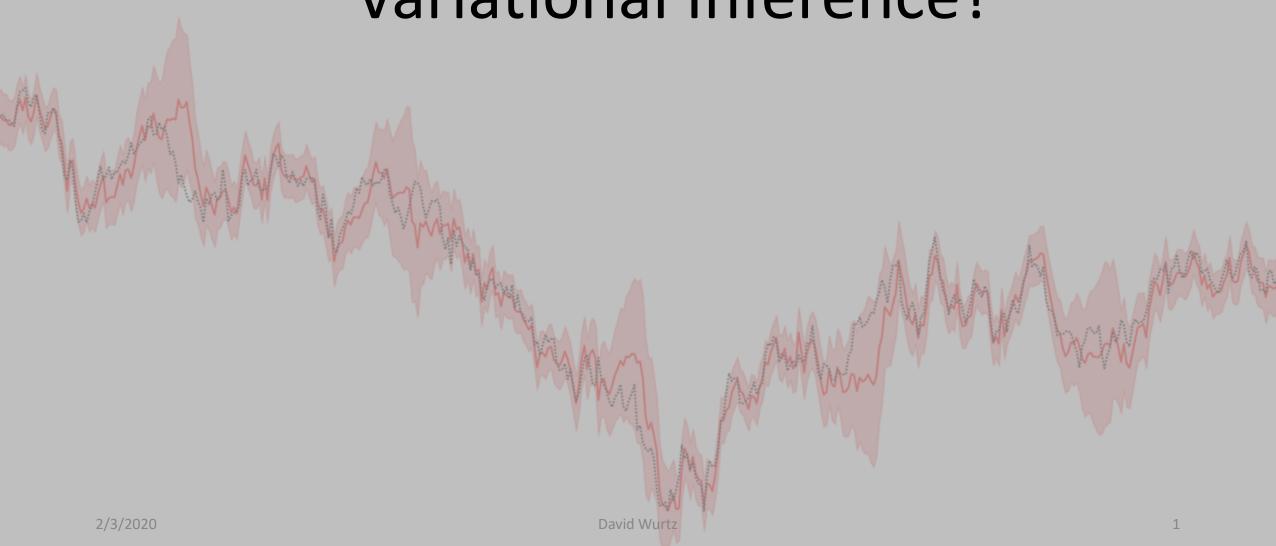
What's so cool about Variational Inference?



Outline

- Motivation
- Background
 - Filtering Posterior
 - Variational Inference
- The cool stuff
 - Variational Bayesian Filtering
 - Modern Variational Inference
- Open Questions
- Conclusion

Motivation

- Speech processing algorithms often have parameters that are "trained" or "tuned".
- Often there is no one tuning that works well for a population of users or scenarios.

Problem Examples

- Smart Mute: earbud bone-conduction is difficult
- Boom-mic beamforming: users move boom around
- Industrial Designers: change the acoustics
- Noise cancelling earbuds: very fit dependent

Solution

- Algorithms should be "data adaptive" or "self-calibrating"
- Get better as more data arrives

P(parameters[t]|data[1:t])

Limitations

- Kalman Filter
 - Both observation and transition densities must Linear and Gaussian
- Unscented Kalman Filter
 - Only gives first and second-order statistics of posterior
- Particle Filter
 - Require lots of particles (MIPS and memory)

Background: Filtering Posterior

- Filtering posterior and posterior inference in general is very expensive
- Only special cases are tractable
 - Kalman Filter

$$\mu_t, \Sigma_t \leftarrow f(\mu_{t-1}, \Sigma_{t-1}, x_t)$$

Approximate Filtering Posterior

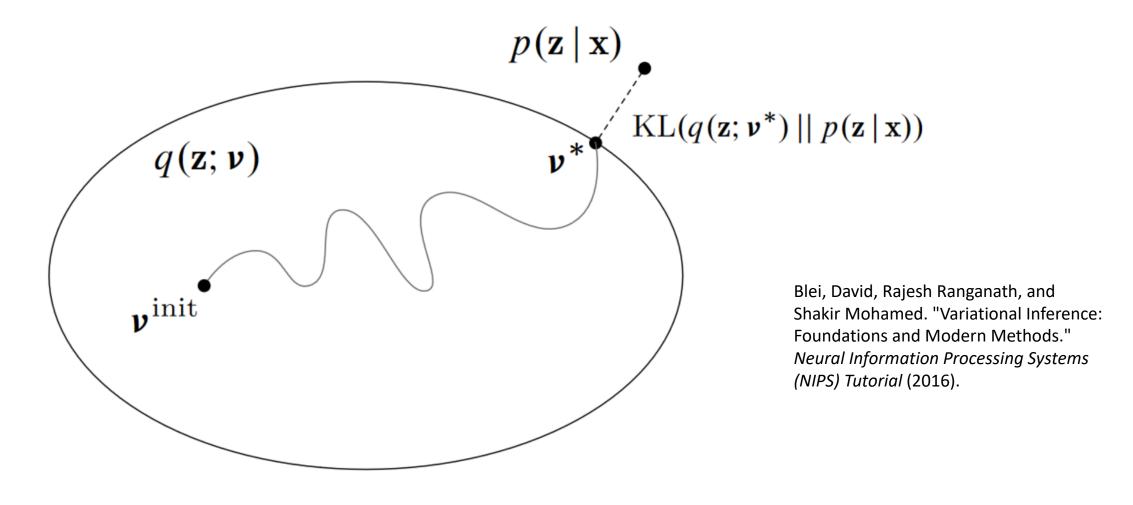
- Unscented Kalman Filter
- Particle Filter

Background: Variational Inference

What is "Variational"?

Formulate the thing you want as the solution to an optimization problem.

Variational Inference



Variational Objective

Definition of KL:

$$KL(q(z) \parallel p(z|x)) \coloneqq \mathbb{E}_{q(z)} \left[\log \frac{q(z)}{p(z|x)} \right]$$

Recall from Bayes' rule:

$$p(z|x) = \frac{p(z,x)}{p(x)}$$

Substituting into KL:

$$KL(q(z) \parallel p(z|x)) = \mathbb{E}_{q(z)}[\log q(z) - \log p(z,x) + \log p(x)]$$

• Simplifying:

$$KL\big(q(z) \parallel p(z|x)\big) = \mathbb{E}_{q(z)}[\log q(z) - \log p(z,x)] + \log p(x)$$

The ELBO

• Rearranging to have an expression for $\log p(x)$:

$$\log p(x) = \mathbb{E}_{q(z)}[\log p(z,x) - \log q(z)] + KL(q(z) \parallel p(z|x))$$

- Maximizing the <u>Evidence Lower BOund</u> necessarily minimizes the KL term. Why?
 - $\log p(x)$ is fixed
 - KL is non-negative

The Variational Family

- The way that q(z) factorizes is a design choice
- Simplest choice is the *Mean-Field Variational Family*

$$q(z) = \prod_{j=1}^{N} q_j(z_j)$$

Optimizing the ELBO

Solutions to the optimization have the following form:

$$q_j^{\star}(z_j) \propto \exp\left(\mathbb{E}_{q(z_{-j})}[\log p(z_j, z_{-j}, x)]\right)$$

- For derivations and examples:
 - Blei, David M., Alp Kucukelbir, and Jon D. McAuliffe. "Variational inference: A review for statisticians." *Journal of the American statistical Association* 112.518 (2017): 859-877.
 - Bishop, Christopher M. *Pattern recognition and machine learning*. springer, 2006.
 - Murphy, Kevin P. Machine learning: a probabilistic perspective. MIT press, 2012.

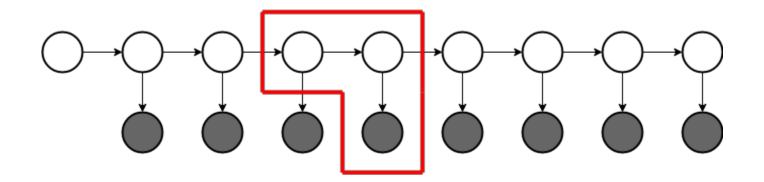
Limitations

- You must be able to write down the model: $p(z_j, z_{-j}, x)$
- The expectations $\mathbb{E}_{q(z_{-j})}[\log p(z_j,z_{-j},x)]$ must be analytically tractable
- Derivations are:
 - model-specific
 - fantastically tedious and error-prone (though the result is often elegant)

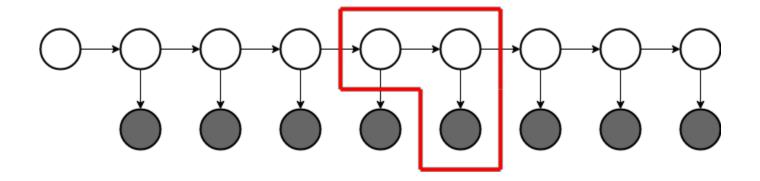
Recap

- Motivation
- Background
 - Filtering Posterior
 - Variational Inference
- The cool stuff
 - Variational Bayesian Filtering
 - Modern Variational Inference
- Open Questions
- Conclusion

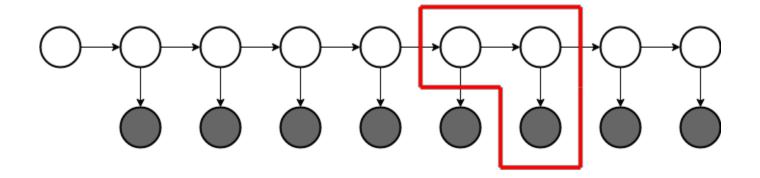
The cool stuff: Variational Bayesian Filtering



The cool stuff: Variational Bayesian Filtering



The cool stuff: Variational Bayesian Filtering



• The "local" joint:

$$p(z_t, z_{t-1}, x_t | x_{1:t-1}) = p(x_t | z_t) p(z_t | z_{t-1}) p(z_{t-1} | x_{1:t-1})$$

(chain rule)

• The "local" joint:

$$p(z_t, z_{t-1}, x_t | x_{1:t-1}) = p(z_t, z_{t-1} | x_{1:t}) p(x_t | x_{1:t-1})$$

(also chain rule)

Using Bayes' rule:

$$p(z_t, z_{t-1}|x_{1:t}) = \frac{p(x_t|z_t)p(z_t|z_{t-1})p(z_{t-1}|x_{1:t-1})}{p(x_t|x_{1:t-1})}$$

• The Filtering Posterior:

$$p(z_t|x_{1:t}) = \int p(z_t, z_{t-1}|x_{1:t}) dz_{t-1}$$

(marginalizing out z_{t-1})

Variational Bayesian Filtering

- The setup needs 2 things...
 - The joint:

$$p(z_t, z_{t-1}, x_t | x_{1:t-1}) = p(x_t | z_t) p(z_t | z_{t-1}) q(z_{t-1} | x_{1:t-1})$$

Choice of variational family:

$$q(z_t, z_{t-1}|x_{1:t}) = \prod_{j=1}^{N} q_j(z_{j,t}, z_{j,t-1}|x_{1:t})$$

For example if $z = {\mu, \Sigma}$, then $q(z_t, z_{t-1} | x_{1:t})$ could factor this way:

$$q(\mu_t, \Sigma_t, \mu_{t-1}, \Sigma_{t-1} | x_{1:t}) = q(\mu_t, \mu_{t-1} | x_{1:t}) \ q(\Sigma_t, \Sigma_{t-1} | x_{1:t})$$

The ELBO

• Same objective as before:

$$\mathbb{E}_{q(Z_t, Z_{t-1}|X_{1:t})}[\log p(z_t, z_{t-1}, x_t|X_{1:t-1}) - \log q(z_t, z_{t-1}|X_{1:t})]$$

Optimizing the ELBO

Same form of solution as before:

$$q_{j}^{\star}(z_{j,t},z_{j,t-1}|x_{1:t}) \propto \exp\left(\mathbb{E}_{q(z_{-j,t},z_{-j,t-1}|x_{1:t})}[\log p(z_{t},z_{t-1},x_{t}|x_{1:t-1})]\right)$$

• End up with a recurrent expression for the shaping parameters, v_t , of the variational filtering posterior:

$$v_t \leftarrow g(v_{t-1}, x_t)$$

• These look like Kalman Filters:

$$\mu_t, \Sigma_t \leftarrow f(\mu_{t-1}, \Sigma_{t-1}, x_t)$$

Examples

- A range of easy to complex examples:
 - Šmídl, Václav, and Anthony Quinn. *The variational Bayes method in signal processing*. Springer Science & Business Media, 2006.
- A frequency-domain audio processing example:
 - S. Malik, J. Benesty, and J. Chen, "A Bayesian framework for blind adaptive beamforming," *IEEE Tran. on Signal Processing*, vol. 62, no. 9, pp. 2370–2384, 2014.

Limitations

- Not a lot of tractable variational families for $q(z_t, z_{t-1} | x_{1:t})$
- You must be able to write down $p(z_t, z_{t-1}, x_t | x_{1:t-1})$
- Expectations must be analytically tractable
 - Problem example:

$$\mathbb{E}_{q(\Sigma_1)}[\log \det(\Sigma_1 + \Sigma_2)]$$

The Cool Stuff: Modern Variational Inference

- Helps address limitations of (Classical) Variational Inference
 - Variational posterior can be learned
 - The model can be learned
 - Variational family can be learned

Blei, David, Rajesh Ranganath, and Shakir Mohamed. "Variational Inference: Foundations and Modern Methods." *Neural Information Processing Systems* (NIPS) Tutorial (2016).

The Main Ideas

- Intractable expectations are approximated with Monte Carlo
- Unknown parameters are learned
- Unknown functions are approximated (e.g. with a DNN)

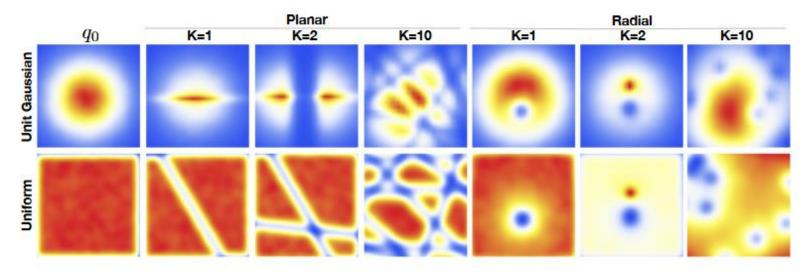
$$\mathbb{E}_{z \sim q(z|x)} \left[\log p_{\phi}(z, x) - \log q_{\theta}(z|x) \right]$$

For example

$$p_{\phi}(x|z) = Normal\left(\mu_{\phi}(z), \Sigma_{\phi}(z)\right)$$
$$q_{\theta}(z|x) = Normal\left(\mu_{\phi}(x), \Sigma_{\phi}(x)\right)$$

The Main Ideas

 You can learn a complex probability distribution by transforming known simple distribution with a composition of learned invertible functions



Rezende, Danilo Jimenez, and Shakir Mohamed. "Variational inference with normalizing flows." arXiv preprint arXiv:1505.05770 (2015).

Open Questions

- The ideas from Modern Variational Inference look like they could be applied to the filtering posterior problem.
 - Given some observations that were generated from known linear gaussian model, how well can you learn a Kalman Filter?
 - How well can Variational Bayes Filters be learned instead of hand-derived?

Conclusion

- Variational Inference gives us a way derive novel filters for many problems.
 - However, we often need to make compromises in our modeling decisions so that derivations are tractable.

- Modern Variational Inference suggests that these filters can be learned, rather than derived.
 - Allowing us to explore models that otherwise wouldn't be considered.