

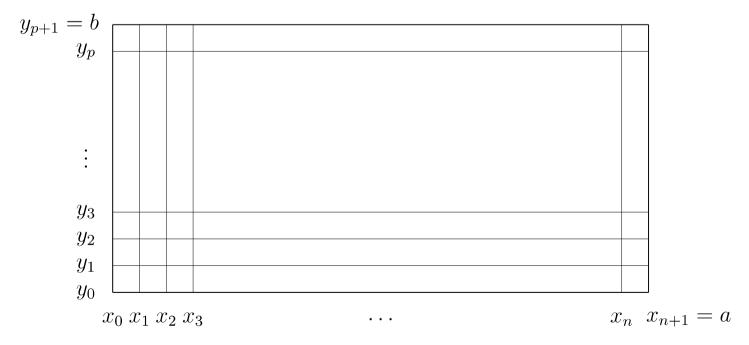
Figure 8.3: Initial conditions in (a) and matlab solution using explicit central difference method for 1D wave equation with friction in (b)

## 8.2 2-D Wave Equation

$$U_{tt} = \beta(U_{xx} + U_{yy}), \quad 0 \le x \le a, \ 0 \le y \le b, \ 0 \le t \le T$$

# 8.2.1 Example: vibrations of a thin elastic membrane fixed at its walls

We discretise in x and y-directions:



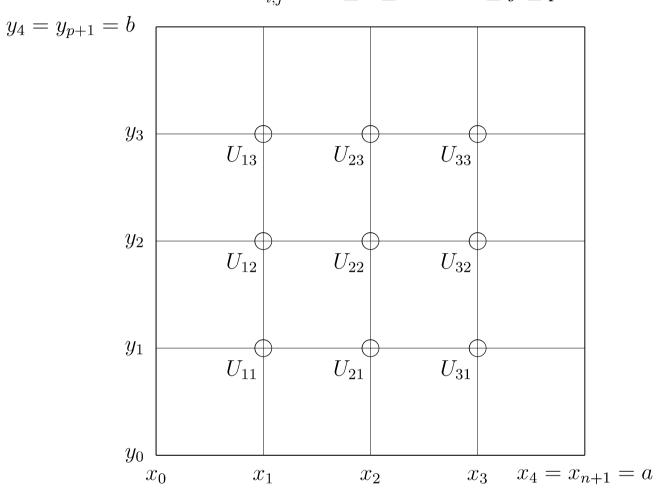
We discretise: 
$$\Delta t = \frac{T}{m}$$
,  $\Delta x = \frac{a}{n+1}$ ,  $\Delta y = \frac{b}{p+1}$ ,  $t_k = k\Delta t$ ,  $x_i = i\Delta x$ ,  $y_j = j\Delta y \leq k \leq m$ ,  $0 \leq i \leq n+1$ ,  $0 \leq j \leq p+1$ , and let  $U_{ij}^k = U(t_k, x_i, y_j)$ 

Suppose we solve for n=3 and p=3 and have Dirichlet boundary conditions:

$$U(0,y,t)=0=U_{oj}^k,\ U(a,y,t)=0=U_{n+1,j}^k=U_{4j}^k,\ U(x,0,t)=0=U_{i0}^k,\ U(x,b,t)=0=U_{i,p+1}^k=U_{i4}^k$$
 and initial conditions:

$$U(x, y, 0) = f(x, y) = f_{ij}$$
  $U_t(x, y, 0) = g(x, y) = g_{ij}$ .

Since we have Dirichlet boundary conditions: the outer boundaries of the region we are solving for are known:  $U_{0,j}^k, U_{n+1,j}^k, U_{i,0}^k, U_{i,p+1}^k$ , and we need to find the interior values:  $U_{i,j}^k$  for  $1 \le i \le n$  and  $1 \le j \le p$ .



We will use the 2-D Central Difference Method

$$U_{tt} = \frac{U_{ij}^{k+1} - 2U_{ij}^{k} + U_{ij}^{k-1}}{\Delta t^{2}},$$

$$U_{xx} = \frac{U_{i+1,j}^{k} - 2U_{ij}^{k} + U_{i-1,j}^{k}}{\Delta x^{2}},$$

$$U_{yy} = \frac{U_{i,j+1}^{k} - 2U_{ij}^{k} + U_{i,j+1}^{k}}{\Delta y^{2}}$$

We let  $s_x = \frac{\beta \Delta t^2}{\Delta x^2}$ ,  $s_y = \frac{\beta \Delta t^2}{\Delta y^2}$  and substitute the central difference approx-

imations into our PDE,  $U_{tt} = \beta(U_{xx} + U_{yy})$  we solve for  $U_{ij}^{k+1}$ :

$$U_{ij}^{k+1} = 2U_{ij}^{k}(1 - s_x - s_y) - U_{ij}^{k-1} + s_x(U_{i+1,j}^k + U_{i-1,j}^k) + s_y(U_{i,j+1}^k + U_{i,j-1}^k)$$

computing  $\vec{U}^{k+1}$  uses the solution at  $\vec{U}^k$  and  $\vec{U}^{k-1}$ .

For first time step  $U_{ij}^1$  needs  $U_{ij}^0$  and  $U_{ij}^{-1}$ . Again we need to use the initial conditions to find the ghost point,  $U_{ij}^{-1}$ :

$$\frac{\partial U_{ij}^0}{\partial t} = U_t(x, y, 0) = \frac{U_{ij}^1 - U_{ij}^{-1}}{2\Delta t} = g(x_i, y_j) = g_{ij} \Rightarrow U_{ij}^{-1} = U_{ij}^1 - 2\Delta t g_{ij}$$

Solution at first time step k = 1:

$$U_{ij}^{1} = U_{ij}^{0}(1 - s_{x} - s_{y}) + \Delta t g_{ij} + \frac{s_{x}}{2}(U_{i+1,j}^{0} + U_{i-1,j}^{0}) + \frac{s_{y}}{2}(U_{i,j+1}^{0} + U_{i,j-1}^{0})$$

If we let 
$$\vec{U}^k = \begin{pmatrix} U_{11}^k \\ U_{12}^k \\ U_{13}^k \\ U_{21}^k \\ U_{22}^k \\ U_{23}^k \\ U_{31}^k \\ U_{32}^k \\ U_{33}^k \end{pmatrix}$$

then for time steps, k > 1, the solution is:

$$U_{ij}^{k+1} = 2U_{ij}^{k}(1 - s_x - s_y) - U_{ij}^{k-1} + s_x(U_{i+1,j}^k + U_{i-1,j}^k) + s_y(U_{i,j+1}^k + U_{i,j-1}^k)$$

and we can write this in vector form:

$$\vec{U}^{k+1} = A\vec{U}^k + \vec{b} - \vec{U}^{k-1}$$

where:

$$A = \begin{pmatrix} \lambda & s_y & 0 & s_x & 0 & 0 & 0 & 0 & 0 \\ s_y & \lambda & s_y & 0 & s_x & 0 & 0 & 0 & 0 \\ 0 & s_y & \lambda & 0 & 0 & s_x & 0 & 0 & 0 \\ s_x & 0 & 0 & \lambda & s_y & 0 & s_x & 0 & 0 \\ 0 & s_x & 0 & s_y & \lambda & s_y & 0 & s_x & 0 \\ 0 & 0 & s_x & 0 & s_y & \lambda & 0 & 0 & s_x \\ 0 & 0 & 0 & s_x & 0 & 0 & \lambda & s_y & 0 \\ 0 & 0 & 0 & 0 & s_x & 0 & s_y & \lambda & s_y \\ 0 & 0 & 0 & 0 & 0 & s_x & 0 & s_y & \lambda & s_y \end{pmatrix}$$

and 
$$\lambda = 2(1 - s_x - s_y)$$

$$b = \begin{pmatrix} s_x U_{01}^k + s_y U_{10}^k \\ s_x U_{02}^k \\ s_x U_{03}^k + s_y U_{14}^k \\ s_y U_{20}^k \\ 0 \\ s_y U_{24}^k \\ s_x U_{41}^k + s_y U_{30}^k \\ s_x U_{42}^k \\ s_x U_{43}^k + s_y s_{34}^k \end{pmatrix}$$

## 8.2.2 Examples of wave equation

#### 1. Elastic wave propagation through rocks in 1-D

$$\sigma_{xx,x} = \rho U_{tt} \tag{8.1}$$

where

$$\sigma_{xx} = E\varepsilon_{xx}, \ \sigma_{xx} = \text{stress}, \ \varepsilon_{xx} = \text{strain}$$

$$= E\frac{\partial U}{\partial x}$$

$$8.1 \Rightarrow EU_{xx} = \rho U_{tt}$$
 or  $U_{tt} = \frac{E}{\rho} U_{xx}$ 

elastic waves propagate with speed  $\sqrt{\frac{E}{\rho}}$ 

### 2. Electromagnetic Wave Equation

$$c^2 \nabla^2 E = \ddot{E} \text{ and } c^2 \nabla^2 B = \ddot{B}$$
 (8.2)

From Maxwell's equations where E is electric field, B is magnetic field. Derived using:

$$\nabla \cdot E = \frac{\rho}{\epsilon_0}, \quad \nabla \times E = -\frac{\partial B}{\partial t}$$
 (8.3)

$$\nabla \cdot B = 0, \quad \nabla \times B = \mu_0 \varepsilon_0 \frac{\partial E}{\partial t}$$
 (8.4)

taking curl of 8.3 and 8.4 and using  $\nabla \times (\nabla \times \vec{V}) = \nabla(\nabla \cdot \vec{V}) - \nabla^2 \vec{V}$  and  $\nabla(\nabla \cdot E) = \nabla\left(\frac{\rho}{\epsilon_0}\right) = 0$ ,  $\nabla(\nabla \cdot B) = 0$  gives Equation 8.2 where  $c = \sqrt{\frac{1}{\mu_0 \epsilon_0}} = 3 \times 10^8 \text{m/s}$ .