# ME2 Computing- Session 6: Numerical solution of differential equations: initial value problems

#### **Learning outcomes:**

- Being able to solve first order ODEs with explicit methods
- Being able to solve first order ODEs with implicit methods
- Being able to solve a system of first order ODEs and Higher order ODEs

## Before you start:

In your H drive create a folder H:\ME2MCP\Session6 and work within it.

We will be testing Tasks A and B with the ODE:  $\frac{dy}{dt} = -2yt - 2t^3$ , whose analytical solution is:  $y = 1 - t^2 + ce^{-t^2}$ 

# Task A: Explicit methods: Forward Euler and RK4

- 1. Write a function, FwEuler, to solve a general ODE  $\frac{dy}{dt} = F(t,y)$  with a forward Euler scheme. The function receives the initial condition,  $t_0$  and  $y_0$ , the time step h and the desired final computational time  $t_{end}$  (all these input arguments are scalars). The function outputs two arrays, t and y, describing the specific solution y(t). Within FwEuler, F(t,y), can be evaluated by invoking a separate function func.
  - Explicit methods are subject to instabilities: consider this when choosing the value of *h*.
- 2. Write a function RK4 to perform as the function at point 1, but implementing a RK4 method instead.

#### Task B: Implicit methods: Backward Euler

1. Write a function, BwEuler, to solve the specific ODE under study, with a backward Euler scheme. The function receives the initial condition,  $t_0$  and  $y_0$ , the time step hand the desired final computational time  $t_{end}$ . The function outputs two arrays, t and y, describing the specific solution y(t).

#### Task C: System of ODEs, with explicit methods

1. Modify the function FwEuler, into a new function FwEulerTwo, to solve the set of two ODEs:

$$\begin{cases} \frac{dy_1}{dt} = F_1(t, y_1, y_2) \\ \frac{dy_2}{dt} = F_2(t, y_1, y_2) \end{cases}$$
 with initial conditions 
$$\begin{cases} y_1(t = t_0) = y_1^0 \\ y_2(t = t_0) = y_2^0 \end{cases}$$

FwEulerTwo receives the vector  $Y_0$  of initial values, the initial and final time  $t_0$  and  $t_{end}$ , and the time step h. FwEulerTwo should output an array t and a two rows array Y with the solutions,  $Y = \begin{bmatrix} y_1(t) \\ y_2(t) \end{bmatrix}$ .

On the side, you also need to define two separate functions, func1, func2, to evaluate  $F_1$  and  $F_2$ , respectively.

2. Test the function to solve the *predator-prey* problem applied to the London property rental market. The cycles of property rental prices vs population are described by the Lokta-Volterra's set of first order ODEs:

$$\begin{cases} \frac{d\mathcal{E}}{dt} = 0.3\mathcal{E}N - 0.8\mathcal{E} \\ \frac{dN}{dt} = 1.1N - N\mathcal{E} \end{cases}$$
 with initial conditions 
$$\begin{cases} \mathcal{E}(t=0) = 0.8 \\ N(t=0) = 7 \end{cases}$$

where £ is the average price of house rentals (in thousands pounds) and N is the number of inhabitants (in millions). Compute the cycles in the period [0:40] years, in steps of 0.019 (i.e. weekly).

3. Plot, on the same graph, the results vs time. Plot also, in a different figure, the number of inhabitants vs the rental price.

## Task D: Higher order ODEs: damped non-linear motion of a pendulum

The oscillation of a pendulum of mass m, attached to a weightless string, is described by the second order ODE:

$$\frac{d^2\theta}{dt^2} + \frac{c}{m}\frac{d\theta}{dt} + \frac{g}{L}\sin\theta = 0$$

where c is the damping coefficient, g the gravitational acceleration and L the length of the string.

The pendulum initially is at rest, displaced at an angle  $\theta_0$ .

The second order ODE can be reduced to a set of two first order ODEs, introducing a new dependent (artificial) variable w:

$$\begin{cases} w = \frac{d\theta}{dt} \\ \frac{dw}{dt} = \left(\frac{d^2\theta}{dt^2}\right) = -\frac{c}{m}\frac{d\theta}{dt} - \frac{g}{L}\sin\theta = -\frac{c}{m}w - \frac{g}{L}\sin\theta \end{cases}$$

1. Determine the motion of the pendulum,  $\theta(t)$ , for the first initial 15 seconds, with initial condition  $\theta(t=0)=\pi/4$ . (Use FwEulertwo with  $\Delta t=0.005s$ ). Use a mass of 0.5Kg and a string L = 1m. Observe the difference between the swinging in a dry place (c = 0.05Ns/m) and within a humid viscous environment (c = 0.18Ns/m).